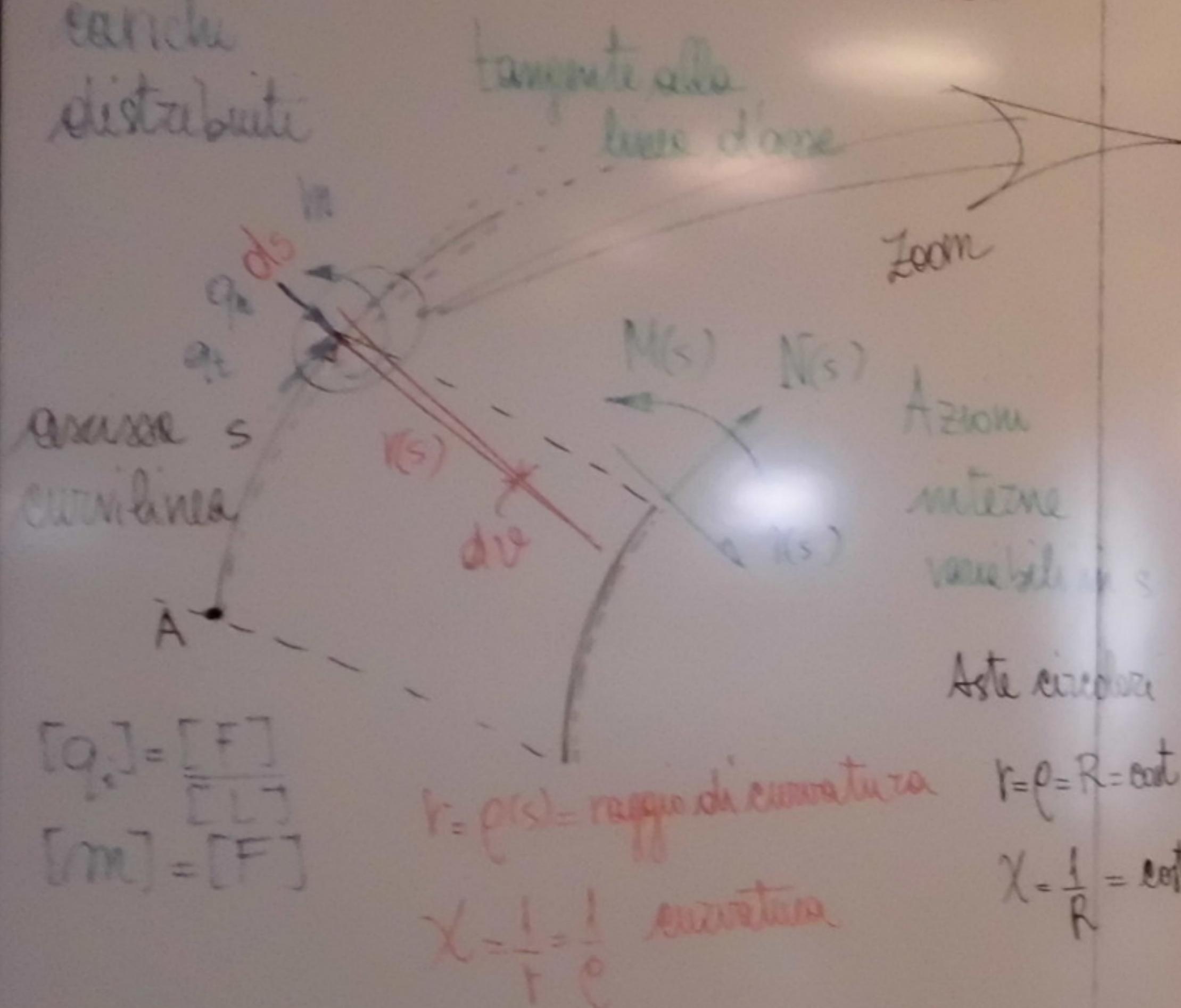


Eq. indeterminate di equilibrio delle astre curvate

carichi
distribuiti



$$[q_s] = \begin{bmatrix} F \\ qL \end{bmatrix}$$

$$[M_s] = \begin{bmatrix} F \end{bmatrix}$$

$$r = r(s) = \text{raggio di curvatura}$$

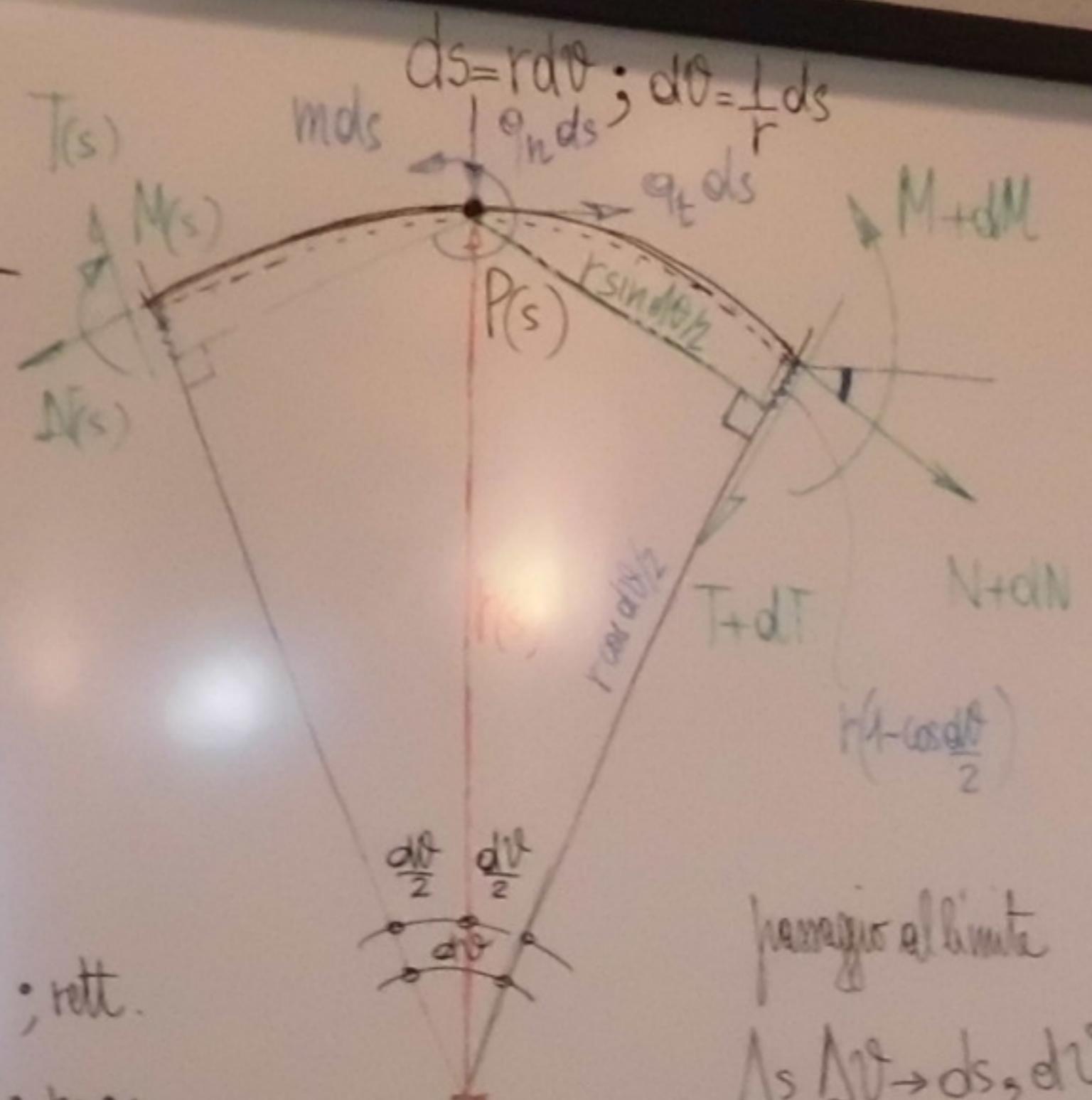
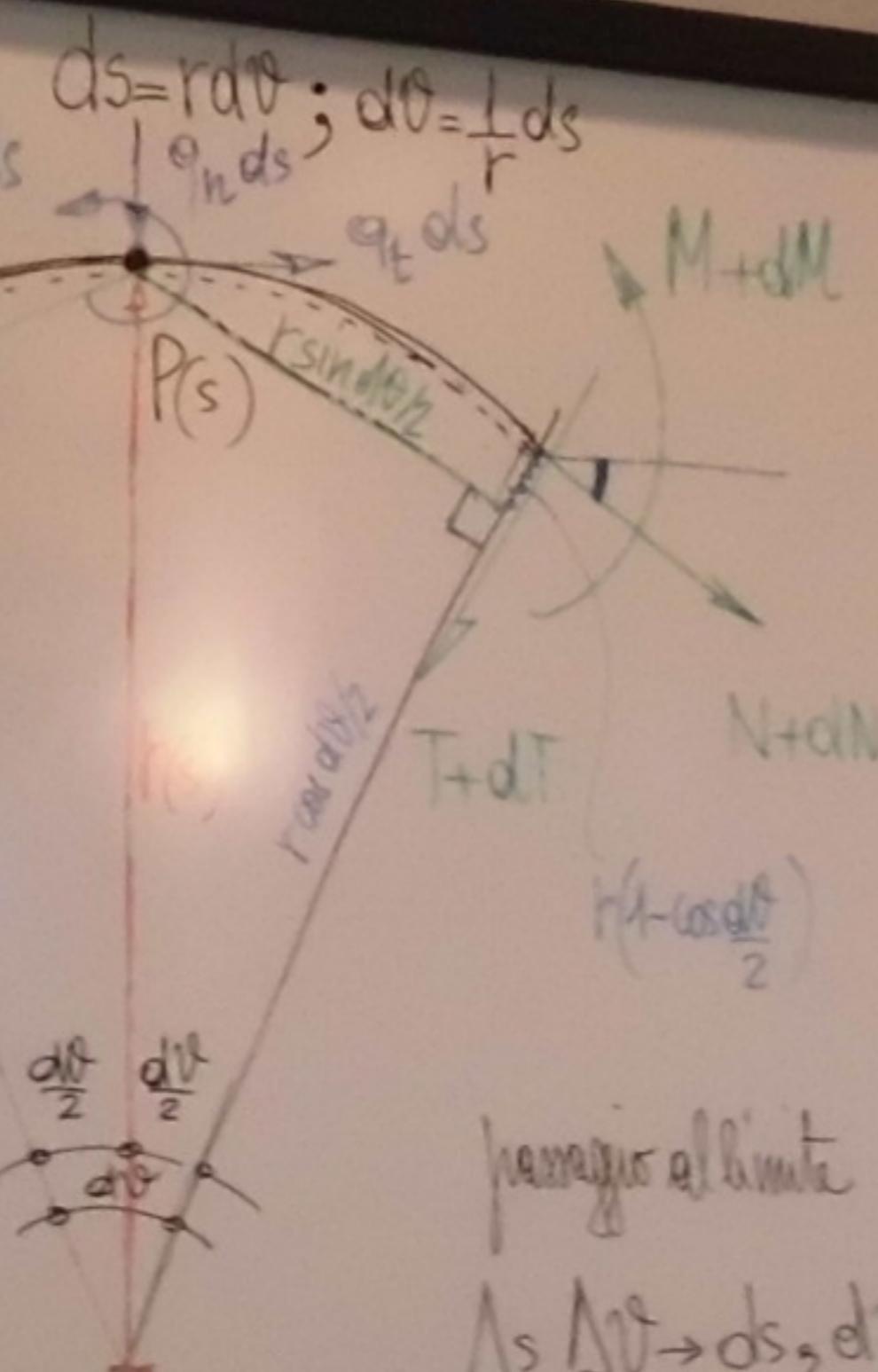
$$\chi = \frac{1}{r} = \frac{1}{r(s)} = \text{curvatura}$$

$$r = \rho = R = \text{cost.}; r \rightarrow \infty$$

$$\chi = \frac{1}{R} = \text{cost.}; \chi \rightarrow 0$$

Zoom
Azione
interna
variabile s

Aste curvate; rett.



Aste curvate; rett.

$$r = \rho = R = \text{cost.}; r \rightarrow \infty$$

