

Homework 6

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Problem 1

(a) Symmetrizing under $\epsilon_1 \leftrightarrow \epsilon_2$ and $\epsilon_4 \leftrightarrow \epsilon_3$, we get

$$\mathcal{M} \rightarrow a (\vec{\epsilon}_1 \cdot \vec{\epsilon}_2) (\vec{\epsilon}_3^* \cdot \vec{\epsilon}_4^*) + \frac{b+c}{2} [(\vec{\epsilon}_1 \cdot \vec{\epsilon}_3^*) (\vec{\epsilon}_2 \cdot \vec{\epsilon}_4^*) + (\vec{\epsilon}_1 \cdot \vec{\epsilon}_4^*) (\vec{\epsilon}_2 \cdot \vec{\epsilon}_3^*)],$$

which implies $b = c$, and we get two independent terms

$$\begin{aligned}\mathcal{M}_0 &\propto (\vec{\epsilon}_1 \cdot \vec{\epsilon}_2) (\vec{\epsilon}_3^* \cdot \vec{\epsilon}_4^*) \\ \mathcal{M}_> &\propto (\vec{\epsilon}_1 \cdot \vec{\epsilon}_3^*) (\vec{\epsilon}_2 \cdot \vec{\epsilon}_4^*) + (\vec{\epsilon}_1 \cdot \vec{\epsilon}_4^*) (\vec{\epsilon}_2 \cdot \vec{\epsilon}_3^*).\end{aligned}$$

(b) In the center of mass frame, the momenta are

$$\begin{aligned}p_1 &= \frac{m_h}{2}(1, 0, 0, 1) & p_3 &= \frac{m_h}{2}(1, \sin \theta, 0, \cos \theta) \\ p_2 &= \frac{m_h}{2}(1, 0, 0, -1) & p_4 &= \frac{m_h}{2}(1, -\sin \theta, 0, -\cos \theta)\end{aligned}$$

For spin-0 Higgs, by conservation of angular momentum the particles in the in state must have equal helicities (and similarly for the out state), while a spin-2 Higgs places no such restriction. For the matrix element $\mathcal{M}(g_+ g_+ \rightarrow h \rightarrow \gamma_+ \gamma_+)$, where the gluons and photons all have helicity +1, we have

$$\begin{aligned}\vec{\epsilon}_1 &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix}, & \vec{\epsilon}_3 &= \frac{1}{\sqrt{2}} \begin{pmatrix} \cos \theta \\ i \\ -\sin \theta \end{pmatrix}, \\ \vec{\epsilon}_2 &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \\ 0 \end{pmatrix}, & \vec{\epsilon}_4 &= \frac{1}{\sqrt{2}} \begin{pmatrix} -\cos \theta \\ i \\ \sin \theta \end{pmatrix}.\end{aligned}$$

The relevant dot products are then

$$\begin{aligned}\vec{\epsilon}_1 \cdot \vec{\epsilon}_2 &= 1 \\ \vec{\epsilon}_3^* \cdot \vec{\epsilon}_4^* &= -1 \\ \vec{\epsilon}_1 \cdot \vec{\epsilon}_3^* &= -\vec{\epsilon}_2 \cdot \vec{\epsilon}_4^* = \frac{1}{2}(\cos \theta + 1) \\ \vec{\epsilon}_2 \cdot \vec{\epsilon}_3^* &= -\vec{\epsilon}_1 \cdot \vec{\epsilon}_4^* = \frac{1}{2}(\cos \theta - 1)\end{aligned}$$

Clearly, the first independent matrix element, \mathcal{M}_0 , does not depend on θ , as is appropriate for a spin-0 Higgs. Meanwhile, in this spin configuration, the second term is θ -dependent but non-vanishing.

