

Stability of Oscillatory Rotating Boundary Layers

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- Why study rotating disks?

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- Why study oscillatory motion on the disk?

Introduction to the Rotating Disk - Setup

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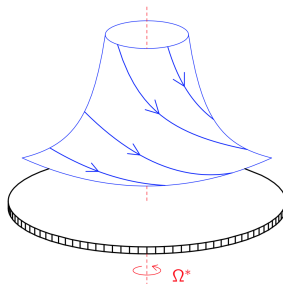


Figure 1: Rotating Disk Profile

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- Why is it an interesting problem?
 - Canonical example of a three-dimensional boundary layer.

Introduction to the Rotating Disk - History

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 - Approximation to swept-wing flow.

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- Why is it an interesting problem?
 - Canonical example of a three-dimensional boundary layer.
 - Approximation to swept-wing flow.
 - More amenable to experiments.

Introduction to the Rotating Disk - Setup

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- First studied in 1921 by Theodore von Kármán who derived an exact similarity solution to the Navier Stokes equations.

$$F(z) = \frac{U^*}{r^* \Omega^*}, \quad G(z) = \frac{V^*}{r^* \Omega^*}, \quad H(z) = \frac{W^*}{(\nu \Omega^*)^{\frac{1}{2}}}$$

where $\mathbf{U} = \mathbf{U}^*(z)$ is the velocity profile in cylindrical polars, Ω^* is the rotation rate of the disk and ν is the kinematic viscosity.

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- This gives system of ODEs to solve for the base flow.
- Worth noting - Reynolds number is equivalent to radial position on the disk.

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- In 1995, Rebecca Lingwood discovered a local *absolute* instability in the rotating disk boundary layer - important because of its proximity to the experimentally observed critical Reynolds number for *transition* to turbulence.

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- The disk admits an inviscid *crossflow* instability, similar to the one present in swept-wing flow, hence the analogy.
- In 1995, Rebecca Lingwood discovered a local *absolute* instability in the rotating disk boundary layer - important because of its proximity to the experimentally observed critical Reynolds number for *transition* to turbulence.
- This absolute instability is not present in the swept-wing configuration due to the lack of periodicity.

Local Eigenvalue Problem

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Usual Approach

- Derive perturbation equations in a similar fashion to the Orr-Sommerfeld problem.
- Reduce to a set of six first order ODEs which can be solved for the wavenumber α .

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- Solve a *velocity-vorticity formulation*, reducing perturbation equations to a set of three second order PDEs.

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Normal mode approximation

$$\hat{\phi}(r, \theta, z, t) = \phi(z)e^{i(\alpha r + \beta R\theta - \omega t)}$$

Velocity-vorticity Formulation

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$$\begin{aligned}\frac{\partial \xi_r}{\partial t} + \frac{1}{r} \frac{\partial N_r}{\partial \theta} - \frac{\partial N_\theta}{\partial z} - \frac{2}{R} \left(\xi_\theta + \frac{\partial w}{\partial r} \right) &= \frac{1}{R} \left[\left(\nabla^2 - \frac{1}{r^2} \right) \xi_r - \frac{2}{r^2} \frac{\partial \xi_\theta}{\partial \theta} \right] \\ \frac{\partial \xi_\theta}{\partial t} + \frac{\partial N_r}{\partial z} - \frac{\partial N_z}{\partial r} + \frac{2}{R} \left(\xi_r - \frac{1}{r} \frac{\partial w}{\partial \theta} \right) &= \frac{1}{R} \left[\left(\nabla^2 - \frac{1}{r^2} \right) \xi_\theta + \frac{2}{r^2} \frac{\partial \xi_r}{\partial \theta} \right] \\ \nabla^2 w &= \frac{1}{r} \left(\frac{\partial \xi_r}{\partial \theta} - \frac{\partial(r \xi_\theta)}{\partial r} \right)\end{aligned}$$

$$\mathbf{u} = (u_r, u_\theta, w), \quad \boldsymbol{\xi} = (\xi_r, \xi_\theta, \xi_z)$$

$$\mathbf{N} = (N_r, N_\theta, N_z) = (\nabla \times \mathbf{U}_B) \times \mathbf{u} + \boldsymbol{\xi} \times \mathbf{U}_B$$

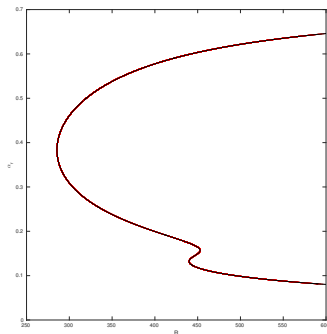
$$u_r = - \int_z^\infty \left(\xi_\theta + \frac{\partial w}{\partial r} \right) dz, \quad u_\theta = \int_z^\infty \left(\xi_r - \frac{1}{r} \frac{\partial w}{\partial \theta} \right) dz$$

$$\xi_z = \frac{1}{r} \int_z^\infty \left(\frac{\partial(r \xi_r)}{\partial r} + \frac{\partial \xi_\theta}{\partial \theta} \right) dz$$

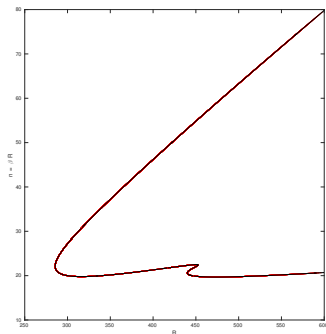
Local Eigenvalue Problem

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(a) Neutral Curve for α_r



(b) Neutral Curve for $n = \beta R$

Periodic Modulation - Motivation

- We can adapt the steady problem to include a time-dependent part by way of oscillations of the disk.

