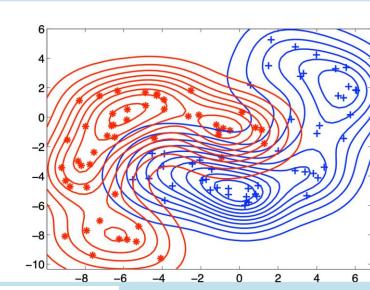
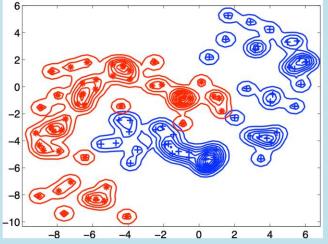
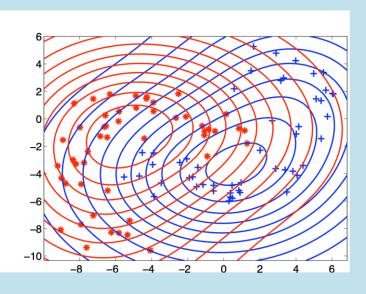
Non-parametric density estimation

Gosia Migut









After practicing with the concepts of this lecture you should be able to:

- Explain the difference between parametric and non-parametric density estimation
- Explain Parzen/Kernel, k-Nearest Neighbour and Naïve Bayes density estimation and classification in detail.
- Explain the advantages and disadvantages of those methods.
- Implement k-nn classifier in Python



Literature

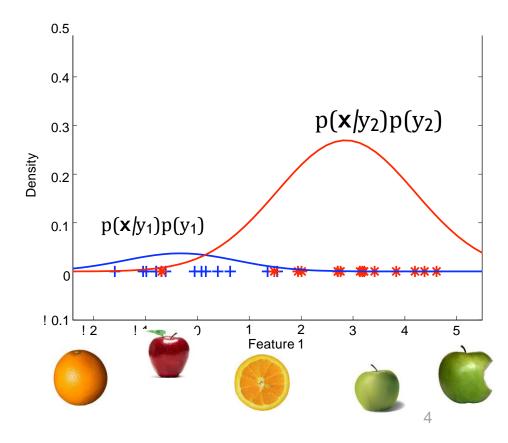
- Chapter 2 section 2.5 from:
 Bishop (2006). Pattern Recognition and Machine Learning. Springer, UK.
- Lecture notes CS229: section 2 and 2.1 (excluding 2.2). Andrew Ng, Standford University. http://cs229.stanford.edu/notes/cs229-notes2.pdf



Last week: parametric density estimation

- Known distribution, eg.: assume a single Gaussian distribution for each of the classes:
 - $\hat{p}(x|y_i) = N(x|\mu_i, \Sigma_i)$
- Estimate the **global** parameters on training set, eg.:
 - estimate μ_i and Σ_i for each of the classes
- For classification use Bayes rule
 - $p(x|y_1)p(y_1) > p(x|y_2)p(y_2)$

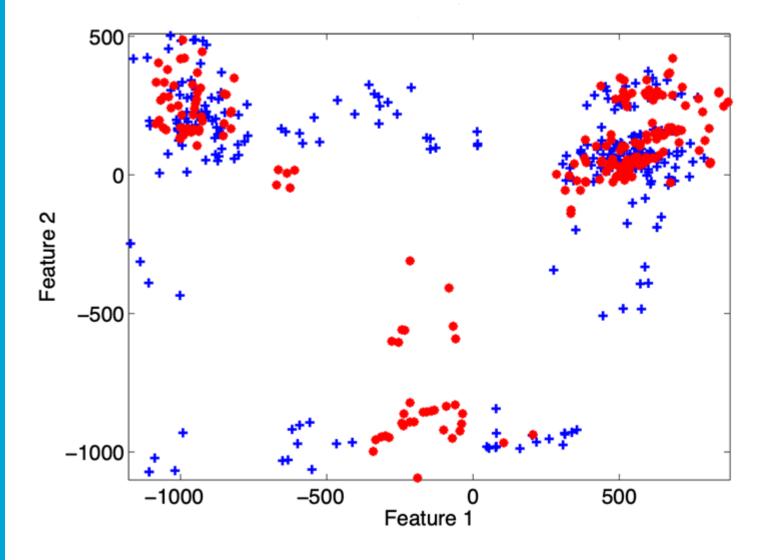




The real life...

Q: Which distribution to assume?

