STAT 339: Statistical Theory

Frequentist Parameter Estimation

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Reminder!

Personal and General Reflections on 50 years of Teaching Statistics

• Event for Undergraduate Teaching Award, Boston Chapter of the ASA



- Tuesday, January 25
- **७**6-7pm ET
- P Register here
- **§** FREE to attend
- ⚠ Please go, if you can!

Examples

- 1. Clinical Trial: What is the risk of major adverse cardiovascular events (MACE) for T2D patients while taking certain treatment regimens?
 - \circ Estimating p, the unknown proportion of MACE for a large group of T2D patients taking a specific treatment
- 2. Piéchart Emporium: What is the average wait time at the checkout counter for PE customers?
 - \circ Estimating μ , the unknown average wait time for PE customers
- 3. **Cell Phone Batteries**: How can we best quantify battery life in a certain type of smart phone?
 - \circ Estimating μ , the unknown average battery life

Considerations: What is the best estimator? How do we determine what makes an estimator best?

Estimators and Estimates

In general, we will refer to θ as the target parameter of interest.

• Can be equal to μ , p, σ^2 , etc., but we'll use θ as a "catch-all".

To estimate one (or more) parameters, we need data!

- For example, suppose the average wait time of a random sample of 20 PE customers was **five minutes**.
 - This is a **point estimate** it is an estimate of θ in the form of a single value.

A point estimator (or statistic), $\hat{\theta}$, is the rule/formula used to calculate the value of an estimate based on sample data.

Examples:

•
$$\bar{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_i$$

$$ullet$$
 $s=\sqrt{rac{1}{n-1}\sum_{i=1}^n(Y_i-ar{Y})^2}$

Estimators and Estimates

Unbiased Estimation

Bias of Point Estimators

Estimators are not perfect! Some are good, some are bad, and others are 💩 💩



Let $\hat{\theta}$ be a point estimator for the parameter θ . Then $\hat{\theta}$ is an **unbiased estimator** if $E(\hat{ heta}) = heta$. If $E(\hat{ heta})
eq heta$, then $\hat{ heta}$ is biased.

• The bias of a point estimator $\hat{\theta}$ is given by $Bias(\hat{\theta}) = E(\hat{\theta}) - \theta$.

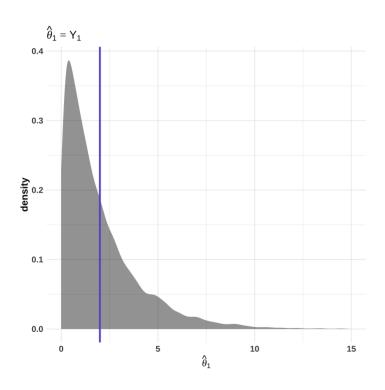
Ideally, the expected value of our estimator $\hat{\theta}$ will equal the parameter (\$\theta\$) that we're trying to estimate.

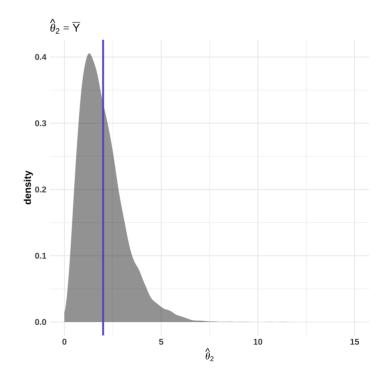
ullet But we also want $\hat{ heta}$ to have a **small variance** - this means a higher fraction of $\hat{ heta}$ values (in repeated sampling) will be close to heta.

Two Unbiased Estimators

 $Y_1, Y_2, Y_3 \sim Exponential(2)$

• Suppose $heta=E(Y_i)=2$. let's try to estimate heta using different $\hat{ heta}$.





Mean Square Error (MSE)

The mean square error (MSE) of a point estimator is the average of the square of the distance between the estimator and target parameter:

$$MSE(\hat{\theta}) = E[(\hat{\theta} - \theta)^2]$$

It can be shown that

$$MSE(\hat{ heta}) = Var(\hat{ heta}) + [Bias(\hat{ heta})]^2.$$

• In other words, $MSE(\hat{\theta})$ is a function of both the variance and bias of $\hat{\theta}$.