$$\chi = \frac{1}{R} = \text{cost.}; \chi \rightarrow 0$$

Equil. in stato indif.
per $P(s), ds$

passaggio al limite

$$\Delta s, \Delta \theta \rightarrow ds, d\theta$$

$$\frac{\Delta A I}{\Delta s} \rightarrow \frac{d A I}{ds}$$

$$\sum F_t^{ds} = 0 \Rightarrow (N + dN - N) \cos \frac{d\theta}{ds} - T \sin \frac{d\theta}{ds} + q_t ds = 0$$

$$N(s) = \frac{dN}{ds} = -\alpha(s) + \frac{T(s)}{r(s)}$$

$$\sum F_n^{ds} = 0 \Rightarrow (T + dT - T) \cos \frac{d\theta}{ds} + 2N \sin \frac{d\theta}{ds} + dN \cos \frac{d\theta}{ds} - q_t ds = 0$$

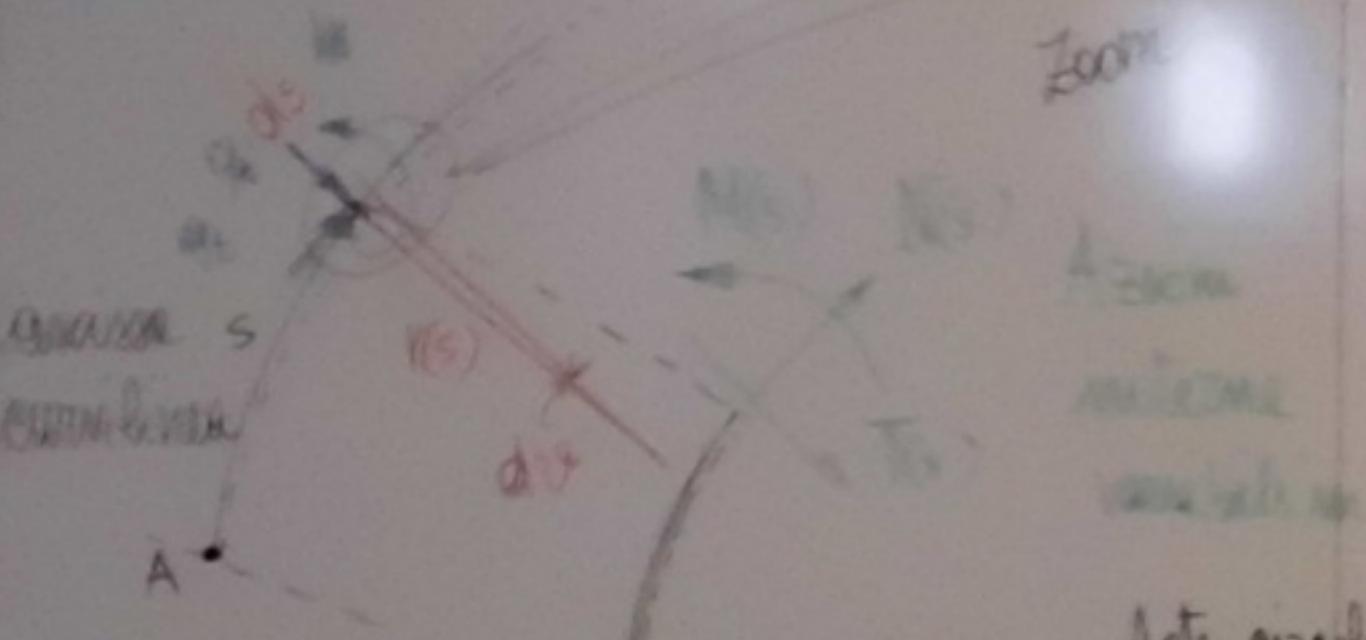
$$T(s) = \frac{dT}{ds} = -\alpha(s) - \frac{N(s)}{r(s)}$$

