## STAT 339: Statistical Theory

Frequentist Parameter Estimation

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### Reminder!

#### Personal and General Reflections on 50 years of Teaching Statistics

• Event for Undergraduate Teaching Award, Boston Chapter of the ASA



- Tuesday, January 25
- **७**6-7pm ET
- P Register here
- **§** FREE to attend
- ⚠ Please go, if you can!

## **Examples**

- 1. Clinical Trial: What is the risk of major adverse cardiovascular events (MACE) for T2D patients while taking certain treatment regimens?
  - $\circ$  Estimating p, the unknown proportion of MACE for a large group of T2D patients taking a specific treatment
- 2. Piéchart Emporium: What is the average wait time at the checkout counter for PE customers?
  - $\circ$  Estimating  $\mu$ , the unknown average wait time for PE customers
- 3. **Cell Phone Batteries**: How can we best quantify battery life in a certain type of smart phone?
  - $\circ$  Estimating  $\mu$ , the unknown average battery life

**Considerations**: What is the best estimator? How do we determine what makes an estimator best?

### **Estimators and Estimates**

In general, we will refer to  $\theta$  as the target parameter of interest.

• Can be equal to  $\mu$ , p,  $\sigma^2$ , etc., but we'll use  $\theta$  as a "catch-all".

To estimate one (or more) parameters, we need data!

- For example, suppose the average wait time of a random sample of 20 PE customers was **five minutes**.
  - $\circ$  This is a **point estimate** it is an estimate of  $\theta$  in the form of a single value.

A point estimator (or statistic),  $\hat{\theta}$ , is the rule/formula used to calculate the value of an estimate based on sample data.

#### **Examples:**

• 
$$\bar{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_i$$

$$ullet$$
  $s=\sqrt{rac{1}{n-1}\sum_{i=1}^n(Y_i-ar{Y})^2}$ 

## **Estimators and Estimates**

## **Unbiased Estimation**

### Bias of Point Estimators

Estimators are not perfect! Some are good, some are bad, and others are 💩 💩



Let  $\hat{\theta}$  be a point estimator for the parameter  $\theta$ . Then  $\hat{\theta}$  is an **unbiased estimator** if  $E(\hat{ heta}) = heta$ . If  $E(\hat{ heta}) 
eq heta$ , then  $\hat{ heta}$  is biased.

• The bias of a point estimator  $\hat{\theta}$  is given by  $Bias(\hat{\theta}) = E(\hat{\theta}) - \theta$ .

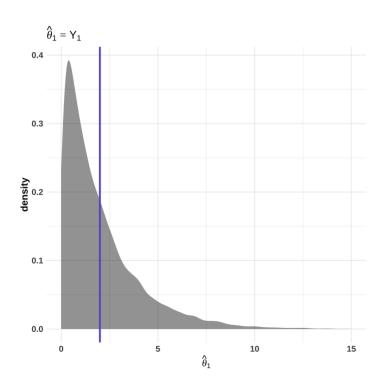
Ideally, the expected value of our estimator  $\hat{\theta}$  will equal the parameter (\$\theta\$) that we're trying to estimate.

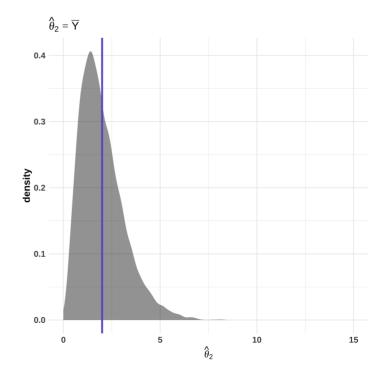
ullet But we also want  $\hat{ heta}$  to have a **small variance** - this means a higher fraction of  $\hat{ heta}$  values (in repeated sampling) will be close to heta.

## Two Unbiased Estimators

 $Y_1, Y_2, Y_3 \sim Exponential(2)$ 

• Suppose  $heta=E(Y_i)=2$ . let's try to estimate heta using different  $\hat{ heta}$ .