A: We don't know the distribution of data = no global parameters to estimate





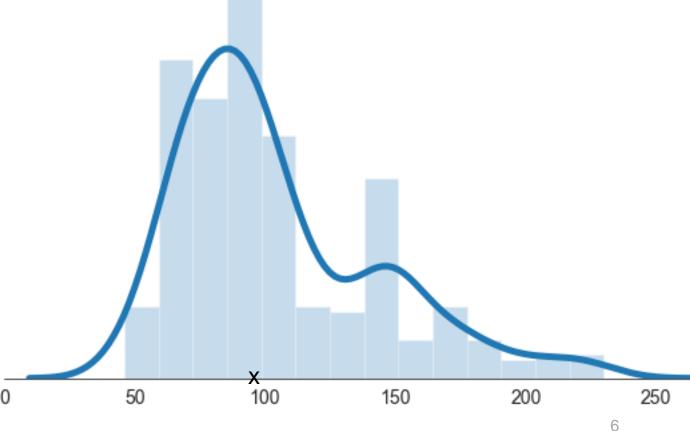
Simple non-parametric density estimation

- Example: we have one feature and *N* samples
- How to estimate the probability density?
 - Histogram

- Split the feature in subregions (bins) of width h
- Count the number of objects in each bin: k_B
- Probability density estimate at point x:

$$\hat{p}(x) = \frac{1}{h} \frac{k_B}{N}$$





Can we do better than histogram?

- Histogram puts all samples between boundaries of each bin.
- Bins location is arbitrary (no unique solution).

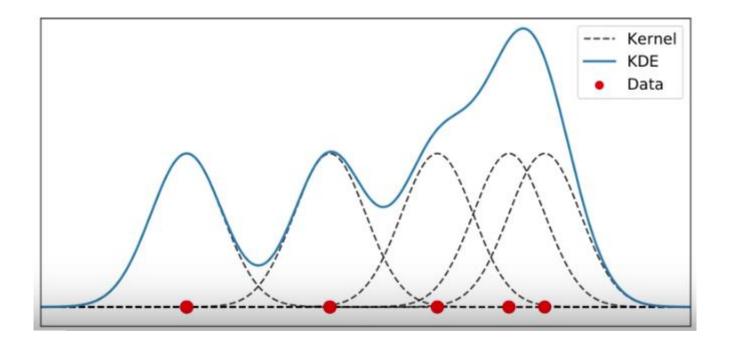
- In practice, two very related methods are used:
 - Parzen (kernel) density estimate
 - k-Nearest-neighbor density estimate (next lecture: theory and lab)



Parzen (window) Density Estimation

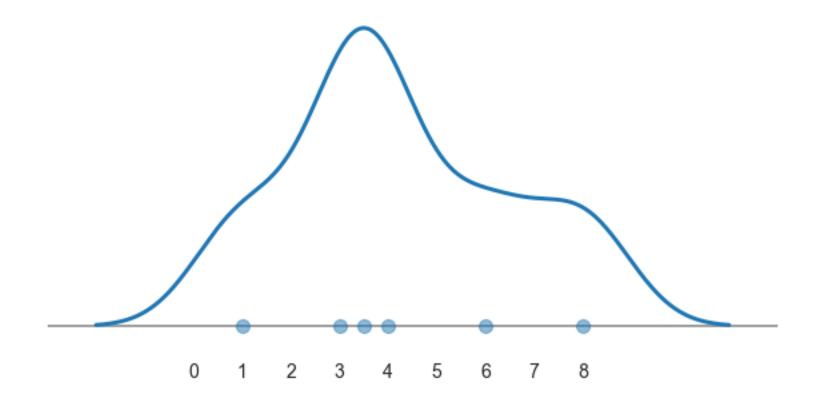
or

Kernel Density Estimation (KDE)





Parzen density estimation: intuition

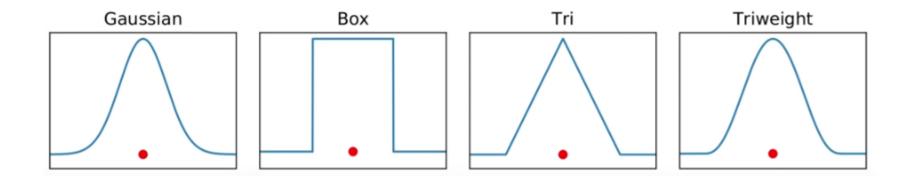




Q: Do you know this type of distribution?

Parzen density estimation: intuition

- Define cell shape (kernel/window function), eg. Gaussian
- Fix size of kernel function (h), eg. $\sigma^2 = 1$



• Q: Is the KDE with a box kernel the same as a histogram?