$$\sum M_p^{ds} = 0 \Rightarrow N + dN - N + (K - K - dN) \cos \frac{d\theta}{ds} - (T \cos \frac{d\theta}{ds} - q_t ds) \sin \frac{d\theta}{ds} = 0$$

$$M(s) = \frac{dM}{ds} = -M(s) + T(s)$$

Eq. momento di equilibrio delle aste curve

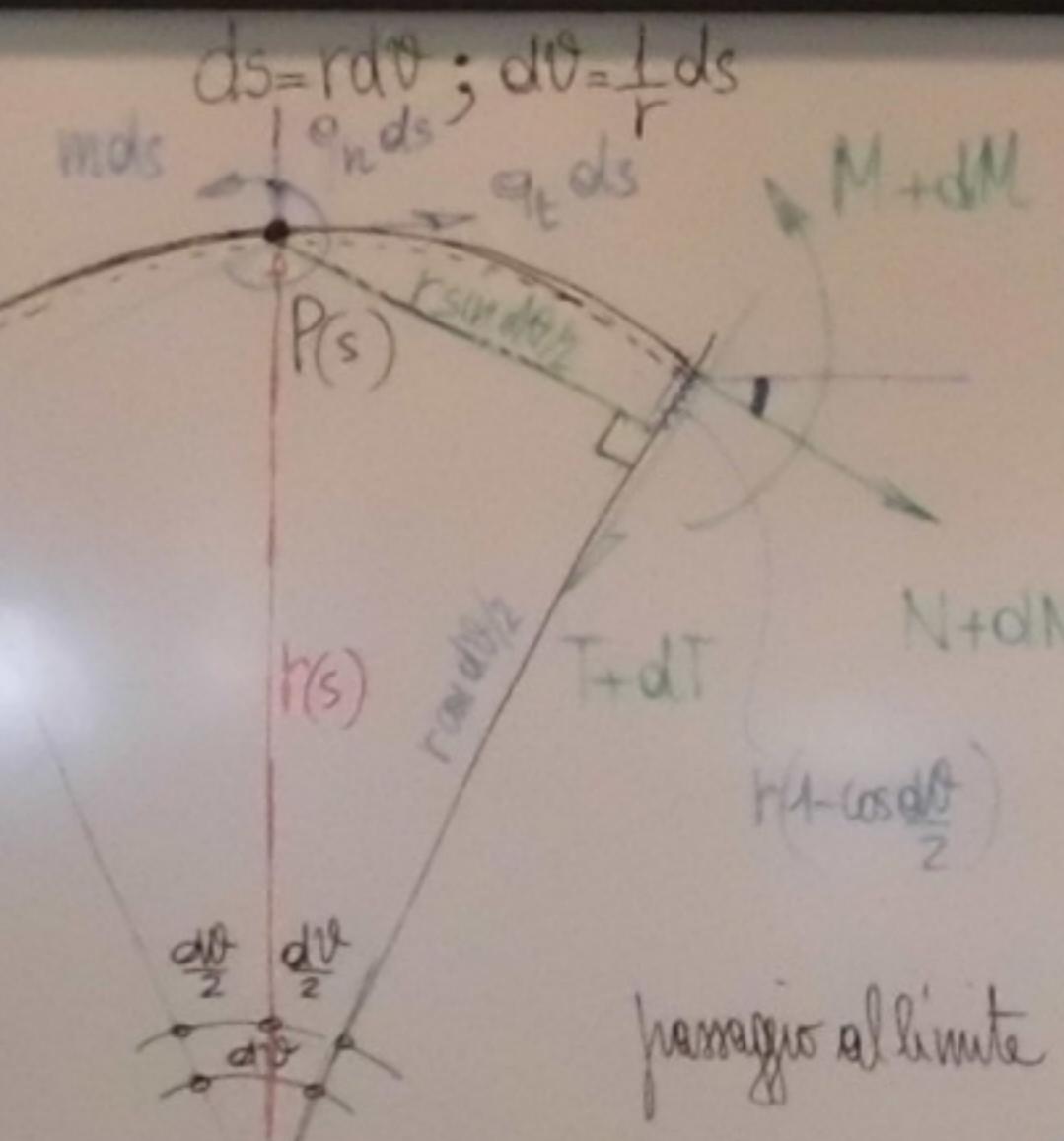
forza
esterni



$$r = r(s) = \text{raggio di curvatura}$$

$$r = R = \text{cost} ; R \rightarrow \infty$$

$$X = \frac{1}{R} = \text{cost} ; X \rightarrow 0$$



Equil. in sede midel.
 $\Delta P(s), ds$

$$\frac{\Delta A}{\Delta s} \rightarrow \frac{dA}{ds}$$

paramiglio all'infinito

$$[F] = [F]$$

$$[M] = [M]$$

$$[T] = [T]$$

$$[N] = [N]$$

$$[q] = [q]$$

$$[M_p] = [M_p]$$

- $\sum F_t^{ds} = 0 \Rightarrow (N + dN - N) \cos \frac{d\theta}{2} - 2T \sin \frac{d\theta}{2} - dT \sin \frac{d\theta}{2} + q_t ds = 0$

$$\boxed{N(s) = \frac{dN}{ds} = -q_t(s) + \frac{T(s)}{r(s)}} \quad \begin{array}{l} \text{scompare nel} \\ \text{processo allineato} \\ 0 (d^2) \end{array}$$

- $\sum F_n^{ds} = 0 \Rightarrow (T + dT - T) \cos \frac{d\theta}{2} + 2N \sin \frac{d\theta}{2} + dN \sin \frac{d\theta}{2} + q_n ds = 0$

$$\boxed{T(s) = \frac{dT}{ds} = -q_n(s) - \frac{N(s)}{r(s)}} \quad \begin{array}{l} \text{acoppiamento } T, N \end{array}$$

- $\sum M_p^{ds} = 0 \Rightarrow N + dN - N + (N - N - dN) r(1 - \cos \frac{d\theta}{2}) - 2Tr \sin \frac{d\theta}{2} - dTr \sin \frac{d\theta}{2} + m ds = 0$

$$\boxed{M_p(s) = \frac{dM}{ds} = -m(s) + T(s)}$$

come per asta rettilinea

Aste rettilinee ($r \rightarrow \infty$)

$$\begin{cases} N(s) = -q_t(s) \\ T(s) = -q_n(s) \\ M(s) = -m(s) + T(s) \end{cases}$$

