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#### 1 Inverse Problems

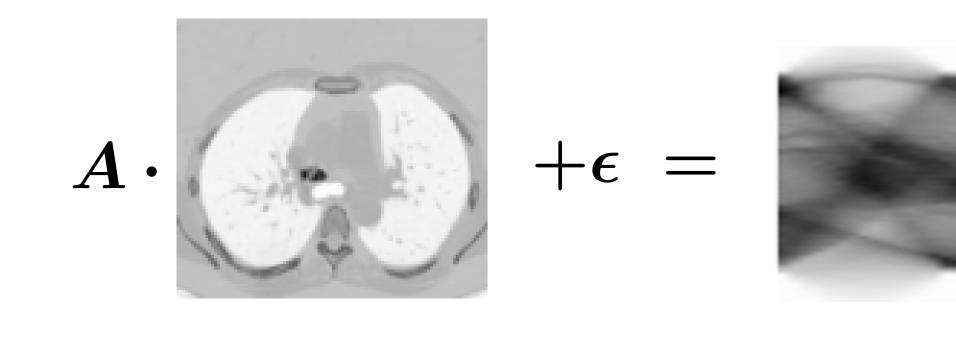
- ightharpoonup Reconstruct image x from measurement  $y=Ax+\epsilon$ , A linear operator.
- lacksquare Difficulty: Applying pseudo-inverse  $A^\dagger$  to measurement amplifies noise.
- Examples in medical imaging: Computed Tomography, Magnetic Resonance Imaging, Photo-Acoustic Tomography.

### 2 The variational approach

Insert prior knowledge into reconstruction by adding regularization functional  $oldsymbol{R}$ . (Benning&Burger 2018, Acta Num. 27) Reconstruct from y by

$$\operatorname{argmin}_x \|Ax - y\| + \lambda R(x)$$

- Popular choice: TV regularization  $R = \| 
  abla x \|_1$ .
- Allows for stability theory and explicit use of the data model, but hand-crafted functionals do not reflect true prior.
- Example of measurements for the Radon transform A used in Computed Tomography.

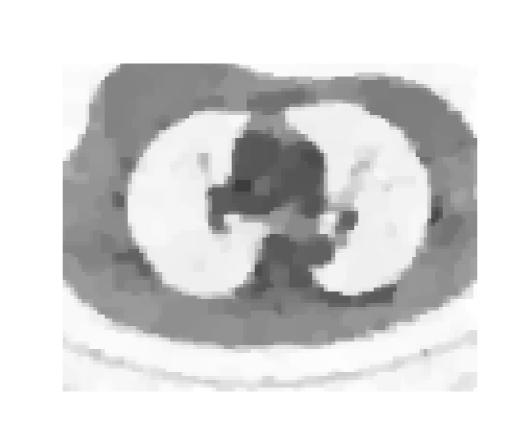


### 4 Results for Computed Tomography and Denoising

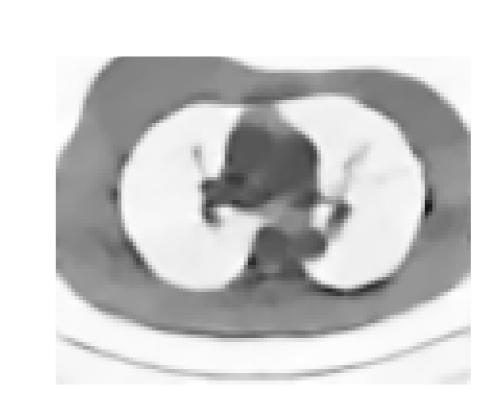
Computed Tomography Reconstruction on LIDC dataset of Lung Scans

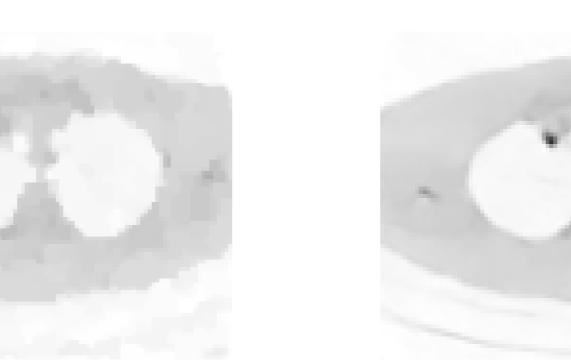


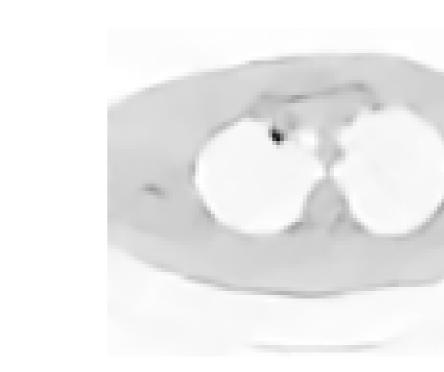












Filtered Backprojection

Noisy Image

Total Variation

Post-Processing

Adversarial Regularizer

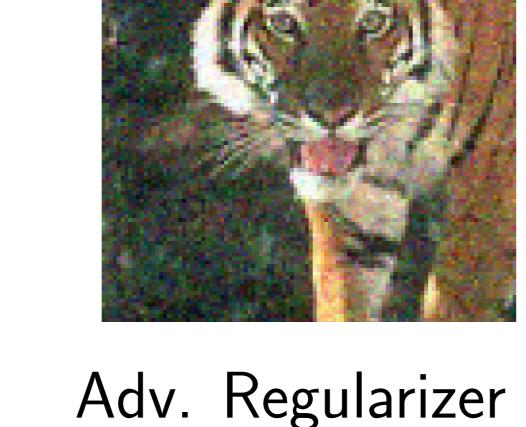
#### Denoising Results on BSDS

Ground truth

Ground truth



Denoising Neural Net



Quantitative Results for Computed Tomography

Method	PSNR (dB)	SSIM
Model-based		
Filtered Backprojection	14.9	.227
Total Variation	27.7	.890
Supervised		
Post-Processing	31.2	.936
RED	29.9	.904
Unsupervised		
Adversarial Reg.	30.5	.927

