

# IoT: Client Devices

Installing Linux, Buildroot

# Software Installation & Use

## NOT EVERY STEP

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- I won't cover every single step in installations

## NOT EASY STUFF

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- I won't cover easy, straight forward stuff either
- This stuff is on the internet, or in documentation

## THINGS THAT ARE COMPLEX, NEED EXPLANATION

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- I WILL cover complex stuff where you're likely to get hung up

This is a graduate level course.

# Download Linux

## UBUNTU 16.04

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- This is the LTS release
- Relatively stable

## BASED ON DEBIAN

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- Easy installation
- Download ISO from <https://ubuntu.com>

## ...OR YOUR FAVORITE DISTRO

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- If you have one
- Examples will be in Ubuntu

# Type of Installation

## SERVER OR WORKSTATION?

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- ▶ Either one is fine, but server generally has no GUI

## GUI OR NO?

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- ▶ I generally do not use a GUI (but you can)
- ▶ Makes for a smaller image

## DEVELOPMENT

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- ▶ No GUI may be more difficult if not comfortable in Linux

# Create Virtual Image

## CREATE A NEW IMAGE

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- ▶ In either Virtualbox or VMWare
- ▶ Follow directions, internet guidance

## FOLLOW THE PROMPTS

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- ▶ Make sure you install SSH during installation
- ▶ You'll want to be able to SSH into the system

## CREATE STRONG PASSWORDS

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- ▶ This is your development workstation after all

# IoT: Client Devices

Vagrant & Buildroot

# What is Buildroot?

## EMBEDDED LINUX BUILD ENVIRONMENT

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- Makes building embedded linux distributions easier

## USES MAKE SEMANTICS

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- Generate makefiles to build embedded linux images

## VARIETY OF INTERFACES

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- I use the basic interface, but you can use others



# What is Vagrant

## PORTABLE DEVELOPMENT ENVIRONMENTS

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- ▶ Uniform development environments
- ▶ Great for distributed teams, QA, build

## VAGRANT & BUILDROOT

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- ▶ Buildroot supports Vagrant
- ▶ This is how we'll install it

## DEPENDENCIES

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- ▶ Vagrant uses Virtualbox natively, must pay for VMWare support

# Installing Vagrant

## VAGRANT BASE INSTALLATION

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- ▶ Download: <https://www.vagrantup.com/>
- ▶ Virtualbox? you should be covered.
- ▶ VMWare? You'll need to buy the VMWare provider
  - ▶ I use VMWare, but tweaked Buildroot to do so
  - ▶ Easier if you use Virtualbox in this case

## VAGRANT DOES NOT USE OWN VIRTUALIZATION

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- ▶ Uses providers to attach to virtualization software
- ▶ Virtualbox provider installed by default, not VMWare

# Installing Buildroot

## BUILDROOT IS COMPLEX AND POWERFUL

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- ▶ RTM: <https://buildroot.org/downloads/manual/manual.html>

## GETTING STARTED

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- ▶ Starting here
- ▶ RTM: <https://buildroot.org/downloads/manual/manual.html#getting-buildroot>

## DOWNLOADS VAGRANTFILE, STARTS VAGRANT

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- ▶ VagrantFile is an internal Ruby DSL
- ▶ Vagrant reads, downloads Linux VM, installs Buildroot

# BuildRoot Running

## BUILDROOT VM RUNNING

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- ▶ The Buildroot VM should be running
- ▶ Useful Vagrant Commands:
  - ▶ `vagrant port`, `vagrant ssh`, `vagrant halt`, `vagrant suspend`
  - ▶ type 'vagrant' at command line to see more

## PORTS USED

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- ▶ `vagrant port` shows active ports
  - ▶ note your Vagrant VM is active on port 2222
  - ▶ You need this to SCP images from your Buildroot VM

# IoT: Client Devices

Client Emulation and Virtual Machines

# IoT Clients

## LINUX

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- ▶ Embedded linux, old Linux versions, standard services

## BUSYBOX, BUILDROOT

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- ▶ <https://www.busybox.net> ; <https://buildroot.org>

## APPLICATION SOFTWARE

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- ▶ Standard C application running in linux system

# Emulating Workflow

## VIRTUALBOX / VMWARE / QEMU

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- Develop on Linux Workstation
- Deploy to stripped Linux image
- Both on host