## Mean Square Error (MSE)

The mean square error (MSE) of a point estimator is the average of the square of the distance between the estimator and target parameter:

$$MSE(\hat{\theta}) = E[(\hat{\theta} - \theta)^2]$$

It can be shown that

$$MSE(\hat{ heta}) = Var(\hat{ heta}) + [Bias(\hat{ heta})]^2.$$

• In other words,  $MSE(\hat{\theta})$  is a function of both the variance and bias of  $\hat{\theta}$ .

**Note**: For unbiased estimators,  $MSE(\hat{\theta}) = Var(\hat{\theta})$ .

### **Biased Estimators**

If an estimator  $\hat{\theta}$  is **biased** we can usually correct it to make it unbiased.

#### Example

Suppose that  $\hat{\theta}$  is an estimator for a parameter  $\theta$  and  $E(\hat{\theta})=a\theta+b$  for some nonzero constants a and b.

- 1. In terms of a, b, and heta, what is  $Bias(\hat{ heta})$ ?
- 2. Find a function of  $\hat{\theta}$ , say,  $\hat{\theta}^*$ , that is an unbiased estimator for  $\theta$ .
- 3. Express  $MSE(\hat{\boldsymbol{\theta}}^*)$  as a function of  $Var(\hat{\boldsymbol{\theta}})$ .

### Order Statistics as Estimators

Let  $Y_1, Y_2, \ldots, Y_n \sim Uniform(0, \theta)$ , where the target parameter is  $\theta$ .

ullet Because heta is the upper bound of the support for the  $Y_i$ , let's try to use

$$Y_{(n)} = \max(Y_1,Y_2,\ldots,Y_n)$$

as an estimator for  $\theta$ .

• Is  $\hat{ heta} = Y_{(n)}$  unbiased for heta?

From STAT 338: The PDF for  $Y_{(n)}$  is

$$g_{(n)}(y) = n[F(y)]^{n-1}f(y),$$

where f(y) is the PDF for Y, and  $F(y) = P(Y \leq y)$ .

### Order Statistics as Estimators

Let  $Y_1,Y_2,\ldots,Y_n$  denote a random sample of size n from a population whose density is given by

$$f(y \mid \alpha) = 3\alpha^3 y^{-4}, \quad \alpha \le y,$$

where lpha>0 is unknown. That is,  $Y_i\sim Pareto(lpha,eta=3)$  , where in general

$$E(Y_i) = \alpha \beta / (\beta - 1).$$

Show that  $\hat{lpha}=Y_{(1)}=\min(Y_1,Y_2,\ldots,Y_n)$  is a biased estimator for lpha.

### Common Unbiased Point Estimators

#### Sample Mean

Suppose  $Y_1, \ldots, Y_n$  are a random sample from some population with mean  $\mu$  and variance  $\sigma^2$ .

• Our target parameter is  $heta=\mu$ . Let's show that  $\hat{ heta}=ar{Y}$  is **unbiased**.

#### Sample Variance

It turns out that

$$\hat{ heta} = rac{1}{n} \sum_{i=1}^n (Y_i - ar{Y})^2$$

is biased for  $\sigma^2$ .

• How can we find an **unbiased** estimator for  $\sigma^2$ ?

#### **Estimator for Binomial Variance**

If Y has a binomial distribution with parameters n and p, then we have seen that  $\hat{p}=Y/n$  is an unbiased estimator for p.

To estimate the variance of Y, where Var(Y)=np(1-p), we generally use

$$\widehat{Var}(Y) = n\hat{p}(1-\hat{p}).$$

- 1. Show that the suggested estimator is a biased estimator of Var(Y).
- 2. Modify  $n\hat{p}\;(1-\hat{p})$  slightly to form an unbiased estimator of Var(Y).

## Bias/Variance Trade-off

While **unbiased** estimators sound desirable, they are not always the best estimators.

In general, we'd like for  $Bias(\hat{\theta})$  to be close to zero. But we also want  $Var(\hat{\theta})$  to be close to zero!

- Higher variance means that estimates might be very different across repeated samples.
- ullet Ideally,  $MSE(\hat{ heta})$  will be as small as possible.

## Bias/Variance Trade-off

$$Y_1, Y_2, \ldots, Y_n \sim iid\ Uniform(0, \theta).$$

Consider three estimators for  $\theta$ :

1. 
$$\hat{ heta}_1=2ar{Y}$$

2. 
$$\hat{ heta}_2 = Y_{(n)}$$
.