$$\mathcal{M}_> \propto (\cos \theta + 1)^2 + (\cos \theta - 1)^2 > 0$$

This is consistent with a spin-2 Higgs with 0 z -component spin projection (i.e. $j = 2$, $m = 0$) For the matrix element $\mathcal{M}(g_+g_- \rightarrow h \rightarrow \gamma_+\gamma_-)$, the polarization vectors are given by

$$\begin{aligned}\vec{\epsilon}_1 = \vec{\epsilon}_2 &= \begin{pmatrix} 1 \\ i \\ 0 \end{pmatrix}, \\ \vec{\epsilon}_3 = \vec{\epsilon}_4 &= \begin{pmatrix} \cos \theta \\ i \\ -\sin \theta \end{pmatrix}.\end{aligned}$$

Clearly, the spin-0 component vanishes (both dot products are zero), while

$$M_> \propto \sin^2 \theta,$$

so the photons can't come out in the exact same orientation as the gluons came in.

(c) If we have a levi-civita fully contracted with the polarizations,

$$\epsilon_{\mu\nu\rho\sigma}\epsilon_1^\mu\epsilon_2^\nu\epsilon_3^\rho\epsilon_4^\sigma,$$

symmetrization with respect to any two indices will vanish (due to the antisymmetry of the levi-civita), but we need to symmetrize w.r.t $1 \leftrightarrow 2$ and $3 \leftrightarrow 4$.

Problem 2

(a)

$$\begin{aligned}V &= m_1^2|H_1|^2 + m_2^2|H_2|^2 - b(H_1^\dagger H_2 + H_2^\dagger H_1) + \frac{g^2 + g'^2}{8} \left(|H_1|^2 - |H_2|^2 \right)^2 + \frac{g^2}{2} (H_2^\dagger \epsilon H_1) (H_2^\dagger \epsilon H_1^*) \\ &= m_1^2 \left(|H_1^+|^2 + |H_1^-|^2 \right) + m_2^2 \left(|H_2^+|^2 + |H_2^-|^2 \right) - 2b \operatorname{Re}[H_1^{+*} H_2^+ + H_1^{-*} H_2^-] \\ &\quad + \frac{g^2 + g'^2}{8} \left(|H_1^+|^2 + |H_1^-|^2 - |H_2^+|^2 - |H_2^-|^2 \right)^2 + \frac{g^2}{2} |H_1^+ H_2^- - H_1^- H_2^+|^2\end{aligned}$$

Given that

$$\frac{\partial V}{\partial H_1^+} \Big|_{H_1=\langle H_1 \rangle, H_2=\langle H_2 \rangle} = -\frac{y^*}{4} \left(4b + \sqrt{2}g^2 v z \right),$$

we can see that $y = 0$ gives a minimum of the potential.

(b)

$$V|_{H_1^+ \rightarrow 0, H_2^+ \rightarrow 0, H_1^- \rightarrow v/\sqrt{2}} =$$

For any complex value of H_2^- , keeping the magnitude fixed while rotating the number towards the positive real axis will decrease the value of the potential. Therefore, at the minimum of the potential H_2^- must lie on the positive real axis.

(c)

$$\begin{aligned} V = & m_1^2 \left(|H_1^+|^2 + \frac{1}{2} |v_1 + h_1 + iA_1|^2 \right) + m_2^2 \left(|H_2^+|^2 + \frac{1}{2} |v_2 + h_2 + iA_2|^2 \right) \\ & - 2b \operatorname{Re}[H_1^{+*} H_2^+] - b [(v_1 + h_1)(v_2 + h_2) + A_1 A_2] \\ & + \frac{g^2 + g'^2}{8} \left(|H_1^+|^2 + |v_1 + h_1 + iA_1|^2 - |H_2^+|^2 - |v_2 + h_2 + iA_2|^2 \right)^2 \\ & + \frac{g^2}{4} |H_1^+ (v_2 + h_2 + iA_2) - (v_1 + h_1 + iA_1) H_2^+|^2 \end{aligned}$$

