Answers to Problem Set 5 Group name: Ferienspass

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1 Question 1

2 Question 2

```
close all;
   clear;
3
  clc;
   y_1 = 1.02;
5
  Var_{ln_eta} = (0.25)^2;
  Mu_ln_eta = -Var_ln_eta/2;
   y_2 = 1.06;
9
  n = 11;
                                                   %11
  [ln_eta,w]=qnwnorm(n,Mu_ln_eta,Var_ln_eta);
      Distribution of log(eta)
11
   eta=exp(w'*ln_eta);
                                                   %
      Expectation of eta
12
13
  14
15 \mid p_1 = y_1;
                                                   %
      Expected Payoff of Project 1
                                                   %
16
   p_2=y_2*eta;
      Expected Payoff of Project 2
17
18
   if p_1 < p_2
19
       disp('Project 2 yields the greater expected payoff
          .');
20
   elseif p_1 == p_2
       disp('Project 1 and project 2 yield the same
21
          expected payoff.');
22
   else
23
       disp('Project 1 yields the greater expected payoff
          .');
```

```
24 | end
25
26
  27
28
   gamma = 1.5;
29
  |u_1| = utility(y_1, gamma);
31
   u_2 = w'*utility(exp(ln_eta)*y_2,gamma);
32
   if u_1 < u_2</pre>
34
       disp('Household will prefer to invest in project
           2.');
   \verb"elseif" u_1 == u_2
       disp('Household will be indifferent betwee project
36
            1 and project 2.');
37
38
       disp('Household will prefer to invest in project
           1.');
39
   end
40
41
   \%%%%%%%%%%%%%%% Question 3 %%%%%%%%%%%%%%%%%%%%
42
43
                                                     %Gamma
   gamma = linspace(0,3,100);
       is now a vector of different values (for plotting
      only)
  y_2 = [1.06 \ 1.1];
45 | u_1=nan(1,100);
46 | u_2=nan(1,100);
47 | difference = nan(2,100);
48 | %Plot intersection point
49 | figure('Name', 'PS5Q2Sub3_Utility')
50 for j=1:2
51 | for i=1:100
  | u_1(1,i) = utility(y_1,gamma(1,i));
  u_2(1,i) = w'*utility(exp(ln_eta)*y_2(1,j),gamma(1,i))
54
  difference(j,i) = u_2(1,i)-u_1(1,i);
55
56
  [Min,Index] = min(abs(difference(j,:)));
57
  subplot(2,1,j)
  plot(gamma,u_1,gamma,u_2,gamma,difference(j,:))
  line([min(gamma), max(gamma)], [0,0], 'Color', 'red', '
      LineStyle','--')
   line([gamma(1,Index),gamma(1,Index)],[0,u_2(1,Index)])
62 | title(['With y_2 = ', num2str(y_2(1,j))])
```

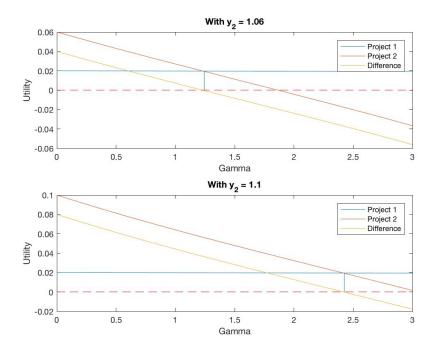
```
63 | legend('Project 1', 'Project 2', 'Difference')
  xlabel('Gamma')
65 | ylabel('Utility')
66
  end
67
68
  figure('Name', 'PS5Q2Sub3_Quad_Diff')
  plot (gamma, (difference(1,:)).^2, gamma, (difference
       (2,:)).^2)
  title('Squared differnces')
71
   xlabel('Gamma')
  |ylabel('Difference in Utility')
73
74 | %Find intersection via grid search
  [Min1, Index1] = min(abs(difference(1,:)));
76
  [Min2, Index2] = min(abs(difference(2,:)));
77
78
  disp('As one can see clearly, changing y_2 changes the
        gamma at which both projects yield the same
       expected utility.');
   fprintf(['\n In the first plot, gamma = ', num2str(
       gamma(1,Index1)),' produced the smallest difference
       . \n For a value close to this, the household will
      be indifferent between the two projects, given y_2
      = 1.06 \n '] );
   fprintf(['\n In the second plot, gamma = ', num2str(
80
      gamma(1, Index2)), ' produced the smallest difference
       . 

 \n For a value close to this, the household will
      be indifferent between the two projects, given y_2
      = 1.1 \n']);
81
  |%Find intersection point numerically using Newton.
       This is equal to finding
   %the gamma for which the difference is equal to zero
       --> Root finding Problem
84
  params = [ln_eta; w; y_1; y_2(1,1)];
  f = @(x) Utility_Difference(x,params);
  y = [1 \ 2];
                                                     %
       initial guess
                                                     %
88
   cc = [0.1; 0.1; 1000];
      criteria
89
   y_sol_1=newton(f,y(1,1),cc);
90
91
  %More to come here!!
92
93 | %Newton
```