З. 
$$\hat{ heta}_3=2Y_1$$
.

Let's find the bias and variance for each.

## **Methods of Estimation**

#### The Method of Moments

## Finding Estimators

Up to this point, we've mostly used intuition to find estimators  $\hat{\theta}$  of  $\theta$ .

- The sample mean,  $\bar{Y}$ , seems like it would be a good estimator for the population mean,  $\mu$ .
- The sample variance,  $s^2$ , seems like it would be a good estimator for the population variance,  $\sigma^2$ .

But what if we wanted to find estimators for the  $\alpha$  and  $\beta$  parameters, using a sample of observations from the  $Gamma(\alpha, \beta)$  distribution?

ullet E(Y)=lphaeta, but we want to find estimators for each of lpha and eta!

#### Two estimation techniques

- 1. Method of Moments
- 2. Method of Maximum Likelihood

### Method of Moments

Recall: The kth moment of a random variable Y is

$$\mu_{k}^{'}=E(Y^{k})$$

ullet Therefore,  $\mu_{1}^{'}=E(Y)$ ,  $\mu_{2}^{'}=E(Y^{2})$ , etc.

We define the kth sample moment as the average,

$$m_{k}^{'} = rac{1}{n} \sum_{i=1}^{n} Y_{i}^{k}.$$

Method of Moments (MOM): Set  $\mu_k^{'}=m_k^{'}$ , for  $k=1,2,\ldots,t$  (\$t=\$ number of parameters to be estimated) and solve for the parameter(s) of interest.

## **Uniform MOM Estimator**

Let  $Y_1, Y_2, \ldots, Y_n \sim iid\ Uniform(0, \theta)$ .

- $\mu_{1}^{'} = E(Y) = \theta/2$
- $m_{1}^{'} = \bar{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_{i}$

## MOM Estimators for Gamma parameters

Let  $Y_1, Y_2, \ldots, Y_n \sim iid \ Gamma(lpha, eta)$ , where lpha and eta are unknown.

- Find the MOM estimators for  $\alpha$  and  $\beta$ .
- $\mu'_1 = E(Y) = \alpha \beta$ .
  - $\circ$  Set this equal to  $\frac{1}{n}\sum_{i=1}^n Y_i = \bar{Y}$ .

• 
$$\mu_2' = E(Y^2) = Var(Y) + [E(Y)]^2 = \alpha \beta^2 + \alpha^2 \beta^2$$
.

 $\circ$  Set this equal to  $rac{1}{n}\sum_{i=1}^n Y_i^2$ .

We need to solve the system of equations for  $\alpha$  and  $\beta$ .

• 
$$ilde{lpha} = rac{nar{Y}^2}{\sum_{i=1}^n (Y_i - ar{Y})^2}$$

$$ullet$$
  $ilde{eta}=rac{ar{Y}}{ ilde{lpha}}=rac{\sum_{i=1}^n(Y_i-ar{Y})^2}{nar{Y}}$ 

## MOM Estimators for Normal parameters

Suppose we have a random sample  $Y_1,Y_2,\ldots,Y_n\sim iid\ Normal(\mu,\sigma^2)$ .

- Find the MOM estimators for  $\mu$  and  $\sigma^2$ .
- $\tilde{\mu} = \bar{X} \Longrightarrow \text{unbiased for } \mu!$
- $ilde{\sigma}^2 = rac{1}{n} \sum_{i=1}^n (Y_i ar{Y})^2 \implies \mathsf{biased} \; \mathsf{for} \; \sigma^2$

### Pros and Cons of MOM

#### **Benefits**

- Simple to use (just equate sample and population moments)
- Can be used to estimate multiple parameter families

#### **Limitations**

- Generate biased estimators in many cases
- Need the moments to exist! (Sorry, Cauchy distribution...)
- MLEs are typically closer to the target quantity...

## Methods of Estimation

#### The Method of Maximum Likelihood

## Likelihood Function

Setting:  $Y_1, Y_2, \ldots, Y_n$  are iid from a distribution with parameter  $\theta$  (which might be a single value or a vector of multiple parameters).

ullet The likelihood function,  $f(\mathbf{y}\mid heta)$ , gives the likelihood of observing our sample

$$(Y_1 = y_1, Y_2 = y_2, \dots, Y_n = y_n)$$

when the parameter is  $\theta$ .

