

## Escuela Politécnica Nacional

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**Fecha:** 15/07/2025

### Repositorio:

https://github.com/SebastianMoralesEpn/Github1.0/tree/ 0bf724d0529e52b252de022dc205debd6085ebed/Talleres/Taller7

# [Taller 2b] Métodos iterativos

Grafique la trayectoria de los siguientes sistemas de ecuaciones:

$$x_1 + x_2 = 7$$
  
 $-2x_1 + 5x_2 = 0$ 

- $X_0 = (0,0)$
- $X_0 = (5,2)$

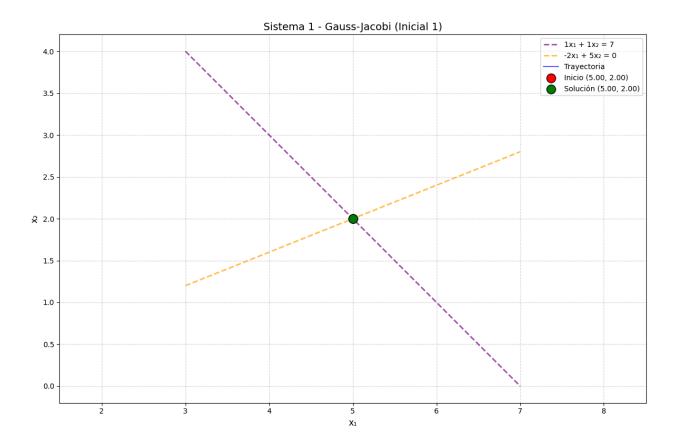
$$\begin{aligned}
 x_1 + x_2 &= 6 \\
 -2x_1 + x_2 &= 0
 \end{aligned}$$

Prueba 3 posiciones iniciales, encuentre una en la que diverge el sistema.

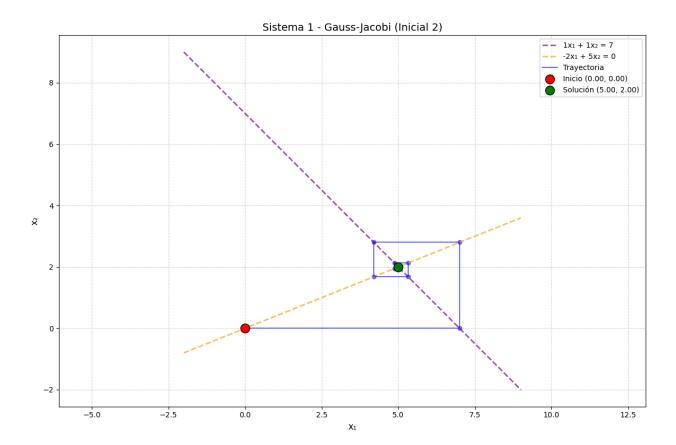
```
In [28]: %load_ext autoreload
```

The autoreload extension is already loaded. To reload it, use: %reload\_ext autoreload

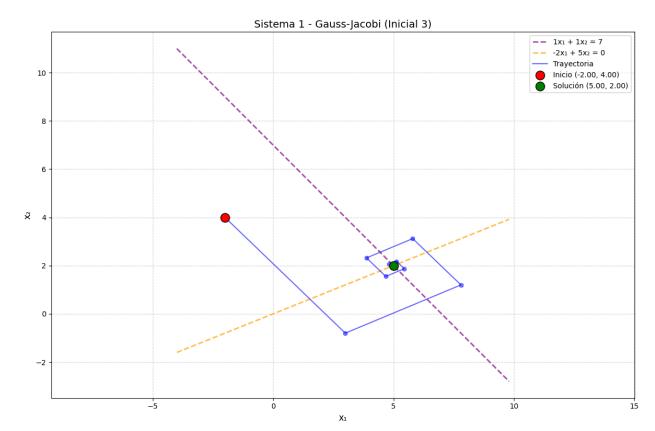
```
for i in range(A.shape[0]):
                 if A[i, 1] != 0: # Para evitar división por cero
                     y vals = (b[i] - A[i, 0]*x vals)/A[i, 1]
                     plt.plot(x vals, y vals, color=colors[i], linestyle='--',
                              linewidth=2, alpha=0.7,
                              label=f'\{A[i,0]\}x_1 + \{A[i,1]\}x_2 = \{b[i]\}'
             # Graficar trayectoria
             plt.plot(tray array[:, 0], tray array[:, 1], 'b-', linewidth=1.5, alpha=0.
             plt.scatter(tray array[:, 0], tray array[:, 1], color='blue', s=30, alpha=
             # Destacar puntos inicial y final
             plt.scatter(tray array[0, 0], tray array[0, 1], color='red', s=150,
                         edgecolor='black', zorder=5, label=f'Inicio ({tray array[0,0]:
             plt.scatter(tray array[-1, 0], tray array[-1, 1], color='green', s=150,
                         edgecolor='black', zorder=5, label=f'Solución ({tray array[-1,
             plt.xlabel('x1', fontsize=12)
             plt.ylabel('x2', fontsize=12)
             plt.title(title, fontsize=14)
             plt.legend(loc='best', fontsize=10)
             plt.grid(True, linestyle='--', alpha=0.5)
             plt.axis('equal')
             plt.tight layout()
             plt.show()
In [30]: # % Sistema 1 - GAUSS-JACOBI
         A1 = np.array([[1, 1], [-2, 5]])
         b1 = np.array([7, 0])
         initial positions = [np.array([5, 2]), np.array([0, 0]), np.array([-2, 4])]
         print("=== SISTEMA 1 - MÉTODO DE GAUSS-JACOBI ===")
         for i, x0 in enumerate(initial positions, 1):
             print(f"\nCaso {i}: Posición inicial {x0}")
             try:
                 x j1, tray j1 = gauss jacobi(A=A1, b=b1, x0=x0, tol=1e-6, max iter=50)
                 plot system with trajectory(A1, b1, tray j1, f"Sistema 1 - Gauss-Jacob
                 print(f"Solución encontrada: [{x j1[0,0]:.6f}, {x j1[1,0]:.6f}]")
             except Exception as e:
                 print(f";Error! El método divergió: {str(e)}")
       === SISTEMA 1 - MÉTODO DE GAUSS-JACOBI ===
       Caso 1: Posición inicial [5 2]
       [07-15 \ 20:25:40][INFO] i= 0 x: [5 \ 2]
        [07-15 \ 20:25:40][INFO] i= 1 x: [[5. 2.]]
```



```
Caso 2: Posición inicial [0 0]
[07-15 \ 20:25:41][INFO] \ i= 0 \ x: [0 \ 0]
[07-15 \ 20:25:41][INFO] i= 1 x: [[7. \ 0.]]
[07-15 \ 20:25:41][INFO] \ i= 2 \ x: [[7. \ 2.8]]
[07-15 \ 20:25:41][INFO] \ i= 3 \ x: [[4.2 \ 2.8]]
[07-15 20:25:41][INF0] i= 4 x: [[4.2 1.68]]
[07-15 \ 20:25:41][INFO] \ i=5 \ x: [[5.32 \ 1.68]]
[07-15 \ 20:25:41][INFO] \ i= 6 \ x: [[5.32 \ 2.128]]
[07-15 20:25:41][INFO] i= 7 x: [[4.872 2.128]]
[07-15 20:25:41][INF0] i= 8 x: [[4.872 1.9488]]
[07-15 20:25:41][INFO] i= 9 x: [[5.0512 1.9488]]
[07-15 20:25:41][INFO] i= 10 x: [[5.0512 2.02048]]
[07-15 20:25:41][INFO] i= 11 x: [[4.97952 2.02048]]
[07-15 20:25:41][INFO] i= 12 x: [[4.97952 1.991808]]
[07-15 20:25:41][INFO] i= 13 x: [[5.008192 1.991808]]
[07-15 20:25:41][INF0] i= 14 x: [[5.008192 2.0032768]]
[07-15 20:25:41][INFO] i= 15 x: [[4.9967232 2.0032768]]
[07-15 20:25:41][INF0] i= 16 x: [[4.9967232 1.99868928]]
[07-15 20:25:41][INFO] i= 17 x: [[5.00131072 1.99868928]]
[07-15 20:25:41][INFO] i= 18 x: [[5.00131072 2.00052429]]
[07-15 20:25:41][INF0] i= 19 x: [[4.99947571 2.00052429]]
[07-15 20:25:41][INF0] i= 20 x: [[4.99947571 1.99979028]]
[07-15 20:25:41][INF0] i= 21 x: [[5.00020972 1.99979028]]
[07-15 20:25:41][INF0] i= 22 x: [[5.00020972 2.00008389]]
[07-15 20:25:41][INF0] i= 23 x: [[4.99991611 2.00008389]]
[07-15 20:25:41][INFO] i= 24 x: [[4.99991611 1.99996645]]
[07-15 20:25:41][INF0] i= 25 x: [[5.00003355 1.99996645]]
[07-15 20:25:41][INF0] i= 26 x: [[5.00003355 2.00001342]]
[07-15 20:25:41][INF0] i= 27 x: [[4.99998658 2.00001342]]
[07-15 20:25:41][INF0] i= 28 x: [[4.99998658 1.99999463]]
[07-15 20:25:41][INFO] i= 29 x: [[5.00000537 1.99999463]]
[07-15 20:25:41][INF0] i= 30 x: [[5.00000537 2.00000215]]
[07-15 20:25:41][INF0] i= 31 x: [[4.99999785 2.00000215]]
[07-15 20:25:41][INF0] i= 32 x: [[4.99999785 1.99999914]]
[07-15 20:25:41][INF0] i= 33 x: [[5.00000086 1.99999914]]
[07-15 20:25:41][INFO] i= 34 x: [[5.00000086 2.00000034]]
[07-15 20:25:41][INF0] i= 35 x: [[4.99999966 2.00000034]]
```