Note: For unbiased estimators, $MSE(\hat{\theta}) = Var(\hat{\theta})$.

Biased Estimators

If an estimator $\hat{\theta}$ is **biased** we can usually correct it to make it unbiased.

Example

Suppose that $\hat{\theta}$ is an estimator for a parameter θ and $E(\hat{\theta})=a\theta+b$ for some nonzero constants a and b.

- 1. In terms of a, b, and heta, what is $Bias(\hat{ heta})$?
- 2. Find a function of $\hat{\theta}$, say, $\hat{\theta}^*$, that is an unbiased estimator for θ .
- 3. Express $MSE(\hat{\boldsymbol{\theta}}^*)$ as a function of $Var(\hat{\boldsymbol{\theta}})$.

Order Statistics as Estimators

Let $Y_1, Y_2, \ldots, Y_n \sim Uniform(0, \theta)$, where the target parameter is θ .

ullet Because heta is the upper bound of the support for the Y_i , let's try to use

$$Y_{(n)}=\max(Y_1,Y_2,\ldots,Y_n)$$

as an estimator for θ .

• Is $\hat{ heta} = Y_{(n)}$ unbiased for heta?

From STAT 338: The PDF for $Y_{(n)}$ is

$$g_{(n)}(y) = n[F(y)]^{n-1}f(y),$$

where f(y) is the PDF for Y, and $F(y) = P(Y \leq y)$.

Order Statistics as Estimators

Let Y_1,Y_2,\ldots,Y_n denote a random sample of size n from a population whose density is given by

$$f(y \mid \alpha) = 3\alpha^3 y^{-4}, \quad \alpha \le y,$$

where lpha>0 is unknown. That is, $Y_i\sim Pareto(lpha,eta=3)$, where in general

$$E(Y_i) = lpha eta/(eta-1) \quad ext{and} \quad Var(Y_i) = rac{lpha^2 eta}{(eta-1)^2 (eta-2)}.$$

Show that $\hat{lpha}=Y_{(1)}=\min(Y_1,Y_2,\ldots,Y_n)$ is a biased estimator for lpha.

• Note: If $Y_1, Y_2, \ldots, Y_n \sim iid\ Pareto(lpha, eta)$, then

$$Y_{(1)} \sim Pareto(\alpha, n\beta).$$

Common Unbiased Point Estimators

Sample Mean

Suppose Y_1, \ldots, Y_n are a random sample from some population with mean μ and variance σ^2 .

• Our target parameter is $heta=\mu$. Let's show that $\hat{ heta}=ar{Y}$ is **unbiased**.

Sample Variance

It turns out that

$$S^{2*} = rac{1}{n} \sum_{i=1}^n (Y_i - ar{Y})^2$$

is biased for σ^2 .

• How can we find an **unbiased** estimator for σ^2 ?

Bias/Variance Trade-off

While **unbiased** estimators sound desirable, they are not always the best estimators.

In general, we'd like for $Bias(\hat{\theta})$ to be close to zero. But we also want $Var(\hat{\theta})$ to be close to zero!

- Higher variance means that estimates might be very different across repeated samples.
- ullet Ideally, $MSE(\hat{ heta})$ will be as small as possible.

Bias/Variance Trade-off

$$Y_1, Y_2, \ldots, Y_n \sim iid\ Uniform(0, \theta).$$

Consider three estimators for θ :

1.
$$\hat{ heta}_1=2ar{Y}$$

2.
$$\hat{ heta}_2 = Y_{(n)}$$
.

З.
$$\hat{ heta}_3=2Y_1$$
.

Let's find the bias and variance for each.

Methods of Estimation

The Method of Moments

Finding Estimators

Up to this point, we've mostly used intuition to find estimators $\hat{\theta}$ of θ .