Lets do some drawing

- Draw histogram with bin size 2
- Draw KDE with box kernel with h=2





Lets do some drawing

- Draw histogram with bin size 2
- Draw KDE with box kernel with h=2

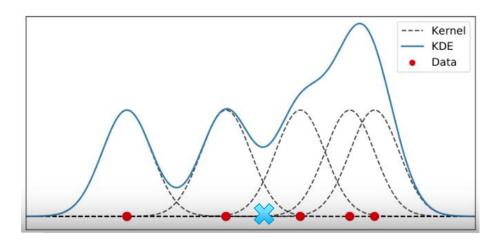








How to find Parzen probability density function estimate at x?



$$\hat{p}(x) = \frac{1}{nh} \sum_{i=1}^{n} K(\frac{x - x_i}{h})$$



Question

Given a set of four data points:

$$x_1 = 2, x_2 = 2.5, x_3 = 3.5, x_4 = 0.5$$

find Parzen probability density function (pdf) estimate at x=3 using the kernel function with width h=1:

$$K(x) = \begin{cases} 0.5 & if |x| < 1 \\ 0 & otherwise \end{cases}$$

Parzen pfd:

$$\hat{p}(x) = \frac{1}{nh} \sum_{i=1}^{n} K(\frac{x - x_i}{h})$$



Solution

- $x_1 = 2, x_2 = 2.5, x_3 = 3.5, x_4 = 0.5$
- x = 3 and h = 1
- $K(x) = \begin{cases} 0.5 & if |x| < 1 \\ 0 & otherwise \end{cases}$

$$\hat{p}(x) = \frac{1}{nh} \sum_{i=1}^{n} K(\frac{x - x_i}{h}) = \frac{1}{4} \left(K\left(\frac{3 - 2}{1}\right) + K\left(\frac{3 - 2.5}{1}\right) + K\left(\frac{3 - 3.5}{1}\right) + K\left(\frac{3 - 0.5}{1}\right) \right) = \frac{1}{4} \left(0 + 0.5 + 0.5 + 0 \right) = \frac{1}{4}$$



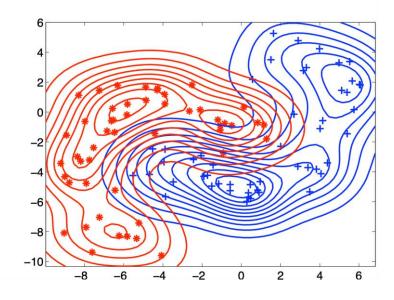
Parzen classifier

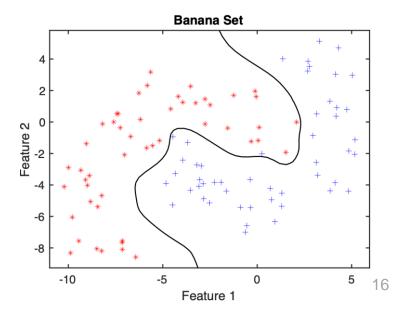
- Fix shape and size of the kernel:
 - Gaussian kernal and Identity matrix as covariance matrix

$$(x|y_i) = \frac{1}{n_i} \sum_{j=1}^{n_i} N(x|x_j^{(i)}, hI)$$

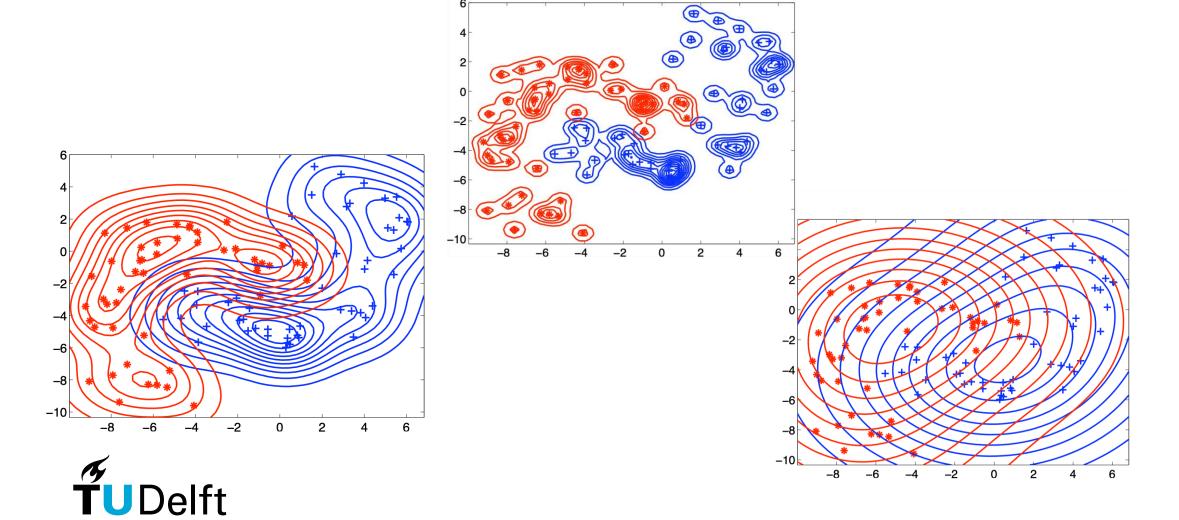
- For classification use Bayes rule
 - $p(x|y_1)p(y_1) > p(x|y_2)p(y_2)$