Aste circolari ($r(s) = \text{cost} = R$)

$$\begin{cases} N(s) = -q_t(s) + \frac{T(s)}{R} = \frac{1}{R} \frac{dT}{ds} \\ T(s) = -q_n(s) - \frac{N(s)}{R} = \frac{1}{R} \frac{dN}{ds} \\ M(s) = -m(s) + T(s) = \frac{1}{R} \frac{dM}{ds} \\ N(s) = -q_t(s) + T(s) = \frac{1}{R} \frac{dT}{ds} \\ T(s) = -q_n(s) - \frac{N(s)}{R} = \frac{1}{R} \frac{dN}{ds} \\ M(s) = -m(s) + T(s) = \frac{1}{R} \frac{dM}{ds} \\ N(s) = -q_t(s) + T(s) = \frac{1}{R} \frac{dT}{ds} \\ T(s) = -q_n(s) - \frac{N(s)}{R} = \frac{1}{R} \frac{dN}{ds} \\ M(s) = -m(s) + T(s) = \frac{1}{R} \frac{dM}{ds} \end{cases}$$

- $\sum F_t^{\text{ds}} = 0 \Rightarrow (N + dN - N) \cos \frac{d\theta}{2} - 2T \sin \frac{d\theta}{2} - dT \sin \frac{d\theta}{2} + q_t^{\text{ds}} ds = 0$

 $N'(s) = \frac{dN}{ds} = -q_t^{\text{(s)}} + \frac{T(s)}{r(s)}$

scompare nel processo all'illimitato
accoppiamento $N \rightarrow T$
- $\sum F_n^{\text{ds}} = 0 \Rightarrow (T + dT - N) \cos \frac{d\theta}{2} + 2N \sin \frac{d\theta}{2} - dN \sin \frac{d\theta}{2} + q_n^{\text{ds}} ds = 0$

 $T'(s) = \frac{dT}{ds} = -q_n^{\text{(s)}} - \frac{N(s)}{r(s)}$

accoppiamento $T \rightarrow N$
- $\sum M_p^{\text{ds}} = 0 \Rightarrow M + dM - M + (N - N - dN)r(1 - \cos \frac{d\theta}{2}) - 2Tr \sin \frac{d\theta}{2} - dTr \sin \frac{d\theta}{2} + m ds = 0$

 $M'(s) = \frac{dM}{ds} = -m(s) + T(s)$

come per astre rettilinee

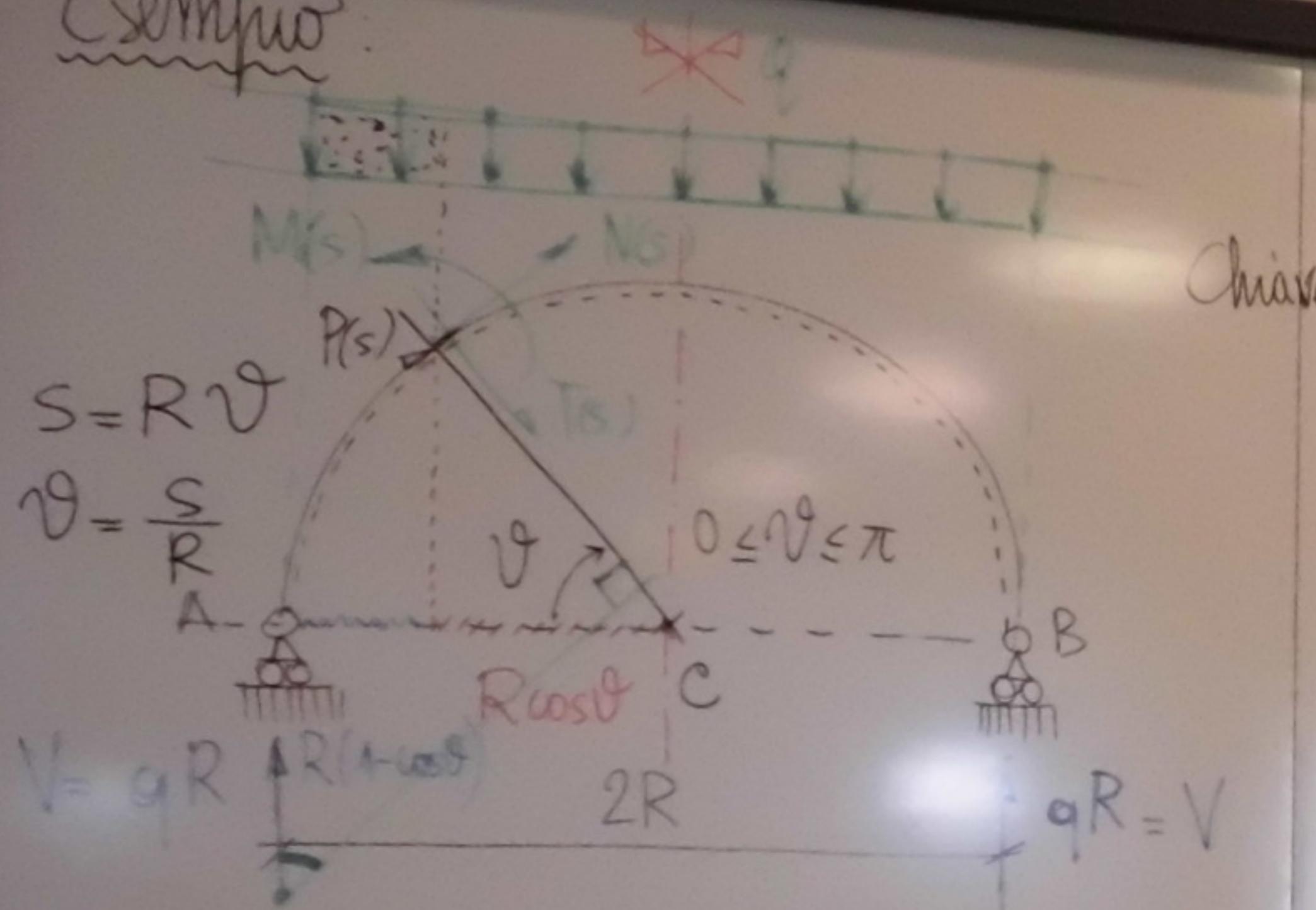
 $N'(s) = \frac{d^2N}{ds^2} = -m'(s) + \left(-q_n - \frac{N(s)}{r}\right) = -(m + q_n) - \frac{N(s)}{r}$

Aste rettilinee ($r \rightarrow \infty$)
 $\begin{cases} N'(s) = -q_t^{\text{(s)}} \\ T'(s) = -q_n^{\text{(s)}} \\ M'(s) = -m(s) + T(s) \end{cases} \Rightarrow M'(s) = -(m + q_n)$

Aste circolari ($r(s) = \text{cost. } R$)
 $\begin{cases} N'(s) = -q_t^{\text{(s)}} + \frac{T(s)}{R} = \frac{1}{R} \frac{dN}{ds} \\ T'(s) = -q_n^{\text{(s)}} - \frac{N(s)}{R} = \frac{1}{R} \frac{dT}{ds} \\ M'(s) = -m(s) + \frac{T(s)}{R} = \frac{1}{R} \frac{dM}{ds} \end{cases}$

 $\begin{cases} N(\theta) = -q_t(\theta)R + T(\theta) \\ T(\theta) = -q_n(\theta)R - N(\theta) \\ M(\theta) = -m(\theta)R + RT(\theta) \end{cases}$

