ESP32-S3-WROOM-1UESP32-S3-WROOM-1U

Datasheet Version 1.4

2.4 GHz Wi-Fi (802.11b/g/n) and Bluetooth® 5 module
Built around ESP32-S3 series of SoCs, Xtensa® dual-core 32-bit LX7 microprocessor
Flash up to 16 MB, PSRAM up to 16 MB
Up to 36 GPIOs, rich set of peripherals
On-board PCB antenna or external antenna connector



ESP32-S3-WROOM-1



ESP32-S3-WROOM-1U



1 Module Overview

Note:

Check the link or the QR code to make sure that you use the latest version of this document: https://www.espressif.com/documentation/esp32-s3-wroom-1_wroom-1u_datasheet_en.pdf



1.1 Features

CPU and On-Chip Memory

- ESP32-S3 series of SoCs embedded, Xtensa® dual-core 32-bit LX7 microprocessor (with single precision FPU), up to 240 MHz
- 384 KB ROM
- 512 KB SRAM
- 16 KB SRAM in RTC
- Up to 16 MB PSRAM

Wi-Fi

- 802.11b/g/n
- Bit rate: 802.11n up to 150 Mbps
- A-MPDU and A-MSDU aggregation
- 0.4 μ s guard interval support
- Center frequency range of operating channel:
 2412 ~ 2484 MHz

Bluetooth

- Bluetooth LE: Bluetooth 5, Bluetooth mesh
- Speed: 125 Kbps, 500 Kbps, 1 Mbps, 2 Mbps
- Advertising extensions
- Multiple advertisement sets
- Channel selection algorithm #2
- Internal co-existence mechanism between Wi-Fi and Bluetooth to share the same antenna

Peripherals

• 36 GPIOs

- 4 strapping GPIOs
- SPI, LCD interface, Camera interface, UART, I2C, I2S, remote control, pulse counter, LED PWM, full-speed USB 2.0 OTG, USB Serial/JTAG controller, MCPWM, SDIO host controller, GDMA, TWAI® controller (compatible with ISO 11898-1), ADC, touch sensor, temperature sensor, timers and watchdogs

Integrated Components on Module

- 40 MHz crystal oscillator
- Up to 16 MB Quad SPI flash

Antenna Options

- ESP32-S3-WROOM-1: On-board PCB antenna
- ESP32-S3-WROOM-1U: External antenna via a connector

Operating Conditions

- Operating voltage/Power supply: 3.0 ~ 3.6 V
- Operating ambient temperature:
 - 65 °C version: -40 ~ 65 °C
 - 85 °C version: -40 ~ 85 °C
 - 105 °C version: -40 ~ 105 °C

Certification

- RF certification: See certificates
- Green certification: RoHS/REACH

Test

HTOL/HTSL/uHAST/TCT/ESD

1.2 Series Comparison

ESP32-S3-WROOM-1 and ESP32-S3-WROOM-1U are two powerful, generic Wi-Fi + Bluetooth LE MCU modules that are built around the ESP32-S3 series of SoCs. On top of a rich set of peripherals, the acceleration for neural network computing and signal processing workloads provided by the SoC make the modules an ideal choice for a wide variety of application scenarios related to Al and Artificial Intelligence of Things (AloT), such as wake word detection, speech commands recognition, face detection and recognition, smart home, smart appliances, smart control panel, smart speaker, etc.

ESP32-S3-WROOM-1 comes with a PCB antenna. ESP32-S3-WROOM-1U comes with an external antenna connector. A wide selection of module variants are available for customers as shown in Table 1 and 2. Among them, H4 series modules operate at $-40 \sim 105$ °C ambient temperature, R8 and R16V series modules operate at $-40 \sim 65$ °C ambient temperature, and other module variants operate at $-40 \sim 85$ °C ambient temperature. For R8 and R16V series modules with Octal SPI PSRAM, if the PSRAM ECC function is enabled, the maximum ambient temperature can be improved to 85 °C, while the usable size of PSRAM will be reduced by 1/16.

