# LASER WAKEFIELD ACCELERATION: Studies using Particle in Cell Method

Master Thesis

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#### Outline

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# Introduction

- The aim of this thesis is to investigate the interaction of high power laser pulses with solid and gaseous targets.
- The fundamentals of the Particle in Cell method are detailed.
- A method of accelerating electrons with very intense lasers is presented.

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**Classical Electrodynamics** 

## Maxwell's Equations

 The dynamics of the electromagnetic fields are given by Maxwell's Equations

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\varepsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} + \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t}$$

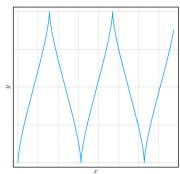
The dynamics of the charged particles are given by

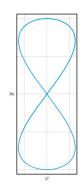
$$\begin{split} \frac{\mathrm{d}\mathbf{x}}{\mathrm{d}t} &= \mathbf{v} \\ \frac{\mathrm{d}\mathbf{v}}{\mathrm{d}t} &= \frac{q}{m} \left( \mathbf{E} + \mathbf{v} \times \mathbf{B} \right) \,. \end{split}$$

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## Electron in a plane wave

- In a plane wave a relativistic electron has a non-trivial oscillation.
- In a particular frame of reference, its motion looks like an 8.





#### The Ponderomotive force

- In a spatially uniform electric field an electron would oscillate around its equilibrium position (in a figure 8 pattern).
- If there is a spatial gradient of the field, a ponderomotive force will appear

$$F_p = -\frac{e^2}{4m\omega^2} \nabla \mathbf{E}^2$$

#### Laser Wakefield

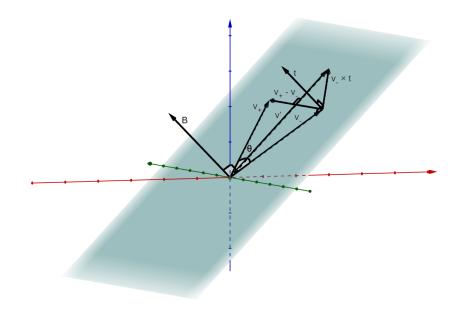
- When a high intensity laser propagates in plasma, the electric field pushes the electrons far away from their equilibrium position (via the ponderomotive force). This is known as the "blowout phase".
- This creates a high intensity field between the electrons and the nuclei left behind. Any charged particles trapped in this region will be accelerated.
- This low density bubble propagates through the plasma as the laser advances.

The Particle in Cell Method

· Solves the equations of motion for the electron

$$\begin{split} \frac{\mathbf{x}_{n+1} - \mathbf{x}_n}{\Delta t} &= \mathbf{v}_{n+1} \\ \frac{\mathbf{v}_{n+1/2} - \mathbf{v}_{n-1/2}}{\Delta t} &= \frac{q}{m} \left( \mathsf{E}(\mathbf{x}_n) + \frac{\mathbf{v}_{n+1/2} + \mathbf{v}_{n-1/2}}{2} \times \mathsf{B}(\mathbf{x}_n) \right) \end{split}$$

• The Boris push algorithm: the motion is decomposed in the contribution from the electric and magnetic field.



## The Boris push

1. 
$$\mathbf{v}^- = \mathbf{v}_{n-1/2} + \frac{q\mathbf{E}}{m} \frac{\Delta t}{2}$$

2. rotate  $v^-$  to obtain  $v^+$  using

2.1 
$$\mathbf{v}' = \mathbf{v}^- + \mathbf{v}^- \times \mathbf{t}$$
, where  $\mathbf{t} = \frac{qB}{m} \frac{\Delta t}{2}$   
2.2  $\mathbf{v}^+ = \mathbf{v}^- + \mathbf{v}' \times \mathbf{s}$ , where  $\mathbf{s} = \frac{2\mathbf{t}}{1+t^2}$ 

3. 
$$\mathbf{v}_{n+1/2} = \mathbf{v}^+ + \frac{q\mathbf{E}}{m} \frac{\Delta t}{2}$$

## Conservation properties

- We want the algorithm to be as close as possible to the original continuous system in terms of symmetries and conserved quantities.
- A linear map  $A: \mathbb{R}^{2d} \to \mathbb{R}^{2d}$  is called symplectic if

$$A^{T}J^{-1}A = J^{-1}, \quad \text{where } J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix},$$

• The Boris push algorithm is not symplectic, but it is volume preserving.