Esempio



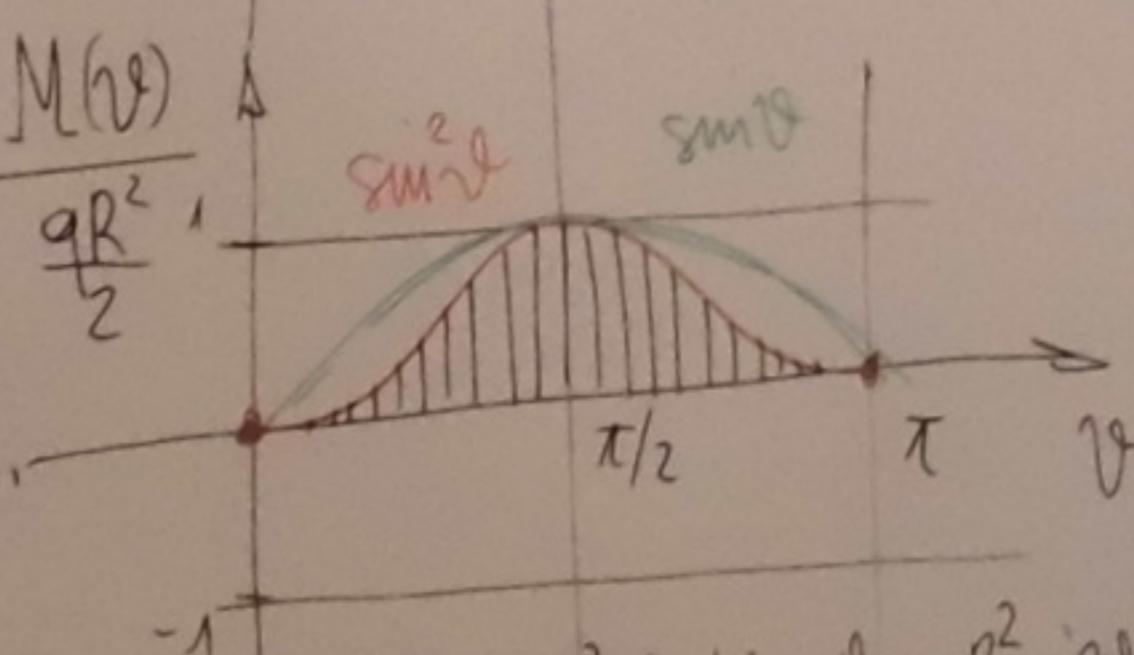
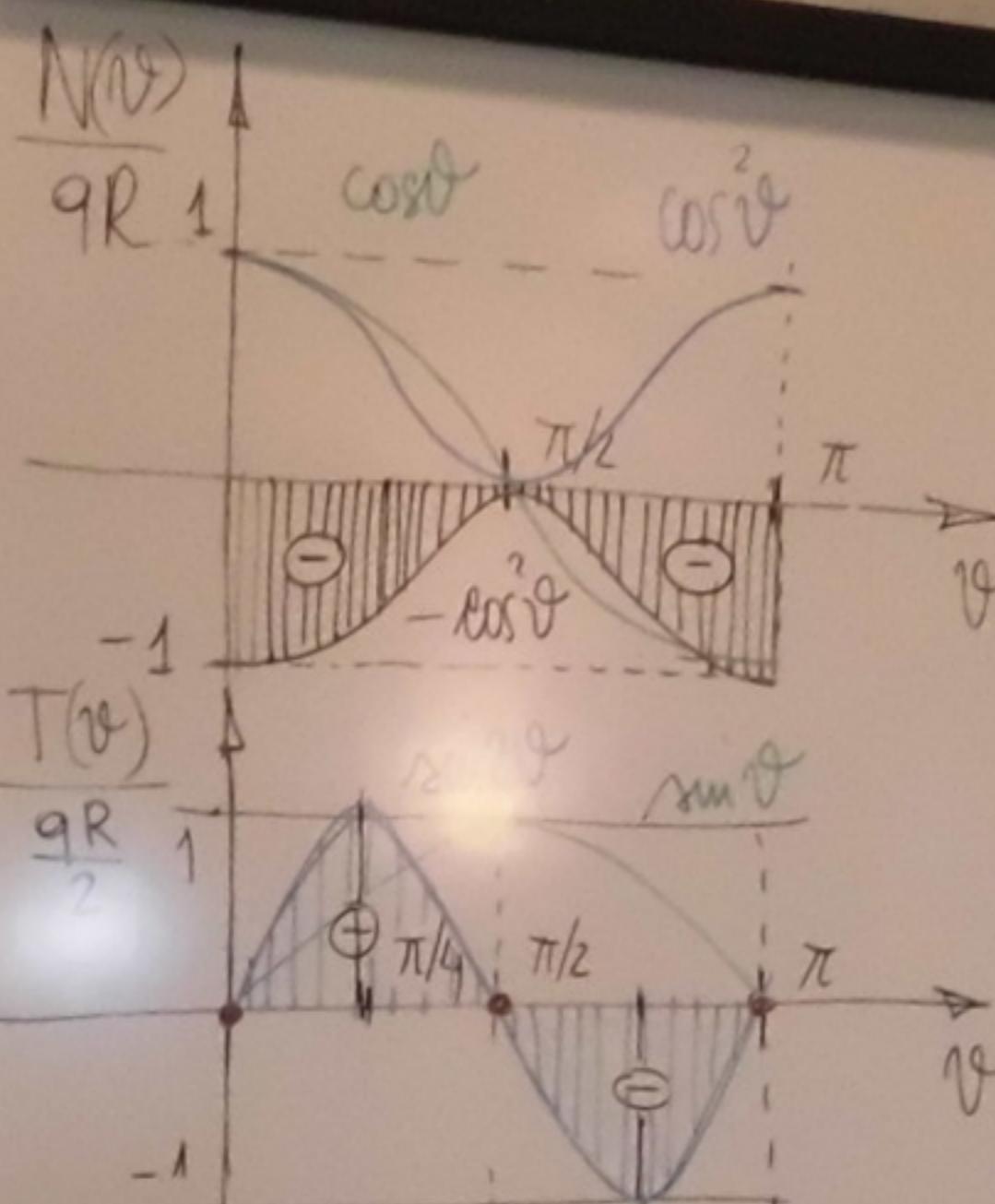
Azioni interne in $P(\vartheta)$

$$\begin{cases} N(\vartheta) = -qR + qR(1-\cos\vartheta) \cos\vartheta = -qR \cos^2\vartheta \\ T(\vartheta) = (qR - qR(1-\cos\vartheta)) \sin\vartheta = qR \frac{\sin\vartheta \cos\vartheta}{2} \\ M(\vartheta) = qR R(1-\cos\vartheta) - qR(1-\cos\vartheta)R(1-\cos\vartheta) \\ = qR^2(1-\cos\vartheta) \left(1 - \frac{1+\cos\vartheta}{2} \right) = \frac{qR^2}{2} (1-\cos^2\vartheta) = \frac{qR^2}{2} \sin^2\vartheta \end{cases}$$

