$$U(s) \xrightarrow{p \text{ signaux}} G(s) \xrightarrow{r \text{ signaux}} Y(s)$$

$$u(t) \xrightarrow{u} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_p \end{bmatrix} \xrightarrow{y} Y(t)$$

$$u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_p \end{bmatrix} \xrightarrow{y} Y(t)$$

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$$S_1 \longrightarrow S_1 \longrightarrow S_1 \longrightarrow y$$





