

COS210 - Theoretical Computer Science
Turing Machines and the Church-Turing Thesis (Part 3)

Equivalence of Multi- and Single-Tape Turing Machines

It may be easier and more efficient to solve a computational problem with a multi-tape Turing machine rather than with a single-tape Turing machine

However, single- and multi-tape Turing machines have the same descriptive power:

Theorem

Let $k \geq 1$ be an integer. Any k -tape Turing machine can be converted to an equivalent single-tape Turing machine

Equivalence of Multi- and Single-Tape Turing Machines

Informal proof:

How to convert a 2-tape Turing machine to an equivalent 1-tape machine

- Let $M = (Q, \Sigma, \Gamma, \delta, q, q_{accept}, q_{reject})$ be a **2**-tape Turing machine
- we construct an equivalent **1**-tape Turing machine
 $N = (Q', \Sigma, \Gamma', \delta', q', q'_{accept}, q'_{reject})$
- the machines M and N are **equivalent** if for every input string w over Σ the following holds:
 - ▶ M **accepts** w if and only if N **accepts** w
 - ▶ M **rejects** w if and only if N **rejects** w
 - ▶ M does **not terminate** on input w if and only if N does **not terminate** on input w

Equivalence of Multi- and Single-Tape Turing Machines

From $M = (Q, \Sigma, \Gamma, \delta, q, q_{accept}, q_{reject})$ to $N = (Q', \Sigma, \Gamma', \delta', q', q'_{accept}, q'_{reject})$

For N we use the following **extended tape alphabet**:

$$\Gamma' = \Gamma \cup \{\dot{a} : a \in \Gamma\} \cup \{\#\}$$

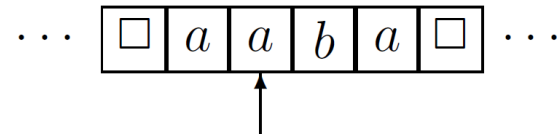
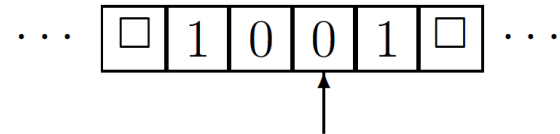
Example:

$$\text{If } \Gamma = \{0, 1, a, b, \square\}, \text{ then } \Gamma' = \{0, 1, a, b, \square, \dot{0}, \dot{1}, \dot{a}, \dot{b}, \dot{\square}, \#\}$$

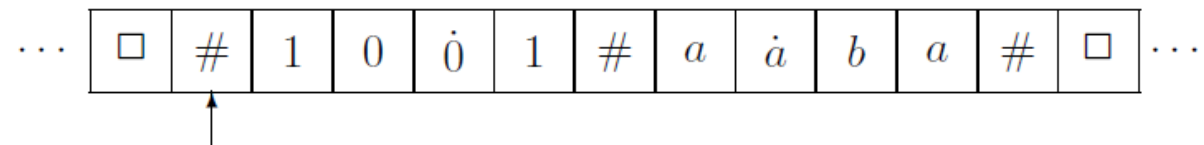
dotted copy of each original symbol, and extra symbol #

Equivalence of Multi- and Single-Tape Turing Machines

A **two-tape configuration** like

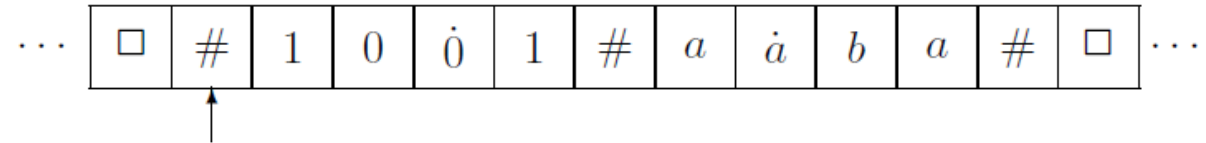


shall be **encoded on a single tape** based on the extended alphabet



- The # **separates** the contents of the original tapes
- **Dotted symbols** represent positions of the **original tape heads**