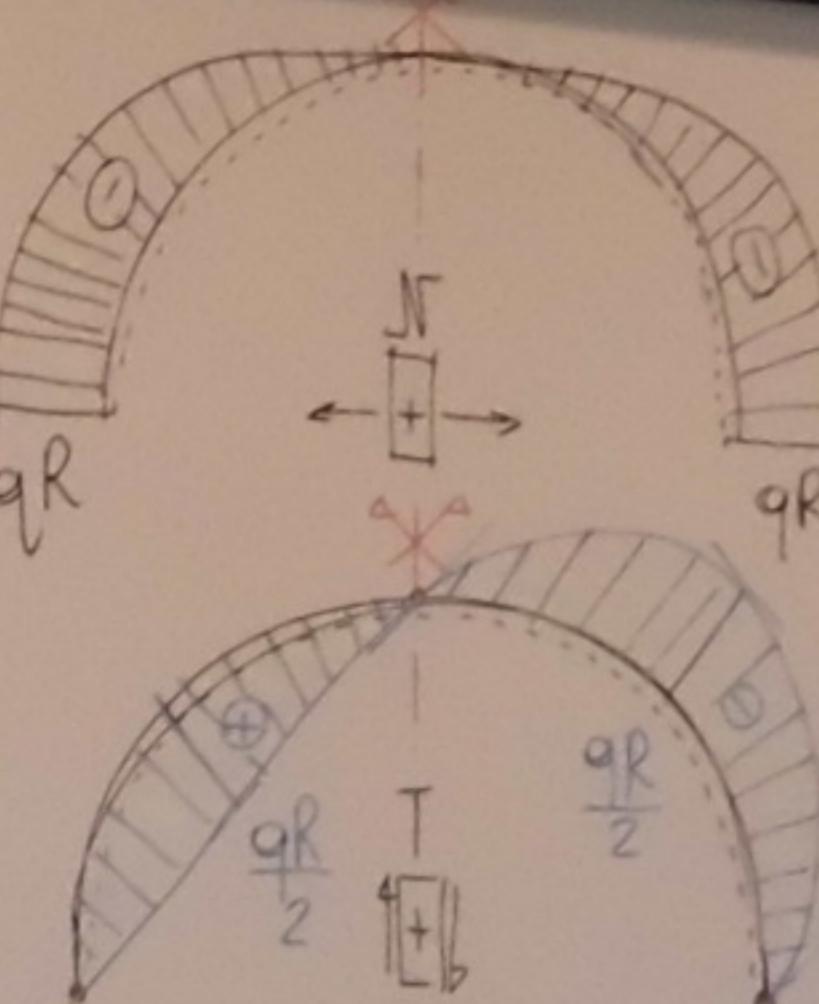
Mise $\vartheta = \pi/2$

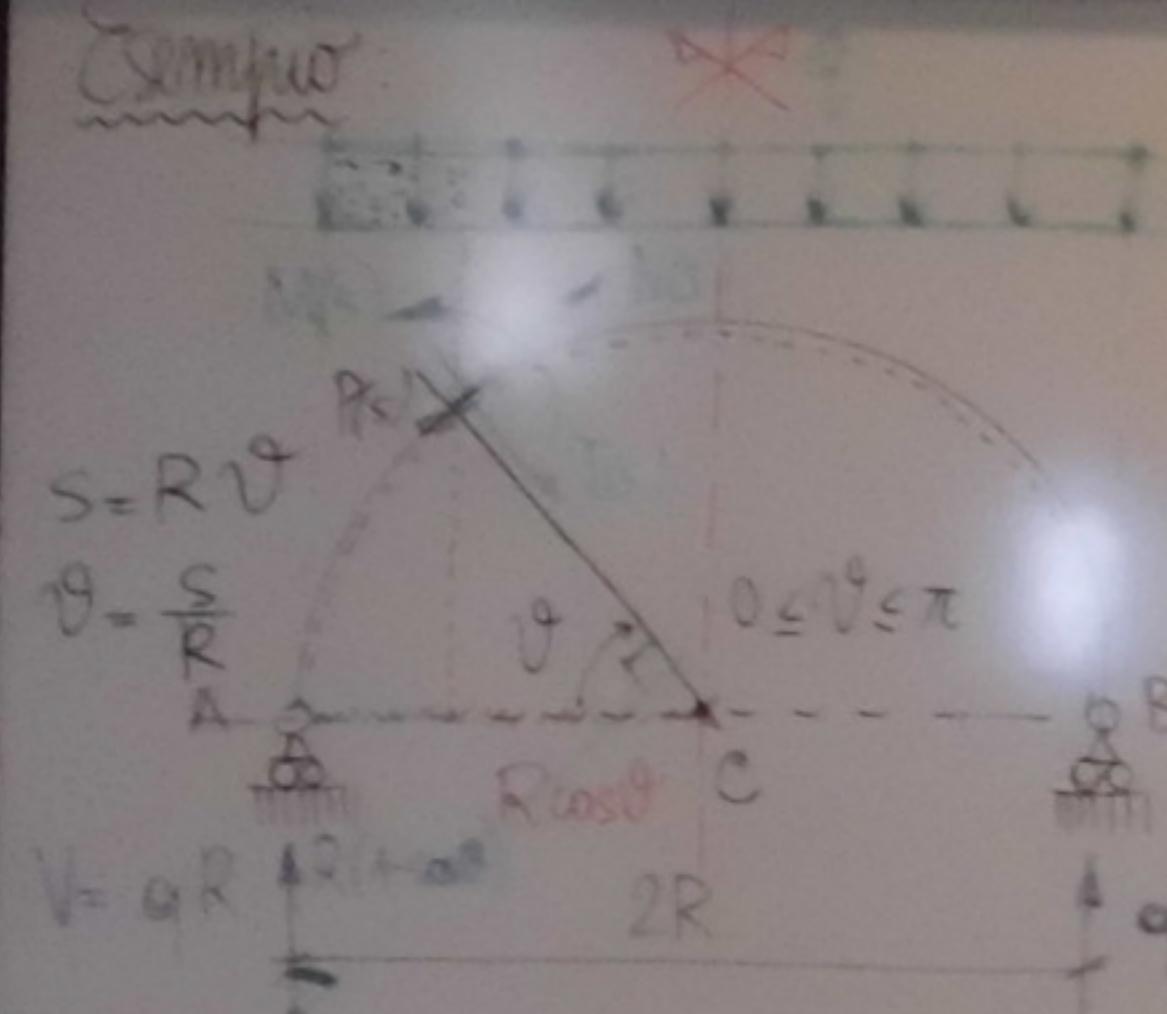
sim.

antism



The figure consists of two parts. The top part is a graph of a function $T(\theta)$ versus θ . The y-axis has labels -1 , 0 , and 1 . The x-axis has labels $\pi/2$ and π . A curve starts at $(0, 1)$, reaches a maximum value of 1 at $\theta = \pi/4$, crosses the θ -axis at $\theta = \pi/2$, reaches a minimum value of -1 at $\theta = 3\pi/4$, and returns to 0 at $\theta = \pi$. The region between the curve and the θ -axis from $\theta = 0$ to $\theta = \pi$ is shaded. Two dashed lines, labeled $\cos \theta$ and $\cos^2 \theta$, are shown above the curve. The bottom part is a graph of $T(\theta)$ versus θ for $\theta \in [0, \pi]$. The y-axis has labels 1 , 0 , and -1 . The x-axis has labels $\pi/4$, $\pi/2$, and π . A triangle is drawn with vertices at $(\pi/4, 1)$, $(\pi/2, 0)$, and $(\pi, -1)$. The angle at the vertex $(\pi/2, 0)$ is labeled $\sin \theta$.