 $\circ$  For simplicity, we define  $\mathbf{y}=(y_1,y_2,\ldots,y_n).$ 

**Example** (Continuous random sample)

$$egin{aligned} f(\mathbf{y} \mid heta) &= f(y_1, y_2, \dots, y_n \mid heta) \ &= f(y_1 \mid heta) imes f(y_2 \mid heta) imes \dots imes f(y_n \mid heta) \end{aligned}$$

**Note**: The likelihood function is sometimes written as  $L(\mathbf{y} \mid \theta)$  or  $L(\theta)$ .

### Maximum Likelihood Estimation

Intuition: Choose  $\hat{\theta}$  as the estimate of  $\theta$  that maximizes the likelihood function!

• In this context,  $\hat{\theta}$  is called the maximum likelihood estimator (MLE).

**Example:** Moose's favorite toys

This box came with 45 balls. Sadly, Moose lost most of them under furniture, and there are **four left**.

- Some are red, and some are yellow, but we don't know exactly how many of each.
- Moose really only cares about the red balls, so let's try to estimate how many are red!



# Moose's Favorite Toys

We have four balls - some are **red**, and some are yellow. Let's try to estimate how many red balls there are among the four remaining.

- I allow Moose to choose three of these balls at random. Suppose all three are red; yay!
- If our sample yields three red balls, what would be a good estimate of the total number of red balls remaining,  $n_r$ ?

The parameter,  $n_r$  can be either 3 or 4. We know that Moose choose Y=3 red balls, so  $n_r$  cannot equal 0, 1, or 2.

ullet Let's find the *likelihood* of obtaining our sample, in two separate worlds: one with  $n_r=3$ , and one with  $n_r=4$ 

$$P(Y=3 \mid n_r=3) = rac{inom{3}{3}inom{1}{0}}{inom{4}{3}} = 0.25$$

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$$P(Y=3 \mid n_r=4) = rac{inom{4}{3}}{inom{4}{3}} = 1$$

Because  $n_r=4$  maximizes the likelihood of the observed sample, our MLE of  $n_r$  is  $\hat{n}_r=4$ .

## Lifetimes of Electrical Components

Suppose the lifetimes of electrical components (in years), Y, are modeled from an exponential distribution. That is,  $Y_1, Y_2, \ldots, Y_n \sim Exponential(\theta)$ .

- We observe a sample of n=5 component lifetimes:  $\mathbf{y}=(3,1.5,2,1.7,2.1)$ . Let's find the MLE  $\hat{\theta}_{MLE}$  for  $\theta$  that maximizes the likelihood of this sample.
- 1. Write likelihood:

$$egin{aligned} L( heta) &= f(\mathbf{y} \mid heta) = f(y_1 \mid heta) imes \cdots imes f(y_5 \mid heta) \ &= \left(rac{1}{ heta}
ight) e^{-y_1/ heta} imes \cdots imes \left(rac{1}{ heta}
ight) e^{-y_5/ heta} \ &= rac{1}{ heta^5} \mathrm{exp}igg(rac{-\sum_{i=1}^5 y_i}{ heta}igg) \ &= rac{1}{ heta^5} \mathrm{exp}igg(rac{-10.3}{ heta}igg) \end{aligned}$$

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- **2**. Take derivative of log-likelihood with respect to  $\theta$ :
  - $\log L(\theta) = -5 \log \theta (10.3/\theta)$
  - $\frac{d \log L(\theta)}{d \theta} = (-5/\theta) + (10.3/\theta^2)$