- The sample mean, \bar{Y} , seems like it would be a good estimator for the population mean, μ .
- The sample variance, s^2 , seems like it would be a good estimator for the population variance, σ^2 .

But what if we wanted to find estimators for the α and β parameters, using a sample of observations from the $Gamma(\alpha, \beta)$ distribution?

ullet E(Y)=lphaeta, but we want to find estimators for each of lpha and eta!

Two estimation techniques

- 1. Method of Moments
- 2. Method of Maximum Likelihood

Method of Moments

Recall: The kth moment of a random variable Y is

$$\mu_{k}^{'}=E(Y^{k})$$

ullet Therefore, $\mu_{1}^{'}=E(Y)$, $\mu_{2}^{'}=E(Y^{2})$, etc.

We define the kth sample moment as the average,

$$m_{k}^{'} = rac{1}{n} \sum_{i=1}^{n} Y_{i}^{k}.$$

Method of Moments (MOM): Set $\mu_k^{'}=m_k^{'}$, for $k=1,2,\ldots,t$ (\$t=\$ number of parameters to be estimated) and solve for the parameter(s) of interest.

Uniform MOM Estimator

Let $Y_1, Y_2, \ldots, Y_n \sim iid\ Uniform(0, \theta)$.

- $\mu_{1}^{'} = E(Y) = \theta/2$
- $m_{1}^{'} = \bar{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_{i}$

MOM Estimators for Gamma parameters

Let $Y_1, Y_2, \ldots, Y_n \sim iid \ Gamma(lpha, eta)$, where lpha and eta are unknown.

- Find the MOM estimators for α and β .
- $\mu'_1 = E(Y) = \alpha \beta$.
 - \circ Set this equal to $\frac{1}{n}\sum_{i=1}^n Y_i = \bar{Y}$.

•
$$\mu_2' = E(Y^2) = Var(Y) + [E(Y)]^2 = \alpha \beta^2 + \alpha^2 \beta^2$$
.

 \circ Set this equal to $\frac{1}{n}\sum_{i=1}^n Y_i^2$.

We need to solve the system of equations for α and β .

•
$$ilde{lpha} = rac{nar{Y}^2}{\sum_{i=1}^n (Y_i - ar{Y})^2}$$

$$ullet$$
 $ilde{eta}=rac{ar{Y}}{ ilde{lpha}}=rac{\sum_{i=1}^n(Y_i-ar{Y})^2}{nar{Y}}$

MOM Estimators for Normal parameters

Suppose we have a random sample $Y_1, Y_2, \ldots, Y_n \sim iid\ Normal(\mu, \sigma^2)$.

- Find the MOM estimators for μ and σ^2 .
- $\tilde{\mu} = \bar{X} \Longrightarrow \text{unbiased for } \mu!$
- $ilde{\sigma}^2 = rac{1}{n} \sum_{i=1}^n (Y_i ar{Y})^2 \implies \mathsf{biased} \; \mathsf{for} \; \sigma^2$

Pros and Cons of MOM

Benefits

- Simple to use (just equate sample and population moments)
- Can be used to estimate multiple parameter families

Limitations

- Generate biased estimators in many cases
- Need the moments to exist! (Sorry, Cauchy distribution...)
- MLEs are typically closer to the target quantity...

Methods of Estimation

The Method of Maximum Likelihood

Likelihood Function

Setting: Y_1, Y_2, \ldots, Y_n are iid from a distribution with parameter θ (which might be a single value or a vector of multiple parameters).

ullet The likelihood function, $f(\mathbf{y}\mid heta)$, gives the likelihood of observing our sample

$$(Y_1 = y_1, Y_2 = y_2, \dots, Y_n = y_n)$$

when the parameter is θ .

 \circ For simplicity, we define $\mathbf{y}=(y_1,y_2,\ldots,y_n).$

Example (Continuous random sample)

$$egin{aligned} f(\mathbf{y} \mid heta) &= f(y_1, y_2, \dots, y_n \mid heta) \ &= f(y_1 \mid heta) imes f(y_2 \mid heta) imes \dots imes f(y_n \mid heta) \end{aligned}$$

Note: The likelihood function is sometimes written as $L(\mathbf{y} \mid \theta)$ or $L(\theta)$.

