

# Algorithms & Data Structures II

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## Introduction to Dynamic Programming

### Weighted Interval Scheduling

*The idea:* Sort by finish time and select

$\text{OPT}(j) = \max(v[j] + \text{OPT}(p[j]), \text{OPT}(j-1))$ . Either you take job  $j$ , and skip conflicts, or don't take it. The algorithm runs in  $O(n \log n)$  time, where  $n$  is the number of jobs.

### Knapsack

*The problem:* Fill a backpack with as many books as possible.  $\text{OPT}(i, w) = \max(\text{OPT}(i-1, w), v[i] + \text{OPT}(i-1, w - w[i]))$ . The option is to take an item  $i$  or not and the algorithm runs in  $O(nW)$  time, where  $n$  is the number of items and  $W$  is knapsack capacity. The algorithm creates a 2D table consisting of  $n \times W$

### Sequence Alignment

*The problem:* Match characters, gap in  $X$ , or gap in  $Y$ . The running time of this algorithm is

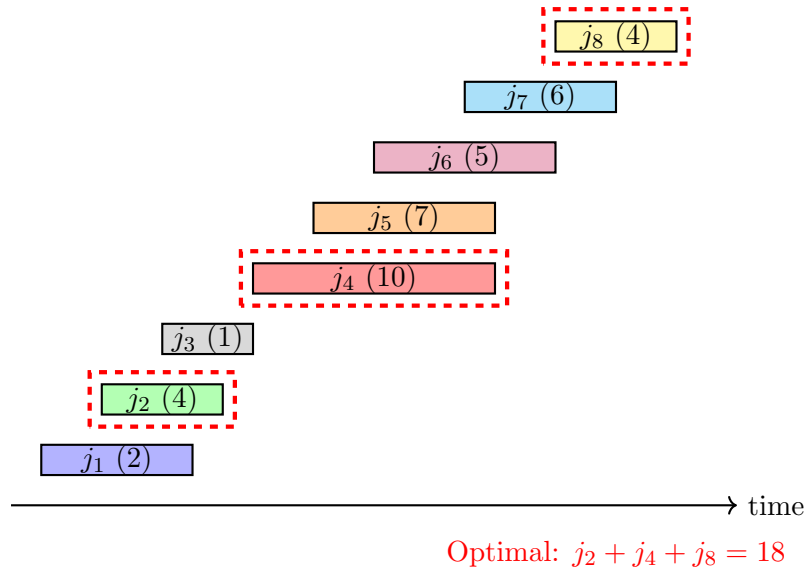


Figure 1: Weighted Interval Scheduling Example: Jobs are sorted by finish time. The optimal solution selects non-overlapping jobs with maximum total value.

## Max Flow & Min Cut

### Flow Algorithms

Name	Running Time	Explanation	Notes
Ford-Fulkerson	$O( f  \cdot m)$	$ f $ = max flow value $m$ = # edges	Pseudopolynomial; can fail to terminate
Scaling	$O(m^2 \log C)$	$C$ = max edge capacity	Weakly polynomial; assumes integer capacities
Edmonds-Karp	$O(m^2 n)$	$n$ = # vertices $m$ = # edges	Uses BFS; strongly polynomial

### Running the algorithms

When running the algorithms by hand, just use a basic approach—it's manageable when the graph is reasonably simple. For min-cut, find the saturated edges (at capacity) along the residual graph boundary between reachable and unreachable vertices from the source.

## Flow Problem Recipe

### Build the Graph

- Vertices (source + sink)
- Edges (capacities + direction)

### Describe the Algorithm

- Find max flow ( $m$ ) and INSERT ALGORITHM
- Return an answer

## Analyse Runtime

- Build Parameters from question
- Remember the time it takes to build the graph

## Randomised Algorithms

### Expected Value

Expected value is the average outcome over many trials. For a discrete random variable  $X$ :

$$\mathbb{E}[X] = \sum_i x_i \cdot \mathbb{P}[X = x_i]$$

**Common trick:** Use indicator random variables. If  $X = X_1 + X_2 + \dots + X_n$  where each  $X_i$  is an indicator (0 or 1), then:

$$\mathbb{E}[X] = \sum_{i=1}^n \mathbb{E}[X_i] = \sum_{i=1}^n \mathbb{P}[X_i = 1]$$

**Geometric distribution:** If success probability is  $p$ , then expected number of trials until first success is  $\frac{1}{p}$ .

**Example - QuickSort:** Let  $X_{ij}$  be an indicator that equals 1 if elements  $i$  and  $j$  are compared, 0 otherwise. Total comparisons:

$$X = \sum_{i < j} X_{ij} \implies \mathbb{E}[X] = \sum_{i < j} \mathbb{E}[X_{ij}] = \sum_{i < j} \mathbb{P}[i \text{ and } j \text{ compared}]$$

Elements  $i$  and  $j$  are compared if one is chosen as pivot before any element between them, so  $\mathbb{P}[i \text{ and } j \text{ compared}] = \frac{2}{j-i+1}$ . Summing gives  $\mathbb{E}[X] = O(n \log n)$ .

### Useful Sums

$$\sum_{n=0}^{\infty} x^n = \frac{1}{1-x}, \quad |x| < 1$$

$$\sum_{n=0}^{\infty} n \cdot x^n = \frac{x}{(1-x)^2}, \quad |x| < 1$$

$$\sum_{k=1}^n \frac{1}{k} = H(n), \quad \ln(n) < H(n) < \ln(n) + 1$$

$$\mathbb{P}[\text{first success in round } j] = (1-p)^{j-1}p$$

$$\mathbb{E}[X] = \sum x_i \cdot \mathbb{P}[X = x_i] \quad \text{where } x_i \in \text{possible outcomes}$$

$$\mathbb{E}[X + Y] = \mathbb{E}[X] + \mathbb{E}[Y]$$

$$\text{if } \mathbb{P}[\text{success}] = p \text{ then } \mathbb{E}[\# \text{ tries to success}] = \frac{1}{p}$$

## Hashing

### Chained Hashing

Store elements in array of linked lists. Each element  $x$  goes to list at  $A[h(x)]$ . Operations take  $O(|A[h(x)]| + 1)$  time. With universal hashing, expected  $O(1)$  time per operation.

## Linear Probing

Store elements directly in array. If  $A[h(x)]$  is occupied, place  $x$  in next empty slot (wrapping around). Forms clusters of consecutive elements. Operations take  $O(C(h(x)) + 1)$  time where  $C(i)$  is cluster size. Cache-efficient but DELETE is  $O(n^2)$ .

## Hash Functions

**Universal hashing:** Family  $H$  is universal if for any  $x \neq y$ ,  $\Pr[h(x) = h(y)] \leq \frac{1}{m}$  for random  $h \in H$ .

**Dot product hashing:** For  $x = (x_1, x_2, \dots, x_r)$  in base  $m$  (prime), define

$$h_a(x) = (a_1x_1 + a_2x_2 + \dots + a_rx_r) \bmod m$$

where  $a = (a_1, \dots, a_r)$  chosen randomly. This family is universal.

## Performance Comparison

Data Structure	SEARCH	INSERT	DELETE	Space
Linked List	$O(n)$	$O(n)$	$O(n)$	$O(n)$
BBST	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(n)$
Direct Addressing	$O(1)$	$O(1)$	$O(1)$	$O( U )$
Chained Hashing (universal)	$O(1)^*$	$O(1)^*$	$O(1)^*$	$O(n)$
Linear Probing	$O(C(h(x)) + 1)$	$O(C(h(x)) + 1)$	$O(n^2)$	$O(n)$

\* Expected time (when using universal hash function)