Periodic Modulation - Motivation

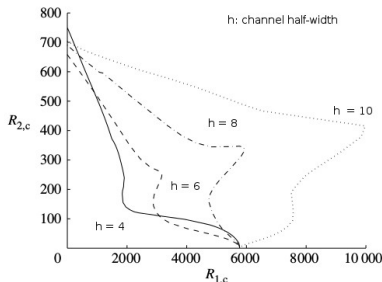
- We can adapt the steady problem to include a time-dependent part by way of oscillations of the disk.
- Adding oscillations to **channel** flow can be stabilising.

Periodic Modulation - Motivation

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- Adding oscillations to **channel** flow can be stabilising.

$$u = \gamma_1 U_1^S + \gamma_2 U_2^P$$

where U_1^S and U_2^P are the steady base flow profiles for Poiseuille channel flow ($\gamma_1 = 0$) and purely oscillatory channel flow ($\gamma_2 = 0$).



Periodic Modulation - Setup

- We can alter the von Kármán similarity variables to include a time-dependent structure

$$F(z, t) = \frac{U^*(z, t)}{r^* \Omega^*}, \quad G(z, t) = \frac{V^*(z, t)}{r^* \Omega^*}, \quad H(z, t) = \frac{W^*(z, t)}{(\nu \Omega^*)^{\frac{1}{2}}}$$

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- System of ODEs becomes time-dependent

$$\begin{aligned} \frac{\partial F}{\partial t} &= F^2 - (G + 1)^2 + F'H - F'' \\ \frac{\partial G}{\partial t} &= 2F(G + 1) + G'H - G'' \\ H' &= -2F \end{aligned}$$

with

$$\begin{aligned} U(0, t) = W(0, t) &= 0, \quad V(0, t) = A \cos(\omega t) \\ U \rightarrow 0 \quad V \rightarrow -1 \quad \text{as} \quad z \rightarrow \infty \end{aligned}$$

ROTATING FRAME

Periodic Modulation - Setup

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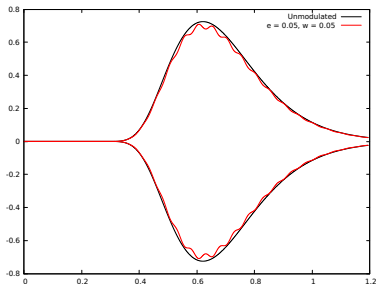
NON-ROTATING (LAB) FRAME

Preliminary Results

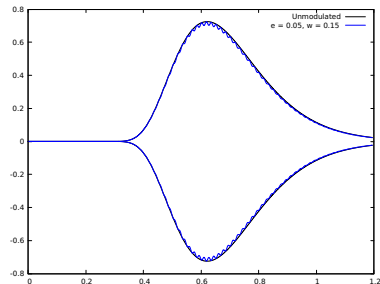
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Imagine an impulsive forcing to the disk surface at some radially localised location $r = r_e$. Boundary conditions in the rotating frame are of the form $G(z = 0) = \epsilon \cos(\omega t)$.



(a) $\epsilon = 0.05$ and $\omega = 0.05$

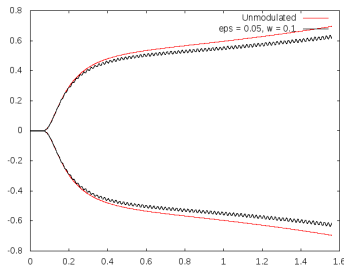


(b) $\epsilon = 0.05$ and $\omega = 0.15$

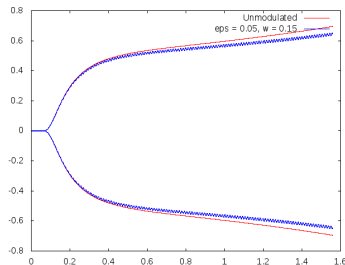
Figure 3: Wavepacket envelopes at $r = 450$ with azimuthal mode number $n = 28$ and an impulse excited at $r_e = 400$

Preliminary Results

Imagine an impulsive forcing to the disk surface at some radially localised location $r = r_e$. Boundary conditions in the rotating frame are of the form $G(z = 0) = \epsilon \cos(\omega t)$.



(a) $\epsilon = 0.05$ and $\omega = 0.1$



(b) $\epsilon = 0.05$ and $\omega = 0.15$

Figure 4: Wavepacket envelopes at $r = 540$ with azimuthal mode number $n = 67$ and an impulse excited at $r_e = 510$

Comparison with Garrett et. al. (2016) - Roughness

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- Garrett et. al. (2016) use boundary conditions on G to approximate anisotropic roughness.
- They show that roughness component can be stabilising.
- Roughness component, *in some sense*, is similar to oscillatory motion.

- Incorporate Floquet theory to further understand oscillatory component.

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- Quantify any apparent effects and provide a physical reasoning.

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- Quantify any apparent effects and provide a physical reasoning.
- Is an oscillatory component stabilising for the rotating disk?

Floquet Theory

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- Take normal mode approximation of the form

$$p(r, \theta, z, t) = \hat{p}(z, t) e^{\mu \tau} e^{i(\alpha r + \beta R \theta)}$$

where $\hat{p}(z, t)$ is periodic in t and all of the exponential growth in time of p is factored into $e^{\mu t}$. Also $\tau = \omega t$ non-dimensionalises the time scale.

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- Decompose time dependent base flow into

$$\mathbf{u}^B(z, t) = \mathbf{u}^{VK}(z) + \sum_{n=-\infty}^{\infty} u_n(z) e^{i \tau}$$

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- Decompose \hat{p} into harmonics such that

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and substitute into equations.

Floquet Theory

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- Gives system of perturbation equations to solve for μ .