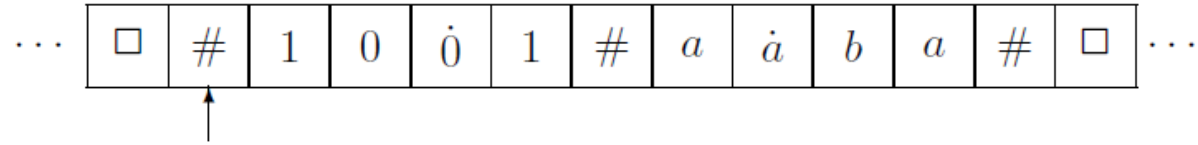
Equivalence of Multi- and Single-Tape Turing Machines



The machine N simulates each computational step of M as follows:

- At the start the tape head of N is at the leftmost symbol #
- The tape head of N moves along the string from left to right
- While moving, the machine N **identifies and memorizes** the current **configuration of the original M** by means of states
 - ▶ N starts in state $q_{?,?}$ where original tape head positions are unknown
 - ▶ first dotted symbol is $\dot{0}$
 \Rightarrow tape head 1 of M points at 0
 N switches to state $q_{0,?}$
 - ▶ second dotted symbol is \dot{a}
 \Rightarrow tape head 2 of M points at a
 N switches to state $q_{0,a}$

Equivalence of Multi- and Single-Tape Turing Machines

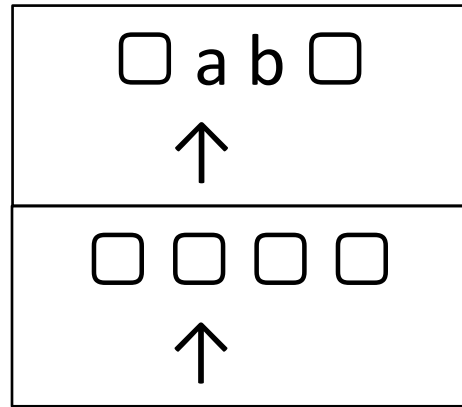


- In the state $q_{0,a}$ the machine N knows the current configuration of the original M
- Hence, N knows how M would update the contents of tape 1 and 2
- Possible updates of M :
 - ▶ replace symbols at tape heads
 - ▶ move tape heads
- How N simulates updates of M :
 - ▶ replace dotted symbols
 - ▶ 'move' the dots (via replacements)
- Simulation of updates may require to shift a part of the tape content to the right
- After the update, N identifies and memorizes updated configuration and simulates the next computational step of M

Step:

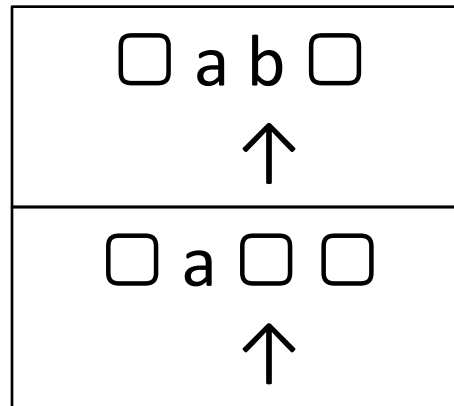
Example – Copy from First to Second Tape

1:



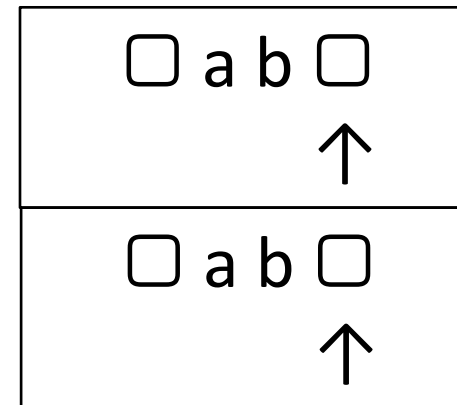
input string on tape 1
tape head 1 on leftmost symbol
tape 2 empty

2:



copy first symbol to tape 2
move both tape heads to the right

3:



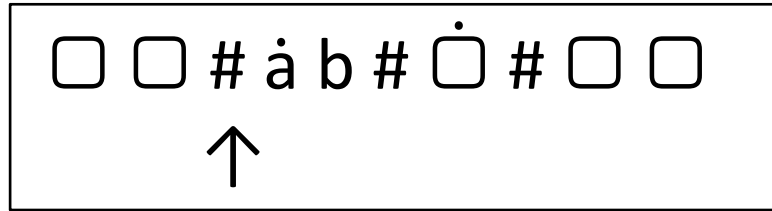
Copy second symbol
to tape 2
move both tape heads
to the right

copying done, switch to accept state

Step:

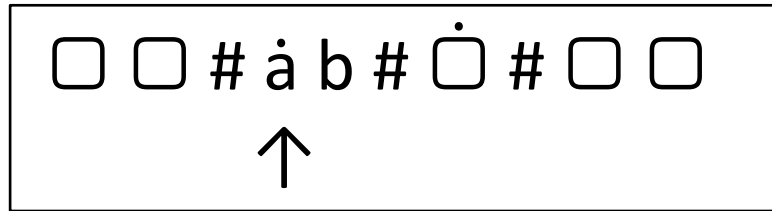
Example – Copy from First to Second Tape

1:



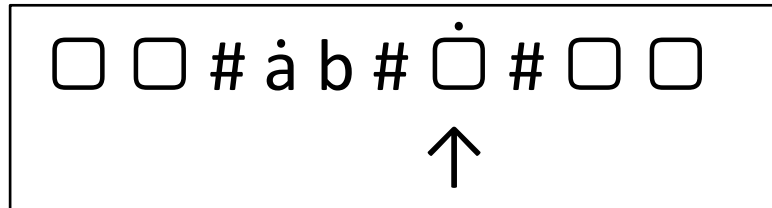
tape head points at leftmost #

2:



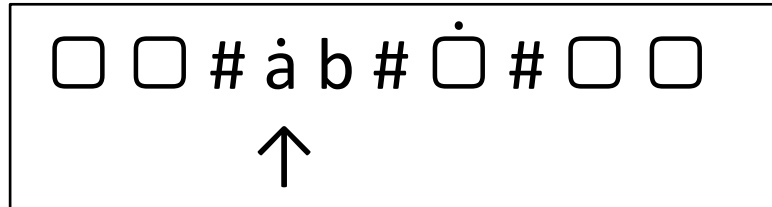
head moves to first dotted symbol
remember a

3:



head moves to second dotted symbol
remember □

4:

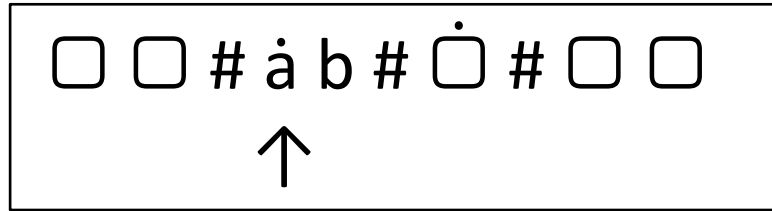


tape head moves back to first dotted
symbol

Step:

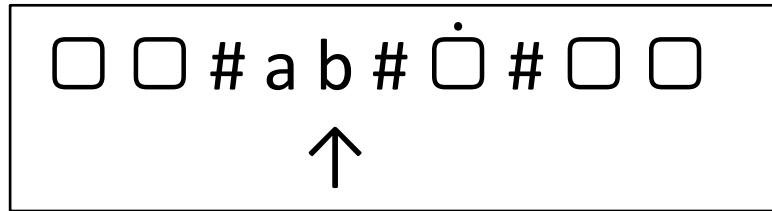
Example – Copy from First to Second Tape

4:



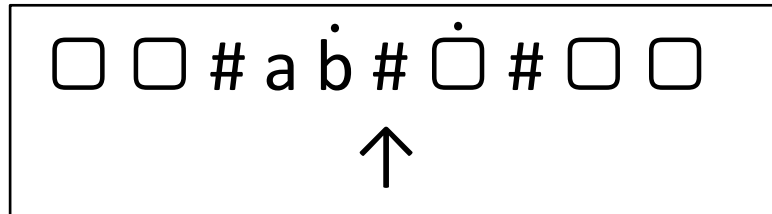
tape head moves back to first dotted symbol

5:



