

# Scott Nguyen

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## EDUCATION

**Master of Science in Electrical Engineering | Space Systems Engineering**

University of New Mexico

**Summer 2026**

GPA: 3.93/4.00

**Master of Science in Aerospace Engineering**

University of Illinois Urbana-Champaign

**Fall 2024**

**Bachelor of Science in Aerospace Engineering**

Iowa State University

**Spring 2022**

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## SKILLS

**Programming Languages:** MATLAB, Python, C/C++, Ruby

**Frameworks / Libraries / Tools:** NumPy, SciPy, Matplotlib, Astropy, Poliastro, bpy, git

**Applications:** Simulink, Blender

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## WORK EXPERIENCE

**Guidance, Navigation & Controls Engineer Intern**

**May 2025 – August 2025**

*Blue Canyon Technologies*

- Verified functionality and polarity of the IMU, Nano Star Tracker, Reaction Wheels, Torque Rods, and Sun Sensors through hardware testing and data validation
- Conducted regression analysis on two-axis **Solar Array Drive Assembly (SADA)** momentum management and tested command interfaces to ensure precise control and system reliability
- Developed automated test scripts in **Ruby** and mapped **SADA** telemetry channels to **COSMOS**, streamlining system validation and real-time monitoring

**Guidance, Navigation & Controls Engineer Intern**

**January 2025 – April 2025**

*Blue Origin*

- Integrated **Active Disturbance Rejection Control (ADRC)** and **Sliding Mode Control (SMC)** to develop a robust algorithm for stabilizing the nonlinear MIMO dynamics of the BE-7 engine
- Evaluated control performance by injecting various disturbances, demonstrating effective rejection and improved accuracy in setpoint tracking
- Integrated flight software into **Simulink** using **S-functions** programmed in **C** to enable testing and verification
- Compiled findings into a technical report and presented control strategies, simulations, and integration insights

**Guidance, Navigation & Controls Engineer Intern**

**May 2024 – August 2024**

*Varda Space Industries*

- Conducted trade studies to optimize gravity models for mission requirements and select the best filter (**Extended Kalman Filter (EKF)** vs. **Unscented Kalman Filter (UKF)**)
- Created Monte Carlo simulations to perform flight safety analysis and develop reentry criteria for capsule reentry
- Implemented an **EKF** for state estimation, optimizing ground station data timing to minimize residuals and enable precise delta-v planning
- Validated GPS error using hardware-in-the-loop testing with Spirent simulation
- Implemented unit testing for the code base and introduced CI/CD pipelines using Bamboo

**Guidance, Navigation & Controls Engineer Intern**

**May 2023 – August 2023**

*Space Dynamics Laboratory*

- Implemented a UKF with range iteration and least squares orbit determination methods using optical navigation
- Simulated high-fidelity dynamic models with J2 perturbations, third-body dynamics, and solar radiation pressure
- Performed Monte Carlo analysis on relative orbits to identify challenging scenarios and refine the algorithm
- Programmed and developed unit tests for **Lambert Solver** to be utilized with **Initial Orbit Determination (IOD)**

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## RESEARCH PROJECTS

**Delta-V Minimization from Geostationary Orbit to Mars**

- Applied trajectory optimization techniques to minimize delta-v for an Earth-to-Mars transfer orbit, enhancing fuel efficiency
- Generated pork-chop plots using Lambert solutions and cross-validated optimizer results with the plot's global and local minimum regions to ensure consistency
- Utilized Blender's Python API to visualize the optimized trajectory and animate planetary motion