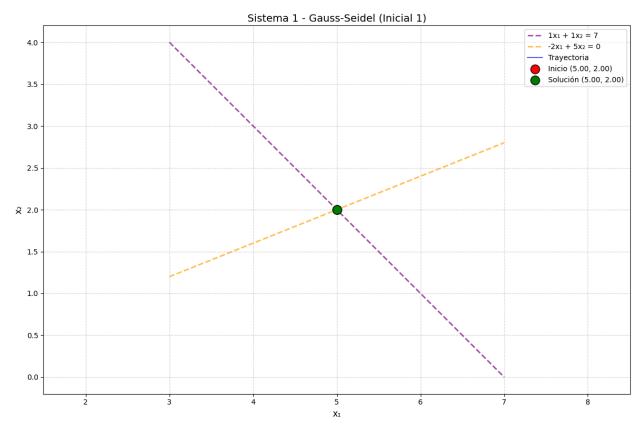
```
Caso 3: Posición inicial [-2 4]
[07-15 \ 20:25:41][INFO] \ i= 0 \ x: [-2 \ 4]
[07-15 \ 20:25:41][INFO] \ i= 1 \ x: [[ 3. -0.8]]
[07-15 20:25:41][INFO] i= 2 x: [[7.8 1.2]]
[07-15 20:25:41][INFO] i= 3 x: [[5.8 3.12]]
[07-15 20:25:41][INF0] i= 4 x: [[3.88 2.32]]
[07-15 20:25:41][INFO] i= 5 x: [[4.68 1.552]]
[07-15 20:25:41][INF0] i= 6 x: [[5.448 1.872]]
[07-15 20:25:41][INF0] i= 7 x: [[5.128 2.1792]]
[07-15 20:25:41][INF0] i= 8 x: [[4.8208 2.0512]]
[07-15 20:25:41][INFO] i= 9 x: [[4.9488 1.92832]]
[07-15 20:25:41][INFO] i= 10 x: [[5.07168 1.97952]]
[07-15 20:25:41][INFO] i= 11 x: [[5.02048 2.028672]]
[07-15 20:25:41][INF0] i= 12 x: [[4.971328 2.008192]]
[07-15 20:25:41][INF0] i= 13 x: [[4.991808 1.9885312]]
[07-15 20:25:41][INF0] i= 14 x: [[5.0114688 1.9967232]]
[07-15 20:25:41][INF0] i= 15 x: [[5.0032768 2.00458752]]
[07-15 20:25:41][INF0] i= 16 x: [[4.99541248 2.00131072]]
[07-15 20:25:41][INFO] i= 17 x: [[4.99868928 1.99816499]]
[07-15 20:25:41][INFO] i= 18 x: [[5.00183501 1.99947571]]
[07-15 20:25:41][INFO] i= 19 x: [[5.00052429 2.000734 ]]
[07-15 20:25:41][INFO] i= 20 x: [[4.999266
                                            2.00020972]]
[07-15 20:25:41][INFO] i= 21 x: [[4.99979028 1.9997064 ]]
[07-15 20:25:41][INF0] i= 22 x: [[5.0002936 1.99991611]]
[07-15 20:25:41][INFO] i= 23 x: [[5.00008389 2.00011744]]
[07-15 20:25:41][INFO] i= 24 x: [[4.99988256 2.00003355]]
[07-15 20:25:41][INF0] i= 25 x: [[4.99996645 1.99995302]]
[07-15 20:25:41][INF0] i= 26 x: [[5.00004698 1.99998658]]
[07-15 20:25:41][INF0] i= 27 x: [[5.00001342 2.00001879]]
[07-15 20:25:41][INF0] i= 28 x: [[4.99998121 2.00000537]]
[07-15 20:25:41][INFO] i= 29 x: [[4.99999463 1.99999248]]
[07-15 20:25:41][INF0] i= 30 x: [[5.00000752 1.99999785]]
[07-15 20:25:41][INF0] i= 31 x: [[5.00000215 2.00000301]]
[07-15 20:25:41][INF0] i= 32 x: [[4.99999699 2.00000086]]
[07-15 20:25:41][INFO] i= 33 x: [[4.99999914 1.9999988 ]]
[07-15 20:25:41][INFO] i= 34 x: [[5.0000012 1.99999966]]
[07-15 20:25:41][INFO] i= 35 x: [[5.00000034 2.00000048]]
```



