

Linear Stability of the Rotating Disk Boundary Layer

Scott Morgan

Supervisor: Dr. Chris Davies

- Why study rotating disks?

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- Why study oscillatory motion on the disk?

Introduction to the Rotating Disk - Setup

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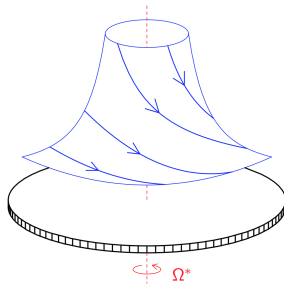


Figure 1: Rotating Disk Profile

Introduction to the Rotating Disk - History

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- Why is it an interesting problem?
 - Canonical example of a three-dimensional boundary layer.

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 - Approximation to swept-wing flow.

Introduction to the Rotating Disk - History

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- Why is it an interesting problem?
 - Canonical example of a three-dimensional boundary layer.
 - Approximation to swept-wing flow.
 - More amenable to experiments.

Introduction to the Rotating Disk - Setup

- First studied in 1921 by Theodore von Kármán who derived an exact similarity solution to the Navier Stokes equations.

$$F(z) = \frac{U^*}{r^* \Omega^*}, \quad G(z) = \frac{V^*}{r^* \Omega^*}, \quad H(z) = \frac{W^*}{(\nu \Omega^*)^{\frac{1}{2}}}$$

where $\mathbf{U} = \mathbf{U}^*(z)$ is the velocity profile in cylindrical polars, Ω^* is the rotation rate of the disk and ν is the kinematic viscosity.

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- Worth noting - Reynolds number is equivalent to radial position on the disk.

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- Worth noting - Reynolds number is equivalent to radial position on the disk.
- **Non-dimensional base flow**

$$\mathbf{u}^B = \left(\frac{r}{R} F, \frac{r}{R} G, \frac{1}{R} H \right)$$

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- In 1995, Rebecca Lingwood discovered a local *absolute* instability in the rotating disk boundary layer - important because of its proximity to the experimentally observed critical Reynolds number for *transition* to turbulence.
- This absolute instability is not present in the swept-wing configuration due to the lack of periodicity.
- The disk flow is *globally* linearly stable, and even in strongly absolutely unstable regions, convective behaviour dominates eventually.

Understanding Stability

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- *Local* behaviour can be analysed using standard techniques for solving the temporal or spatial Orr-Sommerfeld eigenvalue problem as discussed.

Understanding Stability

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- *Local* behaviour can be analysed using standard techniques for solving the temporal or spatial Orr-Sommerfeld eigenvalue problem as discussed.
- *Global* behaviour can be analysed using direct numerical simulations (DNS).

Local Eigenvalue Problem

Usual Approach

- Derive perturbation equations in a similar fashion to the Orr-Sommerfeld problem.
- Reduce to a set of six first order ODEs which can be solved for the wavenumber α .

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- Solve a *velocity-vorticity formulation*, reducing perturbation equations to a set of three second order PDEs.

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Normal mode approximation

$$\hat{\phi}(r, \theta, z, t) = \phi(z)e^{i(\alpha r + \beta R\theta - \omega t)}$$

Velocity-vorticity Formulation

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$$\begin{aligned}\frac{\partial \xi_r}{\partial t} + \frac{1}{r} \frac{\partial N_r}{\partial \theta} - \frac{\partial N_\theta}{\partial z} - \frac{2}{R} \left(\xi_\theta + \frac{\partial w}{\partial r} \right) &= \frac{1}{R} \left[\left(\nabla^2 - \frac{1}{r^2} \right) \xi_r - \frac{2}{r^2} \frac{\partial \xi_\theta}{\partial \theta} \right] \\ \frac{\partial \xi_\theta}{\partial t} + \frac{\partial N_r}{\partial z} - \frac{\partial N_z}{\partial r} + \frac{2}{R} \left(\xi_r - \frac{1}{r} \frac{\partial w}{\partial \theta} \right) &= \frac{1}{R} \left[\left(\nabla^2 - \frac{1}{r^2} \right) \xi_\theta + \frac{2}{r^2} \frac{\partial \xi_r}{\partial \theta} \right] \\ \nabla^2 w &= \frac{1}{r} \left(\frac{\partial \xi_r}{\partial \theta} - \frac{\partial (r \xi_\theta)}{\partial r} \right)\end{aligned}$$