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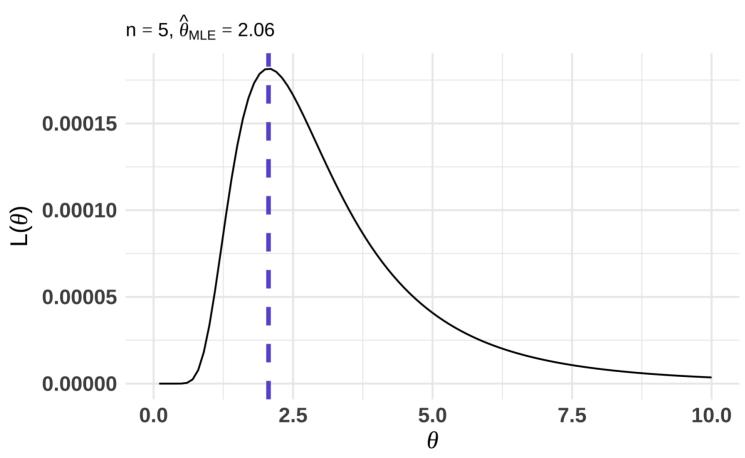
- We observe a sample of n=5 component lifetimes:  $\mathbf{y}=(3,1.5,2,1.7,2.1)$ . Let's find the MLE  $\hat{\theta}_{MLE}$  for  $\theta$  that maximizes the likelihood of this sample.
- **3**. Solve for  $\theta$ :
  - $(-5/\theta) + (10.3/\theta^2) = 0 \implies \theta = 10.3/5 = 2.06$

Therefore,  $\hat{\theta}_{MLE}=2.06$ . Because the data  ${\bf y}$  are observed here, 2.06 is a maximum likelihood estimate of  $\theta$ .

**4**. (Bonus) Take second derivative of log-likelihood, make sure it is negative at heta=2.06.

## **Exponential Likelihood**

#### Likelihood function for $Exp(\theta)$



## Normal Distribution MLEs

Suppose that  $Y_1, Y_2, \ldots, Y_n$  form a random sample from a  $Normal(\mu, \sigma^2)$  distribution.

• Find the MLEs of  $\mu$  and  $\sigma^2$ .

Note:  $\theta = (\mu, \sigma^2)$ , so we need to take two different derivatives of  $\log L(\theta)$ .

#### Solution

- ullet  $\hat{\mu}_{MLE}=ar{Y}$
- $\hat{\sigma}^2_{MLE} = rac{1}{n} \sum_{i=1}^n (Y_i ar{Y})^2$  (a biased estimator!)

## **Uniform MLE**

Suppose that  $Y_1, Y_2, \ldots, Y_n$  form a random sample from a  $Uniform(0, \theta)$  distribution.

- Find the MLE of  $\theta$ .
- 1. Write likelihood:

$$egin{aligned} L( heta) &= f(y_1 \mid heta) imes \cdots imes f(y_n \mid heta) \ &= rac{1}{ heta^n}, \quad ext{if } \ 0 \leq y_i \leq heta \end{aligned}$$

- The first derivative of  $L(\theta)$  does not equal zero for any  $\theta > 0$ .
- However,  $1/\theta^n$  increases as  $\theta$  decreases, so we want to select  $\theta$  to be as small as possible in order to maximize the likelihood.
  - $\circ$  One constraint: All of the  $y_i$  values are between 0 and heta.
  - $\circ$  The smallest value of heta that satisfies this constraint is  $Y_{(n)} = \max(Y_1, \dots, Y_n)$

Therefore, 
$$\hat{ heta}_{MLE} = Y_{(n)}$$
.

### Pros and Cons of MLE

#### **Benefits**

- MLEs are invariant! This means that, if  $\hat{\theta}$  is an MLE for  $g(\hat{\theta})$  is an MLE for  $g(\theta)$ .
- MLEs are consistent.

#### **Limitations**

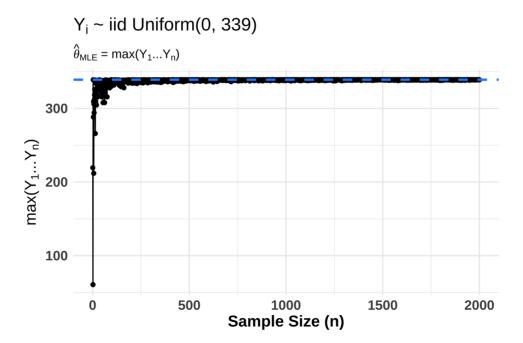
- MLEs do not always exist.
- The MLE is NOT the most likely parameter, given the data (\$E(\theta\mid Y)\$). It estimates the parameter  $\theta$  that maximizes the distribution of  $Y \mid \theta$ 
  - In other words, the MLE gives the parameter estimate most likely to have produced the observed data.