Ordering Code ²	Flash ^{3, 4}	PSRAM ⁵	Ambient Temp. ⁶	Size ⁷
Ordering Code	Fiasii *	PORAIVI	(°C)	(mm)
ESP32-S3-WROOM-1-N4	4 MB (Quad SPI)	-	-40 ~ 85	
ESP32-S3-WROOM-1-N8	8 MB (Quad SPI)	-	-40 ~ 85	
ESP32-S3-WROOM-1-N16	16 MB (Quad SPI)	-	-40 ~ 85	18.0
ESP32-S3-WROOM-1-H4	4 MB (Quad SPI)	-	-40 ~ 105	10.U
ESP32-S3-WROOM-1-N4R2	4 MB (Quad SPI)	2 MB (Quad SPI)	-40 ~ 85	25.5
ESP32-S3-WROOM-1-N8R2	8 MB (Quad SPI)	2 MB (Quad SPI)	-40 ~ 85	20.0 ×
ESP32-S3-WROOM-1-N16R2	16 MB (Quad SPI)	2 MB (Quad SPI)	-40 ~ 85	3.1
ESP32-S3-WROOM-1-N4R8	4 MB (Quad SPI)	8 MB (Octal SPI)	-40 ~ 65	3.1
ESP32-S3-WROOM-1-N8R8	8 MB (Quad SPI)	8 MB (Octal SPI)	-40 ~ 65	
ESP32-S3-WROOM-1-N16R8	16 MB (Quad SPI)	8 MB (Octal SPI)	-40 ~ 65	
ESP32-S3-WROOM-1-N16R16VA8	16 MB (Quad SPI)	16 MB (Octal SPI)	-40 ~ 65	

Table 1: ESP32-S3-WROOM-1 Series Comparison¹

¹ This table shares the same notes presented in Table 2 below.

Ordering Code ²	Flash ^{3, 4}	PSRAM ⁵	Ambient Temp. ⁶	Size ⁷
Ordering Code	1 10011	TOKAW	(°C)	(mm)
ESP32-S3-WROOM-1U-N4	4 MB (Quad SPI)	-	-40 ~ 85	
ESP32-S3-WROOM-1U-N8	8 MB (Quad SPI)	-	-40 ~ 85	
ESP32-S3-WROOM-1U-N16	16 MB (Quad SPI)	-	-40 ~ 85	18.0
ESP32-S3-WROOM-1U-H4	4 MB (Quad SPI)	-	-40 ~ 105	10.U
ESP32-S3-WROOM-1U-N4R2	4 MB (Quad SPI)	2 MB (Quad SPI)	-40 ~ 85	19.2
ESP32-S3-WROOM-1U-N8R2	8 MB (Quad SPI)	2 MB (Quad SPI)	-40 ~ 85	19.2 X
ESP32-S3-WROOM-1U-N16R2	16 MB (Quad SPI)	2 MB (Quad SPI)	-40 ~ 85	3.2
ESP32-S3-WROOM-1U-N4R8	4 MB (Quad SPI)	8 MB (Octal SPI)	-40 ~ 65	3.2
ESP32-S3-WROOM-1U-N8R8	8 MB (Quad SPI)	8 MB (Octal SPI)	-40 ~ 65	
ESP32-S3-WROOM-1U-N16R8	16 MB (Quad SPI)	8 MB (Octal SPI)	-40 ~ 65	
ESP32-S3-WROOM-1U-N16R16VA8	16 MB (Quad SPI)	16 MB (Octal SPI)	-40 ~ 65	

Table 2: ESP32-S3-WROOM-1U Series Comparison

- ² For customization of ESP32-S3-WROOM-1-H4, ESP32-S3-WROOM-1U-H4, and ESP32-S3-WROOM-1U-N16R16VA, please contact us.
- ³ By default, the SPI flash on the module operates at a maximum clock frequency of 80 MHz and does not support the auto suspend feature. If you have a requirement for a higher flash clock frequency of 120 MHz or if you need the flash auto suspend feature, please contact us.
- ⁴ The integrated flash supports:
 - More than 100,000 program/erase cycles
 - More than 20 years data retention time
- ⁵ The modules use PSRAM integrated in the chip's package.
- ⁶ Ambient temperature specifies the recommended temperature range of the environment immediately outside the Espressif module.
- ⁷ For details, refer to Section 10.1 Module Dimensions.
- ⁸ Please note that the VDD_SPI voltage is 1.8 V for ESP32-S3-WROOM-1-N16R16VA and ESP32-S3-WROOM-1U-N16R16VA only.

At the core of the modules is an ESP32-S3 series of SoC *, an Xtensa® 32-bit LX7 CPU that operates at up to 240 MHz. You can power off the CPU and make use of the low-power co-processor to constantly monitor the peripherals for changes or crossing of thresholds.

Note:

For more information on ESP32-S3, please refer to ESP32-S3 Series Datasheet.

For chip revision identification, ESP-IDF release that supports a specific chip revision, and other information on chip revisions, please refer to *ESP32-S3 Series SoC Errata* > Section *Chip Revision Identification*.