## BUILD ROOT

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- Deployment target's x86 (We'll pretend it's MIPS or ARM)

## LINUX WORKSTATION

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- Gcc tools
- Cross-compilation

# VMWare or Virtualbox?

## VIRTUALBOX

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- ▶ Open source, free to use
- ▶ <https://www.virtualbox.org>

## VMWARE

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- ▶ Not free, not exactly cheap either
- ▶ commercial support, more robust

## WHICH ONE?

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- ▶ VMWare is more stable and robust
- ▶ Virtualbox is more picky



# QEMU?

## PROCESSOR EMULATOR

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- ▶ Emulates different processor types

## VIRTUALIZATION TOO

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- ▶ We're not using it for that though

## RUNS IoT CLIENT

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- ▶ Copy and run programs on client

# IoT: Client Devices

Testing our Development Environment

# Start up your VM

## LOG INTO YOUR VM

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- ▶ Start up virtualization
- ▶ Log in
- ▶ Open a few windows

## OTHER TOOLS

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- ▶ I use things like Tmux and Powerline (you don't have to)

# Build an ARM Image

## BUILDROOT

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- ▶ Versatile Platform Baseboard
- ▶ Configure with defaults and Build
- ▶ `cd to Buildroot directory`
- ▶ `$ make qemu_arm_versatile_defconfig`

## WHAT DOES THIS DO?

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- ▶ Creates a base `.config` file with defaults for board
- ▶ Build stock version first

# Now Add SSH

## WHY?

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- ▶ We need to move a cross-compiled executable to the image

## NAVIGATE TO BUILDROOT

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- ▶ Open the configuration menu (make nconfig)
- ▶ Target Packages -> Networking applications -> openssh
- ▶ Rebuild (just type make)

# Build Results

## SO WHAT DID WE BUILD?

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- ▶ Take a look in `$buildroot_home/output/images`
  - ▶ you should see: `zImage`, `rootfs.ext2`, `versatile-pb.dtb`
  - ▶ what are these things?
    - ▶ `zImage`: Kernel image
    - ▶ `rootfs.ext2`: Root filesystem
    - ▶ `versatile-pb.dtb`: Device tree blob (contains hardware info)

# Let's Run

## BUILD INSTRUCTIONS

---

- ▶ `$buildroot_home/board/qemu/arm-versatile/readme.txt`
- ▶ The command line for the new QEMU image is in the readme (see next page for script)

# Running in QEMU

MIGHT BE BETTER AS A SCRIPT

---

```
qemu-versatile.sh:
```

```
qemu-system-arm \
```

```
-M versatilepb \
```

```
-kernel output/images/zImage \
```

```
-dtb output/images/versatile-pb.dtb \
```

```
-drive file=output/images/rootfs.ext2,if=scsi,format=raw -append "root=/dev/sda console=ttyAMA0,115200" \
```

```
-serial stdio \
```

```
-net nic,model=rtl8139 -net user \
```

```
-redir tcp:2222:22
```



# IoT: Client Devices

Testing the QEMU Image

# QEMU VM is Up

## OUR VM IS RUNNING

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- ▶ Excellent!
- ▶ Slightly different - running in terminal
- ▶ Go ahead and log in
  - ▶ root user has no password (we can set this in Buildroot)

## WE NEED TO ADD A USER

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- ▶ adduser to the rescue
- ▶ `$ adduser -h /<username> -s /bin/sh <username>`

# Test SSH

## NOW TEST SSH

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- ▶ from your Linux host, attempt to SSH to QEMU image
  - ▶ `$ ssh -p 2222 <username>@localhost`
  - ▶ Remember the line `-redir tcp:2222:22`

## FAILED!

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- ▶ It keeps asking to change my password, then won't let me in!