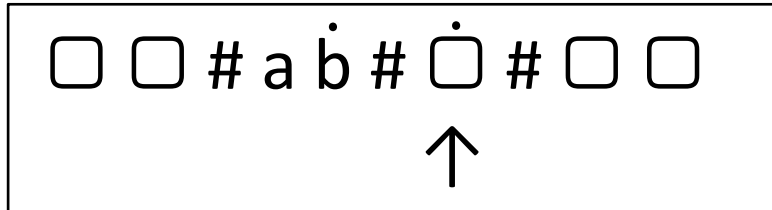
replace **ȧ** by **a**

6:



replace **b** by **ḃ**

7:

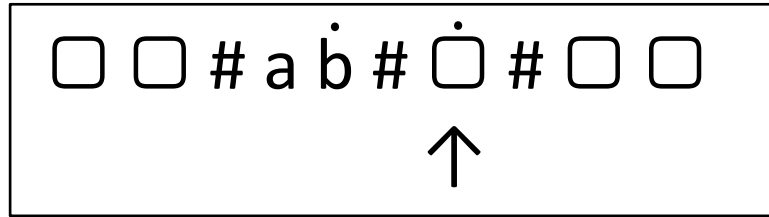


tape head moves to second dotted symbol

Step:

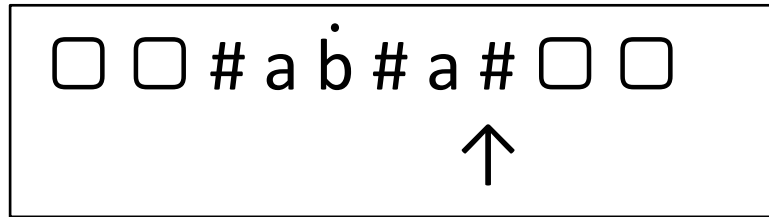
Example – Copy from First to Second Tape

7:



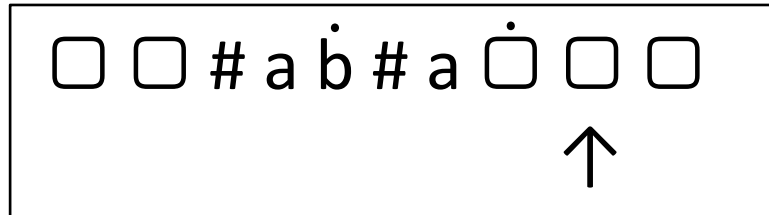
tape head moves to second dotted symbol

8:



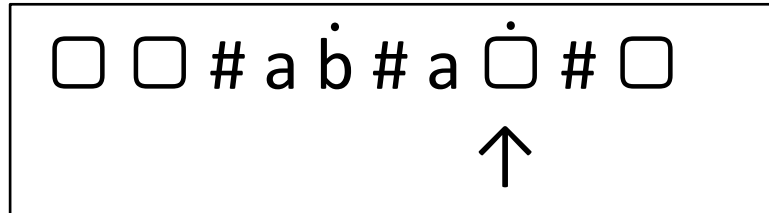
replace □̇ by a

9:



replace # by □̇

10:

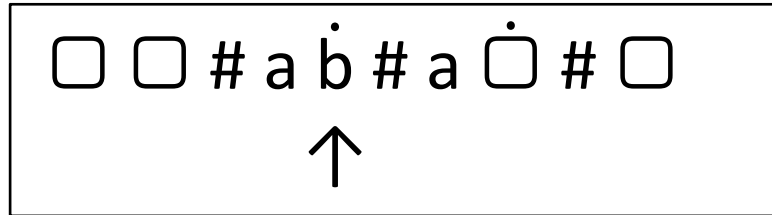


replace □ by #
start moving to the left

Step:

Example – Copy from First to Second Tape

11:



tape head moves to first dotted symbol, remember **b**

...