### 5 Distributional Analysis

- lacktriangle Analyze impact of gradient descent over  $\Psi_\Theta$  on distributions.
- ightharpoonup Define  $\mathbb{P}_{\eta}$  to be distribution obtained from  $\mathbb{P}_{n}$  after one step of gradient descent  $x o x - \eta 
  abla_x \Psi_\Theta(x)$ .
- lackbox Assume  $\Psi_\Theta$  is trained to perfection for  $\lambda=\infty$  and  $\eta \to \operatorname{Wass}(\mathbb{P}_r,\mathbb{P}_\eta)$  is differentiable at  $\eta=0$ , where Wass denotes the Wasserstein distance. Then

$$rac{\mathrm{d}}{\mathrm{d}\eta} \mathrm{Wass}(\mathbb{P}_r,\mathbb{P}_\eta)|_{\eta=0} = -\mathbb{E}_{X\sim\mathbb{P}_n} \left[ \| 
abla_x \Psi_\Theta(X) \|^2 
ight].$$

- In particular, if  $\| \nabla_x \Psi_{\Theta}(x) \| = 1$ , have explicit control over decay rate of Wasserstein distance.
- lacktriangle The decay in Wasserstein distance induced by  $\Psi_{m{\Theta}}$  is the fastest amongst any regularization functional with gradients of unit norm.

#### 6 Analysis and the Data Manifold

- lacksquare Data Manifold Assumption: Ground truth data  $\mathbb{P}_r$  is supported on low-dimensional manifold  $\mathcal{M}$ .
- Assume projecting noisy data  $\mathbb{P}_n$  onto  $\mathcal{M}$  gives rise to the distribution of clean images  $\mathbb{P}_r$ .
- Corresponds to a low-noise assumption in comparison to curvature of Data Manifold.
- lacktriangle Then the optimal critic for  $\lambda=\infty$  is given by the distance function to  $\mathcal{M}$

$$\Psi_{\Theta}(x) = \min_{y \in \mathcal{M}} \|x - y\|_2.$$

Description of the Description of the Optimal Critic can be non-unique. It can in particular be changed arbitrarily outside the support of  $\mathbb{P}_r$  and  $\mathbb{P}_n$ .

# 3 Learning a Regularization Functional

- lacktriangle Learning regularization functional allows to incorporate prior knowledge on data. Use a neural network  $\Psi_\Theta$  to parametrize functional.
- Training the neural network by evaluating performance as regularization functional would require solving nested optimization problem (De Los Reyes et al. 2013, *Inv. Prob. & Imag. 7.4*). Computationally unfeasible.
- Instead train the network as a *critic*. Suppress characteristic noise by *discriminating* between distribution of ground truth data  $\mathbb{P}_r$  and of unregularized inverse  $\mathbb{P}_n$ .
- lacktriangle Additional term to enforce a Lipschitz constraint leads to  $\Psi_\Theta$  parameterizing the Wasserstein distance as in WGANs (Arjovsky et al. 2017, *ICML*; Gulrajani et al. 2017, *NIPS*)

$$\mathbb{E}_{X \sim \mathbb{P}_r} \left[ \Psi_\Theta(X) 
ight] - \mathbb{E}_{X \sim \mathbb{P}_n} \left[ \Psi_\Theta(X) 
ight] + \lambda \cdot \mathbb{E} \left| \left( \left\| 
abla_x \Psi_\Theta(X) 
ight\| - 1 
ight)_+^2 
ight|.$$

lackbox Once trained,  $\Psi_{\Theta}$  is employed to reconstruct from measurement y by solving

$$\operatorname{argmin}_x \|Ax - y\|_2^2 + \lambda \Psi_{\Theta}(x).$$

The minimization problem is solved using first-order methods like gradient descent.

# 8 Advantages

- Direct control over data fidelity during reconstruction along with stability theory allows for qualitative guarantees.
- Unsupervised data is sufficient for training, allowing to use real measurement data for training.
- Model-based approach well-suited for applications in medical imaging.

## 7 Stability

- Stability theory for variational problems can be adapted to learned setting. Difference: Regularization functional additionally 1-Lipschitz, but not necessarily bounded below.
- lacktriangle Assumptions:  $\Psi_{oldsymbol{\Theta}}$  lower semi-cts., 1 -Lipschitz, A continuous.
- lacksquare Either A or  $\Psi_{lacksquare}$  are coercive.
- Let  $y_n 
  ightarrow y$  and let  $x_n$  denote  $x_n$  corresponding minimizers of variational problem. Then  $x_n$  converge to some x weakly and x is a minimizer of

$$||Ax-y||_2^2 + \lambda \Psi_{\Theta}(x).$$

► Conclusion: The solution of the variational problem is weakly stable under changes in the data.