Maximum Likelihood Estimation

Intuition: Choose $\hat{\theta}$ as the estimate of θ that maximizes the likelihood function!

• In this context, $\hat{\theta}$ is called the maximum likelihood estimator (MLE).

Example: Moose's favorite toys

This box came with 45 balls. Sadly, Moose lost most of them under furniture, and there are **four left**.

- Some are red, and some are yellow, but we don't know exactly how many of each.
- Moose really only cares about the red balls, so let's try to estimate how many are red!



Moose's Favorite Toys

We have four balls - some are **red**, and some are yellow. Let's try to estimate how many red balls there are among the four remaining.

- I allow Moose to choose three of these balls at random. Suppose all three are red; yay!
- If our sample yields three red balls, what would be a good estimate of the total number of red balls remaining, n_r ?

The parameter, n_r can be either 3 or 4. We know that Moose choose Y=3 red balls, so n_r cannot equal 0, 1, or 2.

ullet Let's find the *likelihood* of obtaining our sample, in two separate worlds: one with $n_r=3$, and one with $n_r=4$

$$P(Y=3 \mid n_r=3) = rac{inom{3}{3}inom{1}{0}}{inom{4}{3}} = 0.25$$

Moose's Favorite Toys

We have four balls - some are **red**, and some are yellow. Let's try to estimate how many red balls there are among the four remaining.

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$$P(Y=3 \mid n_r=4) = rac{inom{4}{3}}{inom{4}{3}} = 1$$

Because $n_r=4$ maximizes the likelihood of the observed sample, our MLE of n_r is $\hat{n}_r=4$.

Lifetimes of Electrical Components

Suppose the lifetimes of electrical components (in years), Y, are modeled from an exponential distribution. That is, $Y_1, Y_2, \ldots, Y_n \sim Exponential(\theta)$.

- We observe a sample of n=5 component lifetimes: $\mathbf{y}=(3,1.5,2,1.7,2.1)$. Let's find the MLE $\hat{\theta}_{MLE}$ for θ that maximizes the likelihood of this sample.
- 1. Write likelihood:

$$egin{aligned} L(heta) &= f(\mathbf{y} \mid heta) = f(y_1 \mid heta) imes \cdots imes f(y_5 \mid heta) \ &= \left(rac{1}{ heta}
ight) e^{-y_1/ heta} imes \cdots imes \left(rac{1}{ heta}
ight) e^{-y_5/ heta} \ &= rac{1}{ heta^5} \mathrm{exp}igg(rac{-\sum_{i=1}^5 y_i}{ heta}igg) \ &= rac{1}{ heta^5} \mathrm{exp}igg(rac{-10.3}{ heta}igg) \end{aligned}$$

Lifetimes of Electrical Components

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- We observe a sample of n=5 component lifetimes: $\mathbf{y}=(3,1.5,2,1.7,2.1)$. Let's find the MLE $\hat{\theta}_{MLE}$ for θ that maximizes the likelihood of this sample.
- **2**. Take derivative of log-likelihood with respect to θ :
 - $\log L(\theta) = -5 \log \theta (10.3/\theta)$
 - $\frac{d \log L(\theta)}{d \theta} = (-5/\theta) + (10.3/\theta^2)$

Lifetimes of Electrical Components

Suppose the lifetimes of electrical components (in years), Y, are modeled from an exponential distribution. That is, $Y_1, Y_2, \ldots, Y_n \sim Exponential(\theta)$.

