

```

In[10]:= Symbolize[ $\delta_\theta$ ]; Symbolize[ $\Omega_\theta$ ]; Symbolize[ $T_\theta$ ]; Symbolize[ $H_I$ ];
Symbolize[ $\psi_I$ ]; Symbolize[ $c_1$ ]; Symbolize[ $c_2$ ];
Symbolize[ $s_\theta$ ]; Symbolize[ $c_\theta$ ]; Symbolize[ $\omega_1$ ]; Symbolize[ $\omega_2$ ];
$Assumptions = {T > 0, t ∈ ℝ,  $\omega_1$  > 0,  $\omega_2$  > 0,  $\omega$  > 0};

```

## Problem 1

```

In[ ]:=  $\Omega_\theta[t_] = A e^{-\left(\frac{t}{T}\right)^2}$ ;
R[t_] =  $\sqrt{\delta^2 + (\Omega_\theta[t])^2}$  // FullSimplify;

```

```

In[ ]:= Integrate[ $\Omega_\theta[t]$ , {t, -∞, t}]

```

```

Out[ ]:=  $\frac{1}{2} A \sqrt{\pi} T \left(1 + \operatorname{Erf}\left[\frac{t}{T}\right]\right)$ 

```

## Problem 2

```

In[ ]:=  $\delta[t_] = \delta_\theta \left(1 - e^{\frac{t}{T}}\right)^3 \operatorname{HeavisideTheta}[-t]$ ;

```

```

 $H_I[t_] = \frac{1}{2} \left\{ \{0, \Omega_\theta[t] e^{-\frac{1}{2} \delta[t]}\}, \{\Omega_\theta[t] e^{\frac{1}{2} \delta[t]}, 0\} \right\}$ ;

```

```

 $\psi_I[t_] = \{\{c_1[t]\}, \{c_2[t]\}\}$ ;

```

```

 $T_\theta = 3$ ;

```

```

 $T = 1$ ;

```

```

 $\delta_\theta = 30$ ;

```

```

 $A = 30$ ;

```

```

soln1 =

```

```

NDSolve[{ $\frac{d}{dt} \psi_I[t]$ , t} ==  $H_I[t] \cdot \psi_I[t]$ ,  $\psi_I[-T_\theta] == \{\{1\}, \{0\}\}$ ,  $c_1$ , {t, - $T_\theta$ ,  $T_\theta$ }}];

```

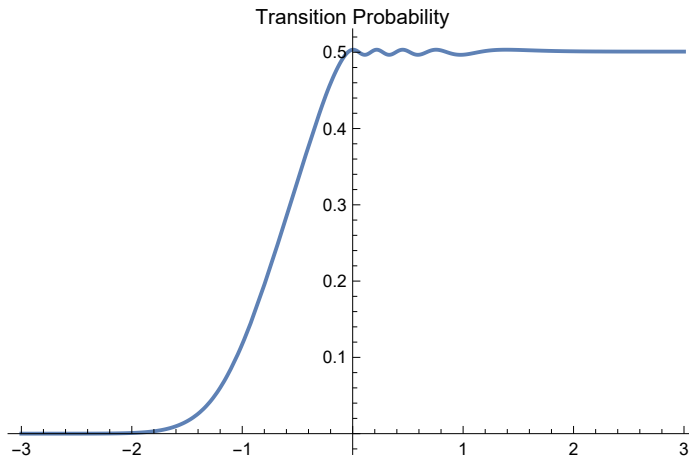
```

soln2 = NDSolve[{ $\frac{d}{dt} \psi_I[t]$ , t} ==  $H_I[t] \cdot \psi_I[t]$ ,  $\psi_I[-T_\theta] == \{\{1\}, \{0\}\}$ ,  $c_2$ , {t, - $T_\theta$ ,  $T_\theta$ }}];

