

People Counting with Fully Convolutional Neural Network

**"study of the bases of the fully
convolutional neural network and
application on the counting of the
crowds"**

INTRODUCTION



Military applications
Design of public space

Security management
Customer analysis



STATE OF THE ART

CNN-based methods

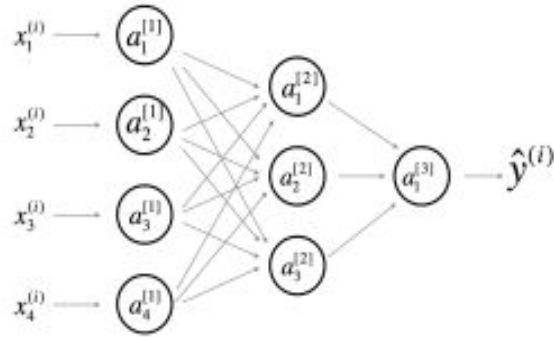
Regression-based approaches

Detection-based approaches

Density estimation based approaches.

DEFINITION

NEURAL NETWORK



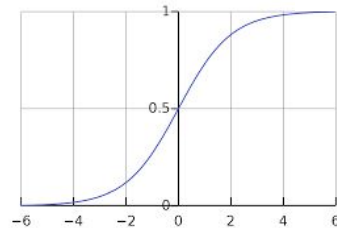
$$a = g^{[l]} (W_x x^{(i)} + b_1) = g^{[l]}(z_1)$$

$$a^{[L]} = g(w^{[L]} a^{[L-1]} + b^{[L]})$$

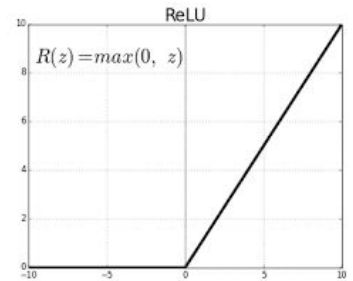
$$z^{[L]} = w^{[L]} a^{[L-1]} + b^{[L]}$$

$$J_0 = (a^{[L]} - y)$$

$$S(x) = \frac{1}{1+e^{-x}}$$



$$f(x) = x + \max(0, x)$$



DEFINITION

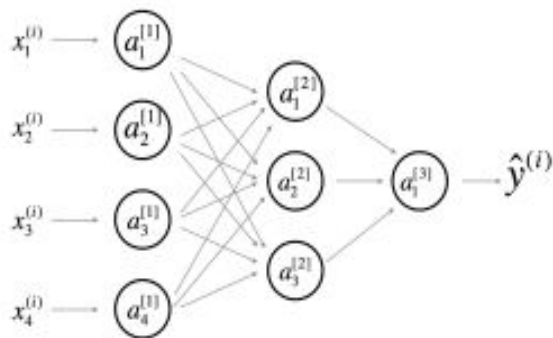
NEURAL NETWORK

$$J_{CE}(\hat{y}, y) = - \sum_{i=0}^m y^{(i)} \log \hat{y}^{(i)}$$

$$J_1(\hat{y}, y) = \sum_{i=0}^m |y^{(i)} - \hat{y}^{(i)}|$$

DEFINITION

NEURAL NETWORK



$$dz^{[2]} = a^{[2]} - y$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

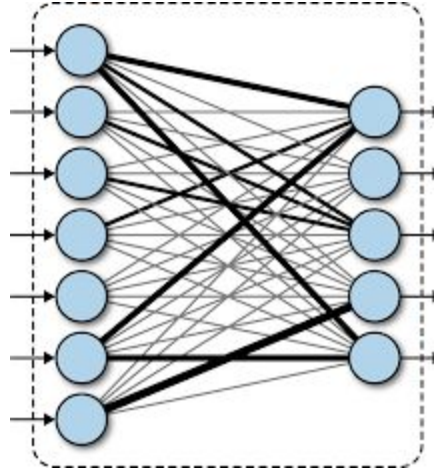
$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