$$\text{Diagram: } \theta = \frac{\pi}{2}$$

$$N(\theta) = qR \cos\theta$$

$$T(\theta) = qR \sin\theta$$

$$M(\theta) = qR^2 \sin\theta$$

$$V = qR \sqrt{2} \sin\theta$$

Aufgabe:

$$N(\theta) = -qR + qR(\cos\theta) \cos\theta = -qR \cos^2\theta$$

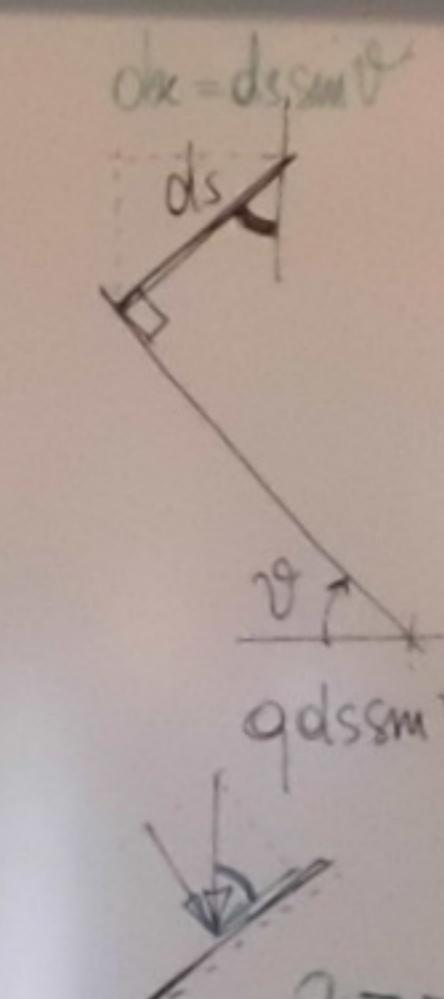
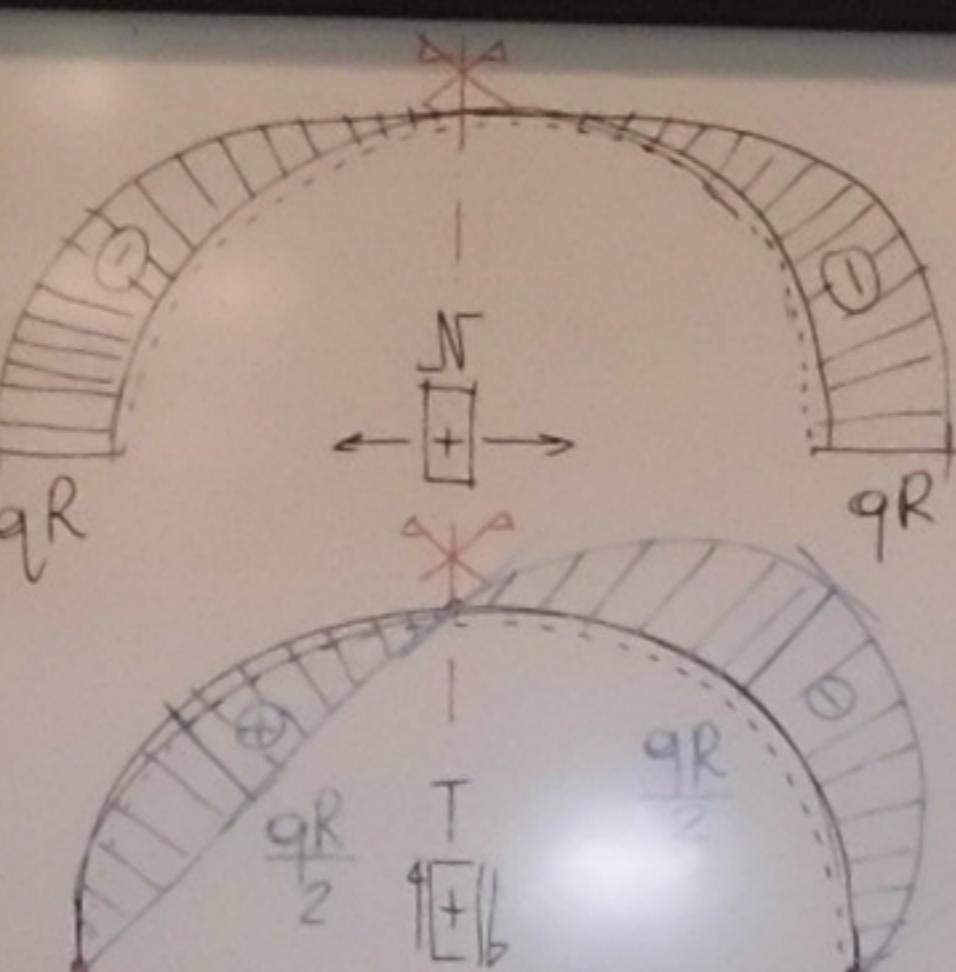
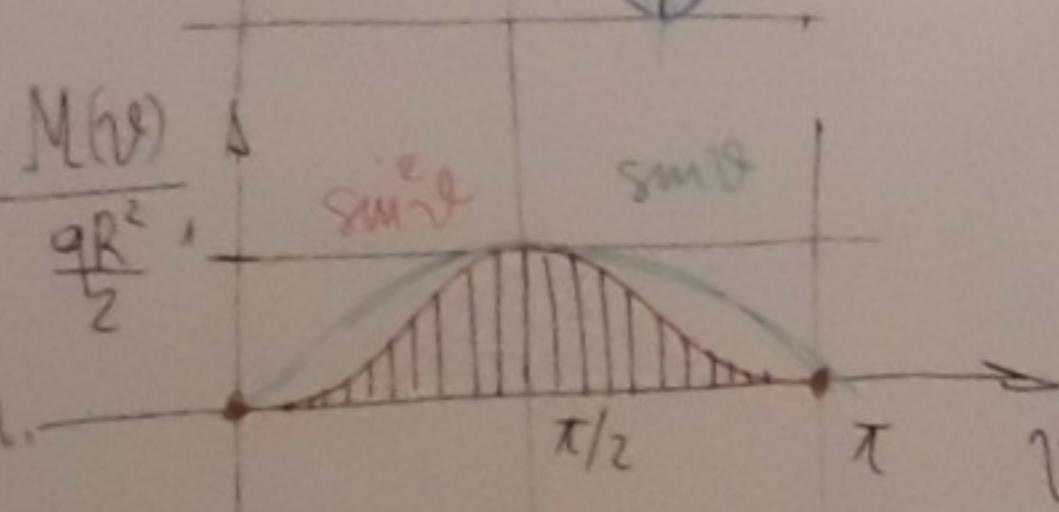
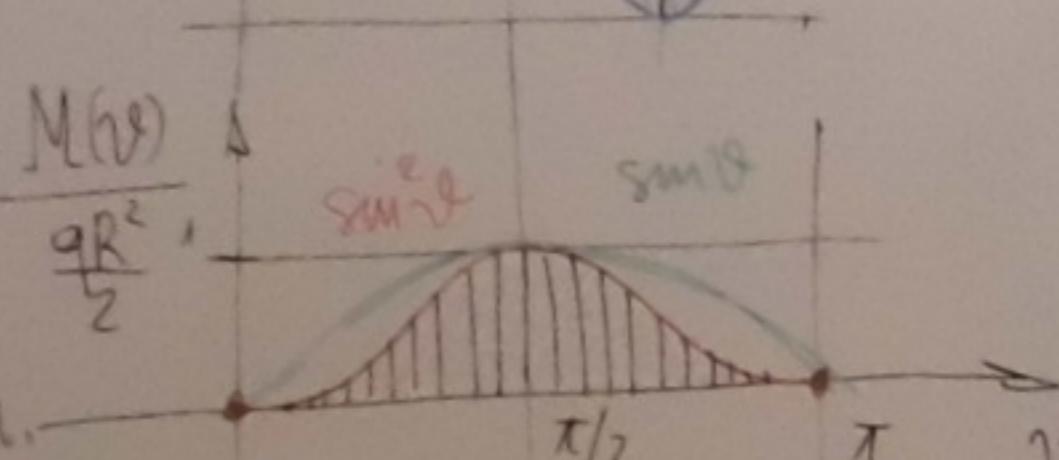
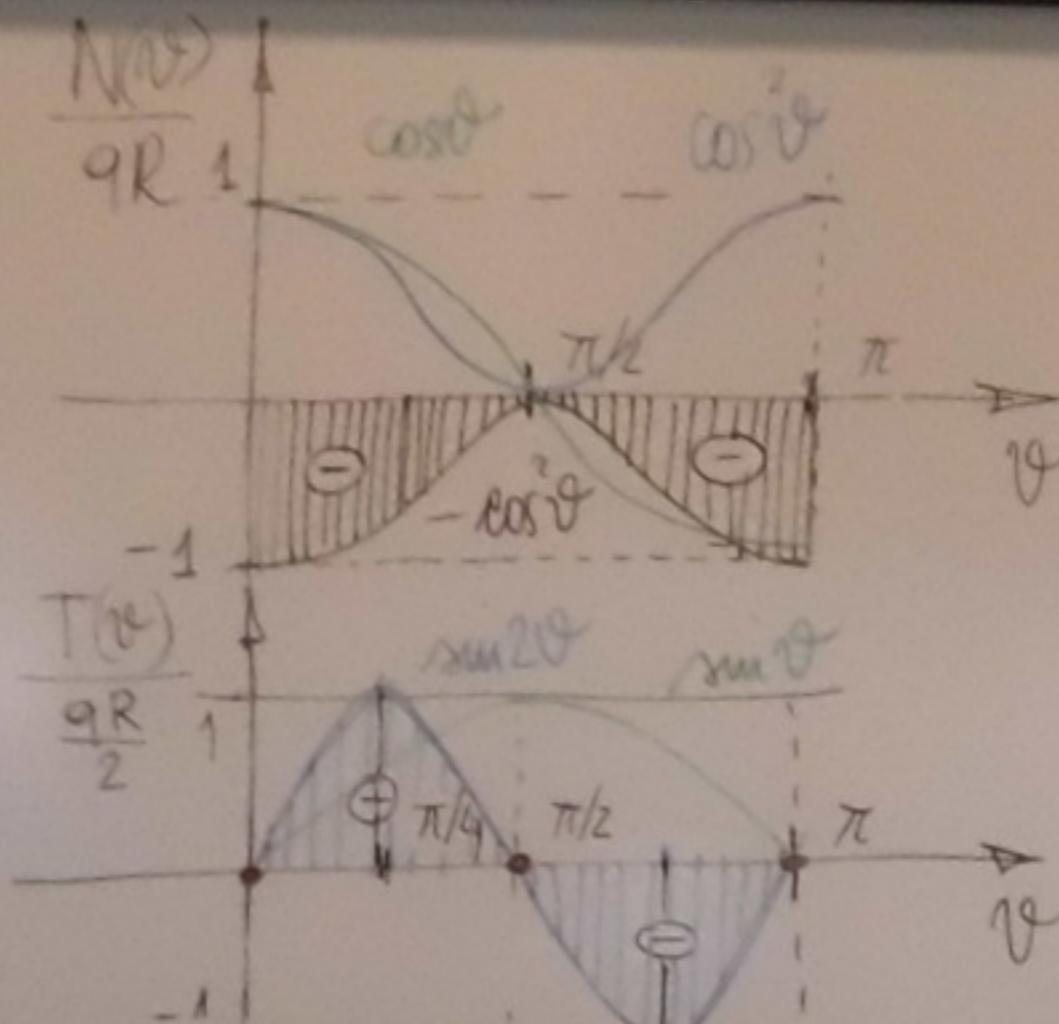
$$T(\theta) = (qR - qR(\cos\theta)) \sin\theta = qR \sin\theta \cos\theta$$