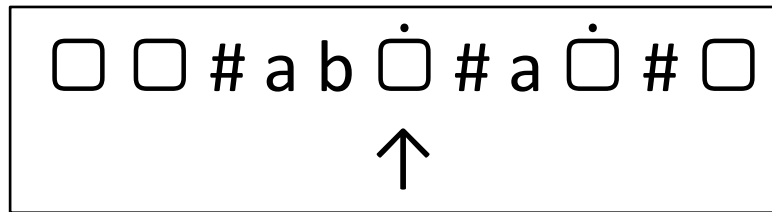
simulate that first dot moves to the right:

replace **ḃ** by **b**

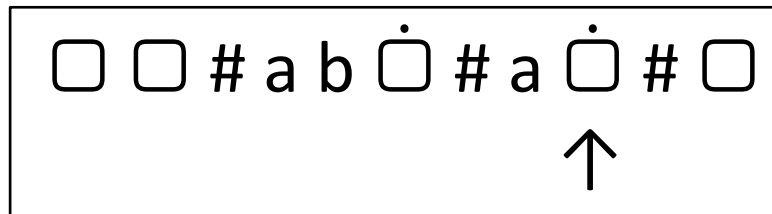
insert □̇ after the **b**

shift remaining tape content to the right

12:



13:

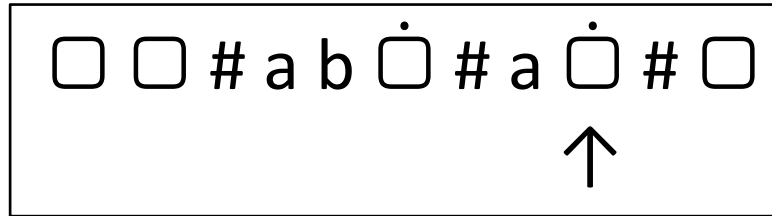


tape head moves to second dotted symbol, remember □

Step:

Example – Copy from First to Second Tape

13:



tape head moves to second dotted symbol

...

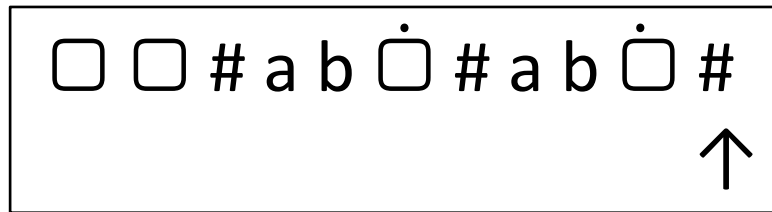
simulate the insertion of **b** between **a** and □:

replace □ by **b**

replace # by □

replace □ by #

14:



copying done,
switch to accept state

Turing Machines and Computability

Theorem

The following computational models are equivalent, i.e., any one of them can be converted to any of the other:

- *Single-tape Turing machines*
- *k-tape Turing machines*
- *Non-deterministic Turing machines*
- *Java programs*
- *C++ programs*

If some computational problem is solvable in general, then it is solvable by a Turing machine

Turing Machines and Computability

Knowing that these computation models are equivalent is important when trying to answer questions of the form

- Does there exist an algorithm X to solve problem Y
- Due to the equivalence between models showing there does or does not exist an algorithm under one model is sufficient
- E.g. if a problem cannot be solved by a Turing machine, then it also cannot be solved by a Java program

History Computability Theory

In 1900, the mathematician David Hilbert presented a list of problems that he considered crucial for the further development of mathematics. One of these problems is the following:

- Does there exist a finite process that decides whether or not any given polynomial equation with integer coefficients has an integer solution?

Example:

$$12x^3y^7z^5 + 7x^2y^4z - x^4 + y^2z^7 - z^3 + 10 = 0$$

- In our context this asks if there exists an algorithm that can solve the problem
- In 1970 it was proven that the answer is no

History Computability Theory

- In the beginning of the twentieth century, mathematicians gave several definitions of computational models, such as Turing machines (1936) and the λ -calculus (1936), and they proved that all these are equivalent
- Later, after programming languages were invented, it was shown that these older notions of an algorithm are equivalent to notions of an algorithm that are based on C programs, Java programs, etc.

The Church-Turing Thesis

In other words, all attempts to give a rigorous definition of the notion of an algorithm led to the same concept. Because of this, computer scientists nowadays agree on what is called the:

Definition (Church-Turing Thesis)

Every computational process that is intuitively considered to be an algorithm can be converted to a Turing machine.

- Some researchers claim it to be a theorem, others a definition.