



shaft\_d

shaft\_dist

shaft\_h

mount\_dist

mount\_l

servo\_l

servo\_h

arm\_dist

arm\_h

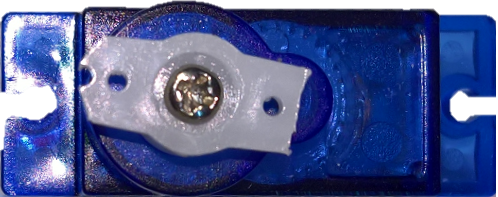


arm\_w2

arm\_w1

arm\_d

arm\_l



servo\_w

hole\_dist