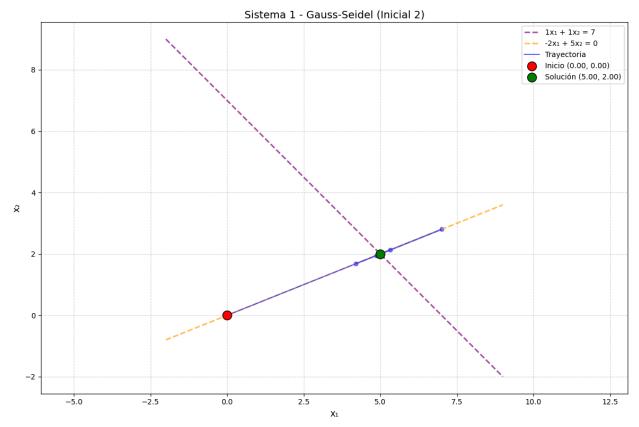
```
In [31]: # %% Sistema 1 - GAUSS-SEIDEL
print("\n=== SISTEMA 1 - MÉTODO DE GAUSS-SEIDEL ===")
for i, x0 in enumerate(initial_positions, 1):
    print(f"\nCaso {i}: Posición inicial {x0}")
    try:
        x_gsl, tray_gsl = gauss_seidel(A=Al, b=bl, x0=x0, tol=le-6, max_iter=5
        plot_system_with_trajectory(Al, bl, tray_gsl, f"Sistema 1 - Gauss-Seidel(B=Al)
        print(f"Solución encontrada: [{x_gsl[0,0]:.6f}, {x_gsl[1,0]:.6f}]")
    except Exception as e:
        print(f";Error! El método divergió: {str(e)}")
```

=== SISTEMA 1 - MÉTODO DE GAUSS-SEIDEL ===

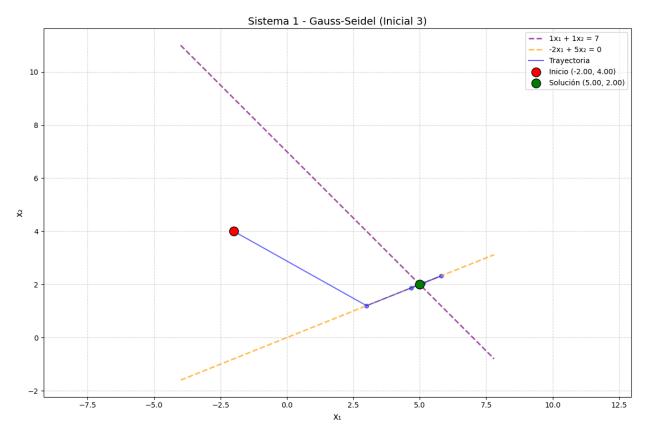
```
Caso 1: Posición inicial [5 2]
[07-15 20:26:23][INFO] i= 0 x: [5 2]
[07-15 20:26:23][INFO] i= 1 x: [[5. 2.]]
```



```
Caso 2: Posición inicial [0 0]
[07-15 \ 20:26:23][INFO] i= 0 x: [0 \ 0]
[07-15 \ 20:26:23][INFO] \ i=1 \ x: [[7. \ 2.8]]
[07-15 \ 20:26:23][INFO] i= 2 x: [[4.2 \ 1.68]]
[07-15 20:26:23][INFO] i= 3 x: [[5.32 2.128]]
[07-15 20:26:23][INFO] i= 4 x: [[4.872 1.9488]]
[07-15 \ 20:26:23][INFO] i = 5 x: [[5.0512 \ 2.02048]]
[07-15 20:26:23][INFO] i= 6 x: [[4.97952 1.991808]]
[07-15 \ 20:26:23][INFO] i = 7 x: [[5.008192 \ 2.0032768]]
[07-15 20:26:23][INF0] i= 8 x: [[4.9967232 1.99868928]]
[07-15 20:26:23][INFO] i= 9 x: [[5.00131072 2.00052429]]
[07-15 20:26:23][INF0] i= 10 x: [[4.99947571 1.99979028]]
[07-15 20:26:23][INFO] i= 11 x: [[5.00020972 2.00008389]]
[07-15 20:26:23][INFO] i= 12 x: [[4.99991611 1.99996645]]
[07-15 20:26:23][INFO] i= 13 x: [[5.00003355 2.00001342]]
[07-15 20:26:23][INF0] i= 14 x: [[4.99998658 1.99999463]]
[07-15 20:26:23][INFO] i= 15 x: [[5.00000537 2.00000215]]
[07-15 20:26:23][INFO] i= 16 x: [[4.99999785 1.99999914]]
[07-15 20:26:23][INFO] i= 17 x: [[5.00000086 2.00000034]]
[07-15 20:26:23][INFO] i= 18 x: [[4.99999966 1.99999986]]
```