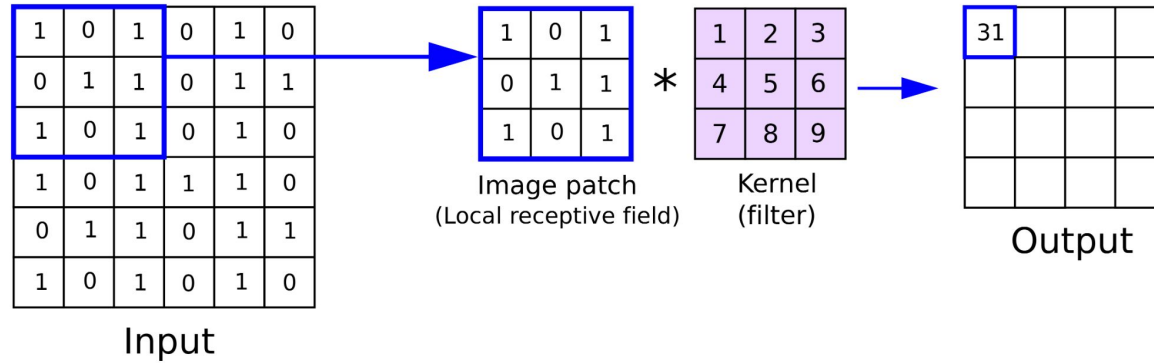
DEFINITION

FULLY CONNECTED LAYER



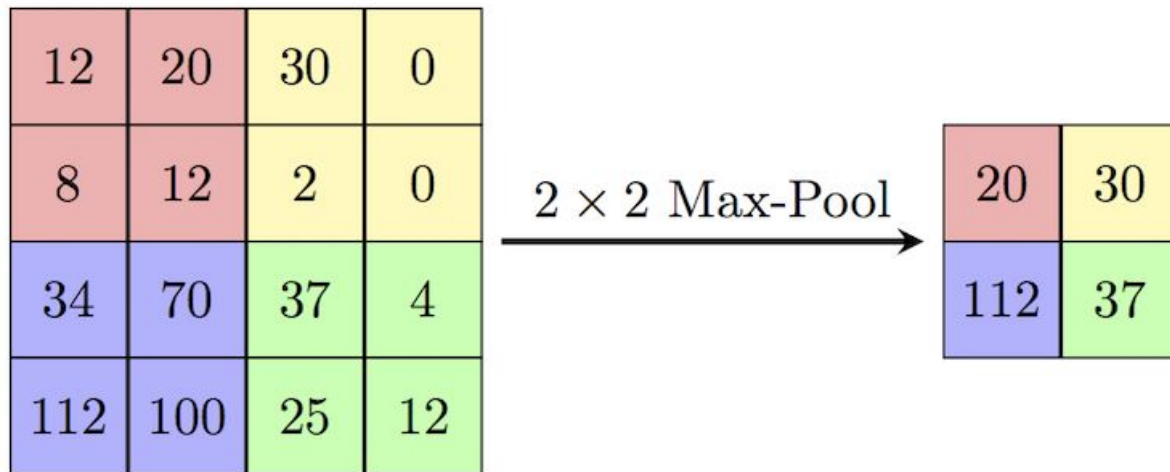
DEFINITION

CONVOLUTION LAYER



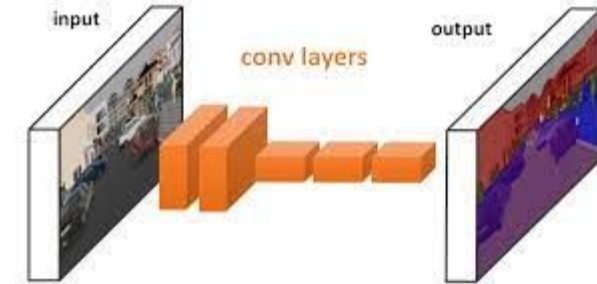
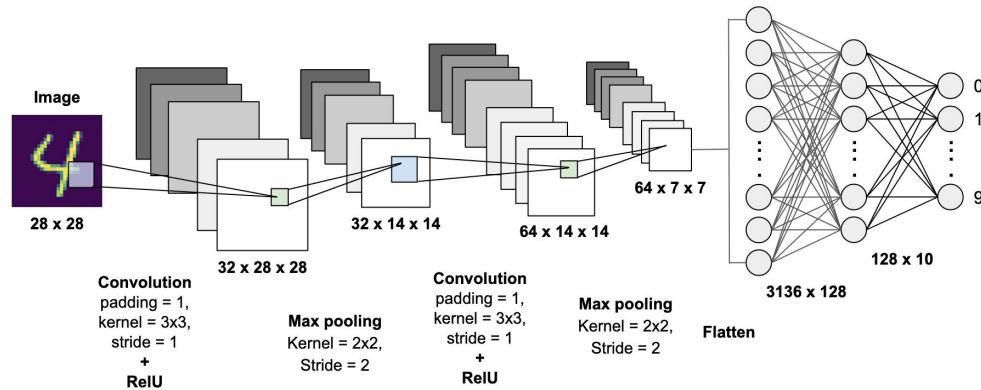
DEFINITION

