

Mean Field Approximation for Interaction Models

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1 Introduction

- General Setting & Introductory Example
- Motivation
- The Mean Field Idea

2 Heterogeneous Interaction Model

- Framework
- Accuracy Results
- Mean Field Refinements

3 Implementations

- Numerical Toolbox

4 Conclusion

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General Setting

- population n **interacting objects** which have (countably many) **states** \mathcal{S}
- object **interactions are stochastic**
- naturally described by $\mathbf{S}^{(n)}(t) = (S_1(t), \dots, S_n(t)) \in \mathcal{S}^n$ (continuous time process)
- $S_k(t) \sim$ state of object k at time t

Many modeling possibilities

load balancing, epidemic modeling, caching, communication protocols, SSD garbage collection, malware propagation, ...

Example: Power-of-2-choice model (JSQ(2))

How to allocate jobs in large server farms?

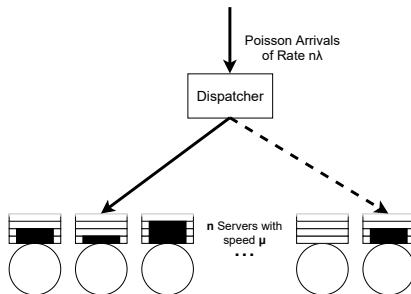
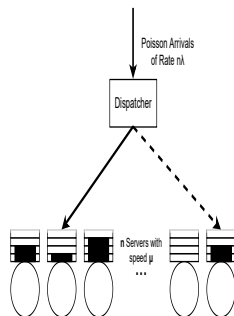


Figure: Power-of-2-choice - introduced by Mitzenmacher in 2001

a simple, effective distribution scheme
can be studied by using the mean field approximation

Example: Power-of-2-choice model (JSQ(2))



$S_i(t) \sim$ number of jobs in queue

- arrival rate $n\lambda$ (λ per server, < 1)
- dispatcher univ. and independently sam
- job added to shorter queue
(equality broken at random)
- server service rate $\mu = 1$

Mean Field Approximation

Goal: want to analyze transient and steady state behavior of the system

Problems:

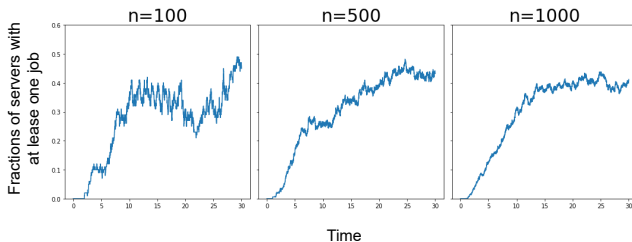
- exponentially growing state space \mathcal{S}^n
- predictions by simulation can be inefficient / inaccurate

Mean Field Approximation can help.

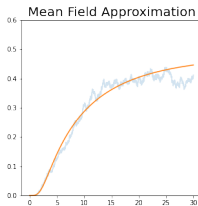
Examples

load balancing, epidemic modeling, caching, communication protocols, SSD garbage collection, malware propagation, ...

Mean Field Idea



$\downarrow \quad n \rightarrow \infty$



How to obtain the mean field limit?

Alternative system representations

$S^{(n)}(t)$ with $S_k^{(n)}(t) \in \mathcal{S}$, $k = \{1 \dots n\}$

$X^{(n)}(t)$ with $X_{k,s}^{(n)}(t) = \mathbf{1}_{\{S_k^{(n)}(t)=s\}}$, $k = \{1 \dots n\}$, $i \in \mathbb{N}$

$Z^{(n)}(t)$ with $Z_s^{(n)}(t) = \frac{1}{n} \sum_{k=1}^n X_{k,s}^{(n)}(t) = \frac{1}{n} \sum_{k=1}^n \mathbf{1}_{\{S_k^{(n)}(t)=s\}}$, $i \in \mathbb{N}$

all are continuous time Markov chains

for Z we use homogeneity (similar statistical behavior of objects) to simplify

How to obtain the mean field limit?

