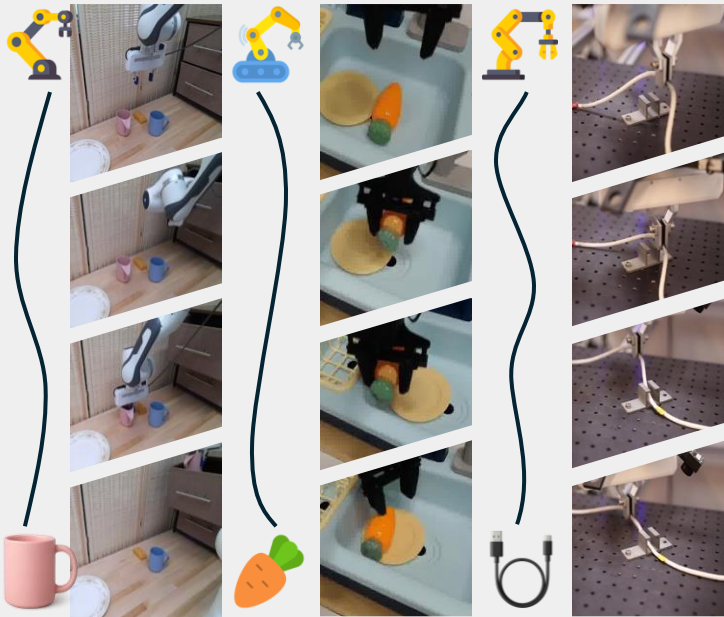
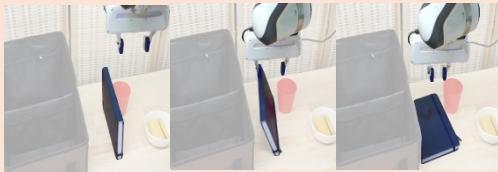




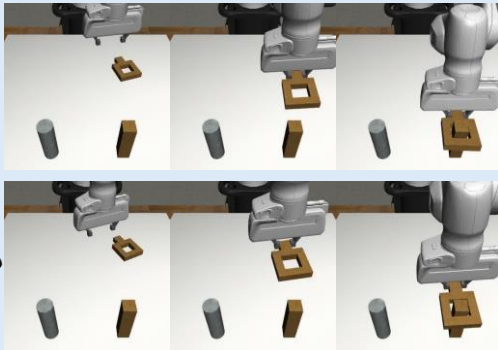
Diverse Robotic Trajectories



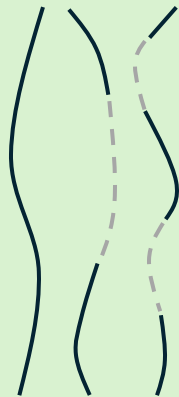
Suboptimal Transitions



Redundant Transitions



Curated Dataset



-- Removed



Better Policy

Success Rate



Original Curated