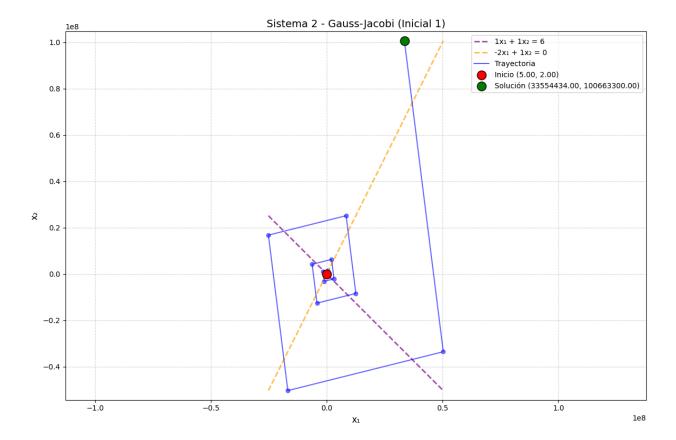
```
Caso 3: Posición inicial [-2 4]
[07-15 \ 20:26:24][INFO] i= 0 x: [-2 \ 4]
[07-15 \ 20:26:24][INFO] \ i=1 \ x: [[3. \ 1.2]]
[07-15 \ 20:26:24][INFO] \ i= 2 \ x: [[5.8 \ 2.32]]
[07-15 20:26:24][INFO] i= 3 x: [[4.68 1.872]]
[07-15 20:26:24][INF0] i= 4 x: [[5.128 2.0512]]
[07-15 20:26:24][INF0] i= 5 x: [[4.9488 1.97952]]
[07-15 20:26:24][INFO] i= 6 x: [[5.02048 2.008192]]
[07-15 20:26:24][INFO] i= 7 x: [[4.991808 1.9967232]]
[07-15 20:26:24][INFO] i= 8 x: [[5.0032768 2.00131072]]
[07-15 \ 20:26:24][INFO] \ i= 9 \ x: [[4.99868928 \ 1.99947571]]
[07-15 20:26:24][INFO] i= 10 x: [[5.00052429 2.00020972]]
[07-15 20:26:24][INF0] i= 11 x: [[4.99979028 1.99991611]]
[07-15 20:26:24][INFO] i= 12 x: [[5.00008389 2.00003355]]
[07-15 20:26:24][INF0] i= 13 x: [[4.99996645 1.99998658]]
[07-15 20:26:24][INF0] i= 14 x: [[5.00001342 2.00000537]]
[07-15 20:26:24][INFO] i= 15 x: [[4.99999463 1.99999785]]
[07-15 20:26:24][INFO] i= 16 x: [[5.00000215 2.00000086]]
[07-15 20:26:24][INF0] i= 17 x: [[4.99999914 1.99999966]]
[07-15 20:26:24][INFO] i= 18 x: [[5.00000034 2.00000014]]
```



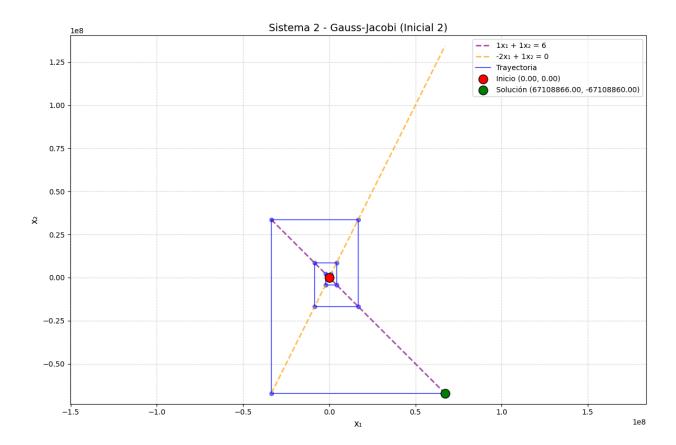
```
In [32]: # %% Sistema 2 - GAUSS-JACOBI
A2 = np.array([[1, 1], [-2, 1]])
b2 = np.array([6, 0])
initial_positions = [np.array([5, 2]), np.array([0, 0]), np.array([-2, 4])]

print("\n=== SISTEMA 2 - MÉTODO DE GAUSS-JACOBI ===")
for i, x0 in enumerate(initial_positions, 1):
    print(f"\nCaso {i}: Posición inicial {x0}")
    try:
        x_j2, tray_j2 = gauss_jacobi(A=A2, b=b2, x0=x0, tol=le-6, max_iter=50)
        plot_system_with_trajectory(A2, b2, tray_j2, f"Sistema 2 - Gauss-Jacob
        print(f"Solución encontrada: [{x_j2[0,0]:.6f}, {x_j2[1,0]:.6f}]")
    except Exception as e:
        print(f";Error! El método divergió: {str(e)}")
```

