

Lecture_06

October 4, 2022

1 A statistical basis for entropy

The first law of thermodynamics can be written as

$$dU = TdS - PdV$$

and is always true. From this, in the last lecture we arrived at the following definition for temperature

$$T = \left(\frac{\partial S}{\partial U} \right)_V$$

Several lectures ago, we also defined temperature in terms of the statistical weight of a system in a given macrostate to be

$$\frac{1}{k_B T} = \frac{d \ln \Omega}{dE}.$$

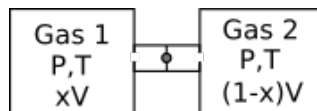
Comparing these, we can then identify another definition of S as

$$S = k_B \ln \Omega.$$

At this point, it's important to note that this definition assumes that the system is in a macrostate with a fixed energy (this comes from the section entitled “Temperature” back in Lecture 2). We'll generalise the result later.

1.1 Entropy of mixing

Let us now consider 2 different ideal gases. They are initially in separate vessels with volume xV and $(1-x)V$ respectively, where $0 < x < 1$. Both gases are at the same pressure, P , and temperature, T .



We can write the pressure of either gas to be

$$P = \frac{N_{1,2} k_B T}{V_{1,2}}$$

Since the pressure in both gases is the same, this gives

$$\frac{N_1 k_B T}{xV} = \frac{N_2 k_B T}{(1-x)V}$$

If we then define $N = N_1 + N_2$ as the total number of particles, then we get that $N_1 = xN$ and $N_2 = (1 - x)N$.

If we now open the tap, then the gases will mix. As we considered for the Joule expansion, we can calculate the entropy by imagining that the mixing occurs reversibly. Let's imagine an isothermal expansion, which means that the internal energies of the gases do not change. This means that

$$TdS = PdV \rightarrow dS = \frac{PdV}{T} \rightarrow dS = \frac{Nk_B}{V}dV$$

Now, to find the total change in entropy, we consider the change in entropy due to gas 1 expanding isothermally to fill the full container, and gas 2 expanding isothermally to fill the full container

$$\Delta S = \int_{xV}^V \frac{N_1 k_B}{V_1} dV_1 + \int_{(1-x)V}^V \frac{N_2 k_B}{V_2} dV_2 \quad (1)$$

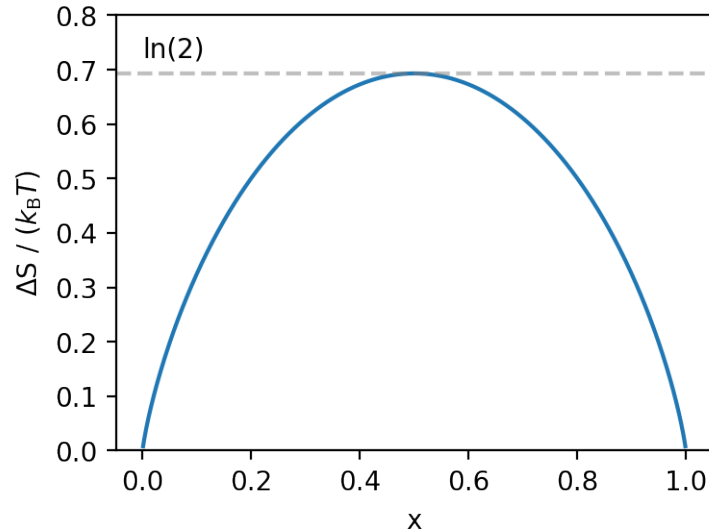
$$= \int_{xV}^V \frac{xN k_B}{V_1} dV_1 + \int_{(1-x)V}^V \frac{(1-x)N k_B}{V_2} dV_2 \quad (2)$$

$$= xN k_B \int_{xV}^V \frac{1}{V_1} dV_1 + (1-x)N k_B \int_{(1-x)V}^V \frac{1}{V_2} dV_2 \quad (3)$$

$$= xN k_B (\ln(V) - \ln(xV)) + (1-x)N k_B (\ln(V) - \ln((1-x)V)) \quad (4)$$

$$= -N k_B [x \ln(x) + (1-x) \ln(1-x)] \quad (5)$$

So how does this look?



From this, it is clear that the maximum change in entropy occurs when $x = 0.5$. We can also arrive at this same result by considering the microstates for the gases. Before mixing, we know that gas 1 is only in the first vessel, while gas 2 is only in the second vessel. After mixing, the number of microstates available to each particle increases by 2 - they can either be in the first vessel, or the second vessel. As such, the statistical weight, Ω , must be multiplied by 2^N to account for these new microstates. This means that

$$\Delta S = k_B \ln 2^N = N k_B \ln 2$$

1.2 Combining Entropy & Probability

Consider again $S = k_B \ln \Omega$. How does the entropy account for microstates? Let's do an example to check.

Imagine we have a system which has 5 macrostates (that is, these states are easily distinguishable by measuring some macrovariable such as energy), each of which is equally likely to occur. This means that

$$S = k_B \ln 5$$

Now assume that each macrostate has 3 microstates (states which we cannot distinguish, so associated perhaps with particle positions or momenta) associated with it, which are also equally likely to occur. This means that there is an additional entropy associated with each of these microstates, $S_{\text{micro}} = k_B \ln 3$.