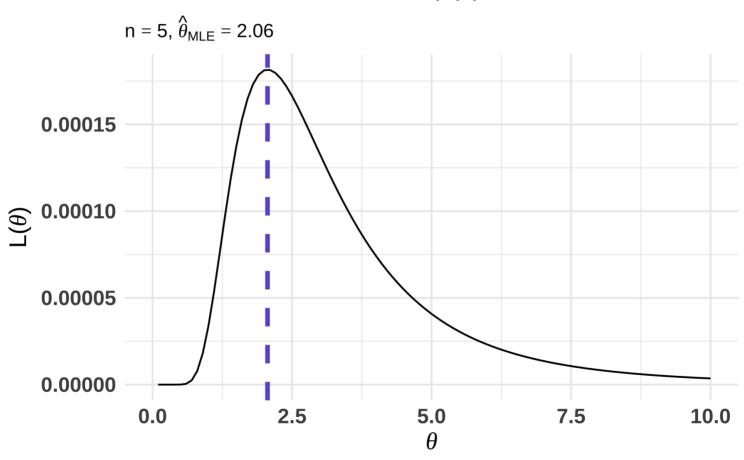
- We observe a sample of n=5 component lifetimes: $\mathbf{y}=(3,1.5,2,1.7,2.1)$. Let's find the MLE $\hat{\theta}_{MLE}$ for θ that maximizes the likelihood of this sample.
- **3**. Solve for θ :
 - $(-5/\theta) + (10.3/\theta^2) = 0 \implies \theta = 10.3/5 = 2.06$

Therefore, $\hat{\theta}_{MLE}=2.06$. Because the data ${\bf y}$ are observed here, 2.06 is a maximum likelihood estimate of θ .

4. (Bonus) Take second derivative of log-likelihood, make sure it is negative at heta=2.06.

Exponential Likelihood

Likelihood function for $Exp(\theta)$



Normal Distribution MLEs

Suppose that Y_1, Y_2, \ldots, Y_n form a random sample from a $Normal(\mu, \sigma^2)$ distribution.

• Find the MLEs of μ and σ^2 .

Note: $\theta = (\mu, \sigma^2)$, so we need to take two different derivatives of $\log L(\theta)$.

Solution

- ullet $\hat{\mu}_{MLE}=ar{Y}$
- $\hat{\sigma}^2_{MLE} = rac{1}{n} \sum_{i=1}^n (Y_i ar{Y})^2$ (a biased estimator!)

Uniform MLE

Suppose that Y_1, Y_2, \ldots, Y_n form a random sample from a $Uniform(0, \theta)$ distribution.

- Find the MLE of θ .
- 1. Write likelihood:

$$egin{aligned} L(heta) &= f(y_1 \mid heta) imes \cdots imes f(y_n \mid heta) \ &= rac{1}{ heta^n}, \quad ext{if } \ 0 \leq y_i \leq heta \end{aligned}$$

- The first derivative of $L(\theta)$ does not equal zero for any $\theta > 0$.
- However, $1/\theta^n$ increases as θ decreases, so we want to select θ to be as small as possible in order to maximize the likelihood.
 - \circ One constraint: All of the y_i values are between 0 and heta.
 - \circ The smallest value of heta that satisfies this constraint is $Y_{(n)} = \max(Y_1, \dots, Y_n)$

Therefore, $\hat{ heta}_{MLE} = Y_{(n)}$.

Pros and Cons of MLE

Benefits

- MLEs are invariant! This means that, if $\hat{\theta}$ is an MLE for $g(\hat{\theta})$ is an MLE for $g(\theta)$.
- MLEs are consistent.

Limitations

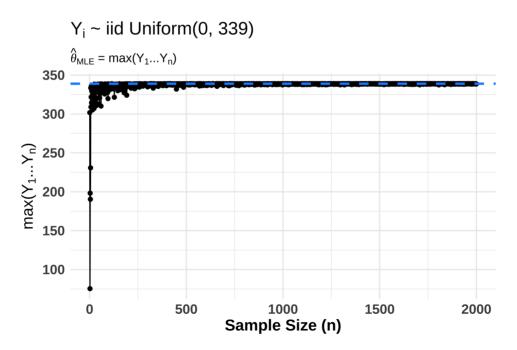
- MLEs do not always exist.
- The MLE is NOT the most likely parameter, given the data (\$E(\theta\mid Y)\$). It estimates the parameter θ that maximizes the distribution of $Y \mid \theta$
 - In other words, the MLE gives the parameter estimate most likely to have produced the observed data.

