

IoT: Client Devices

Testing our Development Environment

Start up your VM

LOG INTO YOUR VM

- ▶ Start up virtualization
- ▶ Log in
- ▶ Open a few windows

OTHER TOOLS

- ▶ I use things like Tmux and Powerline (you don't have to)

Build an ARM Image

BUILDROOT

- ▶ Versatile Platform Baseboard
- ▶ Configure with defaults and Build
- ▶ `cd to Buildroot directory`
- ▶ `$ make qemu_arm_versatile_defconfig`

WHAT DOES THIS DO?

- ▶ Creates a base `.config` file with defaults for board
- ▶ Build stock version first

Now Add SSH

WHY?

- ▶ We need to move a cross-compiled executable to the image

NAVIGATE TO BUILDROOT

- ▶ Open the configuration menu (make nconfig)
- ▶ Target Packages -> Networking applications -> openssh
- ▶ Rebuild (just type make)

Build Results

SO WHAT DID WE BUILD?

- ▶ Take a look in `$buildroot_home/output/images`
 - ▶ you should see: `zImage`, `rootfs.ext2`, `versatile-pb.dtb`
 - ▶ what are these things?
 - ▶ `zImage`: Kernel image
 - ▶ `rootfs.ext2`: Root filesystem
 - ▶ `versatile-pb.dtb`: Device tree blob (contains hardware info)

Let's Run

BUILD INSTRUCTIONS

- ▶ `$buildroot_home/board/qemu/arm-versatile/readme.txt`
- ▶ The command line for the new QEMU image is in the readme (see next page for script)

Running in QEMU

MIGHT BE BETTER AS A SCRIPT

```
qemu-versatile.sh:
```

```
qemu-system-arm \
```

```
-M versatilepb \
```

```
-kernel output/images/zImage \
```

```
-dtb output/images/versatile-pb.dtb \
```

```
-drive file=output/images/rootfs.ext2,if=scsi,format=raw -append "root=/  
dev/sda console=ttyAMA0,115200" \
```

```
-serial stdio \
```

```
-net nic,model=rtl8139 -net user \
```

```
-redir tcp:2222:22
```