Task1 step8

```xml
1 <?xml version="1.0"?>
2 <robot name="my_robot">
3     <link name="base_link">
4         <visual>
5             <geometry>
6                 <box size="0.6 0.4 0.2" />
7             </geometry>
8             <origin xyz="0 0 0.1" rpy="0 0 0" />
9         </visual>
10     </link>
11 </robot>
```
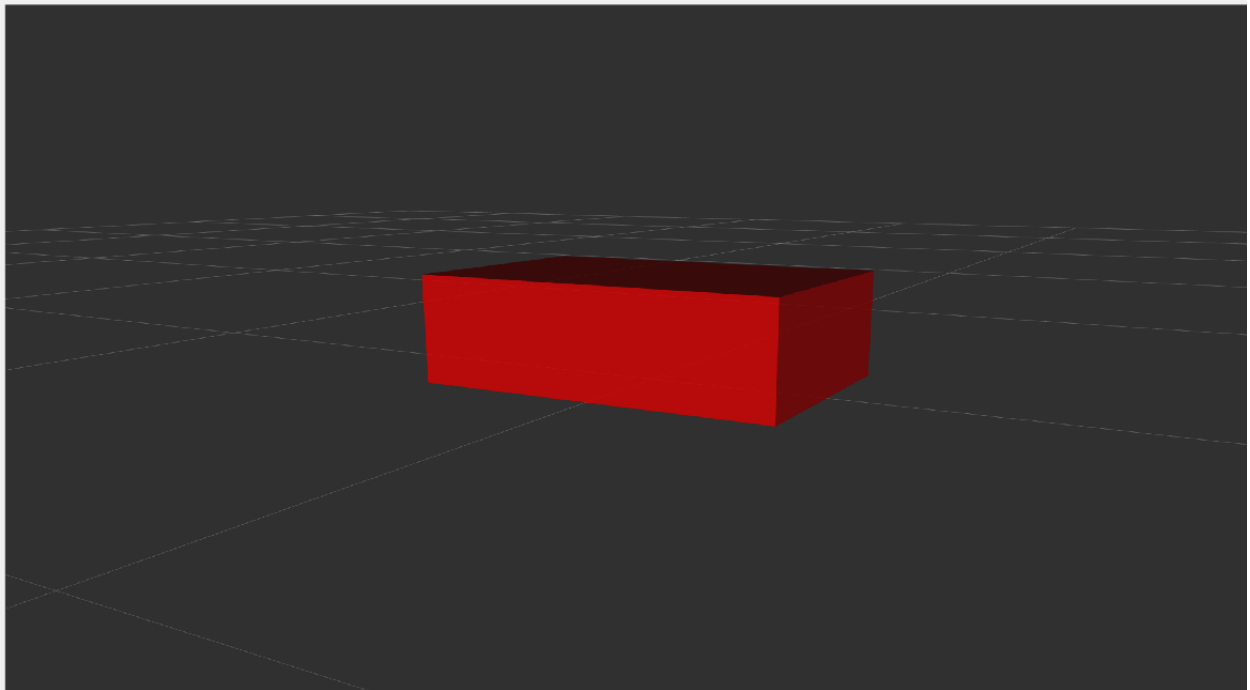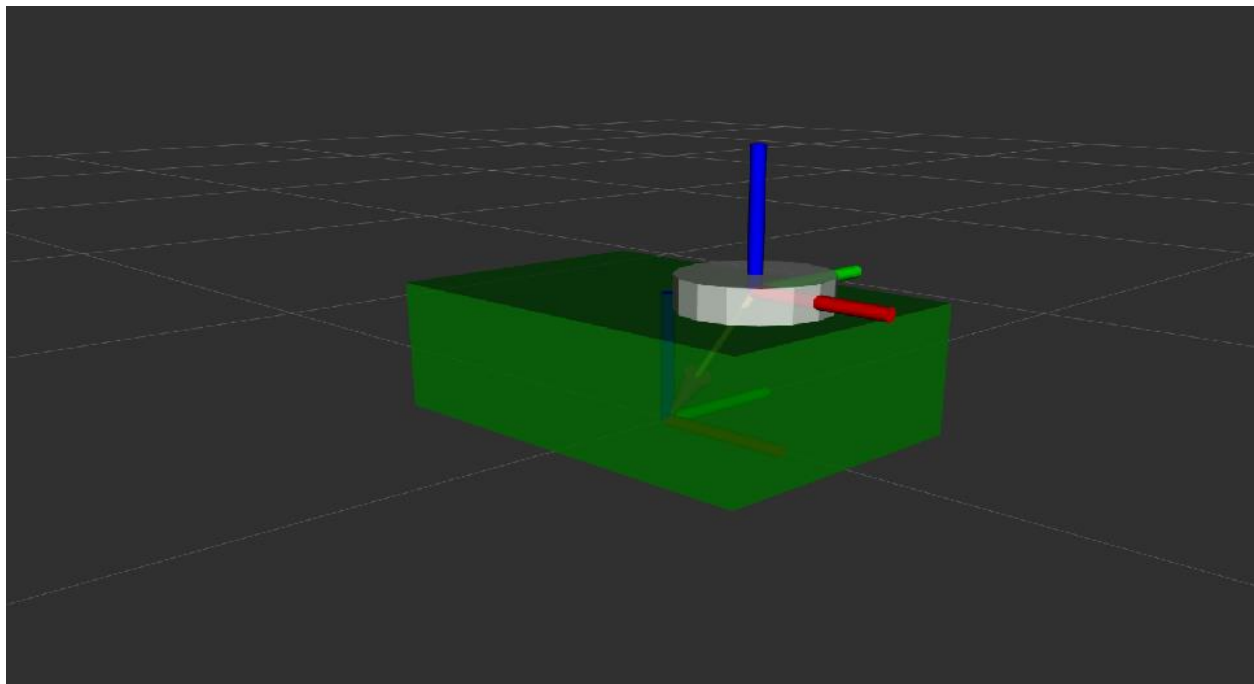