Consistency of the MLE

The estimator $\hat{\theta}_n$ is said to be **consistent** for θ if, for any $\epsilon>0$,

$$\lim_{n o \infty} P(|\hat{ heta}_n - heta| \le \epsilon) = 1.$$

• Basically, this means that if n is large enough, there is a probability of 1 that $\hat{\theta}_n$ will be very close to θ .



Data Reduction: Sufficiency

Sufficient Statistics

Most of the estimators we've chosen have seemed like they would be good estimators.

• The sample mean, $ar{Y}$, is probably a solid estimator for the population mean μ .

Once we calculate \bar{Y} , the actual sample values Y_1, \ldots, Y_n are no longer important; the information in the sample is summarized by \bar{Y} .

 \bullet But does this summary retain all of the information about μ contained in the original n observations?

A statistic that summarizes *all* information in a sample about a target parameter is said to be **sufficient**.

• We'll use sufficient statistics to help determine best (unbiased) estimators.

Factorization Criterion

Theorem

Let U be a statistic based on the random sample Y_1, \ldots, Y_n . Then U is a sufficient statistic for the estimation of a parameter θ if and only if the likelihood $L(\theta) = f(y_1, \ldots, y_n \mid \theta)$ can be factored into two nonnegative functions:

$$L(heta) = g(u, heta) imes h(y_1,\ldots,y_n)$$

where:

- g(u, heta) is a function only of u and heta, and
- $h(y_1,\ldots,y_n)$ is not a function of θ .

Process for Finding a Sufficient Statistic

- 1. Write out the likelihood, $L(\theta) = f(y_1 \mid \theta) \times \cdots \times f(y_n \mid \theta)$.
- 2. Given some statistic U, check if L(heta) can be broken down into g(u, heta) and $h(y_1,\ldots,y_n).$
 - Note: There are often more than one sufficient statistic for any parameter.

Sufficient Statistic Examples

1. Let Y_1, Y_2, \ldots, Y_n be a random sample such that $Y_i \sim Exponential(heta)$ with PDF

$$f(y_i \mid heta) = rac{1}{ heta} e^{-y_i/ heta}, \quad y_i > 0.$$

Show that $U=ar{Y}$ is a sufficient statistic for heta.

2. Let Y_1,Y_2,\ldots,Y_n be a random sample such that $Y_i\sim Beta(heta,1)$ with PDF

$$f(y_i \mid heta) = heta y^{ heta - 1}, \quad 0 < y < 1.$$

Show that $U=\prod_{i=1}^n Y_i=Y_1 imes\cdots imes Y_n$ is a sufficient statistic for heta.

Rao-Blackwell Theorem

Let $\hat{\theta}$ be an unbiased estimator for θ If $\hat{\theta}$ has a smaller variance than all other unbiased estimators for θ , then $\hat{\theta}$ is the **best unbiased estimator** (BUE) (the "boo").



Rao-Blackwell Theorem

Let h(U) be some function of a statistic, U. If:

- ullet U is a sufficient statistic for heta
- $E[h(U)] = \theta$

then it follows that $\hat{\theta} = h(U)$ is the best unbiased estimator for θ .

Sampling Distributions of Estimators

Recap

What have we done so far? \(\bar{X} \) \(\bar{X} \)

We've used **point estimators** (or statistics), $\hat{\theta}$, to estimate unknown target **parameters**, θ .

- These estimators are functions of:
 - o observable random variables in a sample
 - known constants (usually the sample size, n)
- While unknown, θ is assumed to be fixed at some value.

Because statistics are functions of random variables...

All statistics are random variables!

Because all statistics are random variables, all statistics have probability distributions that illustrate (among other things) how much they vary from sample to sample.