$$\mathbf{u} = (u_r, u_\theta, w), \quad \boldsymbol{\xi} = (\xi_r, \xi_\theta, \xi_z)$$

$$\mathbf{N} = (N_r, N_\theta, N_z) = (\nabla \times \mathbf{U}_B) \times \mathbf{u} + \boldsymbol{\xi} \times \mathbf{U}_B$$

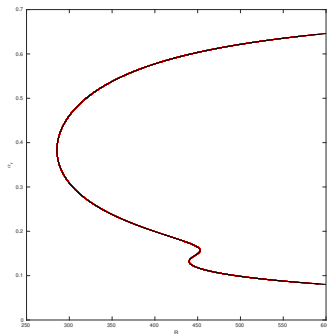
$$u_r = - \int_z^\infty \left(\xi_\theta + \frac{\partial w}{\partial r} \right) dz, \quad u_\theta = \int_z^\infty \left(\xi_r - \frac{1}{r} \frac{\partial w}{\partial \theta} \right) dz$$

$$\xi_z = \frac{1}{r} \int_z^\infty \left(\frac{\partial (r \xi_r)}{\partial r} + \frac{\partial \xi_\theta}{\partial \theta} \right) dz$$

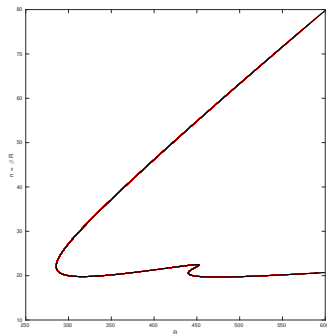
Local Eigenvalue Problem

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(a) Neutral Curve for α_r



(b) Neutral Curve for $n = \beta R$

- Recall base flow profiles

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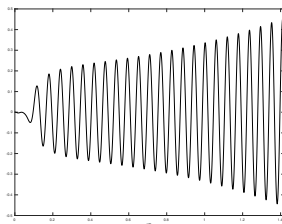
- *Parallel flow approximation* amounts to setting $r = R$.
- But base flow *varies with radius*, so this is not entirely physical.
- Small effect on local, eigenvalue analysis but major effect on global analysis when full temporal and radial variation incorporated.

Direct Numerical Simulations

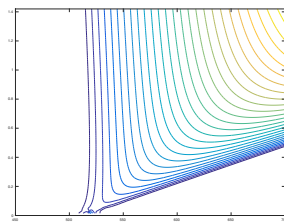
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Imagine an impulsive forcing to the disk surface at some radially localised location $r = r_e$.



(a) Time history at $r = 540$



(b) Spatio-temporal development

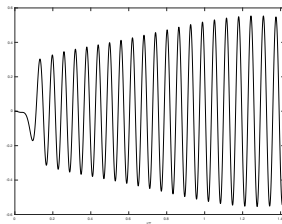
Figure 3: Azimuthal mode number $n = 68$ and impulsive disturbance excited at $r = 520$ - homogeneous flow

Direct Numerical Simulations

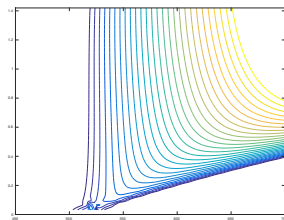
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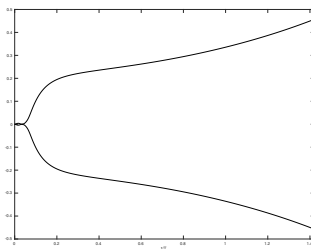
Figure 4: Azimuthal mode number $n = 68$ and impulsive disturbance excited at $r = 520$ - inhomogeneous flow