## Consistency of the MLE

The estimator  $\hat{\theta}_n$  is said to be **consistent** for  $\theta$  if, for any  $\epsilon > 0$ ,

$$\lim_{n o \infty} P(|\hat{ heta}_n - heta| \le \epsilon) = 1.$$

• Basically, this means that if n is large enough, there is a probability of 1 that  $\hat{\theta}_n$  will be very close to  $\theta$ .



# **Data Reduction: Sufficiency**

### **Sufficient Statistics**

Most of the estimators we've chosen have seemed like they would be good estimators.

• The sample mean,  $ar{Y}$ , is *probably* a solid estimator for the population mean  $\mu$ .

Once we calculate  $\bar{Y}$ , the actual sample values  $Y_1, \ldots, Y_n$  are no longer important; the information in the sample is summarized by  $\bar{Y}$ .

 $\bullet$  But does this summary retain all of the information about  $\mu$  contained in the original n observations?

A statistic that summarizes *all* information in a sample about a target parameter is said to be **sufficient**.

• We'll use sufficient statistics to help determine best (unbiased) estimators.

### **Factorization Criterion**

#### **Theorem**

Let U be a statistic based on the random sample  $Y_1, \ldots, Y_n$ . Then U is a sufficient statistic for the estimation of a parameter  $\theta$  if and only if the likelihood  $L(\theta) = f(y_1, \ldots, y_n \mid \theta)$  can be factored into two nonnegative functions:

$$L( heta) = g(u, heta) imes h(y_1,\ldots,y_n)$$

#### where:

- g(u, heta) is a function only of u and heta, and
- $h(y_1, \ldots, y_n)$  is not a function of  $\theta$ .

### **Process for Finding a Sufficient Statistic**

- 1. Write out the likelihood,  $L(\theta) = f(y_1 \mid \theta) \times \cdots \times f(y_n \mid \theta)$ .
- 2. Given some statistic U, check if L( heta) can be broken down into g(u, heta) and  $h(y_1,\ldots,y_n).$ 
  - Note: There are often more than one sufficient statistic for any parameter.

# Sufficient Statistic Examples

1. Let  $Y_1, Y_2, \ldots, Y_n$  be a random sample such that  $Y_i \sim Exponential( heta)$  with PDF

$$f(y_i \mid heta) = rac{1}{ heta} e^{-y_i/ heta}, \quad y_i > 0.$$

Show that  $U=ar{Y}$  is a sufficient statistic for heta.

2. Let  $Y_1,Y_2,\ldots,Y_n$  be a random sample such that  $Y_i\sim Beta( heta,1)$  with PDF

$$f(y_i \mid heta) = heta y^{ heta - 1}, \quad 0 < y < 1.$$

Show that  $U=\prod_{i=1}^n Y_i=Y_1 imes\cdots imes Y_n$  is a sufficient statistic for heta.

### Rao-Blackwell Theorem

Let  $\hat{\theta}$  be an unbiased estimator for  $\theta$  If  $\hat{\theta}$  has a smaller variance than all other unbiased estimators for  $\theta$ , then  $\hat{\theta}$  is the **best unbiased estimator** (BUE) (the "boo").



#### **Rao-Blackwell Theorem**

Let h(U) be some function of a statistic, U. If:

- U is a sufficient statistic for  $\theta$
- $E[h(U)] = \theta$

then it follows that  $\hat{\theta} = h(U)$  is the best unbiased estimator for  $\theta$ .

# Sampling Distributions of Estimators

## Recap

### What have we done so far? 🛮 🛣

We've used **point estimators** (or statistics),  $\hat{\theta}$ , to estimate unknown target **parameters**,  $\theta$ .

- These estimators are functions of:
  - o observable random variables in a sample
  - known constants (usually the sample size, n)
- While unknown,  $\theta$  is assumed to be fixed at some value.

Because statistics are functions of random variables...

#### All statistics are random variables!

Because all statistics are random variables, all statistics have probability distributions that illustrate (among other things) how much they vary from sample to sample.

