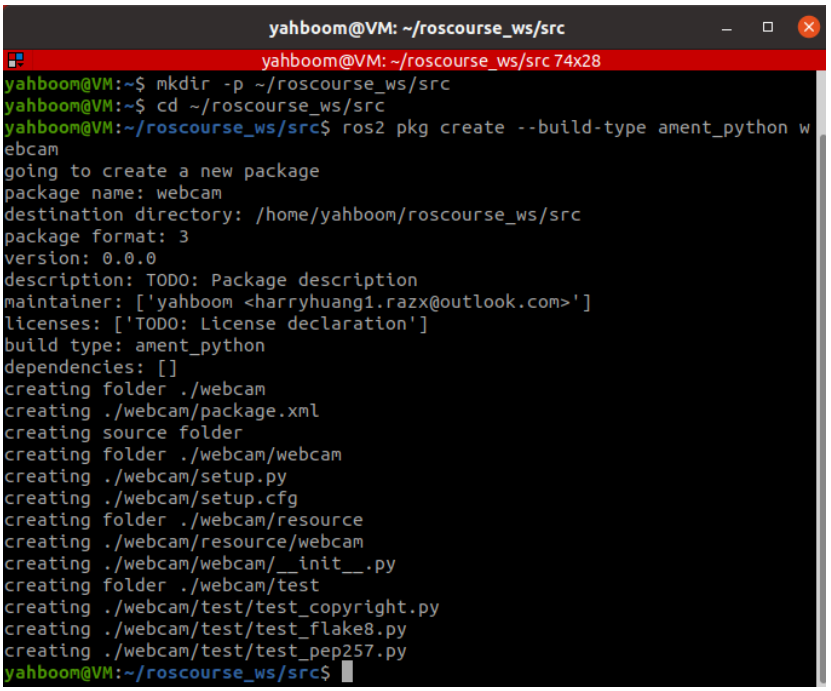
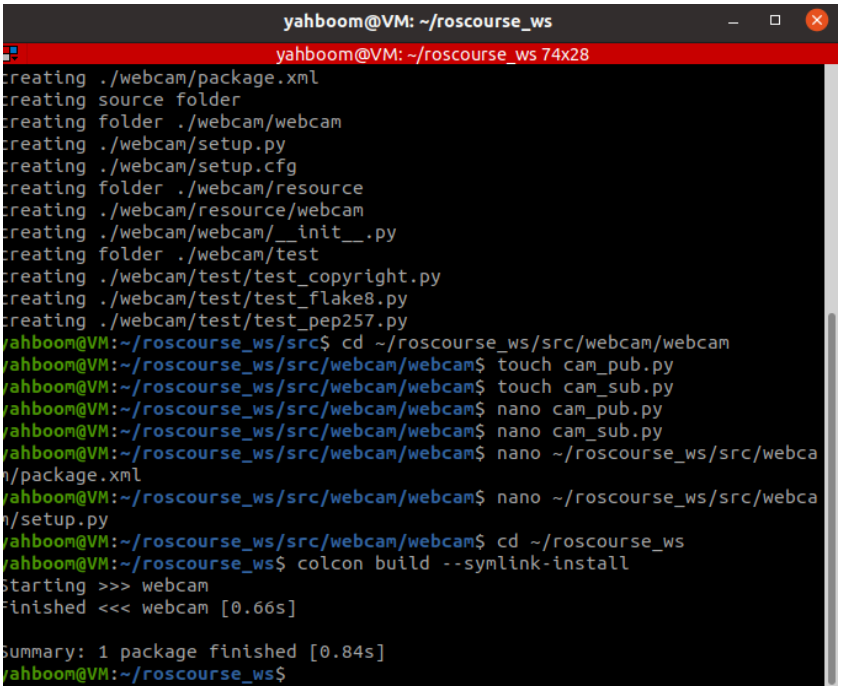
Task2

