

2024-02-26 UN

Apparently we can figure out the oriented distance between a point and a plane using

$$(\hat{\text{point}} \wedge \hat{\text{plane}}) \cdot e_{0123}$$

So I need to code up the meet between a point and a plane

$$\begin{pmatrix} v \cdot e_{032} + v \cdot e_{013} + v \cdot e_{021} + v \cdot e_{123} \\ p \cdot e_1 + p \cdot e_2 + p \cdot e_3 + p \cdot e_0 \end{pmatrix} \wedge$$

$$\begin{aligned} &= (v \cdot e_{032})(p \cdot e_1)(-e_{0123}) \\ &+ (v \cdot e_{013})(p \cdot e_2)(-e_{0123}) \\ &+ (v \cdot e_{021})(p \cdot e_3)(-e_{0123}) \\ &+ (v \cdot e_{123})(p \cdot e_0)(-e_{0123}) \end{aligned}$$

Remember
 $e_1 \wedge e_1 = 0$
and so on...

Wow, so there is only one term, the e_{0123} part of a dual quaternion.

So the result is:

$$\begin{aligned} dq \cdot w &= 0 \\ dq \cdot e_{23} &= 0 \\ dq \cdot e_{31} &= 0 \\ dq \cdot e_{12} &= 0 \\ dq \cdot e_{01} &= 0 \\ dq \cdot e_{02} &= 0 \\ dq \cdot e_{03} &= 0 \\ dq \cdot e_{0123} &= - (v \cdot e_{032})(p \cdot e_1) \\ &\quad - (v \cdot e_{013})(p \cdot e_2) \\ &\quad - (v \cdot e_{021})(p \cdot e_3) \\ &\quad - (v \cdot e_{123})(p \cdot e_0) \end{aligned}$$