#### The Field solver

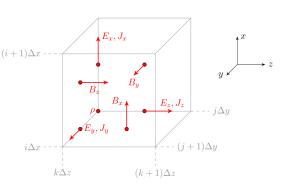
· Solve Maxwell's equations using

$$\begin{split} \frac{\partial \mathbf{B}}{\partial t} &= -\mathbf{\nabla} \times \mathbf{E} \\ \frac{\partial \mathbf{E}}{\partial t} &= c^2 \mathbf{\nabla} \times \mathbf{B} - \frac{1}{\varepsilon_0} \mathbf{j} \,. \end{split}$$

· Let us consider the 1D case first

$$\begin{split} \frac{B_y^{n+1/2}(k+\frac{1}{2}) - B_y^{n-1/2}(k+\frac{1}{2})}{\Delta t} &= -\frac{E_x^n(k+1) - E_x^n(k)}{\Delta z} \\ \frac{E_x^{n+1}(k) - E_x^n(k)}{\Delta t} &= -c^2 \frac{B_y^{n+1/2}(k+\frac{1}{2}) - B_y^{n+1/2}(k-\frac{1}{2})}{\Delta z} - \frac{1}{\varepsilon_0} j_x^{n+1/2}(k) \,. \end{split}$$

- Yee's method uses a leapfrog-like algorithm for staggering in both  $_{(i+1)\Delta x}$  space and time.
- Continuity equations for E and B are automatically satisfied at cell boundaries.



#### The 3D case

The magnetic field is given by

$$\frac{\partial B_y}{\partial t} = -\frac{\partial E_x}{\partial z} + \frac{\partial E_z}{\partial x}$$

which is discretized as

$$\frac{B_{y}^{n+1/2}(i+\frac{1}{2},j,k+\frac{1}{2}) - B_{y}^{n-1/2}(i+\frac{1}{2},j,k+\frac{1}{2})}{\Delta t} = \frac{E_{x}^{n}(i+\frac{1}{2},j,k+1) - E_{x}^{n}(i+\frac{1}{2},j,k)}{\Delta z} + \frac{E_{z}^{n}(i+1,j,k+\frac{1}{2}) - E_{z}^{n}(i,j,k+\frac{1}{2})}{\Delta x}$$

· or

$$\partial_t B_{y}|_{i+\frac{1}{2},j,k+\frac{1}{2}}^n = -\partial_z E_{x}|_{i+\frac{1}{2},j,k+\frac{1}{2}}^n + \partial_x E_{z}|_{i+\frac{1}{2},j,k+\frac{1}{2}}^n$$

### What about the other equations?

· For 
$$\nabla \cdot \mathbf{B} = 0$$
 
$$\frac{\partial \nabla \cdot \mathbf{B}}{\partial t} = \nabla \cdot \frac{\partial \mathbf{B}}{\partial t} = \nabla \cdot (-\nabla \times \mathbf{E}) = 0.$$

· For 
$$abla \cdot \mathbf{E} = rac{
ho}{arepsilon_0}$$

$$\frac{\partial}{\partial t} \left( \nabla \cdot \mathbf{E} - \frac{\rho}{\varepsilon_0} \right) = -\frac{1}{\varepsilon_0} \left[ \frac{\partial \rho}{\partial t} - \nabla \cdot \left( \frac{1}{\mu_0} \nabla \times \mathbf{B} - \mathbf{j} \right) \right]$$
$$= -\frac{1}{\varepsilon_0} \left( \frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{j} \right)$$

## **Numerical Stability**

- In order to accurately represent the physics, the temporal and spatial discretizations must be chosen appropriately.
- For the spatial discretizations, the dimension of a cell must be significantly smaller than the laser wavelength.

$$D_{cell} \ll \lambda_L$$

 The timestep is then computed from the spatial discretizations automatically via the Courant condition.

$$c\Delta t \le \frac{1}{\sqrt{\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{1}{\Delta z^2}}}$$

- PIC codes require significant computational resources (HPC).
- The implementation must take advantage of all the available computing resources (MIP, SIMD, CUDA).
- Scalability is crucial for employing large parallel simulations.
- · Amdahl's law

$$S_A = \frac{1}{(1-p) + \frac{p}{n}}$$
 and  $\lim_{n \to \infty} S_A = \frac{1}{1-p}$ 