Direct Numerical Simulations

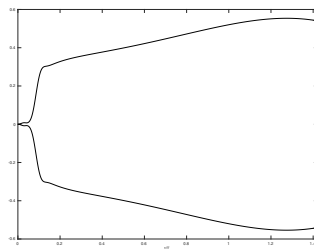
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Imagine an impulsive forcing to the disk surface at some radially localised location $r = r_e$.



(a) Homogeneous



(b) Inhomogeneous

Figure 5: Wavepacket envelopes at $r = 540$ azimuthal mode number $n = 68$ and an impulse excited at $r_e = 520$

Summary So Far

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- Flow has a *local absolute instability* which occurs for $R > 507$.

Summary So Far

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- Flow is *convectively* unstable for $R > 286$.
- Flow has a *local absolute instability* which occurs for $R > 507$.
- Flow is *globally stable* when radial inhomogeneity is incorporated.

Periodic Modulation - Motivation

- We can adapt the steady problem to include a time-dependent part by way of oscillations of the disk.

Periodic Modulation - Motivation

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- Adding oscillations to **channel** flow can be stabilising.

Periodic Modulation - Motivation

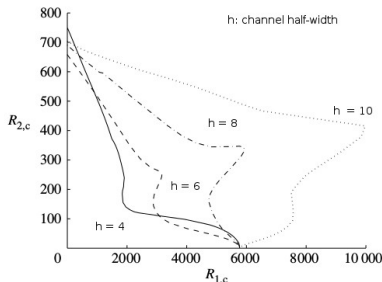
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- We can adapt the steady problem to include a time-dependent part by way of oscillations of the disk.
- Adding oscillations to **channel** flow can be stabilising.

$$u = \gamma_1 U_1^S + \gamma_2 U_2^P$$

where U_1^S and U_2^P are the steady base flow profiles for purely oscillatory channel flow ($\gamma_1 = 0$) and Poiseuille channel flow ($\gamma_2 = 0$).



Periodic Modulation - Setup

- We can alter the von Kármán similarity variables to include a time-dependent structure

$$F(z, t) = \frac{U^*(z, t)}{r^* \Omega^*}, \quad G(z, t) = \frac{V^*(z, t)}{r^* \Omega^*}, \quad H(z, t) = \frac{W^*(z, t)}{(\nu \Omega^*)^{\frac{1}{2}}}$$

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- System of ODEs becomes time-dependent

$$\begin{aligned} \frac{\partial F}{\partial t} &= F^2 - (G + 1)^2 + F'H - F'' \\ \frac{\partial G}{\partial t} &= 2F(G + 1) + G'H - G'' \\ H' &= -2F \end{aligned}$$

with

$$\begin{aligned} U(0, t) = W(0, t) &= 0, \quad V(0, t) = A \cos(\omega t) \\ U \rightarrow 0 \quad V \rightarrow -1 \quad &\text{as } z \rightarrow \infty \end{aligned}$$

ROTATING FRAME

Periodic Modulation - Setup

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NON-ROTATING (LAB) FRAME

Solution Method

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- Map semi-infinite domain $[0, \infty)$ to computational domain $(0, 1]$ using mapping $\eta = \frac{l}{l+z}$

Solution Method

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- Map semi-infinite domain $[0, \infty)$ to computational domain $(0, 1]$ using mapping $\eta = \frac{l}{l+z}$
- Express F and G in terms of odd Chebyshev series and H in terms of even ones:

$$\{F, G\}(\eta) \sim \sum_{n=1}^{\infty} a_n T_{2n-1}(\eta), \quad H(\eta) \sim \frac{b_0}{2} + \sum_{n=1}^{\infty} b_n T_{2n}(\eta)$$

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- Integrate equations twice with respect to η - e.g. for first equation

$$\iint \left(\frac{\partial F}{\partial t} + \mathcal{D}^2 F \right) = \iint (F^2 - G^2 - H \mathcal{D} F)$$

where $\mathcal{D} = \frac{d}{dz} = -\frac{\eta^2}{l} \frac{d}{d\eta}$ and similarly for \mathcal{D}^2

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- Matrix operators are pentadiagonal.

