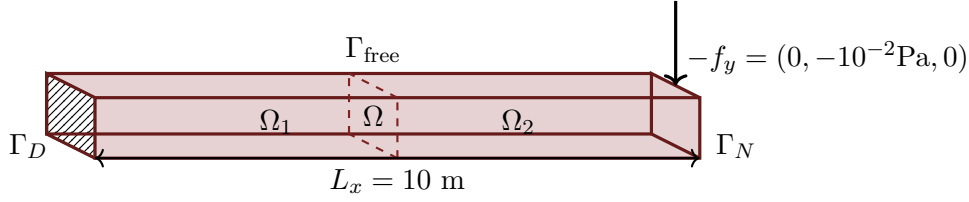


# Weak forms and problem setup — Heterogeneous linear elasticity in a two-material 3D block

## 1 Governing Equations

### 1.1 Geometry and Boundary



Let  $\Omega \subset \mathbb{R}^3$  be the rectangular block:

$$\Omega := (0, L_x) \times (0, L_y) \times (0, L_z), \quad L_x := 10\text{m}, \quad L_y := L_z := 1\text{m}.$$

The domain  $\Omega$  is partitioned at  $x_{\text{int}} := L_x/2$  as:

$$\Omega_1 := \{x < x_{\text{int}}\}, \quad \Omega_2 := \{x \geq x_{\text{int}}\}.$$

Where,  $\Omega = \Omega_1 \cup \Omega_2$ .

The boundary decomposition is:

$$\Gamma_D := \{x = 0\}, \quad \Gamma_N := \{x = L_x\}, \quad \Gamma_{\text{free}} := \partial\Omega \setminus (\Gamma_D \cup \Gamma_N),$$

Where,  $\partial\Omega$  is the boundary of the domain  $\Omega$  and define the closure of  $\Omega$  as follows:  $\overline{\Omega} = \Omega \cup \partial\Omega$ .

### 1.2 Material Parameterization

#### Simulation Parameters

Given Young's modulus  $E \in (0, 10)$  and Poisson ratio  $\nu \in (0, 0.5)$ ,

$$\lambda_0 := \frac{E\nu}{(1+\nu)(1-2\nu)}, \quad \mu_0 := \frac{E}{2(1+\nu)}.$$

Where  $\lambda_0$  and  $\mu_0$  are the Lamé-parameters. Then we define the Lamé-parameters for our two different materials in the rod, at  $\Omega_1$  and  $\Omega_2$  respectively, as follows:

$$(\lambda, \mu)(x; E, \nu) := \begin{cases} (50\lambda_0, 50\mu_0), & x \in \Omega_1, \\ (\lambda_0, \mu_0), & x \in \Omega_2. \end{cases}$$

Units:  $[E] = \text{Pa}$ ,  $[\nu] = 1$ ,  $[\lambda] = \text{Pa}$ ,  $[\mu] = \text{Pa}$ .

Where, the simulation parameters are:  $E$  and  $\nu$ .

### 1.3 Governing Laws

Let  $u : \Omega \rightarrow \mathbb{R}^3$  be the displacement field ( $[u] = \text{m}$ ).

The displacement gradient and the small strain are:

$$\nabla u \in \mathbb{R}^{3 \times 3}, \quad [\nabla u] = 1 \quad (\text{dimensionless}), \quad \varepsilon(u) := \frac{1}{2}(\nabla u + \nabla u^\top), \quad [\varepsilon] = 1 \quad (\text{dimensionless}).$$

For an isotropic linear elastic solid, the Cauchy stress is:

$$\sigma(u) = 2\mu \varepsilon(u) + \lambda \text{tr}(\varepsilon(u)) \mathbf{I}, \quad [\sigma] = \text{Pa}, \quad [\lambda] = [\mu] = \text{Pa},$$

with Lamé-parameters  $(\lambda, \mu)$  specified in the material parameterization and  $\mathbf{I}$  is the identity tensor.

And the traction on a boundary with unit normal  $n$  is:

$$-f_y := \sigma(u) n, \quad [f_y] = \text{Pa}, \quad [n] = 1 \quad (\text{dimensionless}).$$

Where, static equilibrium (no body forces) requires:

$$-\nabla \cdot \sigma(u) = \mathbf{0} \quad \text{in } \Omega, \quad [\nabla \cdot \sigma] = \text{N/m}^3.$$

Where  $\nabla \cdot \sigma(u)$  is the divergence operator being applied to  $\sigma$ .

### 1.4 Governing PDE

Let the space of admissible strong solutions be given by:

$$\mathcal{V}_{\text{strong}} := C^0(\bar{\Omega}) \cap C^2(\Omega).$$

Find  $u \in \mathcal{V}_{\text{strong}}$  such that

$$-\nabla \cdot \sigma(u) = \mathbf{0} \quad \text{in } \Omega, \quad (1)$$

$$u = \mathbf{0} \quad \text{on } \Gamma_D, \quad (2)$$

$$\sigma(u) n = -f_y = (0, -10^{-2}, 0) \quad \text{on } \Gamma_N, \quad (3)$$

$$\sigma(u) n = \mathbf{0} \quad \text{on } \Gamma_{\text{free}}. \quad (4)$$

Here,

$$\sigma(u) := 2\mu \varepsilon(u) + \lambda \text{tr}(\varepsilon(u)) \mathbf{I}, \quad \varepsilon(u) := \frac{1}{2}(\nabla u + \nabla u^\top),$$

where  $\mathbf{I}$  is the identity tensor.

Where  $u \in C^0(\bar{\Omega})$  due to the dirichlet boundary condition 2 on the boundary  $\Gamma_D$  and  $u \in C^2(\Omega)$  due to the strong form 1.

## 2 Weak Form

### 2.1 Variational Statement

Let  $V$  be the test function space:

$$V := \{v \in H^1(\Omega) \mid v = 0 \text{ on } \Gamma_D\}.$$

Given  $(E, \nu)$ , find  $u \in V$  such that

$$a(u, v; E, \nu) = \ell(v) \quad \forall v \in V,$$

$$a(u, v; E, \nu) := \int_{\Omega} [2\mu \varepsilon(u) : \varepsilon(v) + \lambda \operatorname{tr}(\varepsilon(u)) \operatorname{tr}(\varepsilon(v))] dx, \quad (5)$$

$$\ell(v) := \int_{\Gamma_N} -f_y \cdot v ds. \quad (6)$$

## References

- [1] Choi, Youngsoo, Arrighi, William J., Copeland, Dylan M., Anderson, Robert W., & Oxberry, Geoffrey M. (2019, October 17). *libROM*. [Computer software]. <https://github.com/LLNL/libROM>. <https://doi.org/10.11578/dc.20190408.3>; Global pROM for linear elasticity <https://www.librom.net/examples.html> Accessed: 28 July, 2025