

FYS3150-Project 1

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Abstract

1 Introduction

In this project we will use numerical methods to solve the one dimensional Poisson equation. We will be rewriting the Dirichlet boundary conditions as a set of linear equations. Our numerical methods will have varying degrees of accuracy. We are going to compare our algorithms and the CPU time for the different numerical methods.

2 Method

The one dimensional Poisson equation with Dirichlet boundary conditions is given by:

$$-u''(x) = f(x) \quad x \in (0,1) \quad u(0) = u(1) = 0 \quad (1)$$

Let's define the discretized approximation to $u(x)$ as v_i , and to $f(x)$ as f_i . We can then make an approximation of the second derivative of u given by:

$$\frac{-v_{i+1} + v_{i-1} - 2v_i}{h^2} = f_i, \text{ where } i = 1, 2, 3, \dots, n, \quad (2)$$

Here the step length of spacing is given by $h = 1/(n+1)$ and the grid points is defined by $x_i = ih$. We can rewrite equation 2 as a linear set of

equations on the form $\mathbf{A}\mathbf{v} = \tilde{\mathbf{b}}$:

$$\begin{aligned} \mathbf{A}\mathbf{v} &= \begin{bmatrix} 2 & -1 & 0 & \dots & \dots & 0 \\ -1 & 2 & -1 & 0 & \dots & \dots \\ 0 & -1 & 2 & -1 & 0 & \dots \\ \vdots & \vdots & \vdots & \ddots & & \\ 0 & \vdots & \vdots & -1 & 2 & -1 \\ 0 & \vdots & \vdots & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} v_0 \\ v_1 \\ v_2 \\ \vdots \\ v_n \\ v_{n+1} \end{bmatrix} = \begin{bmatrix} 2v_0 - v_1 \\ -v_0 + 2v_1 - v_2 \\ -v_1 + 2v_2 - v_3 \\ \vdots \\ -v_{n-1} + 2v_n - v_{n+1} \\ -v_n + 2v_{n+1} \end{bmatrix} \\ &= \begin{bmatrix} h^2 f_0 \\ h^2 f_1 \\ h^2 f_2 \\ \vdots \\ h^2 f_n \\ h^2 f_{n+1} \end{bmatrix} = \tilde{\mathbf{b}} \end{aligned} \quad (3)$$

In our case we will use the source term $f(x) = 100e^{-10x}$ which gives us a closed form solution $u(x)$ given by:

$$u(x) = 1 - (1 - e^{-10})x - e^{-10x} \quad (4)$$

We will use this solution as a point of reference to discuss the accuracy of our numerical methods.

2.1 General algorithm for tri-diagonal matrix

There exists an algorithm for solving generic sets of linear equations, but in the case for equation (3) where we have a tri-diagonal matrix we can use a different algorithm which decreases the amount of floating point operations needed. We denote the elements in the leading diagonal of \mathbf{A} as b_1, b_2, \dots, b_n , the elements above the leading diagonal as a_2, a_3, \dots, a_n , and the elements below the leading diagonal as c_1, c_2, \dots, c_{n-1} . The algorithm uses a forward substitution to replace the leading diagonal with elements denoted by \tilde{b}_i , and replacing the righthand side in with the elements \tilde{f}_i as shown below:

$$\begin{aligned} \tilde{b}_i &= b_i - \frac{a_i c_{i-1}}{\tilde{b}_{i-1}} \\ \tilde{f}_i &= f_i - \frac{a_i \tilde{f}_{i-1}}{\tilde{b}_{i-1}} \end{aligned}$$

where $\tilde{b}_1 = b_1$ and $\tilde{f}_i = f_i$. The algorithm then continues with a backward substitution which gives the solution:

$$u_{i-1} = \frac{\tilde{f}_{i-1} - c_{i-1}u_i}{\tilde{b}_{i-1}} \quad (5)$$

2.2 Algorithm for specific tri-diagonal matrix

In our special case we can implement a solver that is even simpler than what is described previously. We will exploit the fact that the matrix has identical matrix elements along the diagonal and identical values for the non diagonal elements \tilde{e}_i . In this case we can precalculate the new values for the updated matrix elements d_i without taking into account the values for \tilde{e}_i :

$$d_i = 2 - \frac{1}{\tilde{d}_{i-1}} = \frac{i+1}{i} \quad (6)$$

Here the initial value is $\tilde{d}_1 = 2$. The new righthand side solution \tilde{f}_i is given by:

$$\tilde{f}_i = f_i + \frac{(i-1)\tilde{f}_{i-1}}{i} \quad (7)$$

Here the initial value is $\tilde{f}_1 = f_1$. The last step is to make a backward substitution which gives the final solution u_i :

$$u_{i-1} = \frac{i-1}{i}(\tilde{f}_{i-1} + \tilde{u}) \quad (8)$$

This method requires that we know the last value u_n in the u_i array. This value is given by $u_n = \tilde{f}_n / \tilde{b}_n$.