Alternative system representations

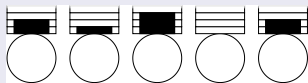
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all are continuous time Markov chains

for Z we use homogeneity (similar statistical behavior of objects) to simplify



$$\rightarrow Z(t) = (0.2, 0.4, 0.2, 0.2, 0, \dots)$$

- arrival rate $n\lambda$ (λ per server, < 1)
- dispatcher univ. and independently samples two servers
- job added to shorter queue
(equality broken at random)
- server service rate $\mu = 1$

Transitions

Arrivals: $Z \rightarrow Z + \frac{1}{n}e_i - \frac{1}{n}e_{i-1}$ at rate $n\lambda((\sum_{j \geq i-1} Z_j)^2 - (\sum_{j \geq i} Z_j)^2)$

Removals: $Z \rightarrow Z + \frac{1}{n}e_{i-1} - \frac{1}{n}e_i$ at rate $n\mu Z_i$

How to obtain the mean field limit?

Drift

For a given **state** x the drift is (informally) given by

$$\sum_y \left(x \begin{array}{c} \nearrow \\ y \end{array} \right) \times p(x \rightarrow y) =: \underbrace{f(x)}_{\text{drift of the system}}$$

More formally, we look at

$$f(\mathbf{z}) = \lim_{dt \rightarrow 0} \frac{1}{dt} \mathbb{E} [\mathbf{Z}(t + dt) - \mathbf{Z}(t) \mid \mathbf{Z}(t) = \mathbf{z}].$$

How to obtain the mean field limit?

Drift of the the JSQ(2) model:

$$\begin{aligned}f_i(\mathbf{z}) &= \mu z_{i+1} + \lambda \left(\left(\sum_{j \geq i-1} z_j \right)^2 - \left(\sum_{j \geq i} z_j \right)^2 \right) \\&\quad - \mu z_i - \lambda \left(\left(\sum_{j \geq i} z_j \right)^2 - \left(\sum_{j \geq i+1} z_j \right)^2 \right), \quad i \geq 1 \\f_0(\mathbf{z}) &= \mu z_1 - \lambda \left(\left(\sum_{j \geq 0} z_j \right)^2 - \left(\sum_{j \geq 1} z_j \right)^2 \right)\end{aligned}$$

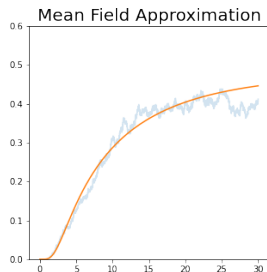
Mean Field Approximation

Solution to the initial value problem (IVP):

$$\dot{\mathbf{z}}(t) = f(\mathbf{z}), \quad \mathbf{z}(0) = \mathbf{Z}(0)$$

Accuracy homogeneous case / known results

- $\sup_{s \leq t} \|Z^{(n)}(s) - z(s)\| \xrightarrow{n \rightarrow \infty} 0$ in probability ¹
- $\mathbb{E} [\|Z^{(n)}(s) - z(s)\|] = O(\frac{1}{\sqrt{n}})$
- $\mathbb{E} [Z^{(n)}(s)] - z(s) = O(\frac{1}{n})$



- same reasoning can be broadly applied
- results generalize to populations of n identical / homogeneous objects (use occupancy measure to describe system)

¹($\forall \epsilon > 0 \mathbb{P}(|Z^{(n)} - Z| > \epsilon) \rightarrow 0$)

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What can we say if objects are heterogeneous?*

* i.e. servers have different speeds,
people are more susceptible / recover faster,
cache objects have varying popularity

Classical Approach

- consider a finite and fixed number of classes C
- within each class $c \in C$ objects have identical behavior
- use mean field approach by letting the numbers of objects n_c of each class tend to infinity

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What if all objects have differing behavior (true heterogeneity)?