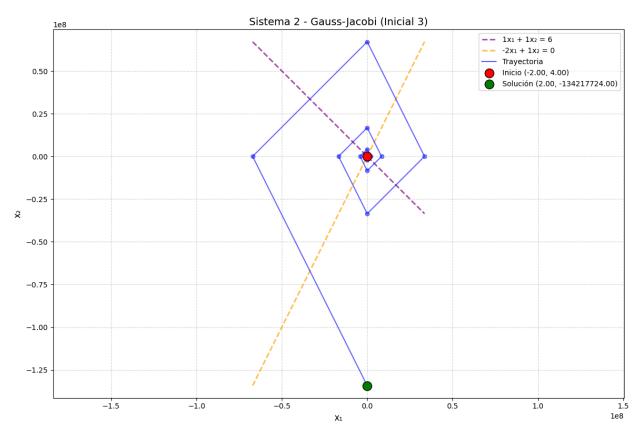
```
Caso 1: Posición inicial [5 2]
[07-15 \ 20:26:57][INFO] i= 0 x: [5 \ 2]
[07-15 \ 20:26:57][INFO] i= 1 x: [[ 4. 10.]]
[07-15 \ 20:26:57][INFO] \ i= 2 \ x: [[-4. \ 8.]]
[07-15 \ 20:26:57][INFO] i= 3 x: [[-2. -8.]]
[07-15 20:26:57][INFO] i= 4 x: [[14. -4.]]
[07-15 20:26:57][INFO] i= 5 x: [[10. 28.]]
[07-15 \ 20:26:57][INFO] i= 6 x: [[-22. 20.]]
[07-15 20:26:57][INFO] i= 7 x: [[-14. -44.]]
[07-15 20:26:57][INFO] i= 8 x: [[ 50. -28.]]
[07-15 20:26:57][INFO] i= 9 x: [[ 34. 100.]]
[07-15 20:26:57][INFO] i= 10 x: [[-94. 68.]]
[07-15 20:26:57][INFO] i= 11 x: [[ -62. -188.]]
[07-15 20:26:57][INFO] i= 12 x: [[ 194. -124.]]
[07-15 20:26:57][INF0] i= 13 x: [[130. 388.]]
[07-15 20:26:57][INFO] i= 14 x: [[-382. 260.]]
[07-15 20:26:57][INF0] i= 15 x: [[-254. -764.]]
[07-15 20:26:57][INFO] i= 16 x: [[ 770. -508.]]
[07-15 20:26:57][INFO] i= 17 x: [[ 514. 1540.]]
[07-15 20:26:57][INFO] i= 18 x: [[-1534. 1028.]]
[07-15 20:26:57][INFO] i= 19 x: [[-1022. -3068.]]
[07-15 20:26:57][INFO] i= 20 x: [[ 3074. -2044.]]
[07-15 20:26:57][INFO] i= 21 x: [[2050. 6148.]]
[07-15 20:26:57][INFO] i= 22 x: [[-6142. 4100.]]
[07-15 20:26:57][INFO] i= 23 x: [[ -4094. -12284.]]
[07-15 20:26:57][INFO] i= 24 x: [[12290. -8188.]]
[07-15 20:26:57][INFO] i= 25 x: [[ 8194. 24580.]]
[07-15 20:26:57][INFO] i= 26 x: [[-24574. 16388.]]
[07-15 20:26:57][INFO] i= 27 x: [[-16382. -49148.]]
[07-15 20:26:57][INFO] i= 28 x: [[ 49154. -32764.]]
[07-15 20:26:57][INFO] i= 29 x: [[32770. 98308.]]
[07-15 20:26:57][INFO] i= 30 x: [[-98302. 65540.]]
[07-15 20:26:57][INFO] i= 31 x: [[ -65534. -196604.]]
[07-15 20:26:57][INF0] i= 32 x: [[ 196610. -131068.]]
[07-15 20:26:57][INFO] i= 33 x: [[131074. 393220.]]
[07-15 20:26:57][INFO] i= 34 x: [[-393214. 262148.]]
[07-15 20:26:57][INFO] i= 35 x: [[-262142. -786428.]]
[07-15 20:26:57][INFO] i= 36 x: [[ 786434. -524284.]]
[07-15 20:26:57][INFO] i= 37 x: [[ 524290. 1572868.]]
[07-15 20:26:57][INF0] i= 38 x: [[-1572862. 1048580.]]
[07-15 20:26:57][INFO] i= 39 x: [[-1048574. -3145724.]]
[07-15 20:26:57][INFO] i= 40 x: [[ 3145730. -2097148.]]
[07-15 20:26:57][INFO] i= 41 x: [[2097154. 6291460.]]
[07-15 20:26:57][INF0] i= 42 x: [[-6291454. 4194308.]]
[07-15 20:26:57][INFO] i= 43 x: [[ -4194302. -12582908.]]
[07-15 20:26:57][INFO] i= 44 x: [[12582914. -8388604.]]
[07-15 20:26:57][INFO] i= 45 x: [[ 8388610. 25165828.]]
[07-15 20:26:57][INFO] i= 46 x: [[-25165822. 16777220.]]
[07-15 20:26:57][INF0] i= 47 x: [[-16777214. -50331644.]]
[07-15 20:26:57][INF0] i= 48 x: [[ 50331650. -33554428.]]
[07-15 20:26:57][INFO] i= 49 x: [[3.3554434e+07 1.0066330e+08]]
```



```
Caso 2: Posición inicial [0 0]
[07-15 \ 20:26:58][INFO] i= 0 x: [0 \ 0]
[07-15 \ 20:26:58][INFO] i= 1 x: [[6. \ 0.]]
[07-15 20:26:58][INFO] i= 2 x: [[ 6. 12.]]
[07-15 \ 20:26:58][INFO] \ i= 3 \ x: [[-6. \ 12.]]
[07-15 \ 20:26:58][INFO] i= 4 x: [[ -6. -12.]]
[07-15 \ 20:26:58][INFO] \ i=5 \ x: [[ 18. -12.]]
[07-15 \ 20:26:58][INFO] i= 6 x: [[18. 36.]]
[07-15 20:26:58][INFO] i= 7 x: [[-30. 36.]]
[07-15 20:26:58][INFO] i= 8 x: [[-30. -60.]]
[07-15 \ 20:26:58][INFO] \ i= 9 \ x: [[ 66. -60.]]
[07-15 20:26:58][INFO] i= 10 x: [[ 66. 132.]]
[07-15 20:26:58][INFO] i= 11 x: [[-126. 132.]]
[07-15 20:26:58][INF0] i= 12 x: [[-126. -252.]]
[07-15 20:26:58][INFO] i= 13 x: [[ 258. -252.]]
[07-15 20:26:58][INFO] i= 14 x: [[258. 516.]]
[07-15 20:26:58][INF0] i= 15 x: [[-510. 516.]]
[07-15 20:26:58][INFO] i= 16 x: [[ -510. -1020.]]
[07-15 20:26:58][INFO] i= 17 x: [[ 1026. -1020.]]
[07-15 20:26:58][INFO] i= 18 x: [[1026. 2052.]]
[07-15 20:26:58][INFO] i= 19 x: [[-2046. 2052.]]
[07-15 20:26:58][INFO] i= 20 x: [[-2046. -4092.]]
[07-15 20:26:58][INF0] i= 21 x: [[ 4098. -4092.]]
[07-15 20:26:58][INFO] i= 22 x: [[4098. 8196.]]
[07-15 20:26:58][INFO] i= 23 x: [[-8190. 8196.]]
[07-15 20:26:58][INF0] i= 24 x: [[ -8190. -16380.]]
[07-15 20:26:58][INFO] i= 25 x: [[ 16386. -16380.]]
[07-15 20:26:58][INFO] i= 26 x: [[16386. 32772.]]
[07-15 20:26:58][INF0] i= 27 x: [[-32766. 32772.]]
[07-15 20:26:58][INFO] i= 28 x: [[-32766. -65532.]]
[07-15 20:26:58][INFO] i= 29 x: [[ 65538. -65532.]]
[07-15 20:26:58][INFO] i= 30 x: [[ 65538. 131076.]]
[07-15 20:26:58][INFO] i= 31 x: [[-131070. 131076.]]
[07-15 20:26:58][INFO] i= 32 x: [[-131070. -262140.]]
[07-15 20:26:58][INFO] i= 33 x: [[ 262146. -262140.]]
[07-15 20:26:58][INFO] i= 34 x: [[262146. 524292.]]
[07-15 20:26:58][INFO] i= 35 x: [[-524286. 524292.]]
[07-15 20:26:58][INFO] i= 36 x: [[ -524286. -1048572.]]
[07-15 20:26:58][INFO] i= 37 x: [[ 1048578. -1048572.]]
[07-15 20:26:58][INFO] i= 38 x: [[1048578. 2097156.]]
[07-15 20:26:58][INFO] i= 39 x: [[-2097150. 2097156.]]
[07-15 20:26:58][INFO] i= 40 x: [[-2097150. -4194300.]]
[07-15 20:26:58][INFO] i= 41 x: [[ 4194306. -4194300.]]
[07-15 20:26:58][INFO] i= 42 x: [[4194306. 8388612.]]
[07-15 20:26:58][INFO] i= 43 x: [[-8388606. 8388612.]]
[07-15 20:26:58][INFO] i= 44 x: [[ -8388606. -16777212.]]
[07-15 20:26:58][INFO] i= 45 x: [[ 16777218. -16777212.]]
[07-15 20:26:58][INFO] i= 46 x: [[16777218. 33554436.]]
[07-15 20:26:58][INF0] i= 47 x: [[-33554430. 33554436.]]
[07-15 20:26:58][INFO] i= 48 x: [[-33554430. -67108860.]]
[07-15 20:26:58][INFO] i= 49 x: [[ 67108866. -67108860.]]
```