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$$\iint \left(\frac{\partial F}{\partial t} + \mathcal{D}^2 F \right) = \iint (F^2 - G^2 - H \mathcal{D} F)$$

- Apply backward three-level scheme for time-discretisation

$$\left(\frac{\partial f}{\partial t} \right)_l = \frac{1}{2\Delta t} (3f_l - 4f_{l-1} + f_{l-2})$$

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$$\left(\frac{\partial f}{\partial t} \right)_I = \frac{1}{2\Delta t} (3f_I - 4f_{I-1} + f_{I-2})$$

- Solve using predictor-corrector

$$\begin{aligned} \left(\frac{3}{2\Delta t} \iint + \iint \mathcal{D}^2 \right) F_{I+1} &= \frac{2}{\Delta t} \iint F_I - \frac{1}{2\Delta t} \iint F_{I-1} \\ &+ \iint (F_I^2 - G_I^2 - H_I \mathcal{D} F_I) \end{aligned}$$

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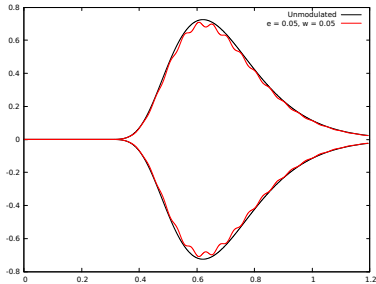
- Oscillation is added after steady state is reached.

Preliminary Results

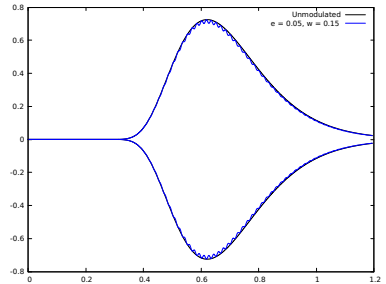
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Imagine an impulsive forcing to the disk surface at some radially localised location $r = r_e$. Boundary conditions in the rotating frame are of the form $G(z = 0) = \epsilon \cos(\omega t)$.



(a) $\epsilon = 0.05$ and $\omega = 0.05$



(b) $\epsilon = 0.05$ and $\omega = 0.15$

Figure 6: Wavepacket envelopes at $r = 450$ with azimuthal mode number $n = 28$ and an impulse excited at $r_e = 400$

Comparison with Garrett et. al. (2016) - Roughness

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- Garrett et. al. (2016) use boundary conditions on G to approximate anisotropic roughness.
- They show that roughness component can be stabilising.
- Roughness component, *in some sense*, is similar to oscillatory motion.

- Incorporate Floquet theory to further understand oscillatory component.

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- Quantify any apparent effects and provide a physical reasoning.

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- Quantify any apparent effects and provide a physical reasoning.
- Is an oscillatory component stabilising for the rotating disk?

Floquet Theory

- Take normal mode approximation of the form

$$p(r, \theta, z, t) = \hat{p}(z, t) e^{\mu \tau} e^{i(\alpha r + \beta R \theta)}$$

where $\hat{p}(z, t)$ is periodic in t and all of the exponential growth in time of p is factored into $e^{\mu t}$. Also $\tau = \omega t$ non-dimensionalises the time scale.

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- Decompose time dependent base flow into

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$$\hat{p} = \sum_{n=-\infty}^{\infty} \hat{p}_n(z) e^{i n \tau}$$

and substitute into equations.

Floquet Theory

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- Gives system of perturbation equations to solve for μ .