

1. (b.) $\dot{x} = \mu x - Mx^2 = x(\mu - Mx)$

Steady state: $\dot{x} = 0 \Rightarrow x(\mu - Mx) = 0$

$\Rightarrow \boxed{x=0}$ or $\boxed{x = \frac{\mu}{M}}$

$f(x) = \mu x - Mx^2$, $f'(x) = \mu - 2Mx$

$x=0$: $f'(x)|_{x=0} = \mu$ If $\mu > 0$, $x=0$ is unstable.

If $\mu < 0$, $x=0$ is stable.

$x = \frac{\mu}{M}$: $f'(x)|_{x=\frac{\mu}{M}} = -\mu$ If $\mu > 0$, $x = \frac{\mu}{M}$ is unstable

If $\mu < 0$, $x = \frac{\mu}{M}$ is stable

2. $\dot{x} = x(\mu_x + M_{xx}x + M_{xy}y) = f(x,y)$

$\dot{y} = y(\mu_y + M_{yx}x + M_{yy}y) = g(x,y)$

(a) $(\bar{x}, 0)$: $\bar{x}(\mu_x + M_{xx}\bar{x}) = 0$,

$(0, \bar{y})$: $\bar{y}(\mu_y + M_{yy}\bar{y}) = 0$

$\bar{x} = -\frac{\mu_x}{M_{xx}}$

$\bar{y} = -\frac{\mu_y}{M_{yy}}$

For (\bar{x}, \bar{y}) : since $\bar{x} \neq 0$, $\bar{y} \neq 0$,

$\begin{bmatrix} \mu_x \\ \mu_y \end{bmatrix} + \begin{bmatrix} M_{xx} & M_{xy} \\ M_{yx} & M_{yy} \end{bmatrix} \begin{bmatrix} \bar{x} \\ \bar{y} \end{bmatrix} = 0$

(b) Jacobian = $\begin{bmatrix} f_x & f_y \\ g_x & g_y \end{bmatrix}$

$f_x(x,y) = \mu_x + 2M_{xx}x$

$f_y(x,y) = M_{xy}x$

$g_x(x,y) = M_{yx}y$

$g_y(x,y) = \mu_y + 2M_{yy}y$

at $(0,0)$: Jacobian = $\begin{bmatrix} \mu_x & 0 \\ 0 & \mu_y \end{bmatrix}$

stable if $\mu_x < 0$ and $\mu_y < 0$, otherwise unstable.

at $(\bar{x}, 0)$: Jacobian = $\begin{bmatrix} -\mu_x & -\mu_x \frac{M_{xy}}{M_{xx}} \\ 0 & \mu_y \end{bmatrix}$

eigenvalues are $-\mu_x, \mu_y$.

stable if $\mu_x > 0$ and $\mu_y < 0$, otherwise unstable.

at $(0, \bar{y})$: Jacobian = $\begin{bmatrix} \mu_x & 0 \\ -\frac{M_{xy}}{M_{yy}} \mu_y & -\mu_y \end{bmatrix}$

stable if $\mu_x < 0$ and $\mu_y > 0$, otherwise unstable.

[If we neglect the effect of y]

(C) $M_{xx} > 0$: $\bar{x} = -\frac{u_x}{M_{xx}}$ [if $u_x > 0$,

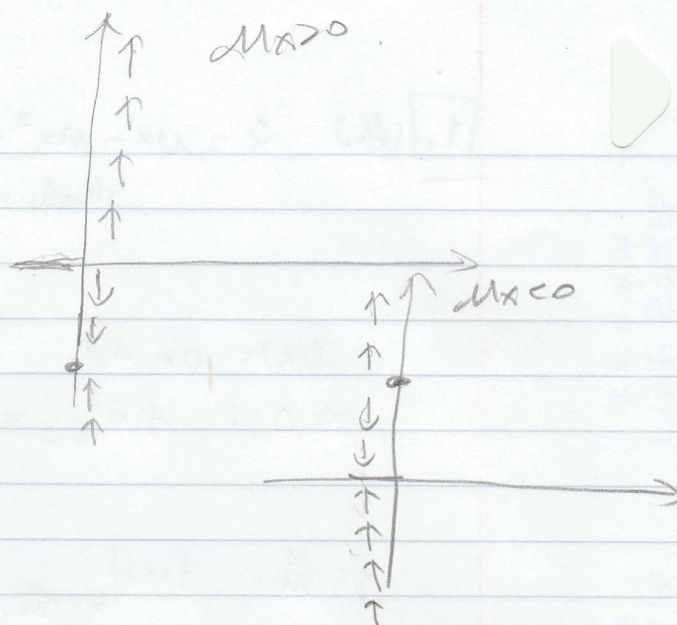
x will diverge if $x > 0$,

converge if $x < 0$.

If $u_x < 0$: x will diverge if

$$x > -\frac{u_x}{M_{xx}},$$

converge if $x < -\frac{u_x}{M_{xx}}$



[3] ^{ex} when $N=2$:

$$\dot{x}_1 = x_1 (u_1 + M_{11}x_1 + M_{12}x_2) \quad \text{same as (2)},$$

$$\dot{x}_2 = x_2 (u_2 + M_{21}x_1 + M_{22}x_2)$$

(b) 4 steady states for $B_2(2)$, $(0,0)$, $(\bar{x},0)$, $(0,\bar{y})$, and (\bar{x},\bar{y}) .

$$\dot{x}_i = x_i (u_i + \sum_{j=1}^N M_{ij} x_j)$$

There are N functions, each one having two possibilities: $x_i = 0$ or $u_i + \sum_{j=1}^N M_{ij} x_j = 0$.

\therefore There are 2^N possibilities for the total group of functions. All 2^N possible groups are linear equations, having 1 solution.

\Rightarrow There are 2^N steady states.

[4] simulation!

$$\dot{x} = x(1 - 0.5x)$$