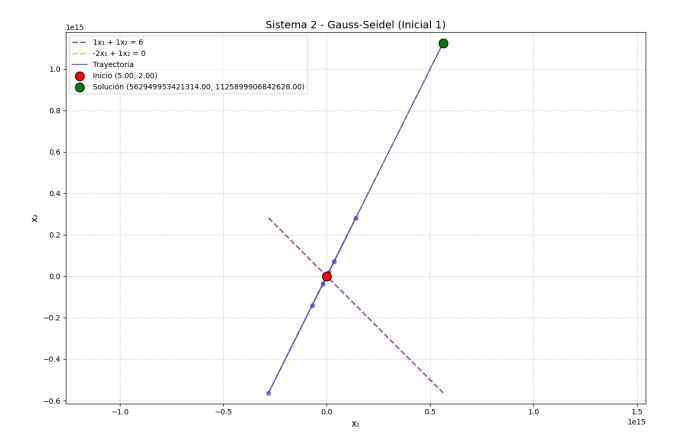
```
Caso 3: Posición inicial [-2 4]
[07-15 \ 20:26:59][INFO] i= 0 x: [-2 \ 4]
[07-15 20:26:59][INFO] i= 1 x: [[ 2. -4.]]
[07-15 20:26:59][INFO] i= 2 x: [[10. 4.]]
[07-15 \ 20:26:59][INFO] \ i= 3 \ x: [[ 2. 20.]]
[07-15 20:26:59][INFO] i= 4 x: [[-14. 4.]]
[07-15 \ 20:26:59][INFO] \ i=5 \ x: [[ 2. -28.]]
[07-15 \ 20:26:59][INFO] i= 6 x: [[34. 4.]]
[07-15 \ 20:26:59][INFO] i= 7 x: [[ 2. 68.]]
[07-15 \ 20:26:59][INFO] i= 8 x: [[-62.
[07-15 20:26:59][INFO] i= 9 x: [[ 2. -124.]]
[07-15 \ 20:26:59][INFO] i = 10 x: [[130.]]
                                          4.11
[07-15 20:26:59][INFO] i= 11 x: [[ 2. 260.]]
[07-15 \ 20:26:59][INFO] i= 12 x: [[-254]][INFO]
                                            4.]]
[07-15 20:26:59][INFO] i= 13 x: [[ 2. -508.]]
[07-15 20:26:59][INFO] i= 14 x: [[514.
[07-15 20:26:59][INFO] i= 15 x: [[
                                     2. 1028.]]
[07-15 \ 20:26:59][INFO] i = 16 x: [[-1022]]
                                              4.11
[07-15 20:26:59][INFO] i= 17 x: [[ 2.000e+00 -2.044e+03]]
[07-15 \ 20:26:59][INFO] i = 18 x: [[2050.]]
[07-15 20:26:59][INFO] i= 19 x: [[2.0e+00 4.1e+03]]
[07-15 \ 20:26:59][INFO] \ i= 20 \ x: [[-4.094e+03 \ 4.000e+00]]
[07-15 20:26:59][INFO] i= 21 x: [[ 2.000e+00 -8.188e+03]]
[07-15 20:26:59][INFO] i= 22 x: [[8.194e+03 4.000e+00]]
[07-15 20:26:59][INFO] i= 23 x: [[2.0000e+00 1.6388e+04]]
[07-15 20:26:59][INFO] i= 24 x: [[-1.6382e+04 4.0000e+00]]
[07-15 \ 20:26:59][INFO] i = 25 x: [[ 2.0000e+00 -3.2764e+04]]
[07-15 \ 20:26:59][INFO] i= 26 x: [[3.277e+04 \ 4.000e+00]]
[07-15 20:26:59][INFO] i= 27 x: [[2.000e+00 6.554e+04]]
[07-15 \ 20:26:59][INFO] \ i= 28 \ x: [[-6.5534e+04 \ 4.0000e+00]]
[07-15 \ 20:26:59][INFO] i= 29 x: [[ 2.00000e+00 -1.31068e+05]]
[07-15 20:26:59][INFO] i= 30 x: [[1.31074e+05 4.00000e+00]]
[07-15 20:26:59][INFO] i= 31 x: [[2.00000e+00 2.62148e+05]]
[07-15 20:26:59][INF0] i= 32 x: [[-2.62142e+05 4.00000e+00]]
[07-15 \ 20:26:59][INFO] \ i= 33 \ x: [[ 2.00000e+00 -5.24284e+05]]
[07-15 20:26:59][INFO] i= 34 x: [[5.2429e+05 4.0000e+00]]
[07-15 \ 20:26:59][INFO] \ i= 35 \ x: [[2.00000e+00 \ 1.04858e+06]]
[07-15 20:26:59][INF0] i= 36 x: [[-1.048574e+06 4.000000e+00]]
[07-15 20:26:59][INF0] i= 37 x: [[ 2.000000e+00 -2.097148e+06]]
[07-15 20:26:59][INF0] i= 38 x: [[2.097154e+06 4.000000e+00]]
[07-15 20:26:59][INFO] i= 39 x: [[2.000000e+00 4.194308e+06]]
[07-15 \ 20:26:59][INFO] i = 40 x: [[-4.194302e+06 \ 4.000000e+00]]
[07-15 20:26:59][INF0] i= 41 x: [[ 2.000000e+00 -8.388604e+06]]
[07-15 20:26:59][INF0] i= 42 x: [[8.38861e+06 4.00000e+00]]
[07-15 20:26:59][INFO] i= 43 x: [[2.000000e+00 1.677722e+07]]
[07-15 20:26:59][INF0] i= 44 x: [[-1.6777214e+07 4.0000000e+00]]
[07-15 20:26:59][INF0] i= 45 x: [[ 2.0000000e+00 -3.3554428e+07]]
[07-15 20:26:59][INFO] i= 46 x: [[3.3554434e+07 4.0000000e+00]]
[07-15 20:26:59][INF0] i= 47 x: [[2.0000000e+00 6.7108868e+07]]
[07-15 20:26:59][INFO] i= 48 x: [[-6.7108862e+07 4.0000000e+00]]
[07-15 20:26:59][INF0] i= 49 x: [[ 2.00000000e+00 -1.34217724e+08]]
```