Does h matter? Intuition on parzen width parameter





Summary of Parzen/Kernel density estimation

Does not assume known distribution

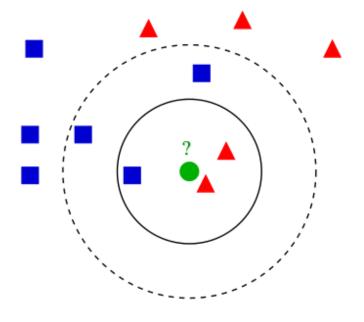
Estimates probability densities using kernel function

Uses kernel funtion of fixed shape and width

Width matters

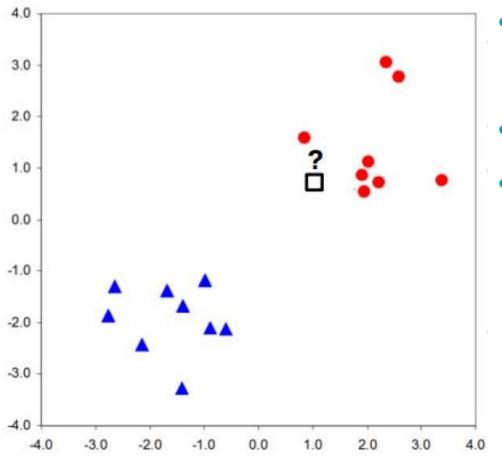


K-nearest Neighbours





K-nearest neighbour intuition



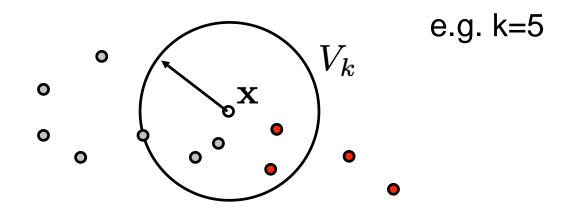
Is the box red or blue?

- How did you do it?
- Nearby points are red



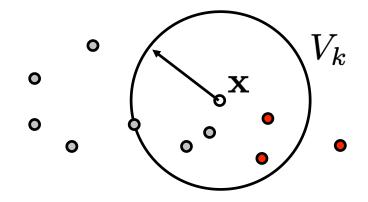
K-nearest neighbour density estimation

- Locate the cell on the new point x
- Do not fix the volume of the cell (V)
- Grow the cell until it covers k objects (find the k-th neighbor)





K-nn density estimation



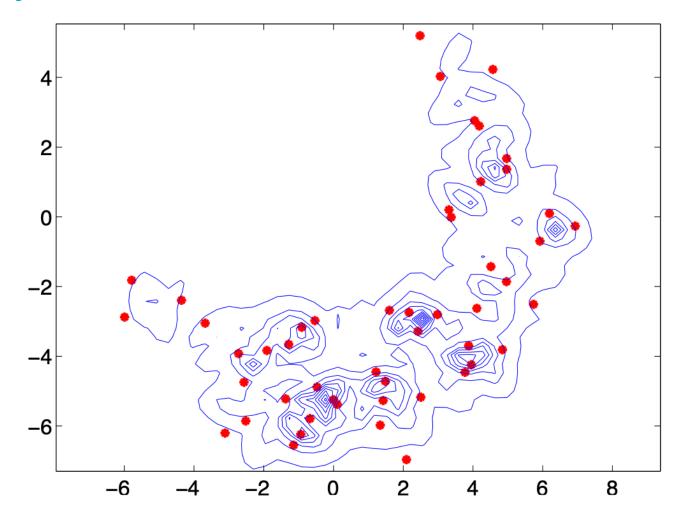
$$\hat{p}(x|y_i) = \frac{k_i}{n_i V_k}$$

- Where V_k is the volume of the sphere centered at x
 - with radius r, being the distance to the k-th nearest neighbour;
- k_i is the number of neighbours of class i within V_k
- n_i is the number of data points of class i in the dataset

• Bayes: $\hat{p}(x|y_i)\hat{p}(y_i) > \hat{p}(x|y_j)\hat{p}(y_j) \to k_i > k_j$



K-nn density estimate





K-nn classification algorithm (lab)

Given:

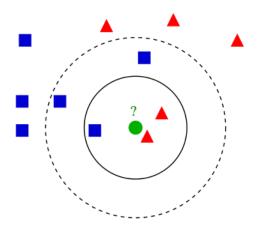
- training examples $\{x_i, y_i\}$
 - x_i attribute-value representation of examples
 - y_i class label: {apple, pear}, digit {0,1, ... 9} etc.
- testing point x that we want to classify

Algorithm:

- compute distance $D(x, x_i)$ to every training example x_i
- select k closest instances $x_{i1} \dots x_{ik}$ and their labels $y_{i1} \dots y_{ik}$
- output the class y^* which is most frequent in $y_{i1} \dots y_{ik}$ (majority vote)



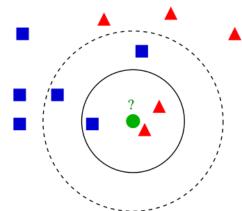
What is the influence of k?