$$\begin{aligned} \frac{\partial V}{\partial h_1} \Big|_{H_1 \rightarrow \langle H_1 \rangle, H_2 \rightarrow \langle H_2 \rangle} &= v_1 m_1^2 - b v_2 + \frac{1}{8} (g^2 + g'^2) v_1 (v_1^2 - v_2^2) = 0 \\ \implies m_1^2 &= b \frac{v_1}{v_2} - \frac{1}{8} (g^2 + g'^2) (v_1^2 - v_2^2) \end{aligned}$$

$$\begin{aligned} \frac{\partial V}{\partial h_2} \Big|_{H_1 \rightarrow \langle H_1 \rangle, H_2 \rightarrow \langle H_2 \rangle} &= v_2 m_2^2 - b v_1 + \frac{1}{8} (g^2 + g'^2) v_2 (v_2^2 - v_1^2) = 0 \\ \implies m_2^2 &= b \frac{v_2}{v_1} - \frac{1}{8} (g^2 + g'^2) (v_2^2 - v_1^2) \end{aligned}$$

(d) See Mathematica printout

(e) See Mathematica printout

(f) See Mathematica printout

```
In[19]:= H1 = {α, β}^T;  
H2 = {γ, δ}^T;  
ε = {{0, 1}, {-1, 0}};  
V = m1^2 H1^†.H1 + m2^2 H2^†.H2 - b (H1^†.H2 + H2^†.H1) +  
       $\frac{g_1^2 + g_2^2}{8} (H1^†.H1 - H2^†.H2)^2 + \frac{g_1^2}{2} (H2^†.ε.H1) (H2^†.ε.H1^*)$ ;  
V // TraditionalForm
```

```
Out[23]//TraditionalForm=
```

$$-b(\gamma \alpha^* + \alpha \gamma^* + \delta \beta^* + \beta \delta^*) + \frac{1}{8}(g_1^2 + g_2^2)(\alpha \alpha^* + \beta \beta^* - \gamma \gamma^* - \delta \delta^*)^2 +$$

$$\frac{1}{2}g_1^2(\beta \gamma - \alpha \delta)(\beta^* \gamma^* - \alpha^* \delta^*) + m_1^2(\alpha \alpha^* + \beta \beta^*) + m_2^2(\gamma \gamma^* + \delta \delta^*)$$

a)

```
In[24]:= sub = {α → 0, β →  $\frac{v}{\sqrt{2}}$ , γ → y, δ → z};
```

```
In[25]:= (D[V /. α* → a, α] /. a → α*) /. sub // FullSimplify // TraditionalForm
```

```
Out[25]//TraditionalForm=
```

$$-\frac{1}{4}y^*(4b + \sqrt{2}g_1^2 v z)$$

b)

```
In[26]:= (V /. sub) /. y → 0 // FullSimplify // TraditionalForm
```

```
Out[26]//TraditionalForm=
```

$$-\sqrt{2}b v \operatorname{Re}(z) + \frac{1}{32}(g_1^2 + g_2^2)(v^2 - 2z z^*)^2 + m_2^2 z z^* + \frac{1}{2}m_1^2 v^2$$

c)

```
In[27]:= sub2 = {β →  $\frac{v_1 + h_1 + \text{i} A_1}{\sqrt{2}}$ , δ →  $\frac{v_2 + h_2 + \text{i} A_2}{\sqrt{2}}$ };
```

```
In[28]:= (V /. sub2) // TraditionalForm
```

```
Out[28]//TraditionalForm=
```