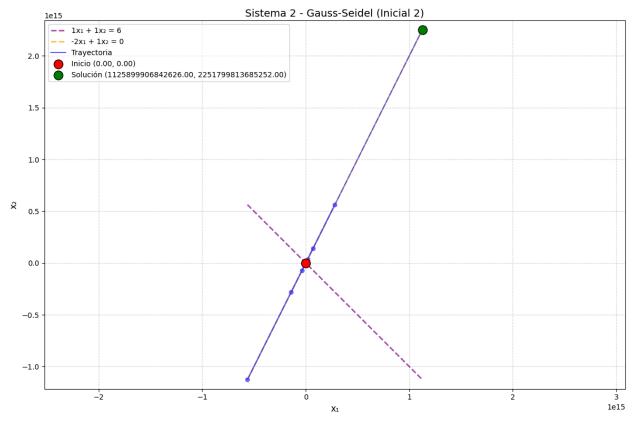
Solución encontrada: [2.000000, -134217724.000000]

```
In [33]: # %% Sistema 2 - GAUSS-SEIDEL
print("\n=== SISTEMA 2 - MÉTODO DE GAUSS-SEIDEL ===")
for i, x0 in enumerate(initial_positions, 1):
    print(f"\nCaso {i}: Posición inicial {x0}")
    try:
        x_gs2, tray_gs2 = gauss_seidel(A=A2, b=b2, x0=x0, tol=le-6, max_iter=5
        plot_system_with_trajectory(A2, b2, tray_gs2, f"Sistema 2 - Gauss-Seid
        print(f"Solución encontrada: [{x_gs2[0,0]:.6f}, {x_gs2[1,0]:.6f}]")
    except Exception as e:
        print(f";Error! El método divergió: {str(e)}")
```

```
Caso 1: Posición inicial [5 2]
[07-15 \ 20:27:23][INFO] i= 0 x: [5 \ 2]
[07-15 \ 20:27:23][INFO] i= 1 x: [[4. 8.]]
[07-15 \ 20:27:23][INFO] \ i= 2 \ x: [[-2. -4.]]
[07-15 \ 20:27:23][INFO] \ i= 3 \ x: [[10. \ 20.]]
[07-15 20:27:23][INFO] i= 4 x: [[-14. -28.]]
[07-15 \ 20:27:23][INFO] \ i=5 \ x: [[34. 68.]]
[07-15 \ 20:27:23][INFO] \ i= 6 \ x: [[-62. -124.]]
[07-15 \ 20:27:23][INFO] i= 7 x: [[130. 260.]]
[07-15 20:27:23][INFO] i= 8 x: [[-254. -508.]]
[07-15 20:27:23][INFO] i= 9 x: [[ 514. 1028.]]
[07-15 20:27:23][INFO] i= 10 x: [[-1022. -2044.]]
[07-15 20:27:23][INFO] i= 11 x: [[2050. 4100.]]
[07-15 20:27:23][INFO] i= 12 x: [[-4094. -8188.]]
[07-15 20:27:23][INFO] i= 13 x: [[ 8194. 16388.]]
[07-15 20:27:23][INFO] i= 14 x: [[-16382. -32764.]]
[07-15 20:27:23][INFO] i= 15 x: [[32770. 65540.]]
[07-15 20:27:23][INFO] i= 16 x: [[ -65534. -131068.]]
[07-15 20:27:23][INFO] i= 17 x: [[131074. 262148.]]
[07-15 20:27:23][INFO] i= 18 x: [[-262142. -524284.]]
[07-15 20:27:23][INFO] i= 19 x: [[ 524290. 1048580.]]
[07-15 \ 20:27:23][INFO] i= 20 x: [[-1048574. -2097148.]]
[07-15 20:27:23][INF0] i= 21 x: [[2097154. 4194308.]]
[07-15 20:27:23][INFO] i= 22 x: [[-4194302. -8388604.]]
[07-15 20:27:23][INFO] i= 23 x: [[ 8388610. 16777220.]]
[07-15 20:27:23][INFO] i= 24 x: [[-16777214. -33554428.]]
[07-15 20:27:23][INFO] i= 25 x: [[33554434. 67108868.]]
[07-15 20:27:23][INF0] i= 26 x: [[-6.71088620e+07 -1.34217724e+08]]
[07-15 20:27:23][INFO] i= 27 x: [[1.3421773e+08 2.6843546e+08]]
[07-15 20:27:23][INF0] i= 28 x: [[-2.68435454e+08 -5.36870908e+08]]
[07-15 20:27:23][INFO] i= 29 x: [[5.36870914e+08 1.07374183e+09]]
[07-15 20:27:23][INF0] i= 30 x: [[-1.07374182e+09 -2.14748364e+09]]
[07-15 20:27:23][INF0] i= 31 x: [[2.14748365e+09 4.29496730e+09]]
[07-15 \ 20:27:23][INFO] \ i= 32 \ x: [[-4.29496729e+09 \ -8.58993459e+09]]
[07-15 20:27:23][INFO] i= 33 x: [[8.58993459e+09 1.71798692e+10]]
[07-15 \ 20:27:23][INF0] \ i= 34 \ x: [[-1.71798692e+10 \ -3.43597384e+10]]
[07-15 20:27:23][INF0] i= 35 x: [[3.43597384e+10 6.87194767e+10]]
[07-15 \ 20:27:23][INFO] \ i= 36 \ x: [[-6.87194767e+10 \ -1.37438953e+11]]
[07-15\ 20:27:23][INFO]\ i=\ 37\ x:\ [[1.37438953e+11\ 2.74877907e+11]]
[07-15 20:27:23][INF0] i= 38 x: [[-2.74877907e+11 -5.49755814e+11]]
[07-15 20:27:23][INFO] i= 39 x: [[5.49755814e+11 1.09951163e+12]]
[07-15 \ 20:27:23][INFO] i= 40 x: [[-1.09951163e+12 \ -2.19902326e+12]]
[07-15 20:27:23][INF0] i= 41 x: [[2.19902326e+12 4.39804651e+12]]
[07-15 \ 20:27:23][INFO] \ i= 42 \ x: [[-4.39804651e+12 \ -8.79609302e+12]]
[07-15 20:27:23][INF0] i= 43 x: [[8.79609302e+12 1.75921860e+13]]
[07-15 20:27:23][INF0] i= 44 x: [[-1.75921860e+13 -3.51843721e+13]]
[07-15 20:27:23][INF0] i= 45 x: [[3.51843721e+13 7.03687442e+13]]
[07-15 \ 20:27:23][INFO] i= 46 x: [[-7.03687442e+13 \ -1.40737488e+14]]
[07-15 20:27:23][INF0] i= 47 x: [[1.40737488e+14 2.81474977e+14]]
[07-15 \ 20:27:23][INFO] i= 48 x: [[-2.81474977e+14 \ -5.62949953e+14]]
[07-15 20:27:23][INF0] i= 49 x: [[5.62949953e+14 1.12589991e+15]]
```