```

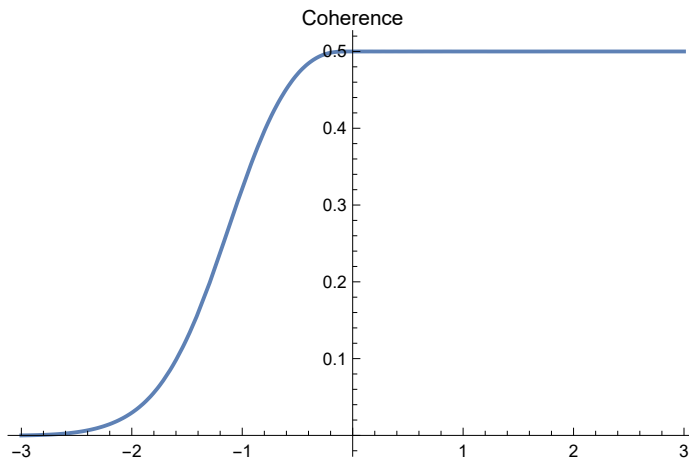
```
In[8]:= Plot[Evaluate[Abs[c2[x]]2 /. soln2], {x, -T0, T0},
  PlotRange → All, PlotLabel → "Transition Probability"]
```

```
Out[8]=
```



```
In[9]:= Plot[Evaluate[Evaluate[Abs[c1[x] Conjugate[c2[x]]] /. soln1] /. soln2],
  {x, -T0, T0}, PlotRange → All, PlotLabel → "Coherence"]
```

```
Out[9]=
```



## Problem 3

```
In[5]:= U = {{e-i ω1 t, 0}, {0, e-i ω2 t}};
  V = {{0, Omega Cos[ω t]}, {Omega Cos[ω t], 0}};
```

```
In[7]:= U†.V.U // FullSimplify // MatrixForm
```

```
Out[7]//MatrixForm=
```

$$\begin{pmatrix} 0 & e^{i t (\omega_1 - \omega_2)} \text{Omega Cos}[t \omega] \\ e^{i t (-\omega_1 + \omega_2)} \text{Omega Cos}[t \omega] & 0 \end{pmatrix}$$

```
In[16]:= U = {{e^{-i \omega t/2}, 0}, {0, e^{i \omega t/2}}};
          U†.V.U // FullSimplify // MatrixForm

Out[17]//MatrixForm=

$$\begin{pmatrix} 0 & e^{i t \omega} \Omega \cos[t \omega] \\ e^{-i t \omega} \Omega \cos[t \omega] & 0 \end{pmatrix}$$

```

## Problem 4

```
In[*]:= R = \sqrt{\delta^2 + \Omega^2};
          \frac{-2 \frac{\Omega_0}{R+\delta}}{\left(\frac{\Omega_0}{R+\delta}\right)^2 - 1} // FullSimplify

Out[*]=

$$\frac{\Omega_0}{\delta}$$

```

## Problem 5

```
In[*]:= "\Omega = \sqrt{\delta^2 + A^2};"
          c_1 = e^{-i \delta t/2} \left( \cos\left[\frac{\Omega t}{2}\right] + \frac{i \delta}{\Omega} \sin\left[\frac{\Omega t}{2}\right] \right);

Out[*]=

$$\Omega = \sqrt{\delta^2 + A^2};$$


In[*]:= c_1 // TrigToExp // Simplify
Out[*]=

$$\frac{1}{2 \Omega} e^{-\frac{1}{2} i t \delta} e^{-\frac{1}{2} i t \Omega} \left( (-1 + e^{i t \Omega}) \delta + (1 + e^{i t \Omega}) \Omega \right)$$


In[*]:= \frac{\left( (-1 + e^{i t \Omega}) \delta + (1 + e^{i t \Omega}) \Omega \right)}{2 \Omega} // FullSimplify
Out[*]=

$$\frac{-\delta + \Omega + e^{i t \Omega} (\delta + \Omega)}{2 \Omega}$$


In[*]:= c_2 = e^{i \delta t/2} \left( \cos\left[\frac{\Omega t}{2}\right] - \frac{i \delta}{\Omega} \sin\left[\frac{\Omega t}{2}\right] \right);

In[*]:= c_2 // TrigToExp // FullSimplify
Out[*]=

$$\frac{e^{\frac{1}{2} i t (\delta - \Omega)} (\delta + \Omega + e^{i t \Omega} (-\delta + \Omega))}{2 \Omega}$$

```