Scott Nguyen

scott.nguven8901@gmail.com | (515) 943-6283 | linkedin.com/in/scottnguven8901

EDUCATION

Master of Science in Electrical Engineering | Space Systems Engineering

University of New Mexico

Master of Science in Aerospace Engineering

University of Illinois Urbana-Champaign

Bachelor of Science in Aerospace Engineering

Iowa State University

Fall 2024

Summer 2026

GPA: 3.94/4.00

Spring 2022

SKILLS

Programming Languages: MATLAB, Python, C/C++, Ruby

Frameworks / Libraries / Tools: NumPy, SciPy, Matplotlib, Astropy, Poliastro, bpy, git

Applications: Simulink, Blender

WORK EXPERIENCE

Guidance, Navigation & Controls Engineer Intern

May 2025 – August 2025 Blue Canyon Technologies

- Verified functionality and polarity of the IMU, Nano Star Tracker, Reaction Wheels, Torque Rods, and Sun Sensors through hardware testing and data validation
- Conducted regression analysis on two-axis Solar Array Drive Assembly (SADA) momentum management and tested command interfaces to ensure precise control and system reliability
- Developed automated test scripts in **Ruby** and mapped **SADA** telemetry channels to **COSMOS**, streamlining system validation and real-time monitoring

Guidance, Navigation & Controls Engineer Intern

January 2025 - April 2025

Blue Origin

- Integrated Active Disturbance Rejection Control (ADRC) and Sliding Mode Control (SMC) to develop a robust algorithm for stabilizing the nonlinear MIMO dynamics of the BE-7 engine
- Evaluated control performance by injecting various disturbances, demonstrating effective rejection and improved accuracy in setpoint tracking
- \bullet Integrated flight software into Simulink using S-functions programmed in C to enable testing and verification
- Compiled findings into a technical report and presented control strategies, simulations, and integration insights

Guidance, Navigation & Controls Engineer Intern

May 2024 - August 2024

Varda Space Industries

- Conducted trade studies to optimize gravity models for mission requirements and select the best filter (Extended Kalman Filter (EKF) vs. Unscented Kalman Filter (UKF))
- Created Monte Carlo simulations to perform flight safety analysis and develop reentry criteria for capsule reentry
- Implemented an EKF for state estimation, optimizing ground station data timing to minimize residuals and enable precise delta-v planning
- Validated GPS error using hardware-in-the-loop testing with Spirent simulation
- Implemented unit testing for the code base and introduced CI/CD pipelines using Bamboo

Guidance, Navigation & Controls Engineer Intern

May 2023 - August 2023

Space Dynamics Laboratory

- Implemented a UKF with range iteration and least squares orbit determination methods using optical navigation
- Simulated high-fidelity dynamic models with J2 perturbations, third-body dynamics, and solar radiation pressure
- Performed Monte Carlo analysis on relative orbits to identify challenging scenarios and refine the algorithm
- Programmed and developed unit tests for Lambert Solver to be utilized with Initial Orbit Determination (IOD)

RESEARCH PROJECTS

Delta-V Minimization from Geostationary Orbit to Mars

- Applied trajectory optimization techniques to minimize delta-v for an Earth-to-Mars transfer orbit, enhancing fuel
- Generated pork-chop plots using Lambert solutions and cross-validated optimizer results with the plot's global and local minimum regions to ensure consistency
- Utilized Blender's Python API to visualize the optimized trajectory and animate planetary motion