The Heterogeneous Framework

- n **interacting objects** which have (finitely many) **states** \mathcal{S}
- object **interactions are stochastic**
- described by $S^{(n)}(t) = (S_1(t), \dots, S_n(t)) \in \mathcal{S}^n$ (continuous time process)
- $S_k(t) \sim$ state of object k at time t
- can still use $X_{(k,s)}(t) = \mathbf{1}_{\{S_k(t)=s\}}$ to represent the system
- $Z(t) = (\frac{1}{n} \sum_k X_{k,s}(t))_s$ does not capture state of single objects

Heterogeneous Power-of-2-choice (JSQ(2)) model

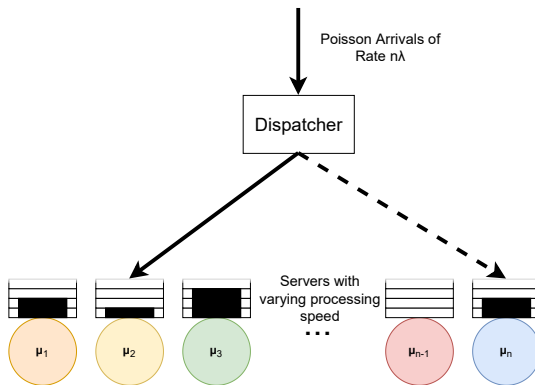
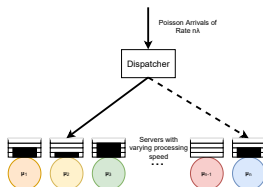


Figure: Power-of-2-choice model with differing server rates.

Transitions



$$\mathbf{X} \mapsto \mathbf{X} - e_{(k,i)} + e_{(k,i-1)}$$

at rate $\mu_k X_{(k,i)}$ (unilateral)

$$\mathbf{X} \mapsto \mathbf{X} + e_{(k,i+1)} - e_{(k,i)}$$

at rate $\lambda X_{(k,i)} \left(\sum_k \sum_{j \geq i} \frac{X_{(k,j)}}{n} + \sum_k \sum_{j \geq i+1} \frac{X_{(k,j)}}{n} \right)$

(pairwise)

Definition of the Mean Field

The drift is

$$f(\mathbf{X}(t)) = \lim_{dt \rightarrow 0} \frac{1}{dt} \mathbb{E} [\mathbf{X}(t + dt) - \mathbf{X}(t) \mid \mathbf{X}(t) = \mathbf{x}]$$

- f can be expressed in unilateral and pairwise transition terms
- entries of f are polynomials

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- f can be expressed in unilateral and pairwise transition terms
- entries of f are polynomials
- mean field approximation is solution to the IVP:

$$\frac{d}{dt} \mathbf{x}(t) = f(\mathbf{x}(t)); \quad \mathbf{x}(0) = \mathbf{X}(0)$$

Assumptions

Existence of uniform bound \bar{r} independent of system size n for transition rates (unilateral, pairwise, ...).

By definition, the drift is a polynomial of degree d and the mean field lies in some compact set $\subset [0, 1]^{n \times S} \rightarrow$ drift is Lipschitz

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Existence of uniform bound \bar{r} independent of system size n for transition rates (unilateral, pairwise, ...).

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Accuracy

For the mean field approximation $\mathbf{x}(t)$ we have

$$\mathbb{P}(S_k(t) = s) = \mathbb{E}[X_{(k,s)}(t)] = x_{(k,s)}(t) + O(1/n)$$

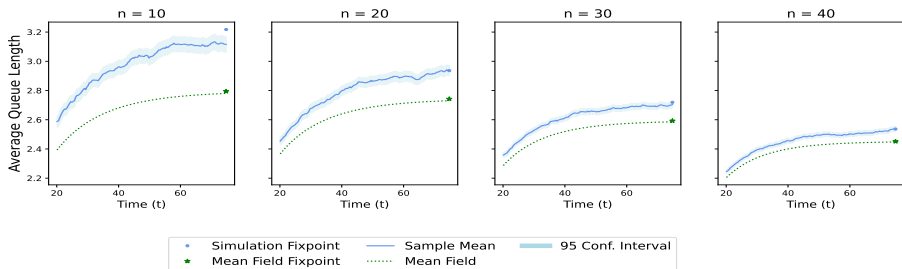


Figure: Average queue size; sample mean vs. mean field approximation vs. refined mean field approximation.