$$\begin{aligned}
 & -b \left(\frac{1}{2} (i A_1 + h_1 + v_1) ((h_2 + v_2)^* - i (A_2)^*) + \frac{1}{2} (i A_2 + h_2 + v_2) ((h_1 + v_1)^* - i (A_1)^*) + \gamma \alpha^* + \alpha \gamma^* \right) + \\
 & \frac{1}{2} g_1^2 \left(\frac{\gamma (i A_1 + h_1 + v_1)}{\sqrt{2}} - \frac{\alpha (i A_2 + h_2 + v_2)}{\sqrt{2}} \right) \left(\frac{\gamma^* ((h_1 + v_1)^* - i (A_1)^*)}{\sqrt{2}} - \frac{\alpha^* ((h_2 + v_2)^* - i (A_2)^*)}{\sqrt{2}} \right) + \\
 & \frac{1}{8} (g_1^2 + g_2^2) \left(\frac{1}{2} (i A_1 + h_1 + v_1) ((h_1 + v_1)^* - i (A_1)^*) - \frac{1}{2} (i A_2 + h_2 + v_2) ((h_2 + v_2)^* - i (A_2)^*) + \alpha \alpha^* - \gamma \gamma^* \right)^2 + \\
 & m_1^2 \left(\alpha \alpha^* + \frac{1}{2} (i A_1 + h_1 + v_1) ((h_1 + v_1)^* - i (A_1)^*) \right) + m_2^2 \left(\gamma \gamma^* + \frac{1}{2} (i A_2 + h_2 + v_2) ((h_2 + v_2)^* - i (A_2)^*) \right)
 \end{aligned}$$

```
In[29]:= eq1 = D[(V // FullSimplify) /. sub2, h1] /.
```

```
{α → 0, γ → 0, A1 → 0, h1 → 0, A2 → 0, h2 → 0, m1 → √M1} // FullSimplify
```

```
eq2 = D[(V // FullSimplify) /. sub2 // FullSimplify, h2] /.
```

```
{α → 0, γ → 0, A1 → 0, h1 → 0, A2 → 0, h2 → 0, m2 → √M2} // FullSimplify
```

```
Out[29]=
```

$$M_1 v_1 - \frac{1}{2} b (1 + v_1) v_2 + \frac{1}{8} (g_1^2 + g_2^2) v_1 (v_1^2 - v_2^2)$$

```
Out[30]=
```

$$-b v_1 + M_2 v_2 + \frac{1}{8} (g_1^2 + g_2^2) v_2 (-v_1^2 + v_2^2)$$

```
In[31]:= Solve[{eq1 == 0}, {M1}] // Quiet // FullSimplify
```

```
Solve[eq2 == 0, M2] // Quiet // FullSimplify
```

```
Out[31]=
```

$$\left\{ \left\{ M_1 \rightarrow \frac{1}{8} \left(4 b v_2 + \frac{4 b v_2}{v_1} + (g_1^2 + g_2^2) (-v_1^2 + v_2^2) \right) \text{ if } v_1 \neq 0 \right\} \right\}$$

```
Out[32]=
```

$$\left\{ \left\{ M_2 \rightarrow \frac{1}{8} (g_1^2 + g_2^2) v_1^2 + \frac{b v_1}{v_2} - \frac{1}{8} (g_1^2 + g_2^2) v_2^2 \text{ if } v_2 \neq 0 \right\} \right\}$$

d)

```

In[33]:= V2 = V /. sub2;
V2 // TraditionalForm
MM =
  {{D[D[V2, α]*, α]*, D[D[V2, α]*, γ]*}, {D[D[V2, γ]*, α]*, D[D[V2, γ]*, γ]*}} /.
  {α → 0, γ → 0, h1 → 0, h2 → 0, A1 → 0, A2 → 0} // FullSimplify;
MM // MatrixForm