• These "special" probability distributions are called **sampling distributions**.

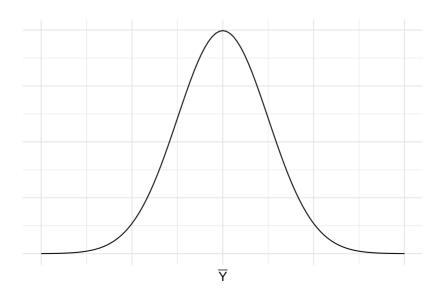
Why sampling distributions?

Before the sample has been taken, we can use the sampling distribution of $\hat{\theta}$ to calculate the probability that $\hat{\theta}$ will be close to θ .

Example

Let $Y_1, Y_2, \ldots, Y_n \sim iid\ Normal(\mu, \sigma^2)$. Then:

$$ar{Y} \sim Normal\left(\mu, rac{\sigma^2}{n}
ight).$$



Chi-Squared Distribution

Again, suppose that $Y_1, Y_2, \ldots, Y_n \sim iid\ Normal(\mu, \sigma^2)$.

- Though now we want to work with the sample variance, S^2 .
- 1. Unbiased Estimator:

$$S^2 = rac{1}{n-1} \sum_{i=1}^n (Y_i - ar{Y})^2$$

2. MLE (and MOM Estimator):

$$\hat{\sigma}^2_{MLE} = rac{1}{n} \sum_{i=1}^n (Y_i - ar{Y})^2$$

It turns out that, except for a scale factor, the sample variance follows a χ^2 (chisquared) distribution with n-1 degrees of freedom.

Chi-Squared Distribution

Theorem

Let Y_1,Y_2,\ldots,Y_n be a random sample from a $Normal(\mu,\sigma^2)$ distribution. Then

$$rac{(n-1)S^2}{\sigma^2} = rac{\sum_{i=1}^n (Y_i - ar{Y})^2}{\sigma^2} \sim \chi^2(n-1).$$

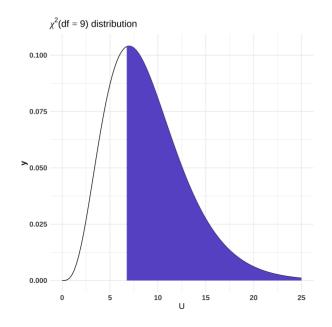
Example

Suppose $Y_1, Y_2, \ldots, Y_{10} \sim iid\ Normal(\mu, \sigma^2 = 4)$.

• μ is unknown, and σ^2 is known.

Because n=10 and $\sigma^2=4$, the sampling distribution $U=9S^2/4\sim \chi^2(df=9)$.

• Let's use this to find $P(S^2>3)$.



$$P(S^2 > 3) = P\left(rac{9S^2}{4} > rac{9 imes 3}{4}
ight) = P(U > 6.75)$$

1 - pchisq(6.75, df = 9)

[1] 0.6631296

Student's t Distribution

When the population standard deviation, σ , is *unknown*, it can be estimated by $S=\sqrt{S^2}$, and the quantity

$$T=rac{ar{Y}-\mu}{s/\sqrt{n}}$$

is used in certain procedures for inference about μ .

• This quantity, T, has a **t distribution** with n-1 degrees of freedom!

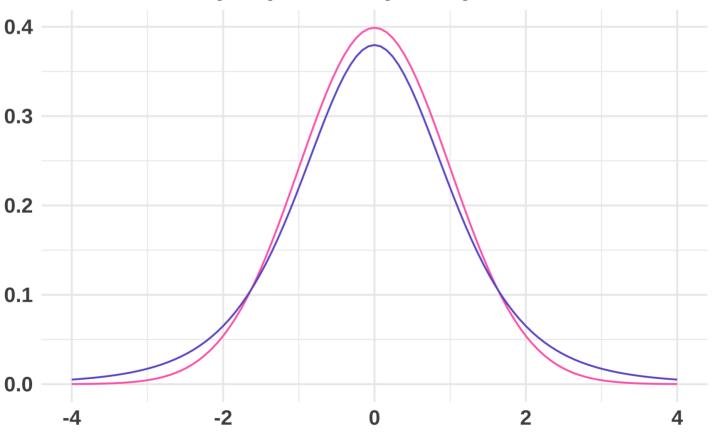
Definition: Let Z be a **standard Normal** random variable, and let W be a χ^2 -distributed random variable with ν degrees of freedom. Then, if Z and W are independent,