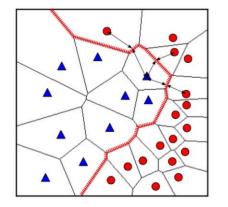
- What is the largest/smallest value of k that you can choose?
 - What will be the classification error then?

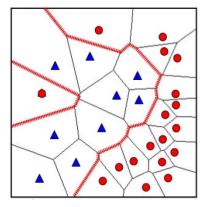


What is the influence of k?



- Value of k has strong effect on k-nn performance
 - Large value → everything classified as the most probable class
 - Small value → highly variable, unstable decision boundaries, eg. for 1-nn:

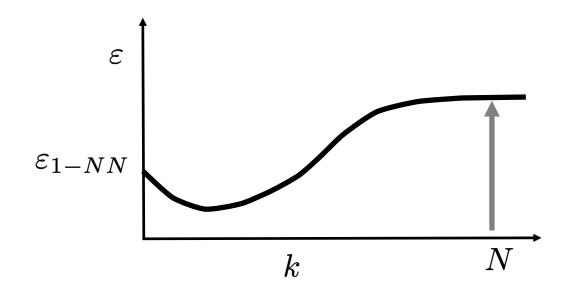






Choosing the value of k

- Selecting the value of k
 - set aside a portion of the training data (validation set)
 - vary k
 - Pick k that gives best generalization performance





K-nn resolving ties

Equal number of positive/negative neighbours?

- Resolving ties:
 - use odd k (doesn't solve multi-class)
 - breaking ties:
 - random: flip the coin to decide positive/negative
 - prior: pick class with greater prior
 - nearest: use 1-nn classifier to decide



Distance measures

- The key component of the kNN algorithm
 - defines which examples are similar and which aren't
 - can have strong effect on performance
- Euclidean (numeric features):

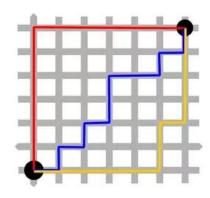
$$D(x, x') = \sqrt{\sum_{d} |x_{d} - x'_{d}|^{2}}$$



Distance measures

Manhattan distance

$$D(x,x') = \sum_{d} |x_d - x'_d|$$



- Hamming (categorical features):
 - number of features where x and x' differ

$$D(x, x') = \sum_{d} 1_{x_d \neq x'_d}$$

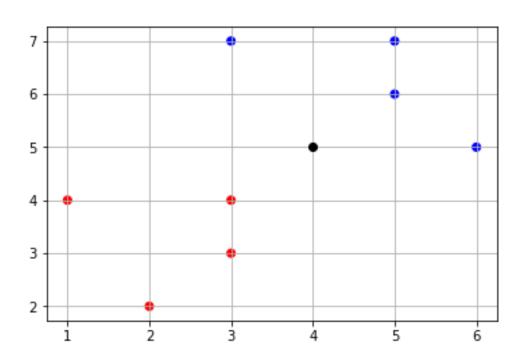
- Other (out of scope), eg.:
 - Kullback-Leibler (KL) divergence (for histograms)
 - Custom distance measures (BM25 for text)



K-nn example

- Given a labeled two-dimensional data set:
 - Red label: (1,4); (2,2); (3,3); (3,4);
 - Blue label: (3,7); (5,7); (5,6); (6,5);
- Predict the label of a new black point (4, 5) using 3-nn classifier with Manhattan distance.

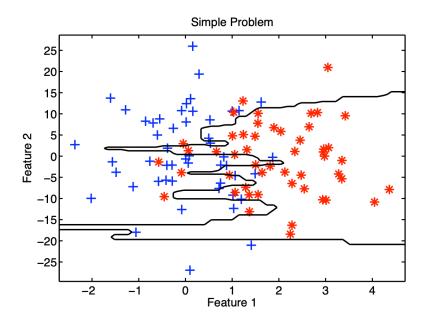
- A. Red label
- B. Blue label

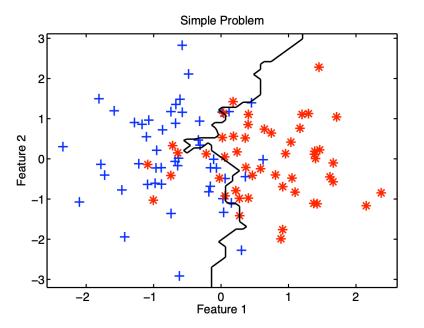




Sometimes strange results

How is this possible?





Scale your features!



