

# Control Systems Track: Comprehensive Program Overview

Mastering Feedback Control for Industrial Applications

Agnes

# Phase 1: System Modeling & Time Domain Analysis



## Introduction to Control Systems & MATLAB Basics

Laying the groundwork by defining control systems and introducing MATLAB as a primary tool for analysis and design.



## Transfer Functions & Block Diagram Algebra

Representing dynamic systems with mathematical models and using block diagram reduction to simplify complex loops.



## Time Domain Analysis

Exploring transient response (rise time, overshoot) and steady-state error to understand system behavior over time.



## Stability Criteria: Routh-Hurwitz Method

Introducing essential methods to determine system stability,



## Key Control Mechanism: The PID Controller

### Overview

The **Proportional-Integral-Derivative (PID)** controller is the cornerstone of feedback control, found in ~98% of industrial applications. Its strength is using a system's

### Error Calculation & Control Action

A PID controller continuously computes an **error signal** (setpoint vs. actual value) and corrects it using three terms: **Proportional**, **Integral**, and **Derivative**.

### Applications

Essential for managing variables like **pressure, flow, and temperature** in chemical processing, water treatment, and food production, ensuring high quality and stability.

# Phase 1: Frequency Domain Analysis & PID Control



## Frequency Domain Analysis

**Bode Plots:** Graphically represent system gain and phase vs. frequency, crucial for assessing stability margins.

**Nyquist Plots:** Offer a comprehensive view of stability by plotting frequency response in the complex plane, essential for robust design.

System Stability

## Core PID Principles

**Feedback Mechanism:** Continuously calculates an 'error signal' by comparing the desired setpoint to the measured process variable.

**Three Control Terms:** Utilizes Proportional (P), Integral (I), and Derivative (D) actions to achieve precise control in a closed-loop system.

Feedback Control

Design &

Practical

# Introduction to Modern Control & Applications

Exploring State-Space, System Properties, and Industrial Implementations



## State Space Representation: A Modern Approach

State-space is a model of a physical system as a set of input, output, and state variables related by first-order differential equations.

### Key Components:

- **State Variables:** Minimal set of variables describing the system's dynamic state.
- **State & Output Equations:** Describe how states change and how outputs relate to states and inputs.

### Advantages:

- Effective for multi-input, multi-output (MIMO) systems.
- Naturally incorporates initial conditions for complete analysis.
- Can be extended to represent non-linear systems.

**Conversion:** Techniques allow for seamless conversion between Transfer Function models and State-Space form, offering engineers flexibility in analysis and design.



## System Analysis: Controllability & Observability

A system is **controllable** if an input can move it from any initial state to any desired final state in finite time.

A system is **observable** if the initial state can be determined from its outputs over a finite time.

These concepts are fundamental for designing effective state-feedback controllers and state observers like Kalman filters.

Control Design



## Industrial Automation: Real-World Applications

Modern control systems are the backbone of industrial automation, enabling precision and



# Phase 2: Capstone Mini Project Kick-off



## Strategic Planning: Scoping & Team Formation

**Defining Scope:** Clearly articulate project goals, boundaries, and expected deliverables to ensure alignment.

**Team Dynamics:** Identify key roles, assign responsibilities, and establish communication protocols for effective collaboration.

**Foundation:** Laying a robust groundwork is crucial for the successful execution of the capstone project.

Project Planning



## Foundational Analysis: Modeling & Objectives

**System Representation:** Develop precise mathematical models (e.g., transfer function) of the chosen system.

**Target Definition:** Define specific control objectives like desired setpoint tracking, efficient disturbance rejection, and optimal response time.

**Precision:** An accurate model and well-defined objectives are paramount for effective controller design.

System Dynamics

# State Space Applications & Industrial Case Studies

## Advanced State Space Control

Moving beyond basic state-space representation, advanced techniques leverage the system's internal states for superior control performance and robustness. These methods offer systematic approaches to achieve precise and optimal control.

### Pole Placement

A direct design method where feedback gains are selected to explicitly assign the closed-loop poles (eigenvalues) of the system to desired locations, achieving predictable transient response characteristics like settling time and overshoot.

### Linear Quadratic Regulator (LQR)

An optimal control approach that determines state-feedback gains by minimizing a quadratic cost function, achieving an optimal balance between precise performance and minimal control effort, resulting in smoother control and better stability.

OPTIMAL CONTROL

SYSTEM OPTIMIZATION

## Diverse Industrial Applications

### Process Control

Maintains precise conditions in chemical reactors, power generation, and water treatment, ensuring quality, efficiency, and safety.



Robotics

## Industry Implementation

### Distributed Control Systems (DCS)

Integrated systems for complex, continuous process industries (e.g., power plants, refineries) providing centralized control and high reliability.



Image Sources: Smart Manufacturing Plant Stock Photos, Tech Robotics Stock Photos, Automotive Control Systems Photos, ABB DCS, Plc Control Stock Photos.

# Career Launchpad & Program Conclusion



## Final Project: Showcase Your Expertise

**Culminating Effort:** The final project serves as the pinnacle of the program, integrating all learned concepts in a practical, real-world control system challenge.

**Presentation & Defense:** Formally present your solutions, methodologies, and results to a panel of instructors and industry experts, honing essential professional communication skills.

**Comprehensive Documentation:** Prepare a detailed project report and technical documentation, reinforcing structured problem-solving and technical writing.

Project Culmination

Innovation & Application

# Thank You & Further Engagement



# Thank You

For your time and attention. We look forward to connecting with you and exploring the future of control systems together.



## General Inquiries & Support

Have questions about our control systems track or need further details? Our team is ready to assist you.

Contact Us: [x@y.com](mailto:x@y.com)

Contact

Engagement



## Discover Our AI Solutions

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Innovation

Future