MAX POOLING LAYER

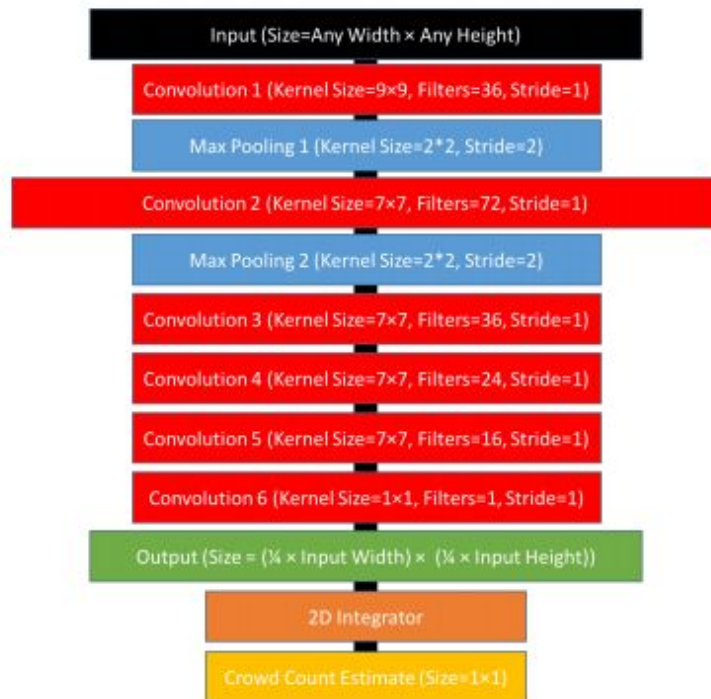
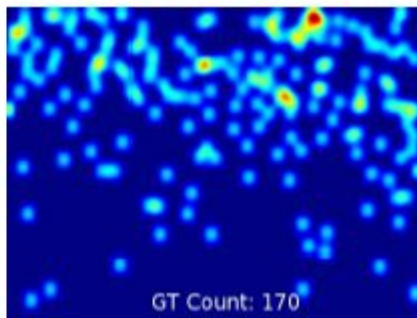


DEFINITION

FULLY CONNECT LAYER



ALGORITHM

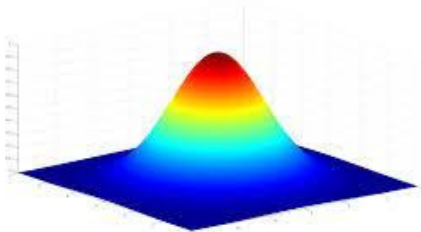
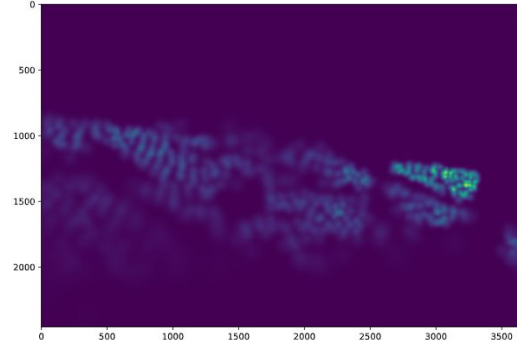


METRICS

$$MAE = \frac{1}{N} \sum_1^N |z_i - \check{z}_i|$$

$$MSE = \sqrt{\frac{1}{N} \sum_1^N (z_i - \check{z}_i)^2}$$

IMPLEMENTATION



$$G_{\sigma i} = 0,3 * \overline{d_i}$$

$$g(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{1}{2} \frac{(x - \mu)^2}{\sigma^2}\right)$$

IMPLEMENTATION



IMPLEMENTATION

```
#CROP IMAGE
def crop(I,width,height):
    x,y,*z =I.shape
    image= I[int(x/2-width/2):int(x/2+width/2), int(y/2-height/2):int(y/2+height/2)]
    return image
def MultipleCrop(I,width,height):
    x,y,z =I.shape
    images=[]
    numberImageRow=int(x/width)
    numberImageColumn=int(y/height)
    for i in range(0,numberImageColumn):
        for j in range(0,numberImageRow):
            images.append(I[int(j*width):int(j*width+width), int(i*height):int(i*height+height)])
    return images

#INTEGRATION
```

IMPLEMENTATION

```
#create model
model=Sequential([
    #encoder
    Convolution2D(36,(9,9),input_shape=(None,None,3), padding="same", activation="relu",
    kernel_initializer=initializers.random_normal( stddev=0.01)),|
    MaxPool2D(pool_size=(2,2), strides=(2,2),padding="same"),
    Convolution2D(72,(7,7), padding="same", activation="relu",kernel_initializer=initializers.random_normal(stddev=0.01)),
    MaxPool2D(pool_size=(2, 2),strides=(2,2)),
    Convolution2D(36,(7,7), padding="same", activation="relu",kernel_initializer=initializers.random_normal(stddev=0.01)),
    Convolution2D(24,(7,7), padding="same", activation="relu",kernel_initializer=initializers.random_normal(stddev=0.01)),
    Convolution2D(16,(7,7), padding="same", activation="relu",kernel_initializer=initializers.random_normal(stddev=0.01)),
    Convolution2D(1,(1,1), padding="same", kernel_initializer=initializers.random_normal(stddev=0.01)),#activation="relu"
    UpSampling2D((2, 2)),
    UpSampling2D((2, 2)),
    # Conv2DTranspose(1,kernel_size=(4,4),strides=(4,4),use_bias=False )
])
```

```
from keras.optimizers import SGD

loss_function=keras.losses.MeanSquaredError(reduction='auto')
opt=SGD(learning_rate=0.00001, momentum=0.9, decay=0.0005 , nesterov= True)|
model.compile(loss=loss_function, optimizer=opt,metrics=['accuracy'])
```


RESULTS