```

Out[34]//TraditionalForm=

$$\begin{aligned}
& -b \left(\frac{1}{2} (i A_1 + h_1 + v_1) ((h_2 + v_2)^* - i (A_2)^*) + \frac{1}{2} (i A_2 + h_2 + v_2) ((h_1 + v_1)^* - i (A_1)^*) + \gamma \alpha^* + \alpha \gamma^* \right) + \\
& \frac{1}{2} g_1^2 \left(\frac{\gamma (i A_1 + h_1 + v_1)}{\sqrt{2}} - \frac{\alpha (i A_2 + h_2 + v_2)}{\sqrt{2}} \right) \left(\frac{\gamma^* ((h_1 + v_1)^* - i (A_1)^*)}{\sqrt{2}} - \frac{\alpha^* ((h_2 + v_2)^* - i (A_2)^*)}{\sqrt{2}} \right) + \\
& \frac{1}{8} (g_1^2 + g_2^2) \left(\frac{1}{2} (i A_1 + h_1 + v_1) ((h_1 + v_1)^* - i (A_1)^*) - \frac{1}{2} (i A_2 + h_2 + v_2) ((h_2 + v_2)^* - i (A_2)^*) + \alpha \alpha^* - \gamma \gamma^* \right)^2 + \\
& m_1^2 \left(\alpha \alpha^* + \frac{1}{2} (i A_1 + h_1 + v_1) ((h_1 + v_1)^* - i (A_1)^*) \right) + m_2^2 \left(\gamma \gamma^* + \frac{1}{2} (i A_2 + h_2 + v_2) ((h_2 + v_2)^* - i (A_2)^*) \right)
\end{aligned}$$

Out[36]//MatrixForm=

$$\begin{pmatrix} m_1^2 + \frac{1}{8} (g_2^2 (v_1^2 - v_2^2) + g_1^2 (v_1^2 + v_2^2)) & -b - \frac{1}{4} g_1^2 v_1 v_2 \\ -b - \frac{1}{4} g_1^2 v_1 v_2 & m_2^2 + \frac{1}{8} (g_2^2 (-v_1^2 + v_2^2) + g_1^2 (v_1^2 + v_2^2)) \end{pmatrix}$$

```

In[37]:= Eigenvalues[MM] // FullSimplify // FullSimplify

```

Out[37]=

$$\begin{aligned}
& \left\{ \frac{1}{8} \left(4 m_1^2 + 4 m_2^2 + g_1^2 (v_1^2 + v_2^2) - \sqrt{64 b^2 + (4 m_1^2 - 4 m_2^2 + g_2^2 v_1^2)^2 + 32 b g_1^2 v_1 v_2 - 2 (4 g_2^2 (m_1^2 - m_2^2) + (-2 g_1^4 + g_2^4) v_1^2) v_2^2 + g_2^4 v_2^4} \right), \right. \\
& \left. \frac{1}{8} \left(4 m_1^2 + 4 m_2^2 + g_1^2 (v_1^2 + v_2^2) + \sqrt{64 b^2 + (4 m_1^2 - 4 m_2^2 + g_2^2 v_1^2)^2 + 32 b g_1^2 v_1 v_2 - 2 (4 g_2^2 (m_1^2 - m_2^2) + (-2 g_1^4 + g_2^4) v_1^2) v_2^2 + g_2^4 v_2^4} \right) \right\}
\end{aligned}$$

e)

```

In[38]:= V2 = FullSimplify[V2];
V2 // TraditionalForm

```

Out[39]//TraditionalForm=

$$\begin{aligned}
& \frac{1}{32} \left(-32 b (A_1 A_2 + \gamma \alpha^* + \alpha \gamma^* + (h_1 + v_1) (h_2 + v_2)) + \right. \\
& 8 g_1^2 (-\alpha A_2 + A_1 \gamma + i (\alpha (h_2 + v_2) - \gamma (h_1 + v_1))) (\gamma^* (A_1 + i (h_1 + v_1)) - \alpha^* (A_2 + i (h_2 + v_2))) + \\
& (g_1^2 + g_2^2) (A_1^2 - A_2^2 + 2 \alpha \alpha^* - 2 \gamma \gamma^* + (h_1 - h_2 + v_1 - v_2) (h_1 + h_2 + v_1 + v_2))^2 + \\
& \left. 16 m_1^2 (A_1^2 + 2 \alpha \alpha^* + (h_1 + v_1)^2) + 16 m_2^2 (A_2^2 + 2 \gamma \gamma^* + (h_2 + v_2)^2) \right)
\end{aligned}$$

```
In[40]:= MM2 = {{D[V2, A1, A1], D[V2, A1, A2]}, {D[V2, A2, A1], D[V2, A2, A2]}} /.
  {α → 0, γ → 0, h1 → 0, h2 → 0, A1 → 0, A2 → 0} // FullSimplify;
MM2 // MatrixForm
```

```
Out[41]//MatrixForm=
```