# Configuration Details

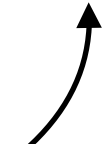
## .../ETC/SHADOW PROBLEMS

---

- ▶ the /etc/shadow file is not updated, and we're not running password management services
- ▶ we'll need to update manually
- ▶ as root edit /etc/shadow so the last line looks like this:

<username>:\$1\$7UvOizz/\$SOcRUgT9PVcpyaQ9O3E9I0:10933:0:99999:7:::

*This was 0, now 10933*



# Test Cross-Compilation

## NOW TEST CROSS-COMPILATION

---

- ▶ Simple test program in C:

```
#include <stdio.h>

int main(void) {
    printf("running.\n");
    return 0;
}
```

- ▶ `$ arm-linux-gnueabi-gcc -static -o test main.c`
- ▶ `$ scp -P 2222 ./test cclamb@localhost:~/`
- ▶ ...run test program on ARM image

# Solid!

## CONGRATS!

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- ▶ Embedded linux system on emulated ARM processor
- ▶ Cross-compiled a C program
- ▶ Moved program to ARM host
- ▶ Ran program

WE CAN FINALLY GET STARTED WITH CODE

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# IoT: Client Devices

Binwalk

# What is Binwalk?

## FIRMWARE ANALYSIS

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- ▶ Allows you to list the contents of a firmware file
- ▶ Perform entropy analysis
- ▶ Identify platform dependencies

## FIRMWARE EXTRACTION

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- ▶ Filesystems
- ▶ Operating systems
- ▶ Application software



# Installation

## RUNS ON LINUX

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- ▶ You'll need to use your linux VM

## COMPLEX INSTALLATION PROCESS

---

- ▶ Many dependencies

## WRITTEN IN PYTHON

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- ▶ Dependencies are in both Python and at OS level

# Installation

## INSTALLATION INSTRUCTIONS *MOSTLY* ACCURATE

---

- Packages correct
- Some things better installed with APT, not PIP

## INSTALLATION TOOLS

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- PIP: An installation framework for Python
- APT: An installation framework for Debian

## YOU'LL USE BOTH

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- Python libs with PIP, OS packages with APT

# Installation

## PYTHON 2 OR PYTHON 3?

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- ▶ I use Python 2, but you can use Python 3
- ▶ Don't install both

## HOW DO I INSTALL?

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- ▶ See <https://github.com/devttys0/binwalk/blob/master/INSTALL.md>
- ▶ I suggest you install libcapstone3 as well via APT
  - ▶ `sudo apt install libcapstone3`

# Installation

HOW DO I KNOW IT WORKED?

---

```
cclamb@angr:~$ binwalk
```

```
Binwalk v2.1.1
```

```
Craig Heffner, http://www.binwalk.org
```

```
Usage: binwalk [OPTIONS] [FILE1] [FILE2] [FILE3] ...
```

```
Disassembly Scan Options:
```

-Y, --disasm	Identify the CPU architecture of a file using the capstone disassembler
-T, --minsn=<int>	Minimum number of consecutive instructions to be considered valid (default: 500)

# It didn't work!

## LIBCAPSTONE3

---

- ▶ Try installing libcapstone3 from APT if you didn't originally.
- ▶ `$ sudo apt install libcapstone3`

## PYTHON ERRORS

---

- ▶ Use only Python 2 or Python 3
- ▶ Deinstall all your python, they try again with one or the other, not both

# IoT: Client Devices

Other Tools

# Radare (optional)

## DISASSEMBLER

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- ▶ Allows disassembly of multiple instruction sets

## REVERSE ENGINEERING TOOLSET

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- ▶ Very complex though

## GUI AND CLI

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- ▶ Bokken, WebUI
- ▶ <http://radare.org> for more info

# Git

## YOU NEED A VERSION CONTROL SYSTEM

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- Rollback to working versions
- Tracking changes
- Configuration files, source code, other

## GITHUB

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- <http://www.github.com>
- We'll use it for assignment evaluation too
- Register for an account, it's free



# Gnu Binutils

## TOOLS FOR BINARY ANALYSIS, DEBUGGING

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- readelf, objdump, strip, strings, nm and more
- Visibility into binary files

## READELF

---

- -a (use less, this does everything) others

## OBJDUMP

---

- -h, -f, -x, -d, -D, -t

# Gnu Cross-Compilers

## COMPILE ON X86 LINUX FOR OTHER ARCHITECTURES

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- ▶ Sorcery Workbench (<https://www.mentor.com/embedded-software/sourcery-tools/sourcery-codebench/editions/lite-edition/>)
- ▶ Ubuntu distros (ARM has best support out of the box)

# How to install?

## GNU BINUTILS

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- ▶ `$ sudo apt install binutils-mips-linux-gnu binutils-mipsel-linux-gnu binutils-arm-linux-gnueabi`

## GNU CROSS-COMPILERS

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- ▶ `$ sudo apt install gcc-arm-linux-gnueabi`

# Summary

## SO WHAT DO WE HAVE?

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- ▶ Linux VM
- ▶ Version Control System
- ▶ Buildroot
- ▶ Binwalk
- ▶ Binutils for various architectures
- ▶ Cross compiler
- ▶ QEMU (and qemu-user-static)

# IoT: Client Devices

Reversing: Download and Extract

# Firmware Image

## TP-LINK HS110 v1

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- ▶ <http://www.tp-link.com/us/download/HS110.html#Firmware>
- ▶ ZIP archive, go ahead and unzip
- ▶ You'll have some files and a BIN file
- ▶ BIN file is the firmware image!