$$T=rac{Z}{\sqrt{W/
u}}$$

is said to have a **t distribution** with ν degrees of freedom.

Student's t vs. Normal

Pink: Normal(0, 1); Blue: t(df = 5)



F Distribution

Suppose now that we are comparing the variances from two normal samples:

- $ullet X_1, X_2, \dots, X_n \sim N(\mu_X, \sigma_X^2)$
- $ullet Y_1, Y_2, \dots, Y_n \sim N(\mu_Y, \sigma_Y^2)$

Question

Are the sample data consistent with the assumption that $\sigma_X^2 = \sigma_Y^2$?

- We know that S_X^2 and S_Y^2 are unbiased estimators of σ_X^2 and σ_Y^2 , respectively.
 - \circ Let's look at the ratio, S_X^2/S_Y^2 .
- ullet It turns out that, if we divide each S^2 by its respective σ^2 , then the ratio

$$rac{S_X^2/\sigma_X^2}{S_Y^2/\sigma_Y^2} \sim F(df_1 = n_X - 1, df_2 = n_Y - 1)$$

F Distribution

General Definition

Let W_1 and W_2 be independent χ^2 -distributed random variables with u_1 and u_2 df, respectively. Then

$$F = rac{W_1/
u_1}{W_2/
u_2} \sim F(
u_1,
u_2).$$

Example: Suppose...

$$ullet$$
 $X_1,\ldots,X_{21}\sim N(\mu_X,\sigma_X^2)$, $S_X^2=994.7$

$$ullet$$
 $Y_1,\ldots,Y_{15}\sim N(\mu_Y,\sigma_Y^2)$, $S_Y^2=250.3$

Is it reasonable to assume that $\sigma_X^2 = \sigma_Y^2$?

IF
$$\sigma_X^2 = \sigma_Y^2$$
 , then $rac{S_X^2}{S_Y^2} \sim F(20,14)$:

$$P(rac{S_X^2}{S_Y^2} > rac{994.7}{250.3}) = P(F > 3.97) = 0.006$$

Recap

We have developed **sampling distributions** of statistics calculated by using observations in random samples from **Normal** populations.

If
$$Y_1,\ldots,Y_n\sim iid\;N(\mu,\sigma^2)$$
 , then...

1.
$$\sqrt{n}(ar{Y}-\mu)/\sigma \sim N(0,1)$$

2.
$$(n-1)S^2/\sigma^2 \sim \chi^2(n-1)$$

3.
$$\sqrt{n}(ar{Y}-\mu)/S \sim t(n-1)$$

4. $F=(S_1^2/\sigma_1^2)/(S_2^2/\sigma_2^2)\sim F(n_1-1,n_2-1)$, provided that the samples are independent.

These sampling distributions will help us quite a bit later on with confidence intervals and hypothesis tests!

Frequentist Estimation

This first unit of STAT 339 has been devoted to estimation from a **frequentist** perspective.

- Frequentists view probability as a representation of a long-run frequency over a large (sometimes infinite) number of repetitions of an experiment.
- The true value of a parameter, θ , is fixed and unknown.

In the next unit, we will focus on estimation from a Bayesian perspective.

- Bayesians view probability as a representation of a relative plausibility of an event.
- Parameters, θ , are themselves treated as random variables, assigned some prior distribution.
 - Gives weight to prior knowledge.

While we will study various procedures through both frequentist and Bayesian lenses, these are **not** competing!

 Both perspectives aim to learn from data, both use data to fit models, evaluate hypotheses, etc.