1.3 Applications

- Smart Home
- Industrial Automation
- Health Care
- Consumer Electronics
- Smart Agriculture
- POS Machines
- Service Robot
- Audio Devices

- Generic Low-power IoT Sensor Hubs
- Generic Low-power IoT Data Loggers
- Cameras for Video Streaming
- USB Devices
- Speech Recognition
- Image Recognition
- Wi-Fi + Bluetooth Networking Card
- Touch and Proximity Sensing

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2 Block Diagram

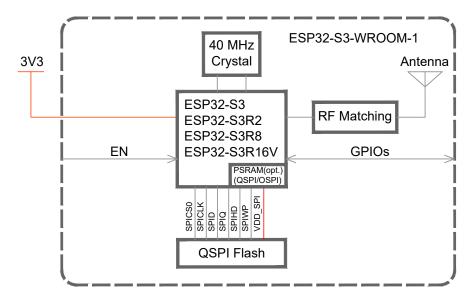


Figure 1: ESP32-S3-WROOM-1 Block Diagram

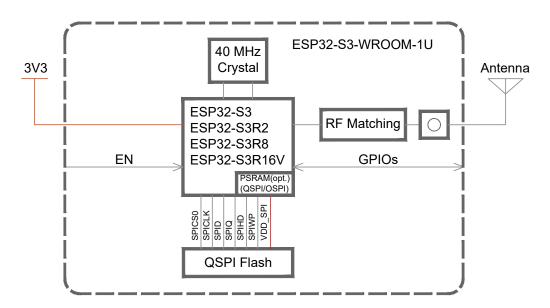


Figure 2: ESP32-S3-WROOM-1U Block Diagram

3 Pin Definitions

3.1 Pin Layout

The pin diagram below shows the approximate location of pins on the module. For the actual diagram drawn to scale, please refer to Figure 10.1 *Module Dimensions*.

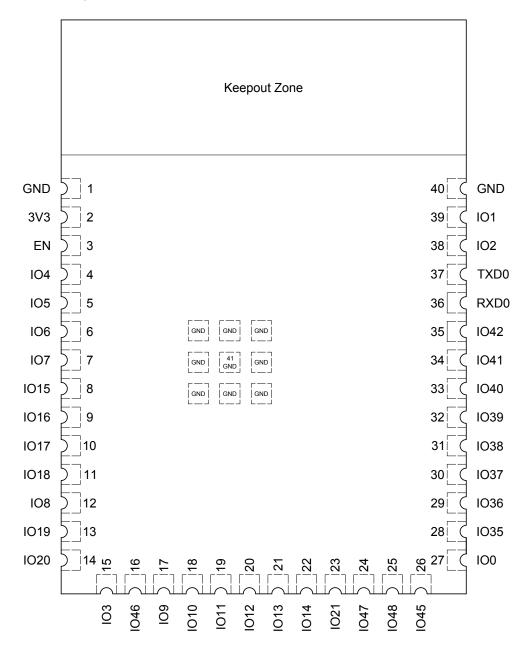


Figure 3: Pin Layout (Top View)

Note A:

The pin diagram is applicable to ESP32-S3-WROOM-1 and ESP32-S3-WROOM-1U, but the latter has no antenna keepout zone.

To learn more about the keepout zone for module's antenna on the base board, please refer to <u>ESP32-S3 Hardware Design Guidelines</u> > Section Positioning a Module on a Base Board.

Pin Description 3.2

The module has 41 pins. See pin definitions in Table 3 *Pin Definitions*.

For explanations of pin names and function names, as well as configurations of peripheral pins, please refer to ESP32-S3 Series Datasheet.