# What Does it Do?

## SMART PLUG

---

- ▶ Programmed via app
- ▶ Provides Usage, time used information
- ▶ uses Kasa app (see app store, google play)

STILL USES FULL LINUX!



DECIMAL	HEXADECIMAL	DESCRIPTION
15904	0x3E20	U-Boot version string, "U-Boot 1.1.4 (Oct 16 2015 - 11:22:22)"
15952	0x3E50	CRC32 polynomial table, big endian
17244	0x435C	uImage header, header size: 64 bytes, header CRC: 0xA2B5F4E6, created: 2015-10-16 03:22:22, image size: 38777 bytes, Data Address: 0x80010000, Entry Point: 0x80010000, data CRC: 0xFED80D4A, OS: Linux, CPU: MIPS, image type: Firmware Image, compression type: lzma, image name: "u-boot image"
17308	0x439C	LZMA compressed data, properties: 0x5D, dictionary size: 33554432 bytes, uncompressed size: 112564 bytes
66240	0x102C0	uImage header, header size: 64 bytes, header CRC: 0x4D2B83AC, created: 2015-10-16 03:22:56, image size: 772570 bytes, Data Address: 0x80002000, Entry Point: 0x8019BF90, data CRC: 0xC849B1ED, OS: Linux, CPU: MIPS, image type: OS Kernel Image, compression type: lzma, image name: "Linux Kernel Image"
66304	0x10300	LZMA compressed data, properties: 0x5D, dictionary size: 33554432 bytes, uncompressed size: 2238780 bytes
1114816	0x1102C0	Squashfs filesystem, little endian, version 4.0, compression: lzma, size: 2112689 bytes, 194 inodes, blocksize: 16384 bytes, created: 2015-10-16 03:25:36

cclamb@ubuntu:~/Work/tplink \$

# Now What?

Let's take a look inside



Onto Analysis!

# IoT: Client Devices

Reverse Engineering

# Types of Firmware

## No Host

---

- ▶ No OS, services and operating code mixed
- ▶ Hard drives, USB, simple micro controllers
- ▶ BIOS, EFI/UEFI, etc.
- ▶ Smaller, simpler, less powerful

## HOSTED

---

- ▶ Embedded Linux
- ▶ Have some kind of OS
- ▶ Userspace services on OS
- ▶ Larger, more complex, more powerful

# Reverse Engineering

## WHY REVERSE ENGINEERING?

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- ▶ See what others do
- ▶ Understand why
- ▶ Understand mistakes and avoid them!

## START WITH DOWNLOADABLE IMAGES

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- ▶ These don't always exist

# Reversing a Device

## SCAN THE DEVICE

---

- Scan ports, monitor traffic examine protocols, dynamic analysis

## RUNNING SOFTWARE

---

- We can run code using QEMU
- Real device better though

## ALL GOOD THINGS!

---

- We're not reverse engineers
- We just want to see the code

# What to Reverse?

## PUBLICLY AVAILABLE IMAGES

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- ▶ Downloadable, we'll use TP-Link firmware images
- ▶ Saves you from extracting or buying the device

## NOTE: SHOULD YOUR FIRMWARES BE AVAILABLE?

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- ▶ Controversial
- ▶ Hiding images is security by obscurity