K-nn pros and cons

- Simple and flexible classifiers
- Often a very good classification performance
- It is simple to adapt the complexity of the classifier

- Relatively large training sets are needed
- The complete training set has to be stored
- Distances to all training objects have to be computed
- The features have to be scaled sensibly
- The value for k has to be optimized



Naïve Bayes Classifier



Recap Bayes classifer

- For classification we need p(y|x)
- We can use Bayes' theorem if we can estimate p(y) and p(x|y)

$$p(y|x) = \frac{p(x|y)p(y)}{p(x)}$$

 Assigning an object to the class with the maximum posterior probability gives the Bayes' classifier

$$p(x|y_1)p(y_1) > p(x|y_2)p(y_2)$$



Warming up question

- Suppose we have trained a generative model and now get a new test example x. Our model tells us that: $p(x|y_0) = 0.01$, $p(x|y_1) = 0.03$ and $p(y_0) = p(y_1) = 0.5$
- What is $p(y_1|x)$?
 - A. 0.015
 - B. 0.25
 - C. 0.75
 - D. Insufficient information to compute. We also need to know the p(x).



Solution

•
$$p(y_1|x) = \frac{p(x|y_1)p(y_1)}{p(x)}$$

•
$$p(x) = p(x|y_1)p(y_1) + p(x|y_0)p(y_0)$$

•
$$p(y_1|x) = \frac{0.03*0.5}{0.03*0.5+0.01*0.5} = 0.75$$



Density estimation

 So, we want to estimate a class conditional probability density function:

Typically, each feature vector x has many features:

$$p(x|y) = p(x_1, x_2, x_3, x_4, ..., x_d|y)$$

 To estimate this joint pdf (conditional on the class), we need LOTS of data... (curse of dimensionality)



Naive Bayes: conditional independence assumption

- We make a strong assumption: all features are independent
- We assume conditional independence given y
- We just estimate $p(x_i|y)$ per feature and multiply them.

$$p(x|y) = p(x_1, x_2, x_3, x_4, ..., x_d|y) = \prod_{i=1}^{d} p(x_i|y)$$

= $p(x_1|y)p(x_2|y) ... p(x_d|y)$

No curse of dimensionality!



Conditional independence example

- We assume conditional independence of two variables given a third variable.
- Example: probablity of going to the beach and having a heartstroke may be independent if we know the wheather is hot

$$p(B,S|H) = p(B|H)p(S|H)$$

- Hot weather "explains" all the dependence between beach and heartstroke
- In classification: class value explains all the dependence between features



Naive Bayes: conditional independence assumption

- We make a strong assumption: all features are independent
- We assume conditional independence given y
- We just estimate $p(x_i|y)$ per feature and multiply them.

$$p(x|y) = p(x_1, x_2, x_3, x_4, ..., x_d|y) = \prod_{i=1}^d p(x_i|y)$$

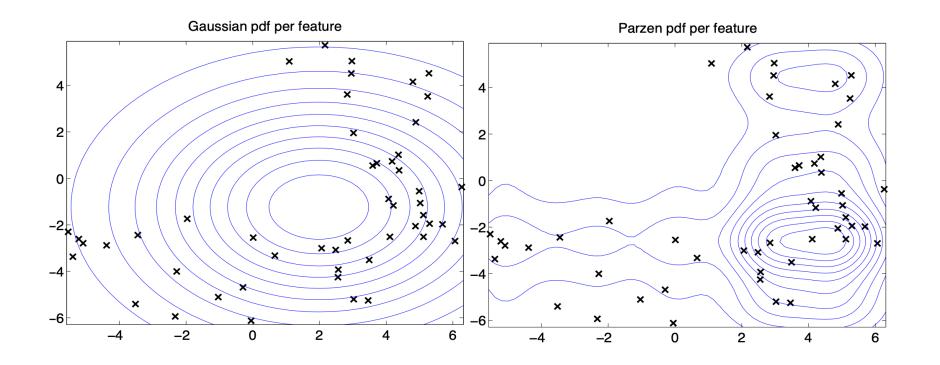
= $p(x_1|y)p(x_2|y) ... p(x_d|y)$

No curse of dimensionality!