There are a total of 15 unique states the system can be in (5 macro, 3 micro for each macro). The total entropy of the system is thus given by

$$S_{\text{total}} = k_B \ln 15$$

which can be decomposed into

$$S_{\text{total}} = k_B \ln 5 + k_B \ln 3$$

This means that we can write

$$S_{\text{total}} = S + S_{\text{micro}}$$

The reasons for doing this will become clear in a second.

Now, consider a system which has a total of N equally-likely microstates. These microstates are subdivided into groups corresponding to macrostates, such that a macrostate i has a total of n_i microstates associated with it. We require that

$$\sum_i n_i = N$$

(That is, summing together the number of microstates in each macrostate is the same as the total number of microstates available). The probability that the system is in the i th macrostate is then given by

$$P_i = \frac{n_i}{N}.$$

The total entropy of this system is

$$S_{\text{total}} = k_B \ln N$$

The problem we are faced with is that, quite often, N is difficult to measure. For examples like dipoles oriented in magnetic fields, we have a rough idea (it's of order 2^M for M particles), but this is only for a very specific example. In general, we have

$$S_{\text{total}} = S + S_{\text{micro}}$$

where S is the entropy due to the number of macrostates while S_{micro} is an unknown entropy contribution to the number of available microstates. This is given by

$$S_{\text{micro}} = \langle S_i \rangle = \sum_i P_i S_i$$

Given this, we can do the following

$$S = S_{\text{total}} - S_{\text{micro}} \quad (6)$$

$$= k_B(\ln N - \sum_i P_i \ln n_i) \quad (7)$$

$$= k_B \sum_i P_i (\ln N - \ln n_i) \quad (8)$$

$$(9)$$

Now, $\ln(N) - \ln(n_i) = \ln(N/n_i) = \ln(1/P_i) = -\ln(P_i)$. This gives us Gibbs' definition of Entropy

$$S = -k_B \sum_i P_i \ln(P_i)$$

2 Thermodynamic Potentials

Up until this point, we have been working a lot with the internal energy of a system, U , which is a function of state. In principle, we can combine U with any other functions of state (P , V , S , T) to create new functions of state. These are called **thermodynamic potentials**. In this next section, we are going to look at some thermodynamic potentials which can be very useful in certain situations.

2.1 Internal energy, U

We've spent a lot of time dealing with U , so I'm not going to dwell on it too much. Below is simply a summary of where we've encountered U previously. First,

$$dU = TdS - PdV$$

which is the fundamental thermodynamic potential. From this, we can state that, $U = U(S, V)$. Now we will define an isochoric process as one during which the volume stays constant ($dV = 0$). In this case, we have

$$dU = TdS$$

If we have a reversible isochoric process, then we also have that

$$dU = dQ = C_V dT$$

Thus

$$\Delta U = \int_{T_1}^{T_2} C_V dT$$

The fundamental thermodynamic relation also gives us that

$$T = \left(\frac{\partial U}{\partial S} \right)_V ; P = - \left(\frac{\partial U}{\partial V} \right)_S$$

This is only true at constant volume. To handle a process at constant pressure, we need a different potential.

2.2 Enthalpy, H

Let enthalpy be

$$H = U + PV.$$

Thus, an infinitesimal change in H is given by

$$dH = TdS - PdV + PdV + VdP \quad (10)$$

$$dH = TdS + VdP \quad (11)$$

From this, we can say that $H = H(S, P)$. For an isobaric process ($dP = 0$), we then have

$$dH = TdS$$

and for a reversible process we have

$$dH = dQ = C_P dT$$

Thus

$$\Delta H = \int_{T_1}^{T_2} C_P dT$$

Thus, for a process performed at constant pressure, then the enthalpy represents the heat transferred to or from the system. Our definition of the enthalpy also gives us that

$$T = \left(\frac{\partial H}{\partial S} \right)_P ; V = \left(\frac{\partial H}{\partial P} \right)_S$$

2.3 Helmholtz Free Energy (or Helmholtz Function)

The above potentials are both functions of entropy, S , which can difficult to vary experimentally. This next thermodynamic potential does not suffer the same drawback. Let's define the Helmholtz Free Energy as

$$F = U - TS.$$

This gives

$$dF = TdS - PdV - TdS - SdT \quad (12)$$

$$= -SdT - PdV \quad (13)$$

From this, we can say that $F = F(T, V)$. For an isothermal process, we thus have

$$dF = -PdV$$

giving

$$\Delta F = - \int_{V_1}^{V_2} PdV$$

Our definition of the Helmholtz Free Energy also gives us that

$$S = - \left(\frac{\partial F}{\partial T} \right)_V ; P = - \left(\frac{\partial F}{\partial V} \right)_T$$

2.4 Gibbs Free Energy (or Gibbs Function)

Let

$$G = H - TS$$

This gives

$$dG = TdS + VdP - TdS - SdT \tag{14}$$

$$= -SdT + VdP \tag{15}$$

Thus $G = G(T, P)$, which is particularly useful as both T and P are easy to control and change in experiments. Thus, if you have an isothermal isobaric process, then $dG = 0$. This will be useful when we are studying phase transitions later. Our definition of the Gibbs Free Energy also gives us that

$$S = - \left(\frac{\partial G}{\partial T} \right)_P ; V = \left(\frac{\partial G}{\partial P} \right)_T$$