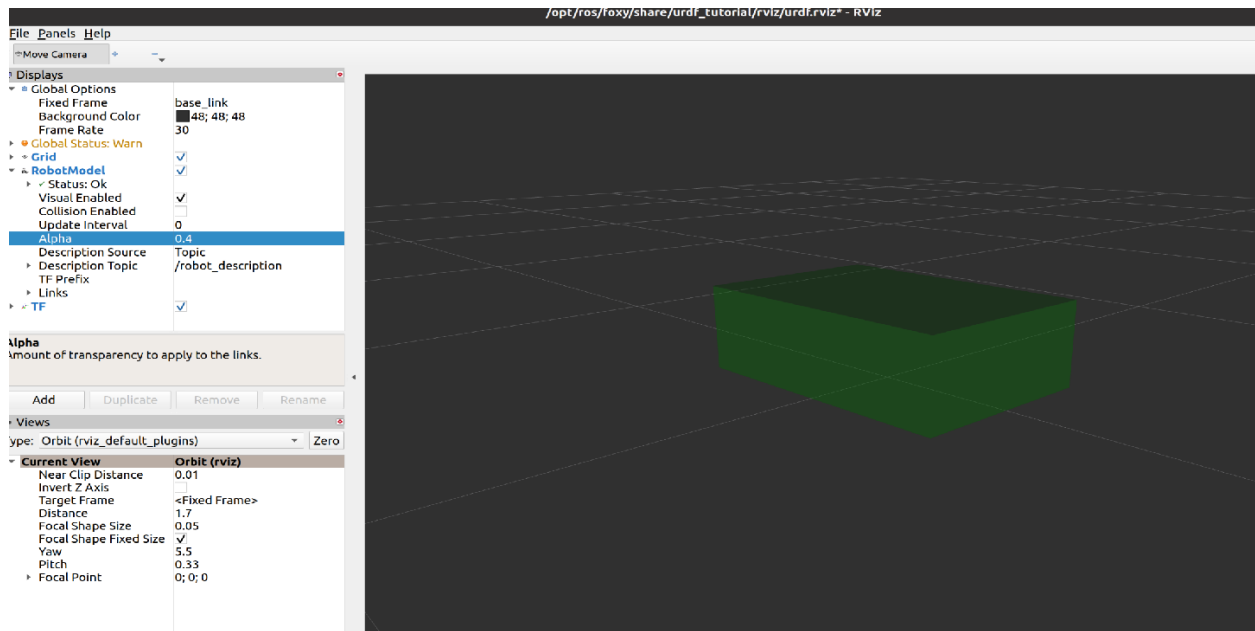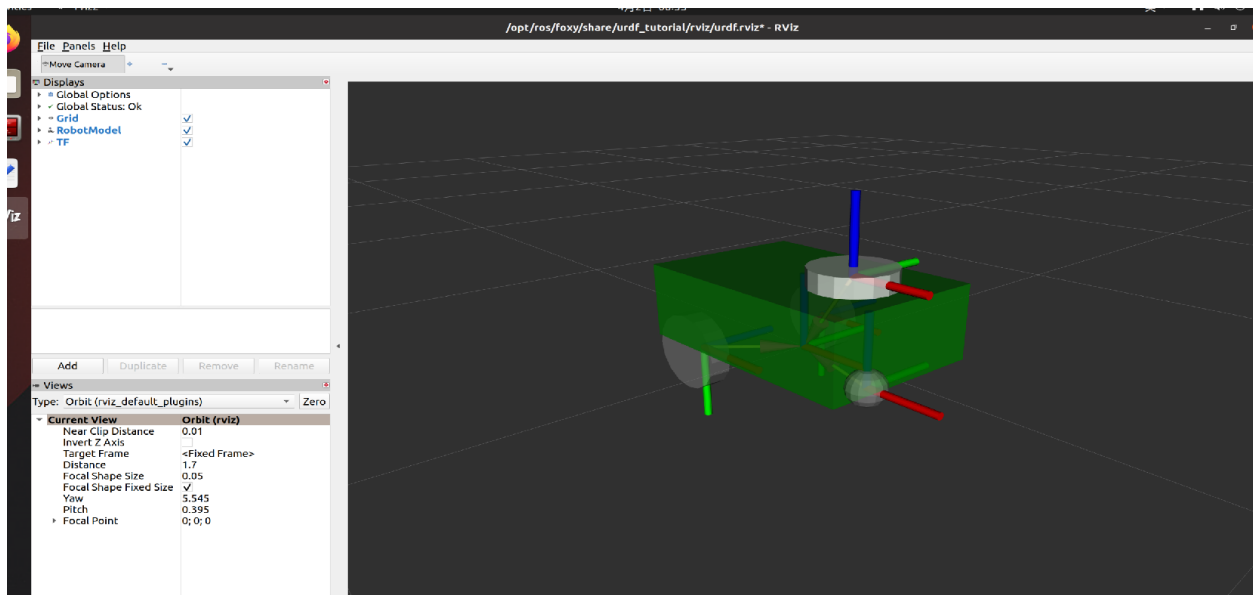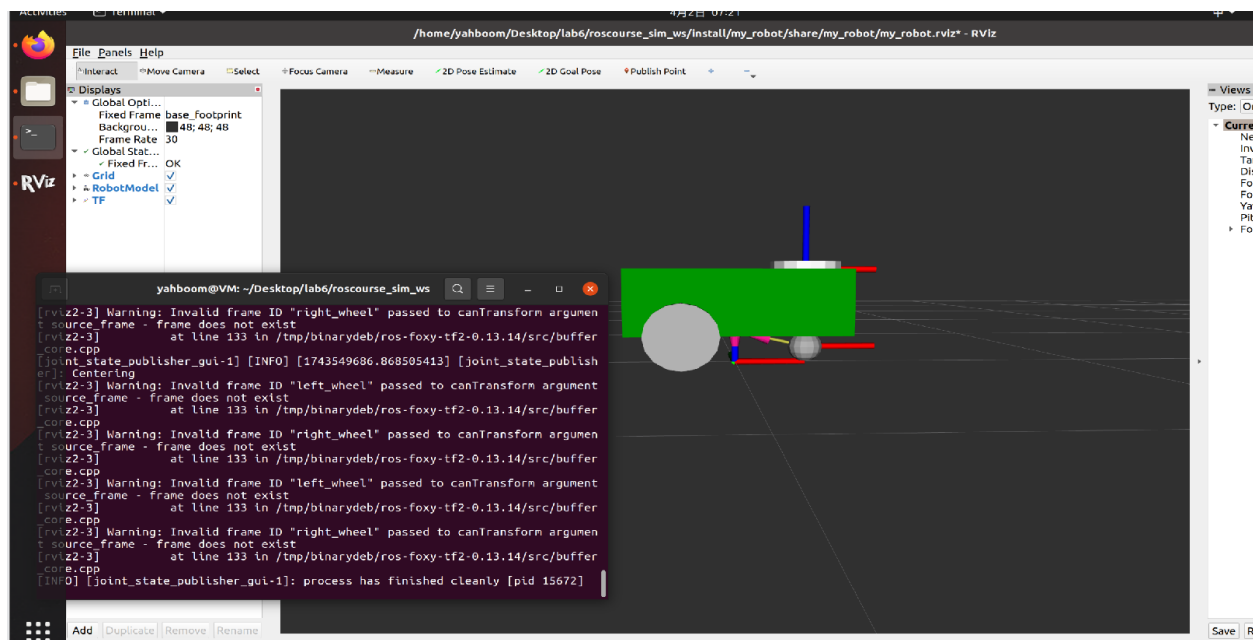
Task1 step 18

Task1 step 36

Task2 step 6

Task3 step3