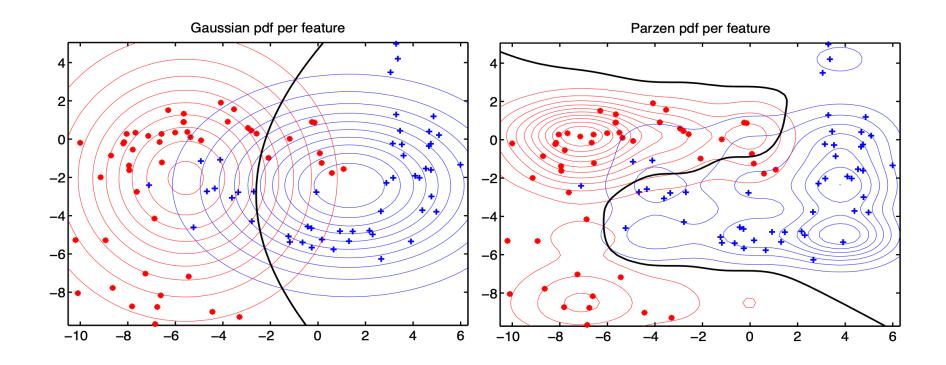
Parametric vs. non-parametric

• You still have to choose a model for $p(x_i|y)$





Naive Bayes classifier





Continuous data example

- Distinguish children from adults based on size
 - Classes: $y = \{a, c\}$, features: $x = \{height (cm), weight (kg)\}$
 - Training examples: 4 adults, 12 children
- Class probabilities $p(a) = \frac{4}{4+12} = 0.25, p(c) = 0.75$
- Model for adults:
 - Assume height and weight are independent
 - Height, estimate Gaussian with mean, variance

$$\begin{cases} \mu_{h,a} = \frac{1}{4} \sum_{i:y_i = a} h_i \\ \sigma_{h,a}^2 = \frac{1}{4} \sum_{i:y_i = a} (h_i - \mu_{h,a})^2 \end{cases}$$

- Weight, estimate Gaussian $(\mu_{w,a}, \sigma_{w,a}^2)$
- Model for children: use $(\mu_{h,c}, \sigma_{h,c}^2)$, $(\mu_{w,c}, \sigma_{w,c}^2)$



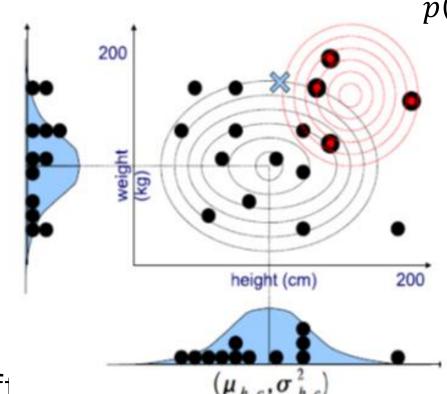
Continuous example

$$p(w|a) = \frac{1}{\sqrt{2\pi\sigma_{w,a}^2}} exp - (\frac{w - \mu_{w,a}^2}{2\sigma_{w,a}^2})$$

$$p(h|a) = \frac{1}{\sqrt{2\pi\sigma_{h,a}^2}} exp - (\frac{h - \mu_{h,a}^2}{2\sigma_{h,a}^2})$$