• These "special" probability distributions are called **sampling distributions**.

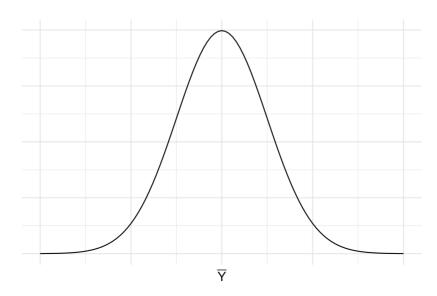
# Why sampling distributions?

Before the sample has been taken, we can use the sampling distribution of  $\hat{\theta}$  to calculate the probability that  $\hat{\theta}$  will be close to  $\theta$ .

### Example

Let  $Y_1, Y_2, \ldots, Y_n \sim iid\ Normal(\mu, \sigma^2)$ . Then:

$$ar{Y} \sim Normal\left(\mu, rac{\sigma^2}{n}
ight).$$



# **Chi-Squared Distribution**

Again, suppose that  $Y_1, Y_2, \ldots, Y_n \sim iid\ Normal(\mu, \sigma^2)$ .

- Though now we want to work with the sample variance,  $S^2$ .
- 1. Unbiased Estimator:

$$S^2 = rac{1}{n-1} \sum_{i=1}^n (Y_i - ar{Y})^2$$

2. MLE (and MOM Estimator):

$$\hat{\sigma}^2_{MLE} = rac{1}{n} \sum_{i=1}^n (Y_i - ar{Y})^2$$

It turns out that, except for a scale factor, the sample variance follows a  $\chi^2$  (chisquared) distribution with n-1 degrees of freedom.

## **Chi-Squared Distribution**

### **Theorem**

Let  $Y_1,Y_2,\ldots,Y_n$  be a random sample from a  $Normal(\mu,\sigma^2)$  distribution. Then

$$rac{(n-1)S^2}{\sigma^2} = rac{\sum_{i=1}^n (Y_i - ar{Y})^2}{\sigma^2} \sim \chi^2(n-1).$$

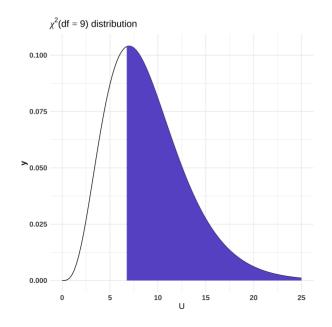
# Example

Suppose  $Y_1, Y_2, \ldots, Y_{10} \sim iid\ Normal(\mu, \sigma^2 = 4)$ .

•  $\mu$  is unknown, and  $\sigma^2$  is known.

Because n=10 and  $\sigma^2=4$ , the sampling distribution  $U=9S^2/4\sim \chi^2(df=9)$ .

• Let's use this to find  $P(S^2>3)$ .



$$P(S^2 > 3) = P\left(rac{9S^2}{4} > rac{9 imes 3}{4}
ight) = P(U > 6.75)$$

1 - pchisq(6.75, df = 9)

## [1] 0.6631296

### Student's t Distribution

When the population standard deviation,  $\sigma$ , is *unknown*, it can be estimated by  $S=\sqrt{S^2}$ , and the quantity

$$T=rac{ar{Y}-\mu}{s/\sqrt{n}}$$

is used in certain procedures for inference about  $\mu$ .

• This quantity, T, has a **t distribution** with n-1 degrees of freedom!

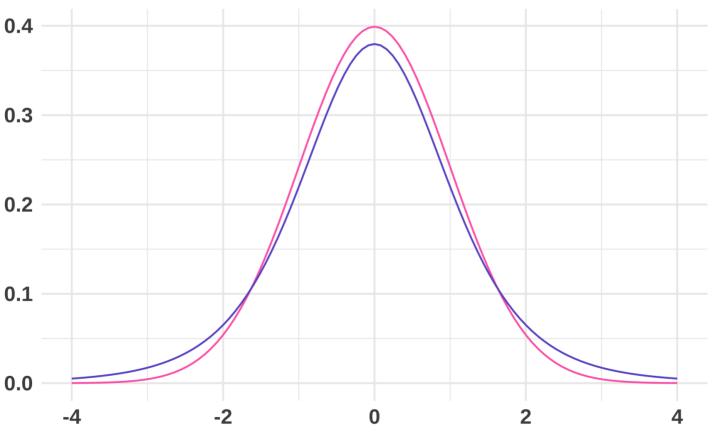
**Definition**: Let Z be a **standard Normal** random variable, and let W be a  $\chi^2$ -distributed random variable with  $\nu$  degrees of freedom. Then, if Z and W are independent,

$$T = rac{Z}{\sqrt{W/
u}}$$

is said to have a **t distribution** with  $\nu$  degrees of freedom.