Idea of the Proof

- want to study $\mathbb{E} [X_{(k,s)}(t)] - x_{(k,s)}(t)$ by relating the generators of the stochastic system and ODE
- define $\psi(\tau) = \mathbb{E} [\mathbf{x}(\mathbf{X}(\tau), t - \tau)]$ with $\mathbf{x}(\mathbf{X}(\tau), t - \tau)$ the mean field approximation starting in $\mathbf{X}(\tau)$
- rewrite $\mathbb{E}[\mathbf{X}(t) - \mathbf{x}(\mathbf{X}(0), t)] = \psi(t) - \psi(0)$
- justify $\psi(t) - \psi(0) = \int_0^t \frac{d}{ds} \psi(s) ds$ and bound $\frac{d}{ds} \psi(s)$

Refinement

Possible to define a **refinement term** $\mathbf{v}(t)$ following the ideas of [Gast, Van Houdt] [Gast et al.] to **increase accuracy**.

We call $\mathbf{x}(t) + \mathbf{v}(t)$ the refined mean field.

Increased Accuracy

$$\mathbb{P}(S_k(t) = s) = \mathbb{E}[X_{(k,s)}(t)] = x_{(k,s)}(t) + v_{(k,s)}(t) + O(1/n^2)$$

Proof Idea

- follows similar idea as for mean field
- use equality $\mathbb{E}[\mathbf{X}(t) - \mathbf{x}(\mathbf{X}(0), t)] = \psi(t) - \psi(0) = \int_0^t \frac{d}{ds} \psi(s) ds$
- look at $\mathbb{E}[\mathbf{X}(t) - \mathbf{x}(\mathbf{X}(0), t)] - \mathbf{v}(\mathbf{X}(0), t) = \int_0^t \frac{d}{ds} \psi(s) - \frac{d}{ds} v(s) ds$

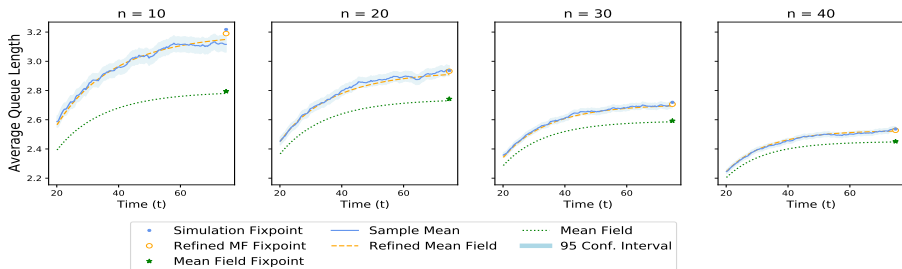


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rmf_tool – A library to Compute (Refined) Mean Field Approximation(s)

Model Implementation

```
In [2]: import rmf_tool.src.rmf_tool as rmf

# This code creates an object that represents a "density dependent population process"
ddpp = rmf.DDPP()

# Set parameters
mu, _lambda, K = 1.0, 0.9, 9

In [4]: # Add transitions using mathematical formulation:
for i in range(K):
    if i >= 1:
        ddpp.add_transition(e(i), eval('lambda x: _lambda*(x[{}]*x[{}]) - x[{}]*x[{}]').format(i-1,i-1,i,i)) # arrivals
    if i < K-1 and i > 0:
        ddpp.add_transition(-e(i), eval('lambda x: mu*(x[{}]) - x[{}]').format(i,i+1)) # removals
```