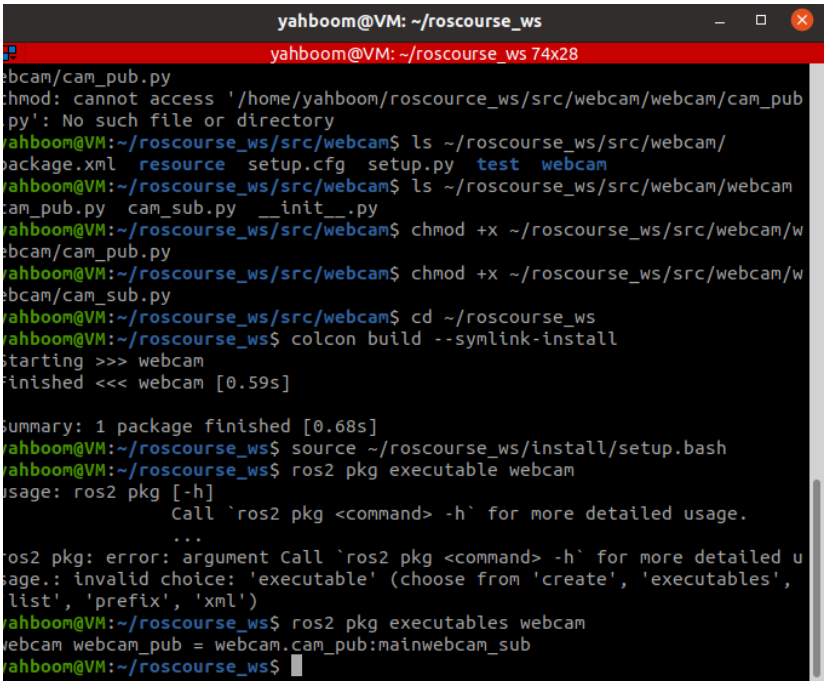
step1:



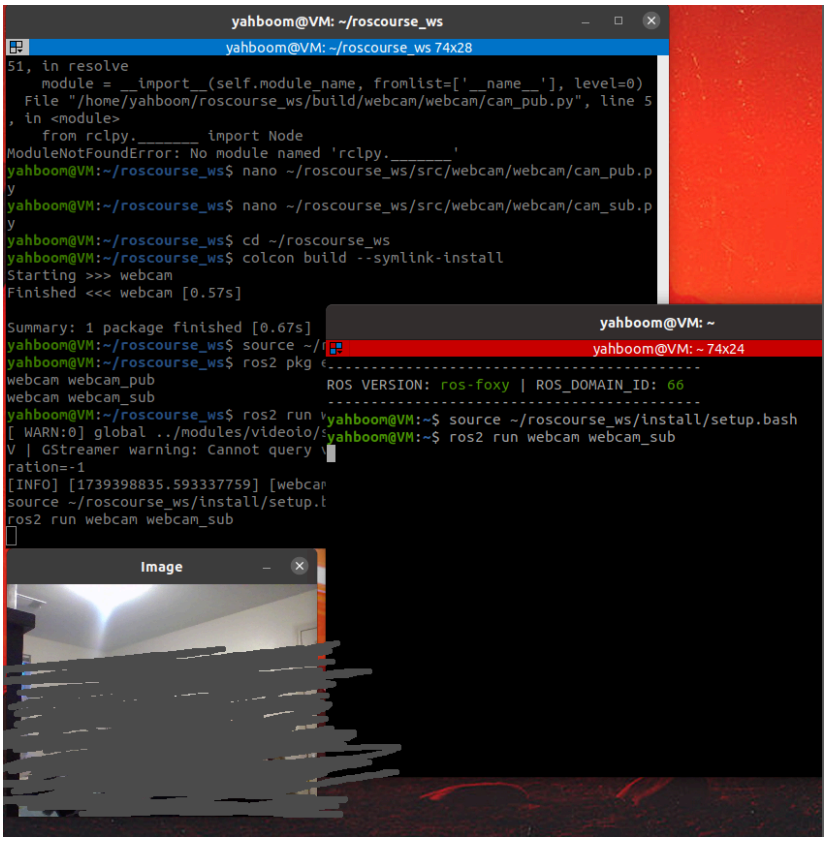
step8:



step11:

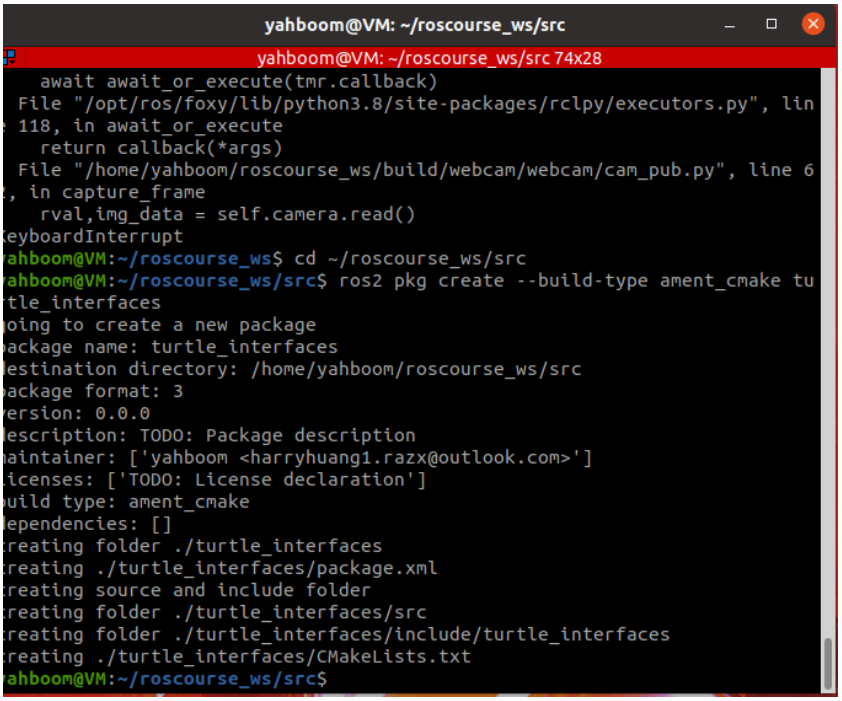


step13:

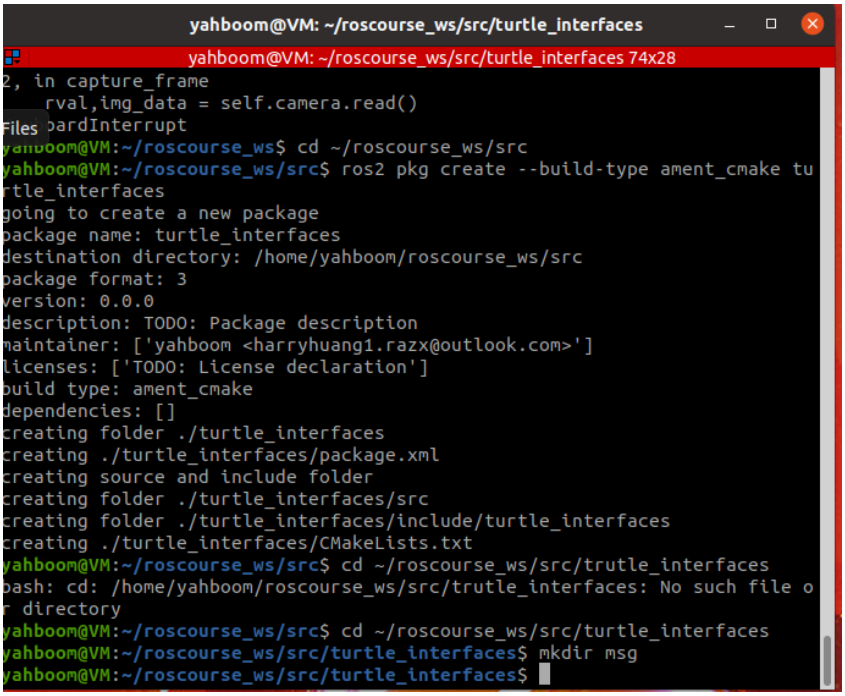


Task3

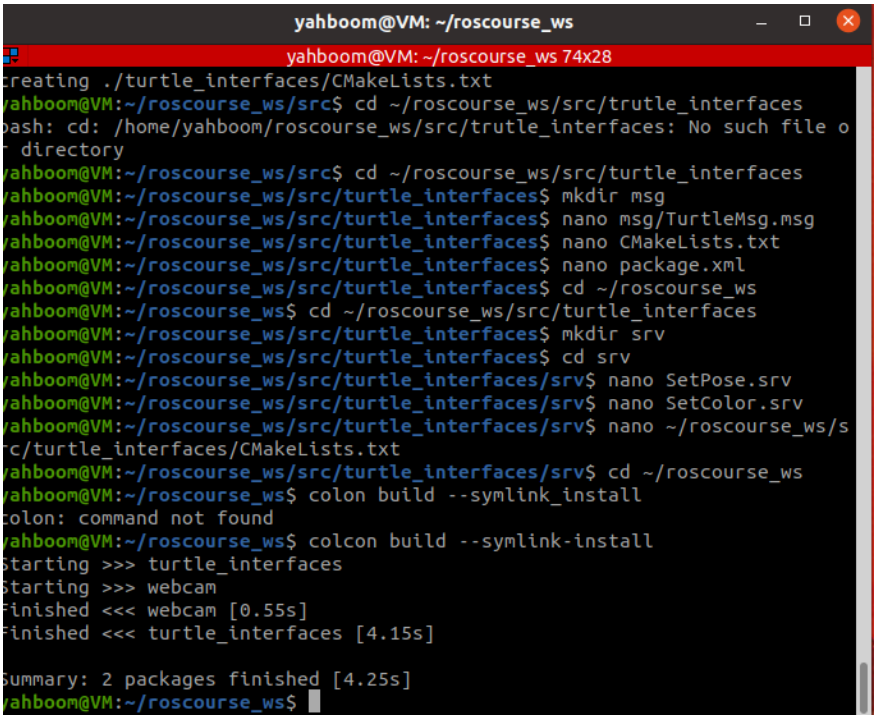
step1:



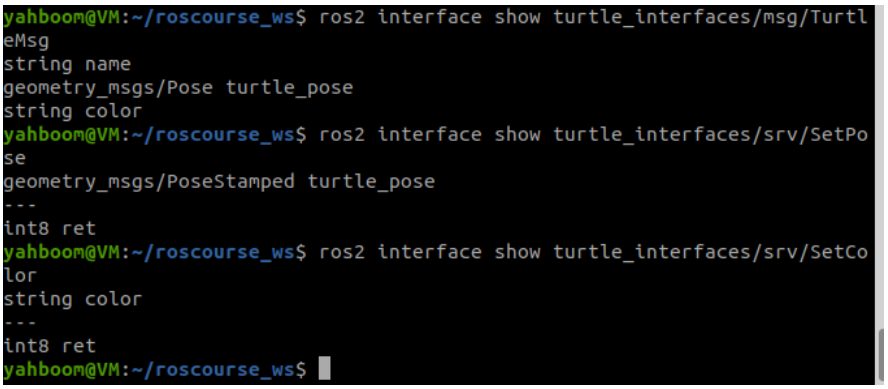
step4:



step20:

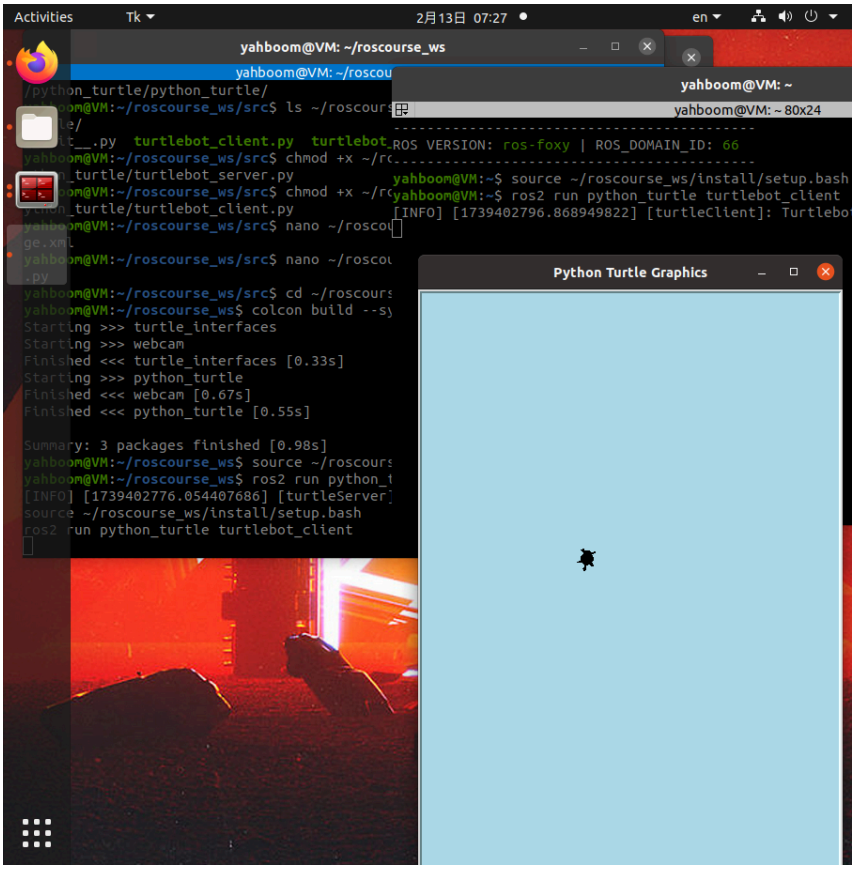


step22:

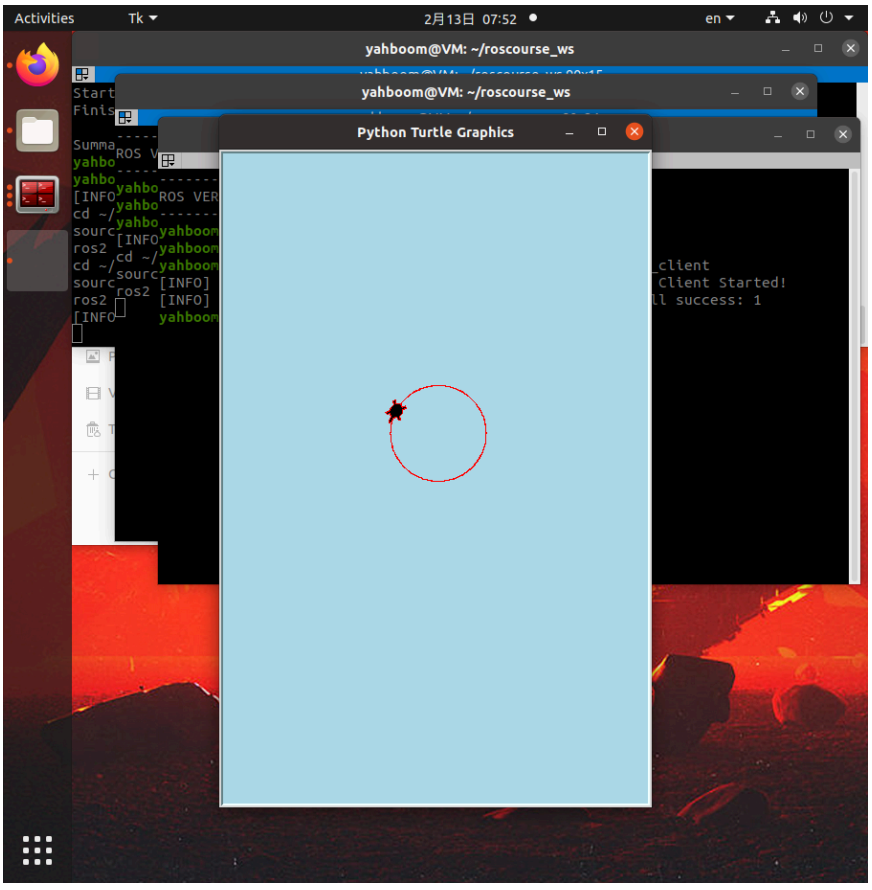


Task3

step7:


Activities
Tk
2月13日 07:27
en
yahboom@VM: ~/roscourse_ws
yahboom@VM: ~
yahboom@VM: ~ 80x24
ROS VERSION: ros-foxy | ROS_DOMAIN_ID: 66
yahboom@VM:~$ source ~/roscourse_ws/install/setup.bash
yahboom@VM:~$ ros2 run python_turtle turtlebot_client
[INFO] [1739402796.868949822] [turtleClient]: Turtlebot
Python Turtle Graphics
Starting >>> turtle_interfaces
Starting >>> webcam
Finished <<< turtle_interfaces [0.33s]
Starting >>> python_turtle
Finished <<< webcam [0.67s]
Finished <<< python_turtle [0.55s]
Summary: 3 packages finished [0.98s]
source ~/roscourse_ws/install/setup.bash
ros2 run python_turtle turtlebot_client

step16:


Activities
Tk
2月13日 07:52
en
yahboom@VM: ~/roscourse_ws
yahboom@VM: ~/roscourse_ws
Python Turtle Graphics
Client Started!
ll success: 1