# IoT: Client Devices

Reversing: HS110 Filesystem

# Take a look around!

Here, we've listed the /bin directory (I used `tree`; to install, type *sudo apt install tree* at the command line)

```
cclamb — ssh -X 192.168.120.134 — 58x31
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ ls
bin  etc  linuxrc  proc  sbin  tmp
dev  lib  mnt      root  sys   usr
cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ tree bin
bin
├── ash -> busybox
├── busybox
├── cat -> busybox
├── chmod -> busybox
├── cp -> busybox
├── date -> busybox
├── echo -> busybox
├── ip -> busybox
├── kill -> busybox
├── length-decode
├── login -> busybox
├── ls -> busybox
├── minidump
├── mkdir -> busybox
├── mount -> busybox
├── ping -> busybox
├── ps -> busybox
├── pwd -> busybox
├── rm -> busybox
├── rmdir -> busybox
├── sh -> busybox
├── umount -> busybox
└── vi -> busybox

0 directories, 23 files
cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $
```



```
cclamb — ssh -X 192.168.120.135 — 89x26
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root/etc $ tree .
.
├── 2048_newroot.cer
├── ath
│   ├── activateVAP
│   ├── apcfg
│   └── apup
├── fstab
├── group
├── inittab
├── passwd
├── public.key
├── rc.d
│   ├── rcS
│   └── rc.wlan
├── resolv.conf -> /tmp/resolv.conf
├── shadow
├── sw.version
└── wpa2

3 directories, 14 files
cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root/etc $
```

# /etc is always fun!

We have password files, certificates, and startup configs

```
cclamb — ssh -X 192.168.120.135 — 89x26
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root/etc $ tail rc.d/rcS
# lets force them to write
echo 20 > /proc/sys/vm/dirty_ratio

# when the dirty pages cross more than 5% of sys memory,
# kick in the pdflush
echo 5 > /proc/sys/vm/dirty_background_ratio

#/usr/sbin/telnetd &

/usr/bin/shd &
cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root/etc $
```

# Startup Files

Various services and a non-standard daemon

```
cclamb — ssh -X 192.168.120.135 — 89x26
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root/usr/bin $ tree .
.
├── [ -> ../../bin/busybox
├── arping -> ../../bin/busybox
├── calDump
├── shd
├── shdTester
├── test -> ../../bin/busybox
├── tftp -> ../../bin/busybox
└── tty -> ../../bin/busybox

0 directories, 8 files
cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root/usr/bin $
```

# /usr/bin

Application level software!

# IoT: Client Devices

So what have we learned?

# So Far...

## EXTRACTED FIRMWARE IMAGE

---

- ▶ Full OS, embedded linux image, for TP-Link smart plug

## EXAMINED THE OS AND BOOTLOADER

---

- ▶ An older version of Linux
- ▶ And equally old version of U-Boot

## LOOKED THROUGH THE FILESYSTEM

---

- ▶ Checked out config files
- ▶ Found application daemon

**All Your Product!**

**YOU ARE  
RESPONSIBLE!**

# IoT: Client Devices

Running Application Executables



# Application Analysis

## REGULAR APPLICATIONS

---

- ▶ GDB, LLDB
- ▶ Binutils
- ▶ Tracing Tools (DTrace, Strace, etc.)

## CROSS-COMPILATION PROBLEMS

---

- ▶ Cross-compiled binutils

But What about dynamic analysis?

# QEMU to the Rescue!

## QEMU CAN RUN APPLICATIONS LOCALLY

---

- ▶ chroot
- ▶ qemu-\*-static (e.g. qemu-mips-static)

## HOW TO USE

---

- ▶ Easiest if you use the extracted filesystem
- ▶ copy the appropriate static execution utility
- ▶ run cross-compiled

```

[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ pwd
/home/cclamb/Work/tplink/hs110/squashfs-root
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ ls
bin dev etc lib linuxrc mnt proc root sbin sys tmp usr
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ which qemu-mips-static
/usr/bin/qemu-mips-static
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ cp /usr/bin/qemu-mips-static .
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ ls
bin dev etc lib linuxrc mnt proc qemu-mips-static root sbin sys tmp usr
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ sudo chroot . ./qemu-mips-static /usr/b
in/shd
[[sudo] password for cclamb:
qemu: uncaught target signal 11 (Segmentation fault) - core dumped
Segmentation fault (core dumped)
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ sudo chroot . ./qemu-mips-static /usr/b
in/shd -h
sudo: unable to resolve host HS110(US)
options for /usr/bin/shd
    -k      kill all shd process
    -t      enter test mode
    -h      print this help
cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ 

```

# Running /usr/bin/shd

with flags and without!