Supports Density Dependent Population Processes & heterogeneous Framework

²https://github.com/ngast/rmf_tool

```
In [15]: # Set initial state
ddpp.set_initial_state(e(0))

# Calculate mean field
T, x_transient = ddpp.ode(time=30)
```

```
In [16]: # Simulate a trajectory for N=50
T_n50, X_n50 = ddpp.simulate(N=50, time=30)
# and for N=1000
T_n1k, X_n1k = ddpp.simulate(N=1000, time=30)
```



Allows to easily obtain (for transient and steady state):
mean field, refined mean field approximation, simulations

³https://github.com/ngast/rmf_tool

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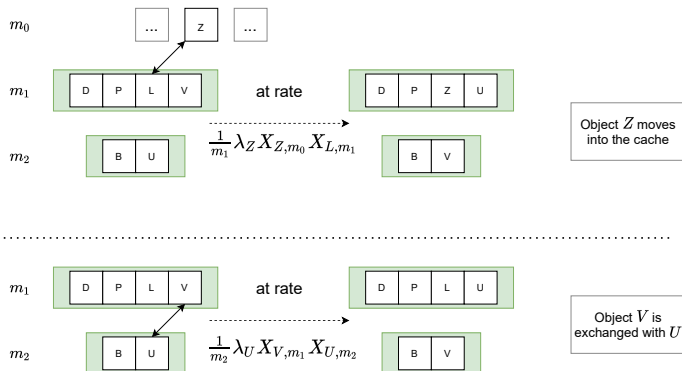
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- historically used for homogeneous and partially heterogeneous systems
- can be applied to fully heterogeneous (population) interaction models

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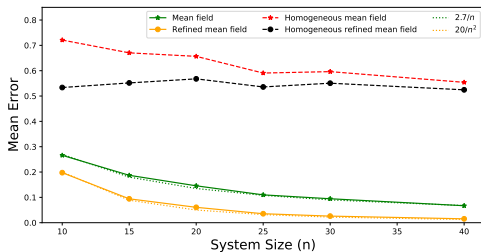
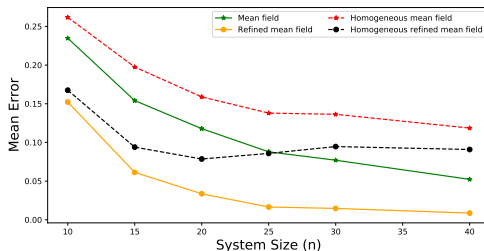
Thank you!

A Caching Example

Requests for object k arrive according to a Poisson process with intensity λ_k



Comparison of homogeneous and heterogeneous approximations



$$\dot{v}_{(k_1, s_1)}(t) = \sum_{u \in \mathcal{I}} \frac{\partial f_{(k_1, s_1)}}{\partial x_u}(\mathbf{x}(t)) v_u(t) + \frac{1}{2} \sum_{u, l \in \mathcal{I}} \frac{\partial^2 f_{(k_1, s_1)}}{\partial x_l \partial x_u}(\mathbf{x}(t)) w_{u, l}(t),$$

$$\begin{aligned} \dot{w}_{(k_1, s_1), (k_2, s_2)}(t) &= \sum_{u \in \mathcal{I}} w_{u, (k_2, s_2)}(t) \frac{\partial f_{(k_1, s_1)}}{\partial x_u}(\mathbf{x}(t)) \\ &\quad + \sum_{u \in \mathcal{I}} w_{u, (k_1, s_1)}(t) \frac{\partial f_{(k_2, s_2)}}{\partial x_u}(\mathbf{x}(t)) + Q_{(k_1, s_1), (k_2, s_2)}(\mathbf{x}(t)), \end{aligned}$$

$$Q_{(k, s), (k_1, s_1)}(\mathbf{x}) = \lim_{dt \rightarrow 0} \frac{1}{dt} \mathbb{E} \left[(\mathbf{X}(t + dt) - \mathbf{X}(t))_{(k, s), (k_1, s_1)}^{\otimes 2} \mid \mathbf{X}(t) = \mathbf{x} \right]$$

References



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A Refined Mean Field Approximation. Proceedings of the ACM on Measurement and Analysis of Computing Systems 1, 2



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