

```

• begin
•     import Pkg;     Pkg.activate()
•
•     using DataFrames
•     using Plots
• end

```



Activating project at `~/julia/environments/v1.8`



euler (generic function with 1 method)

```

• function euler(s, a, b, x₀, T₀, S₀, h)
•     x = [x₀]
•     T = [T₀]
•     S = [S₀]
•
•     while x[end]+h < b
•         push!(T, T[end] + h * S[end])
•         push!(S, S[end] + h * s(x[end], T[end-1], S[end]))
•         push!(x, x[end] + h)
•     end
•
•     return x, T, S
• end

```

Метод вариации постоянных

$$y'' + \frac{1}{x}y' - 2y = x^2$$

$$0.5 \leq x \leq 1, y'(0.5) = -0.5, y'(1) = -1$$

(0, 0)

• $\alpha_0, \alpha_1 = 0, 0$

(1, 1)

• $\beta_0, \beta_1 = 1, 1$

(-0.5, -1.0)

• $\gamma_0, \gamma_1 = -0.5, -1.$

Z, Z_1, Z_2

$$\begin{cases} Z''(x) + \frac{1}{x}Z'(x) - 2Z(x) = x^2, 0.5 \leq x \leq 1 \\ Z(0.5) = 0, Z'(0.5) = 0 \end{cases}$$

$$\begin{cases} T'(x) = S(x) \\ S'(x) = -\frac{1}{x}S(x) + 2T(x) + x^2, 0.5 \leq x \leq 1 \\ T(0.5) = 0, S(0.5) = 0 \end{cases}$$

```
(  
  1:  [0.5, 0.6, 0.7, 0.8, 0.9, 1.0]  
  2:  [0.0, 0.0, 0.0025, 0.00818333, 0.0180048, 0.0331622]  
  3:  [0.0, 0.025, 0.0568333, 0.0982143, 0.151574, 0.219334]  
)
```

```
• x, T, S = euler(  
•   (x, t, s) -> -s/x + 2*t + x^2,  
•   0.5, 1.,  
•   0.5,  
•   .0, .0,  
•   .1  
• )
```

$$\begin{cases} Z_1''(x) + \frac{1}{x}Z_1'(x) - 2Z_1(x) = 0, 0.5 \leq x \leq 1 \\ Z_1(0.5) = 0, Z_1'(0.5) = 1 \end{cases}$$

$$\begin{cases} T_1'(x) = S_1(x) \\ S_1'(x) = -\frac{1}{x}S_1(x) + 2T_1(x), 0.5 \leq x \leq 1 \\ T_1(0.5) = 0, S_1(0.5) = 1 \end{cases}$$

```
([0.0, 0.1, 0.18, 0.248667, 0.311124, 0.370747], [1.0, 0.8, 0.686667, 0.624571, 0.596233, 0.571124])
```

```
• T1, S1 = euler(  
•   (x, t, s) -> -s/x + 2*t,  
•   0.5, 1.,  
•   0.5,  
•   .0, 1.,  
•   .1  
• )[2:3]
```

$$\begin{cases} Z_2''(x) + \frac{1}{x}Z_2'(x) - 2Z_2(x) = 0, 0.5 \leq x \leq 1 \\ Z_2(0.5) = 1, Z_2'(0.5) = 0 \end{cases}$$

$$\begin{cases} T_2'(x) = S_2(x) \\ S_2'(x) = -\frac{1}{x}S_2(x) + 2T_2(x), 0.5 \leq x \leq 1 \\ T_2(0.5) = 1, S_2(0.5) = 0 \end{cases}$$

```
(
  1: [1.0, 1.0, 1.02, 1.05667, 1.1085, 1.17498]
  2: [0.0, 0.2, 0.366667, 0.518286, 0.664833, 0.812662]
)
```

```
• T2, S2 = euler(
•   (x, t, s) -> -s/x + 2*t,
•   0.5, 1.,
•   0.5,
•   1., .0,
•   .1
• )[2:3]
```

C_1, C_2

```
A = 2x3 Matrix{Float64}:
 1.0      0.0      -0.5
0.59221  0.812662 -1.21933
```

```
• A = [
•   α0*T1[1] + β0*S1[1] α0*T2[1] + β0*S2[1] y0 - α0*T[1] - β0*S[1]
•   α1*T1[end] + β1*S1[end] α1*T2[end] + β1*S2[end] y1 - α1*T[end] - β1*S[end]
• ]
```

```
[-0.5, -1.13605]
```

```
• C1, C2 = A[:, [1,2]] \ A[:, 3]
```

y_k

```
yk = [-1.13605, -1.18605, -1.24628, -1.31658, -1.39687, -1.48705]
```

```
• yk = C1.*T1 + C2.*T2 + T
```

	x_k	T	S	T_1	S_1	T_2	S_2	y_k
1	0.5	0.0	0.0	0.0	1.0	1.0	0.0	-1.13605
2	0.6	0.0	0.025	0.1	0.8	1.0	0.2	-1.18605
3	0.7	0.0025	0.0568333	0.18	0.686667	1.02	0.366667	-1.24628
4	0.8	0.00818333	0.0982143	0.248667	0.624571	1.05667	0.518286	-1.31658
5	0.9	0.0180048	0.151574	0.311124	0.596233	1.1085	0.664833	-1.39687
6	1.0	0.0331622	0.219334	0.370747	0.59221	1.17498	0.812662	-1.48705

```

• DataFrame(
•    $x_k = x$ ,
•    $T = T$ ,  $S = S$ ,
•    $T_1 = T_1$ ,  $S_1 = S_1$ ,
•    $T_2 = T_2$ ,  $S_2 = S_2$ ,
•    $y_k = y_k$ 
• )

```