# Why chroot?

YOU MAY NOT ALWAYS NEED IT

---

- ▶ statically linked applications

USING LIBRARIES? YOU NEED CHROOT

---

- ▶ shd uses a few
- ▶ how do we know?

Dynamic section at offset 0x180 contains 30 entries:

Tag	Type	Name/Value
0x00000001	(NEEDED)	Shared library: [librt.so.0]
0x00000001	(NEEDED)	Shared library: [libm.so.0]
0x00000001	(NEEDED)	Shared library: [libpthread.so.0]
0x00000001	(NEEDED)	Shared library: [libresolv.so.0]
0x00000001	(NEEDED)	Shared library: [libgcc_s.so.1]
0x00000001	(NEEDED)	Shared library: [libc.so.0]
0x0000000c	(INIT)	0x4160b8
0x0000000d	(FINI)	0x598070
0x00000004	(HASH)	0x400298
0x00000005	(STRTAB)	0x40c3f4
0x00000006	(SYMTAB)	0x4042f4
0x0000000a	(STRSZ)	35906 (bytes)
0x0000000b	(SYMENT)	16 (bytes)
0x70000016	(MIPS_RLD_MAP)	0x5f0860
0x00000015	(DEBUG)	0x0
0x00000003	(PLTGOT)	0x5f0870
0x00000011	(REL)	0x416078
0x00000012	(RELSZ)	64 (bytes)
0x00000013	(RELENT)	8 (bytes)
0x70000001	(MIPS_RLD_VERSION)	1

# Shared Libraries

```
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ ls -al lib
total 928
drwxrwxr-x  3 cclamb cclamb  4096 Oct 15  2015 .
drwxrwxr-x 12 cclamb cclamb  4096 Jan  6 11:03 ..
-rwxr-xr-x  1 cclamb cclamb 20704 Oct 15  2015 ld-uClibc-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   19 Jan  2 16:11 ld-uClibc.so.0 -> ld-uClibc-0.9.30.so
-rw-r--r--  1 cclamb cclamb 10148 Oct 15  2015 libcrypt-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   18 Jan  2 16:11 libcrypt.so.0 -> libcrypt-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   19 Jan  2 16:11 libc.so.0 -> libuClibc-0.9.30.so
-rw-r--r--  1 cclamb cclamb  8312 Oct 15  2015 libdl-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   15 Jan  2 16:11 libdl.so.0 -> libdl-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   13 Jan  2 16:11 libgcc_s.so -> libgcc_s.so.1
-rw-r--r--  1 cclamb cclamb 174432 Oct 15  2015 libgcc_s.so.1
-rw-r--r--  1 cclamb cclamb 100968 Oct 15  2015 libm-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   14 Jan  2 16:11 libm.so.0 -> libm-0.9.30.so
-rw-r--r--  1 cclamb cclamb   917 Oct 15  2015 libnsl-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   16 Jan  2 16:11 libnsl.so.0 -> libnsl-0.9.30.so
-rw-r--r--  1 cclamb cclamb  71528 Oct 15  2015 libpthread-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   20 Jan  2 16:11 libpthread.so.0 -> libpthread-0.9.30.so
-rw-r--r--  1 cclamb cclamb   917 Oct 15  2015 libresolv-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   19 Jan  2 16:11 libresolv.so.0 -> libresolv-0.9.30.so
-rw-r--r--  1 cclamb cclamb  3412 Oct 15  2015 librt-0.9.30.so
lrwxrwxrwx  1 cclamb cclamb   15 Jan  2 16:11 librt.so.0 -> librt-0.9.30.so
-rw-r--r--  1 cclamb cclamb 364240 Oct 15  2015 libuClibc-0.9.30.so
-rw-r--r--  1 cclamb cclamb   3964 Oct 15  2015 libutil-0.9.30.so
```

# Packaged Libraries

/usr/bin/shd needs to find these to run!

# IoT: Client Devices

Reversing: Image Analysis

# So Far...

## U-BOOT BOOT LOADER

---

- ▶ Version 1.1.4, built in late 2015

## LINUX KERNEL

---

- ▶ Also built in late 2015

## FILESYSTEM

---

- ▶ Squash-fs filesystem, late 2015



# Extracting

NOW LET'S USE BINWALK TO EXTRACT THE FILES

---

- ▶ `binwalk -e -C extracted -M <imagename>`

WHAT DOES THIS DO?