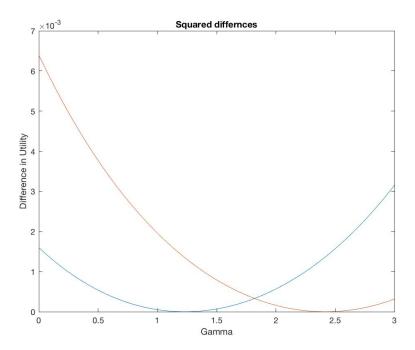
```
94 | function [x,fx,ef,iter] = newton(f,x,cc)
95
96
   % convergence criteria
97
   tole = cc(1,1); told = cc(2,1); maxiter = cc(3,1);
99
   % newton algorithm
100
   for j = 1:maxiter
        [fx,dfx] = f(x);
102
103
        xp = x - dfx fx;
104
        D = (norm(x-xp) \le tole*(1+norm(xp)) && norm(fx)
            <= told);
        if D == 1
105
106
             break;
107
        else
108
             x = xp;
109
        end
110
   end
111
    ef = 0; if D == 1; ef = 1; end
112
    iter = j;
113
    end
114
115
    %Function whose root if to be found
116
   function [fx,dfx] = Utility_Difference(x,y)
117
118
   weight = [y(1,1);y(2,1);y(3,1);y(4,1);y(5,1);y(6,1);y
        (7,1); y (8,1); y (9,1); y (10,1); y (11,1)];
    rv = [y(12,1); y(13,1); y(14,1); y(15,1); y(16,1); y(17,1); y
119
        (18,1); y(19,1); y(20,1); y(21,1); y(22,1)];
120
121
    y_1 = y(23,1);
122
    y_2=y(24,1);
123
124
   fx = utility(y_1,x) - weight'*utility(exp(rv)*y_2,x);
125
126
   dfx = derivate(y_1,x)-weight'*derivate(exp(rv)*y_2,x);
127
128
129
    end
130
   % Declare CRRA utility function
132
   function u= utility(x,gamma)
        if gamma == 1
134
             u = log(x);
135
        else
136
             u=(x.^(1-gamma)-1)./(1-gamma);
```

```
137
               disp(u);
138
         \verb"end"
     end
140
141
     function dgu = derivate(x,gamma)
142
         if gamma == 1
143
              dgu = 0.1; %Guess?
144
         else
             dgu = ((x.^(1-gamma)-1)-(x.^(1-gamma)-1).*(1-gamma)
145
                 gamma)-1)./((1-gamma).^2);
146
         end
147
148
     end
```

The approximate point where the household is indifferent between the two projects can be found via grid search. Graphically, the point where the two utility curves intersect in the point where the household becomes indifferent between the two projects. In both graphs, this point is marked by the vertical line going upwards from the horizontal line crossing through zero. Alternatively,



this point can also be found where the squared difference comes close to zero. However, for a truly satisfying result, grid search is not sufficient. The root of the difference function has to be found numerically. Here, the Newton algorithm is applied. For this, the first derivative with respect to γ has to be computed.



Since this is possible analytically, the derivation is provided below.

$$u(c_t) = \frac{c_t^{1-\gamma} - 1}{1-\gamma} = \frac{c_t^{1-\gamma}}{1-\gamma} - \frac{1}{1-\gamma}$$

$$= \frac{e^{(1-\gamma)\ln(c_t)}}{1-\gamma} - \frac{1}{1-\gamma}$$
(2)

$$=\frac{e^{(1-\gamma)\ln(c_t)}}{1-\gamma}-\frac{1}{1-\gamma}\tag{2}$$

The first derivative with respect to γ can then be calculated:

$$\frac{\partial u(c_t)}{\partial \gamma} = \frac{(-1)e^{(1-\gamma)\ln(c_t)}(1-\gamma) - (-1)e^{(1-\gamma)\ln(c_t)}}{(1-\gamma)^2} - \frac{0 - (-1) * 1}{(1-\gamma)^2} \qquad (3)$$

$$= \frac{e^{(1-\gamma)\ln(c_t)} - e^{(1-\gamma)\ln(c_t)}(1-\gamma)}{(1-\gamma)^2} - \frac{1}{(1-\gamma)^2}$$

$$= \frac{e^{(1-\gamma)\ln(c_t)} - e^{(1-\gamma)\ln(c_t)}(1-\gamma) - 1}{(1-\gamma)^2}$$
(5)

$$= \frac{e^{(1-\gamma)\ln(c_t)} - e^{(1-\gamma)\ln(c_t)}(1-\gamma)}{(1-\gamma)^2} - \frac{1}{(1-\gamma)^2}$$
(4)

$$= \frac{e^{(1-\gamma)\ln(c_t)} - e^{(1-\gamma)\ln(c_t)}(1-\gamma) - 1}{(1-\gamma)^2}$$
 (5)

$$=\frac{c_t^{1-\gamma} - c_t^{1-\gamma}(1-\gamma) - 1}{(1-\gamma)^2} \tag{6}$$

(7)

Which can be used for the calculation of the Newton Algorithm. In the case

that γ = 1

$$\frac{\partial u(c_t)}{\partial \gamma} = \frac{\partial \ln c_t}{\partial \gamma} = 0. \tag{8}$$

(9)