$$M(\theta) = qR R(\cos\theta) - qR(\cos\theta) R(\cos\theta)$$

$$= qR^2 \cos\theta \left(1 - \frac{1 + \cos\theta}{2}\right)^2 = \frac{qR^2}{2} (1 - \cos^2\theta) = \frac{qR^2}{2} \sin^2\theta \rightarrow M(\theta) = \frac{qR^2}{2} \sin^2\theta \cos\theta = \frac{qR^2}{2} \sin^2\theta \cos\theta = R T(\theta)$$

Ansatz:

antizym



$$N(\theta) = -qR 2 \cos\theta (-\sin\theta)$$

$$= qR \sin 2\theta$$

$$= \frac{q}{2} \sin 2\theta R + qR \sin 2\theta$$

$$T(\theta) = \frac{qR}{2} \cos 2\theta \cdot 2$$

$$= qR (\cos^2\theta - \sin^2\theta)$$

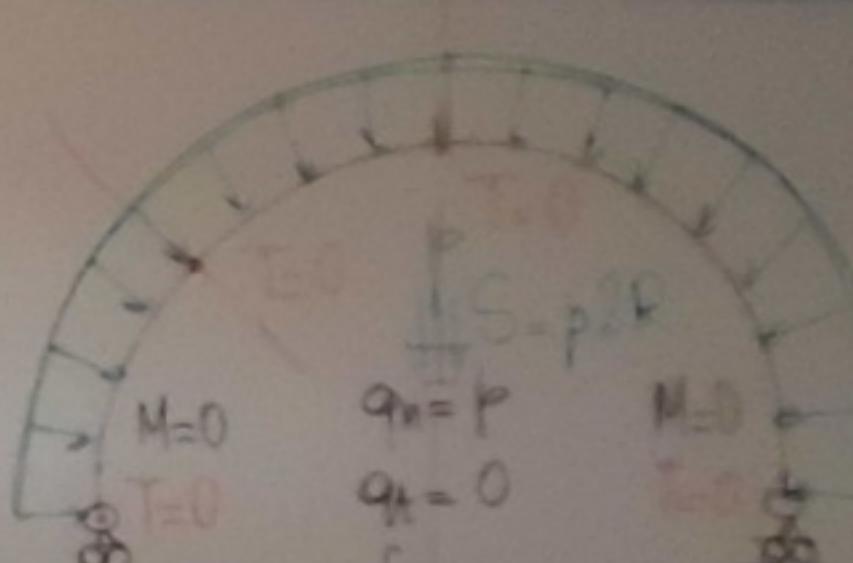
$$= -qR \sin^2\theta + qR \cos^2\theta$$

$$q_t = -\frac{qdssm\theta \cos\theta}{ds}$$

$$= -\frac{q}{2} \sin 2\theta$$

$$q_n = \frac{qdssm\theta \sin\theta}{ds}$$

$$= q \sin^2\theta$$



$$M=0 \quad q_n=P \quad M=0 \quad T=0 \quad q_t=0 \quad T=0$$

$$M=0 \quad q_n=P \quad M=0 \quad T=0 \quad q_t=0 \quad T=0$$

$$N(s) = -q(s) \rightarrow T(s) = -\frac{1}{R} \frac{dN}{ds}$$

$$T(s) = -q(s) - N(s) = -\frac{1}{R} \frac{dT}{ds}$$

$$M(s) = -m(s) + T(s) = \frac{1}{R} \frac{dm}{ds}$$

$$N'(s) = -q(R) + T(s) \rightarrow$$

$$T'(s) = -q_n(s) - N(s) \rightarrow$$

$$M'(s) = -m(s) + T(s) \rightarrow$$

$$N''(s) = -q(R) + T(s) \rightarrow$$

$$T''(s) = -q_n(s) - N(s) \rightarrow$$

$$M''(s) = -m(s) + T(s) \rightarrow$$

