Recorded at time: 1564492300.261 map Broadcaster: /map\_odom\_broadcaster Average rate: 14.563 Hz Most recent transform: 1564492300.993 (-0.732 sec old) Buffer length: 5.494 sec odom Broadcaster: /my\_serial\_node Average rate: 17.917 Hz Most recent transform: 1564492300.146 ( 0.115 sec old) Buffer length: 4.800 sec base\_footprint Broadcaster: /state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1564492300.261 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /state\_publisher Broadcaster: /base2laser Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 20.140 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1564492300.261 sec old) Most recent transform: 1564492300.231 ( 0.031 sec old) Most recent transform: 0.000 ( 1564492300.261 sec old) Buffer length: 0.000 sec Buffer length: 4.866 sec left\_motor right\_motor plate\_1\_link standoff\_2in\_1\_link standoff\_2in\_2\_link standoff\_2in\_3\_link standoff\_2in\_4\_link front\_caster\_link laser Broadcaster: /state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 4.043 Hz Average rate: 4.043 Hz Average rate: 10000.000 Hz Most recent transform: 1564492300.109 (0.152 sec old) Most recent transform: 1564492300.109 (0.152 sec old) Most recent transform: 0.000 ( 1564492300.261 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.700 sec Buffer length: 4.700 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec right\_wheel\_link plate\_2\_link standoff\_2in\_5\_link standoff\_2in\_6\_link standoff\_2in\_7\_link standoff\_2in\_8\_link left\_wheel\_link Broadcaster: /state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1564492300.261 sec old) Buffer length: 0.000 sec

view\_frames Result

laser\_link