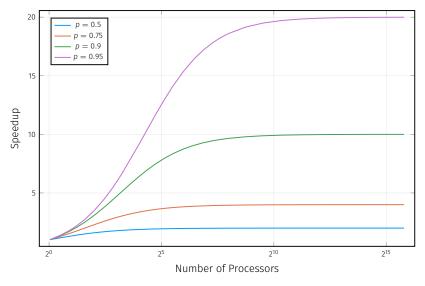
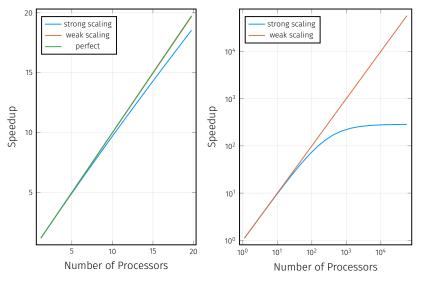


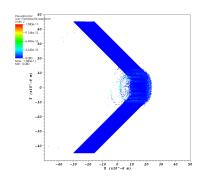
Figure 1: The speedup computed with Amdahl's law

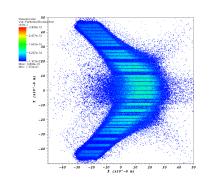


**Figure 2:** The theoretical speedup compared with linear axis and small number of processors on the left and log-log scale with a large number of processors on the right

## Results

## Solid targets





- (a) The kinetic energy of the electrons right after the pulse hits the cone
- (b) The kinetic energy of the electrons a long time after the pulse hits the cone

**Figure 3:** The kinetic energy of the electrons for the  $I = 10^{21} \,\mathrm{W}\,\mathrm{cm}^{-2}$  laser pulse

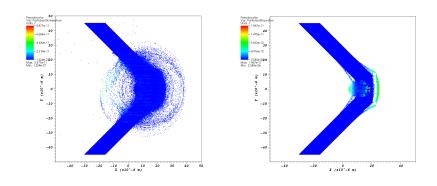
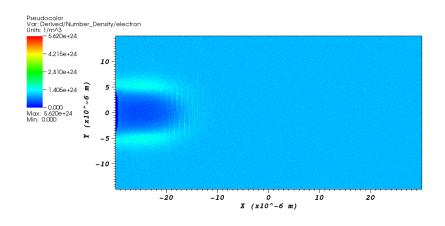
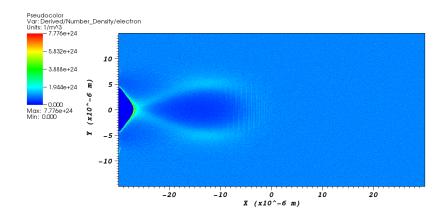
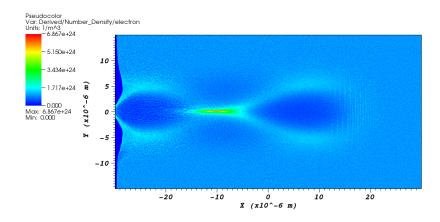


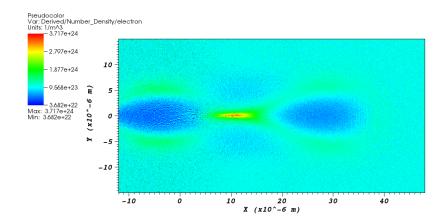
Figure 4: The kinetic energy of the electrons and protons for the  $I = 10^{22} \,\mathrm{W\,cm^{-2}}$  laser pulse

## **Gaseous targets**









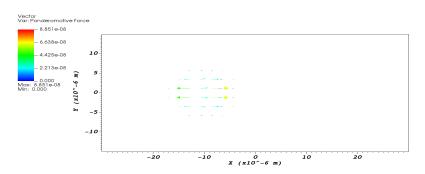


Figure 5: The ponderomotive force for the  $I=10^{18}\,\mathrm{W\,cm^{-2}}$  laser pulse

## Conclusions

#### Conclusions

- This thesis addresses the large field of laser plasma interactions in a computational framework.
- This thesis is devoted to a class of self-consistent methods of solving the dynamics of electrically charged particles in strong electromagnetic fields.
- The most prominent effect observed in my numerical simulations is the laser wakefield acceleration visible in the case of gaseous targets subjected to highly intense laser pulses.