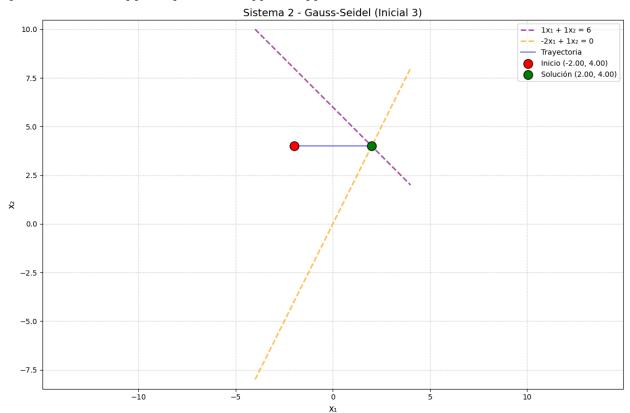


```
Caso 2: Posición inicial [0 0]
[07-15 \ 20:27:24][INFO] \ i= 0 \ x: [0 \ 0]
[07-15 \ 20:27:24][INFO] i= 1 x: [[ 6. 12.]]
[07-15 20:27:24][INFO] i= 2 x: [[ -6. -12.]]
[07-15 20:27:24][INFO] i= 3 x: [[18. 36.]]
[07-15 20:27:24][INFO] i= 4 x: [[-30. -60.]]
[07-15 \ 20:27:24][INFO] i= 5 x: [[ 66. 132.]]
[07-15 \ 20:27:24][INFO] \ i= 6 \ x: [[-126. -252.]]
[07-15 20:27:24][INFO] i= 7 x: [[258. 516.]]
[07-15 20:27:24][INFO] i= 8 x: [[ -510. -1020.]]
[07-15 20:27:24][INFO] i= 9 x: [[1026. 2052.]]
[07-15 20:27:24][INFO] i= 10 x: [[-2046. -4092.]]
[07-15 20:27:24][INFO] i= 11 x: [[4098. 8196.]]
[07-15 20:27:24][INFO] i= 12 x: [[ -8190. -16380.]]
[07-15 20:27:24][INFO] i= 13 x: [[16386. 32772.]]
[07-15 20:27:24][INFO] i= 14 x: [[-32766. -65532.]]
[07-15 20:27:24][INFO] i= 15 x: [[ 65538. 131076.]]
[07-15 20:27:24][INFO] i= 16 x: [[-131070. -262140.]]
[07-15 20:27:24][INFO] i= 17 x: [[262146. 524292.]]
[07-15 20:27:24][INFO] i= 18 x: [[ -524286. -1048572.]]
[07-15 20:27:24][INFO] i= 19 x: [[1048578. 2097156.]]
[07-15 20:27:24][INFO] i= 20 x: [[-2097150. -4194300.]]
[07-15 20:27:24][INF0] i= 21 x: [[4194306. 8388612.]]
[07-15 20:27:24][INF0] i= 22 x: [[ -8388606. -16777212.]]
[07-15 20:27:24][INFO] i= 23 x: [[16777218. 33554436.]]
[07-15 20:27:24][INFO] i= 24 x: [[-33554430. -67108860.]]
[07-15 20:27:24][INF0] i= 25 x: [[6.71088660e+07 1.34217732e+08]]
[07-15 20:27:24][INFO] i= 26 x: [[-1.34217726e+08 -2.68435452e+08]]
[07-15 20:27:24][INFO] i= 27 x: [[2.68435458e+08 5.36870916e+08]]
[07-15 20:27:24][INF0] i= 28 x: [[-5.36870910e+08 -1.07374182e+09]]
[07-15 20:27:24][INFO] i= 29 x: [[1.07374183e+09 2.14748365e+09]]
[07-15 20:27:24][INF0] i= 30 x: [[-2.14748365e+09 -4.29496729e+09]]
[07-15 20:27:24][INFO] i= 31 x: [[4.2949673e+09 8.5899346e+09]]
[07-15 20:27:24][INF0] i= 32 x: [[-8.58993459e+09 -1.71798692e+10]]
[07-15 20:27:24][INFO] i= 33 x: [[1.71798692e+10 3.43597384e+10]]
[07-15 20:27:24][INF0] i= 34 x: [[-3.43597384e+10 -6.87194767e+10]]
[07-15 20:27:24][INF0] i= 35 x: [[6.87194767e+10 1.37438953e+11]]
[07-15 \ 20:27:24][INF0] \ i= 36 \ x: [[-1.37438953e+11 \ -2.74877907e+11]]
[07-15 20:27:24][INF0] i= 37 x: [[2.74877907e+11 5.49755814e+11]]
[07-15 20:27:24][INF0] i= 38 x: [[-5.49755814e+11 -1.09951163e+12]]
[07-15 20:27:24][INFO] i= 39 x: [[1.09951163e+12 2.19902326e+12]]
[07-15 \ 20:27:24][INFO] \ i= \ 40 \ x: \ [[-2.19902326e+12 \ -4.39804651e+12]]
[07-15 20:27:24][INF0] i= 41 x: [[4.39804651e+12 8.79609302e+12]]
[07-15 \ 20:27:24][INFO] \ i= 42 \ x: [[-8.79609302e+12 \ -1.75921860e+13]]
[07-15 20:27:24][INFO] i= 43 x: [[1.75921860e+13 3.51843721e+13]]
[07-15 20:27:24][INF0] i= 44 x: [[-3.51843721e+13 -7.03687442e+13]]
[07-15 20:27:24][INF0] i= 45 x: [[7.03687442e+13 1.40737488e+14]]
[07-15 \ 20:27:24][INFO] \ i=\ 46 \ x: \ [[-1.40737488e+14 \ -2.81474977e+14]]
[07-15 20:27:24][INF0] i= 47 x: [[2.81474977e+14 5.62949953e+14]]
[07-15 20:27:24][INF0] i= 48 x: [[-5.62949953e+14 -1.12589991e+15]]
[07-15 20:27:24][INF0] i= 49 x: [[1.12589991e+15 2.25179981e+15]]
```



Solución encontrada: [1125899906842626.000000, 2251799813685252.000000]

Caso 3: Posición inicial  $[-2 \ 4]$  [07-15 20:27:25][INFO] i= 0 x:  $[-2 \ 4]$  [07-15 20:27:25][INFO] i= 1 x:  $[[2. \ 4.]]$ 



## **Animaciones:**

Las animaciones se encuentran en el repositorio en la carpeta animations..