2.3 Relative error

Algorithms have a varying degree of uncertainty. We will test how precise our algorithm is for the specific tri-diagonal matrix case. The numerical solution will be compared to the analytical solution given the relative error ϵ_i :

$$\epsilon_i = \log_{10} \left(\left| \frac{v_i - u_i}{u_i} \right| \right) \quad (9)$$

For the numerical v_i and analytical u_i function values. We wish to extract the max value of the relative error for varying numbers of grid points n . This will give us some information about how precise the numerical approximation is compared to the analytical solution.

2.4 LU decomposition

We are now going to LU decomposition the matrixes 10×10 , 100×100 , 1000×1000 and $10\,000 \times 10\,000$. What the LU decomposition does, is that it rewrite a matrix as the product of two other matrices L and U, like this:

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \dots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ l_{21} & 1 & \dots & 0 \\ \vdots & \vdots & \dots & \vdots \\ l_{n1} & l_{n2} & \dots & 1 \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ 0 & u_{22} & \dots & u_{2n} \\ \vdots & \vdots & \dots & \vdots \\ 0 & 0 & \dots & u_{nn} \end{bmatrix}$$

There are several reasons why we use LU decomposition instead of standard Gaussian elimination. First of all, it is straight forward to solve the determinant of a matrix. Second, if we still need to solve a set of linear equation with the same matrix, but with a different vector, the number of FLOPS is of order n^3 . Where FLOPS is floating point operations per second. Where a such operation is the inverse.

By using LU decomposition, it will be comfortably to solve the inverse, determinate and linear equation.

In order to calculate a set of linear equation by using the LU decomposition for matrix $Ax=w$. We first need to compose a matrix A to two matrices L and U. When we have done that we split our equation in to two equation, which you can see under here.

$$\begin{aligned} Ax &= LUx = b \\ Ax &= LUx = b \\ Ly &= b \wedge Ux = y \end{aligned}$$

Where b is given as the one-dimensional Poisson equation times the square of the step length h .

$$b = -\frac{d^2u}{dx^2}h^2 = f(x)h^2$$

Since we now have obtained two separated equation, we now solve for y in equation

$$\mathbf{L}\mathbf{y} = \mathbf{b} \rightarrow \mathbf{L}\mathbf{y} = \mathbf{b}$$

. Which we afterwards plug in

$$\mathbf{U}\mathbf{x} = \mathbf{y} \rightarrow \mathbf{x} = \mathbf{U}^{-1}\mathbf{y}$$

, which then gives us vector \mathbf{x} .

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3 Implementation

All programs used is available at:

https://github.com/Sebamun/FYS3150_Projekter

We implement the algorithms numerically with varying values of grid points n .

Her må jeg si noe om hvorfor jeg valgte de grensene jeg valgte for den relative feilen. Vil ikke ha med ytterpunkter \rightarrow feilen blir gigantisk. Se på forholdet.

4 Results

4.1 General algorithm

4.2 Algorithm for specific tri-diagonal matrix

4.3 Relative error

4.4 LU decomposition

5 Discussion

5.1 LU decomposition

If we compare our solution from the general algorithm and the CPU-time with the LU decomposition, we see that it takes a lot of more time to cal-

calculate the LU decomposition. This comes that it takes n^3 steps to find the LU decomposition, which is the same for gauss-elimination. But when we calculate LU decomposition, we calculate a set of two equations instead of one. This shows us that there are more steps for calculating just one vector. If we are going to calculate other vectors as well for the same matrix, it will show us that the LU decomposition will be much more effective. This comes from that we have already calculated the LU decomposition, which leads us to the calculation of the vector now is just n^2 .

The reason why we can't use LU decomposition on a $10^5 \times 10^5$ matrix comes from the random access memory problem. The data that should be stored from the operation takes too much memory that the computer can't handle the operation we want to.

The number of floating point operations that the LU decomposition uses to solve the set of linear equations equals $\frac{2}{3}n^3$. This means that the FLOPS depend on the size of the matrix. When the matrix becomes large, we can ignore the orders n and n^2 .

6 Concluding remarks

Country List			
Country Name or Area Name	ISO ALPHA 2 Code	ISO ALPHA 3 Code	ISO numeric Code
Afghanistan	AF	AFG	004
Aland Islands	AX	ALA	248
Albania	AL	ALB	008
Algeria	DZ	DZA	012
American Samoa	AS	ASM	016
Andorra	AD	AND	020
Angola	AO	AGO	024