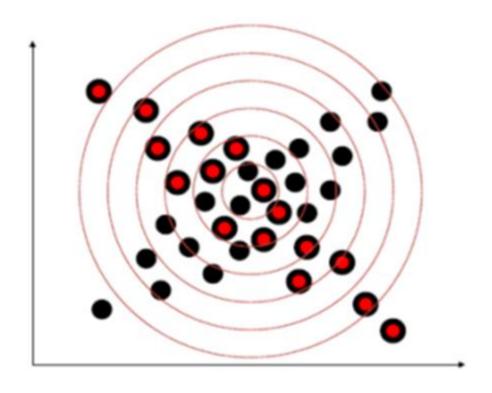
$$p(x|a) = p(w|a)p(h|a)$$

$$p(a|x) = \frac{p(x|a)p(a)}{p(x)}$$



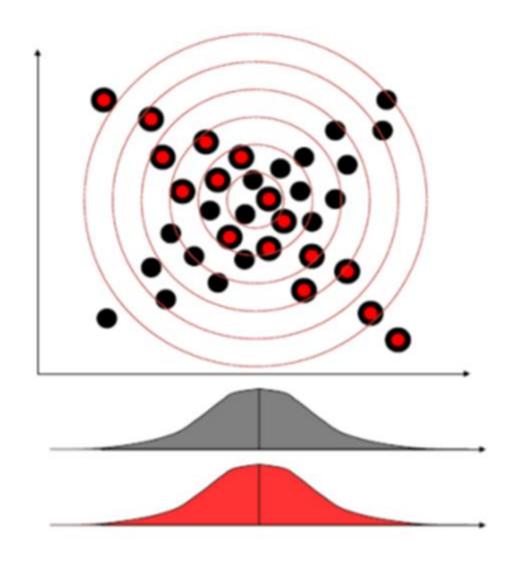


Problem with Naive Bayes



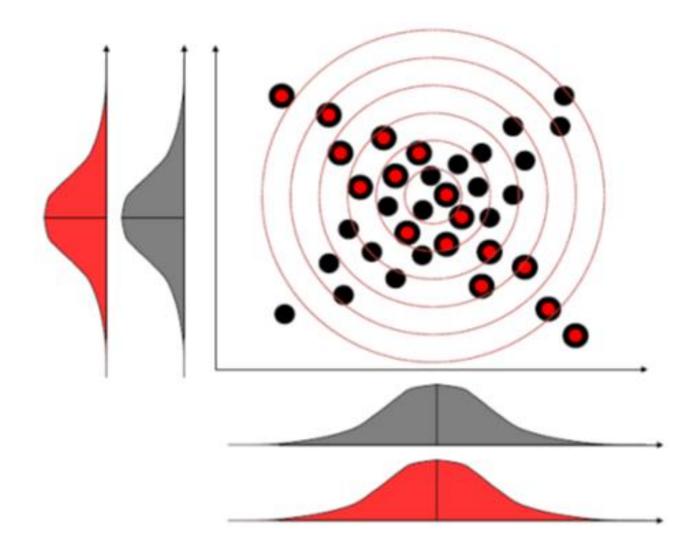


Problem with Naive Bayes





Problem with Naive Bayes





Discrete example

Separate spam from valid email (features = words)

D1: "send us your password"	spam
D2: "send us review"	valid
D3: "review your password"	valid
D4: "review us"	spam
D5: "send your password"	spam
D6: "send us your account"	spam

p(spam) = 4/6 p(valid) = 2/6				
	spam	valid		
Password	2/4	1/2		
Review	1/4	2/2		
Send	3/4	1/2		
Us	3/4	1/2		
Your	3/4	1/2		
Account	1/4	0/2		

New email "review us now"



Discrete example

- New email: "review us now"
- p("review us"|spam) = $p([0, 1, 0, 1, 0, 0]|spam) = (1 \frac{2}{4})(\frac{1}{4})(1 \frac{3}{4})(\frac{3}{4})(1 \frac{3}{4})(1 \frac{1}{4}) = 0.0044$

• p("review us"|valid) =
$$p([0, 1, 0, 1, 0, 0]|valid) = \left(1 - \frac{1}{2}\right)\left(\frac{2}{2}\right)\left(1 - \frac{1}{2}\right)\left(\frac{1}{2}\right)\left(1 - \frac{1}{2}\right)\left(1 - \frac{0}{2}\right) = 0.0625$$



p(spam) = 4/6 p(valid) = 2/6

Password

Review

Send

Us

spam

2/4

1/4

3/4

3/4

3/4

1/4

valid

1/2

2/2

1/2

1/2

1/2

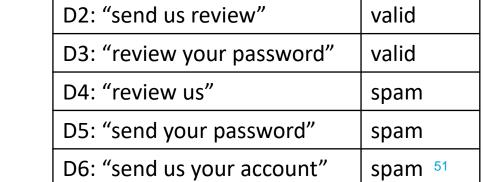
0/2

Solution

- p("review us"|spam) = 0.0044
- p("review us"|valid) = 0.0625

p(spam) = 4/6 p(valid) = 2/6				
	spam	valid		
Password	2/4	1/2		
Review	1/4	2/2		
Send	3/4	1/2		
Us	3/4	1/2		
Your	3/4	1/2		
Account	1/4	0/2		

- p("review us"|spam)p(spam) = 0.0044 * 4/6 = 0.0029
- p("review us"|valid)p(valid) = 0.0625 * 2/6 = 0.02
- Note: identical example!



spam

D1: "send us your password"



Zero frequency problem

 No email containing "account" is valid p("account"|valid) = 0/2

p(spam) = 4/6 p(valid) = 2/6				
	spam	valid		
Password	2/4	1/2		
Review	1/4	2/2		
Send	3/4	1/2		
Us	3/4	1/2		
Your	3/4	1/2		
Account	1/4	0/2		

- Solution: never allow zero probabilities
 - Laplace smoothing: add a small positive number to the counts (K-> number of classes)

$$p(w|c) = \frac{num(w,c) + \varepsilon}{num(c) + K\varepsilon}$$



Fooling Naive Bayes

- Every word contributes independently to p(spam|email)
- Add lots of valid words into spam email.



Naive Bayes pros and cons

- Can handle high dimensional feature spaces
- Can't deal with correlated features

- Fast training time
- Can handle continuous and discrete data



Exercise Naive Bayes

 Predict if Bob will default his loan

Bob:

Homeowner: no

Maritial status: married

Job experience: 3

Home owner	Maritial status	Job experience	Deafulted
Yes	Single	3	No
No	Married	4	No
No	Single	5	No
Yes	Married	4	No
No	Divorced	2	Yes
No	Married	4	No
Yes	Divorced	2	No
No	Married	3	Yes
No	Married	3	No
Yes	Single	2	Yes



After practicing with the concepts of this lecture you should be able to:

- Explain the difference between parametric and non-parametric density estimation
- Explain Parzen, k-Nearest Neighbour and Naïve Bayes density estimation and classification in detail.
- Explain the advantages and disadvantages of those methods.
- Implement k-nn classifier in Python