$$\begin{pmatrix} m_1^2 + \frac{1}{8} (g_1^2 + g_2^2) (v_1^2 - v_2^2) & -b \\ -b & m_2^2 - \frac{1}{8} (g_1^2 + g_2^2) (v_1^2 - v_2^2) \end{pmatrix}$$

```
In[42]:= Eigenvalues[MM2] // FullSimplify
```

```
Out[42]=
```

$$\left\{ \frac{1}{8} \left(4 m_1^2 + 4 m_2^2 - \sqrt{64 b^2 + (4 m_1^2 - 4 m_2^2 + (g_1^2 + g_2^2) (v_1^2 - v_2^2))^2} \right), \right. \\ \left. \frac{1}{8} \left(4 m_1^2 + 4 m_2^2 + \sqrt{64 b^2 + (4 m_1^2 - 4 m_2^2 + (g_1^2 + g_2^2) (v_1^2 - v_2^2))^2} \right) \right\}$$

f)

```
In[43]:= MM3 = {{D[V2, h1, h1], D[V2, h1, h2]}, {D[V2, h2, h1], D[V2, h2, h2]}} /.
  {α → 0, γ → 0, h1 → 0, h2 → 0, A1 → 0, A2 → 0} // FullSimplify;
MM3 // MatrixForm
```

```
Out[44]//MatrixForm=
```

$$\begin{pmatrix} m_1^2 + \frac{1}{8} (g_1^2 + g_2^2) (3 v_1^2 - v_2^2) & -b - \frac{1}{4} (g_1^2 + g_2^2) v_1 v_2 \\ -b - \frac{1}{4} (g_1^2 + g_2^2) v_1 v_2 & m_2^2 - \frac{1}{8} (g_1^2 + g_2^2) (v_1^2 - 3 v_2^2) \end{pmatrix}$$

```
In[45]:= Eigenvalues[MM3] // FullSimplify
```

```
Out[45]=
```

$$\left\{ \frac{1}{8} \left(4 m_1^2 + 4 m_2^2 + (g_1^2 + g_2^2) (v_1^2 + v_2^2) - 2 \sqrt{(16 b^2 + (2 m_1^2 - 2 m_2^2 + (g_1^2 + g_2^2) v_1^2)^2 +} \right. \right. \\ \left. \left. 8 b (g_1^2 + g_2^2) v_1 v_2 - (g_1^2 + g_2^2) (4 m_1^2 - 4 m_2^2 + (g_1^2 + g_2^2) v_1^2) v_2^2 + (g_1^2 + g_2^2)^2 v_2^4} \right), \right. \\ \left. \frac{1}{8} \left(4 m_1^2 + 4 m_2^2 + (g_1^2 + g_2^2) (v_1^2 + v_2^2) + 2 \sqrt{(16 b^2 + (2 m_1^2 - 2 m_2^2 + (g_1^2 + g_2^2) v_1^2)^2 +} \right. \right. \\ \left. \left. 8 b (g_1^2 + g_2^2) v_1 v_2 - (g_1^2 + g_2^2) (4 m_1^2 - 4 m_2^2 + (g_1^2 + g_2^2) v_1^2) v_2^2 + (g_1^2 + g_2^2)^2 v_2^4} \right) \right\}$$