## Student's t vs. Normal

**Pink: Normal(0, 1); Blue: t(df = 5)** 



### F Distribution

Suppose now that we are comparing the variances from two normal samples:

- $ullet X_1, X_2, \dots, X_n \sim N(\mu_X, \sigma_X^2)$
- $ullet Y_1, Y_2, \dots, Y_n \sim N(\mu_Y, \sigma_Y^2)$

### Question

Are the sample data consistent with the assumption that  $\sigma_X^2 = \sigma_Y^2$ ?

- We know that  $S_X^2$  and  $S_Y^2$  are unbiased estimators of  $\sigma_X^2$  and  $\sigma_Y^2$ , respectively.
  - $\circ$  Let's look at the ratio,  $S_X^2/S_Y^2$ .
- ullet It turns out that, if we divide each  $S^2$  by its respective  $\sigma^2$ , then the ratio

$$rac{S_X^2/\sigma_X^2}{S_Y^2/\sigma_Y^2} \sim F(df_1 = n_X - 1, df_2 = n_Y - 1)$$

### F Distribution

#### **General Definition**

Let  $W_1$  and  $W_2$  be independent  $\chi^2$ -distributed random variables with  $u_1$  and  $u_2$  df, respectively. Then

$$F = rac{W_1/
u_1}{W_2/
u_2} \sim F(
u_1,
u_2).$$

Example: Suppose...

$$ullet$$
  $X_1,\ldots,X_{21}\sim N(\mu_X,\sigma_X^2)$  ,  $S_X^2=994.7$ 

$$ullet$$
  $Y_1,\ldots,Y_{15}\sim N(\mu_Y,\sigma_Y^2)$  ,  $S_Y^2=250.3$ 

Is it reasonable to assume that  $\sigma_X^2 = \sigma_Y^2$ ?

IF 
$$\sigma_X^2 = \sigma_Y^2$$
 , then  $rac{S_X^2}{S_Y^2} \sim F(20,14)$  :

$$P(rac{S_X^2}{S_Y^2} > rac{994.7}{250.3}) = P(F > 3.97) = 0.006$$

## Recap

We have developed **sampling distributions** of statistics calculated by using observations in random samples from **Normal** populations.

If 
$$Y_1,\ldots,Y_n\sim iid\;N(\mu,\sigma^2)$$
 , then...

1. 
$$\sqrt{n}(ar{Y}-\mu)/\sigma \sim N(0,1)$$

2. 
$$(n-1)S^2/\sigma^2 \sim \chi^2(n-1)$$

3. 
$$\sqrt{n}(ar{Y}-\mu)/S \sim t(n-1)$$

4.  $F=(S_1^2/\sigma_1^2)/(S_2^2/\sigma_2^2)\sim F(n_1-1,n_2-1)$ , provided that the samples are independent.

These sampling distributions will help us quite a bit later on with confidence intervals and hypothesis tests!

## Frequentist Estimation

This first unit of STAT 339 has been devoted to estimation from a **frequentist** perspective.

- Frequentists view probability as a representation of a long-run frequency over a large (sometimes infinite) number of repetitions of an experiment.
- The true value of a parameter,  $\theta$ , is fixed and unknown.

In the next unit, we will focus on estimation from a Bayesian perspective.

- Bayesians view probability as a representation of a relative plausibility of an event.
- Parameters,  $\theta$ , are themselves treated as random variables, assigned some prior distribution.
  - Gives weight to prior knowledge.

While we will study various procedures through both frequentist and Bayesian lenses, these are **not** competing!

 Both perspectives aim to learn from data, both use data to fit models, evaluate hypotheses, etc.