---

- ▶ `-e`: extract the contents of the image
- ▶ `-C`: place the results in the 'extracted' subdirectory
- ▶ `-M`: recursively scan extracted stuff

```
[cclamb@ubuntu:~/Work/tplink/extracted/_hs110v1_us_1.0.7_Build_151016_Rel.24186.bin.extracted] $ ls
10300  10300.7z  _10300.extracted  1102C0.squashfs  439C  439C.7z  squashfs-root
[cclamb@ubuntu:~/Work/tplink/extracted/_hs110v1_us_1.0.7_Build_151016_Rel.24186.bin.extracted] $ binwalk ../../hs110v1_us_1.0.7_Build_151016_Rel.24186.bin
```

DECIMAL	HEXADECIMAL	DESCRIPTION
15904	0x3E20	U-Boot version string, "U-Boot 1.1.4 (Oct 16 2015 - 11:22:22)"
15952	0x3E50	CRC32 polynomial table, big endian
17244	0x435C	uImage header, header size: 64 bytes, header CRC: 0xA2B5F4E6, created: 2015-10-16 03:22:22, image size: 38777 bytes, Data Address: 0x80010000, Entry Point: 0x80010000, data CRC: 0xFED80D4A, OS: Linux, CPU: MIPS, image type: Firmware Image, compression type: lzma, image name: "u-boot image"
17308	0x439C	LZMA compressed data, properties: 0x5D, dictionary size: 33554432 bytes, uncompressed size: 112564 bytes
66240	0x102C0	uImage header, header size: 64 bytes, header CRC: 0x4D2B83AC, created: 2015-10-16 03:22:56, image size: 772570 bytes, Data Address: 0x80002000, Entry Point: 0x8019BF90, data CRC: 0xC849B1ED, OS: Linux, CPU: MIPS, image type: OS Kernel Image, compression type: lzma, image name: "Linux Kernel Image"
66304	0x10300	LZMA compressed data, properties: 0x5D, dictionary size: 33554432 bytes, uncompressed size: 2238780 bytes
1114816	0x1102C0	Squashfs filesystem, little endian, version 4.0, compression: lzma, size: 2112689 bytes, 194 inodes, blocksize: 16384 bytes, created: 2015-10-16 03:25:36

```
cclamb — ssh -X 192.168.120.134 — 89x26
[cclamb@ubuntu:~/Work/tplink/hs110 $ strings -n 10 10300 > strings.out
[cclamb@ubuntu:~/Work/tplink/hs110 $ head strings.out
initcall_debug
Linux version 2.6.31--LSDK-9.2.0_U11.14 (yt@yangtao.localdomain) (gcc version 4.3.3 (GCC)
) #10 Tue Sep 8 15:36:13 HKT 2015
%s version %s (yt@yangtao.localdomain) (gcc version 4.3.3 (GCC) ) %s
plat_time_init
ar7240_serial_setup
ar7240_spi_flash_read_page
ar7240wdt_init
pause_on_oops
Od<2>BUG: recent printk recursion!
printk.time
[cclamb@ubuntu:~/Work/tplink/hs110 $ strings -n 10 439C > 439C-strings.out
[cclamb@ubuntu:~/Work/tplink/hs110 $ head 439C-strings.out
U-Boot 1.1.4 (Oct 16 2015 - 11:22:19)
ag7240_miiphy_write
ag7240_miiphy_read
ag7240_get_ethaddr
ag7240_mii_setup
reset - Perform RESET of the CPU
    Image Name:      %.*s
    Created:         %4d-%02d-%02d  %2d:%02d:%02d UTC
    Image Type:
Invalid OS
cclamb@ubuntu:~/Work/tplink/hs110 $
```

# Strings

Seems to confirm binwalk results, but now we have a kernel version (released in 2009!)

```
[cclamb@ubuntu:~/Work/tplink/hs110 $ ls
10300      _10300.extracted  439C      439C-strings.out  squashfs-root
10300.7z   1102C0.squashfs   439C.7z   hex.out           strings.out
[cclamb@ubuntu:~/Work/tplink/hs110 $ cd squashfs-root/
[cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $ ls
bin  dev  etc  lib  linuxrc  mnt  proc  root  sbin  sys  tmp  usr
cclamb@ubuntu:~/Work/tplink/hs110/squashfs-root $
```

# The filesystem

Take a look at squashes-root; it has a complete filesystem!