Table 3: Pin Definitions

SND	Name	No.	Type ^a	Function
High: on, enables the chip.	GND	1	Р	GND
EN	3V3	2	Р	Power supply
Note: Do not leave the EN pin floating.				High: on, enables the chip.
104	EN	3	I	Low: off, the chip powers off.
105 5				Note: Do not leave the EN pin floating.
106	104	4	I/O/T	RTC_GPIO4, GPIO4, TOUCH4, ADC1_CH3
107	105	5	I/O/T	RTC_GPIO5, GPIO5, TOUCH5, ADC1_CH4
1015 8	106	6	I/O/T	RTC_GPIO6, GPIO6, TOUCH6, ADC1_CH5
1016 9	107	7	I/O/T	RTC_GPIO7, GPIO7, TOUCH7, ADC1_CH6
1017 10	1015	8	I/O/T	RTC_GPI015, GPI015, UORTS, ADC2_CH4, XTAL_32K_P
1018	1016	9	I/O/T	RTC_GPIO16, GPIO16, UOCTS, ADC2_CH5, XTAL_32K_N
108	IO17	10	I/O/T	RTC_GPIO17, GPIO17, U1TXD, ADC2_CH6
1019	1018	11	I/O/T	RTC_GPIO18, GPIO18, U1RXD, ADC2_CH7, CLK_OUT3
1020	108	12	I/O/T	RTC_GPIO8, GPIO8, TOUCH8, ADC1_CH7, SUBSPICS1
103	1019	13	I/O/T	RTC_GPIO19, GPIO19, U1RTS, ADC2_CH8, CLK_OUT2, USB_D-
1046 16	1020	14	I/O/T	RTC_GPIO20, GPIO20, U1CTS, ADC2_CH9, CLK_OUT1, USB_D+
17	103	15	I/O/T	RTC_GPIO3, GPIO3, TOUCH3, ADC1_CH2
IO10	1046	16	I/O/T	GPIO46
1010	109	17	I/O/T	RTC_GPIO9, GPIO9, TOUCH9, ADC1_CH8, FSPIHD, SUBSPIHD
IO11 19	1010	18	I/O/T	
1012 20	1011	10	L/O/T	
1012 20	1011	19	1/0/1	
IO14 22 I/O/T RTC_GPIO14, GPIO14, TOUCH14, ADC2_CH3, FSPIWP, FSPIDQS, SUBSPIWP IO21 23 I/O/T RTC_GPIO21, GPIO21 IO47 ° 24 I/O/T SPICLK_P_DIFF,GPIO47, SUBSPICLK_P_DIFF IO48 ° 25 I/O/T SPICLK_N_DIFF,GPIO48, SUBSPICLK_N_DIFF IO45 26 I/O/T GPIO45 IO0 27 I/O/T RTC_GPIO0, GPIO0 IO35	1012	20	I/O/T	
1014 22 1/0/T SUBSPIWP 1021 23 1/0/T RTC_GPI021, GPI021 1047	IO13	21	I/O/T	RTC_GPI013, GPI013, TOUCH13, ADC2_CH2, FSPIQ, FSPII07, SUBSPIQ
IO21 23 I/O/T RTC_GPIO21, GPIO21 IO47 ° 24 I/O/T SPICLK_P_DIFF,GPIO47, SUBSPICLK_P_DIFF IO48 ° 25 I/O/T SPICLK_N_DIFF,GPIO48, SUBSPICLK_N_DIFF IO45 26 I/O/T GPIO45 IO0 27 I/O/T RTC_GPIO0, GPIO0 IO35	IO14	22	I/O/T	
IO47 ° 24 I/O/T SPICLK_P_DIFF, GPIO47, SUBSPICLK_P_DIFF IO48 ° 25 I/O/T SPICLK_N_DIFF, GPIO48, SUBSPICLK_N_DIFF IO45 26 I/O/T GPIO45 IO0 27 I/O/T RTC_GPIO0, GPIO0 IO35 b 28 I/O/T SPIIO6, GPIO35, FSPID, SUBSPID IO36 b 29 I/O/T SPIIO7, GPIO36, FSPICLK, SUBSPICLK IO37 b 30 I/O/T SPIDQS, GPIO37, FSPIQ, SUBSPIQ	1021	23	I/O/T	
IO48 ° 25 I/O/T SPICLK_N_DIFF,GPIO48, SUBSPICLK_N_DIFF IO45 26 I/O/T GPIO45 IOO 27 I/O/T RTC_GPIOO, GPIOO IO35 b 28 I/O/T SPIIO6, GPIO35, FSPID, SUBSPID IO36 b 29 I/O/T SPIIO7, GPIO36, FSPICLK, SUBSPICLK IO37 b 30 I/O/T SPIDQS, GPIO37, FSPIQ, SUBSPIQ				=
IO45 26 I/O/T GPIO45 IO0 27 I/O/T RTC_GPIOO, GPIOO IO35 b 28 I/O/T SPIIO6, GPIO35, FSPID, SUBSPID IO36 b 29 I/O/T SPIIO7, GPIO36, FSPICLK, SUBSPICLK IO37 b 30 I/O/T SPIDQS, GPIO37, FSPIQ, SUBSPIQ				
IOO 27 I/O/T RTC_GPIOO, GPIOO IO35 b 28 I/O/T SPIIO6, GPIO35, FSPID, SUBSPID IO36 b 29 I/O/T SPIIO7, GPIO36, FSPICLK, SUBSPICLK IO37 b 30 I/O/T SPIDQS, GPIO37, FSPIQ, SUBSPIQ				
IO35 b 28 I/O/T SPIIO6, GPIO35, FSPID, SUBSPID IO36 b 29 I/O/T SPIIO7, GPIO36, FSPICLK, SUBSPICLK IO37 b 30 I/O/T SPIDQS, GPIO37, FSPIQ, SUBSPIQ				
IO36 b29I/O/TSPIIO7, GPIO36, FSPICLK, SUBSPICLKIO37 b30I/O/TSPIDQS, GPIO37, FSPIQ, SUBSPIQ				_
IO37 b 30 I/O/T SPIDQS, GPIO37 , FSPIQ, SUBSPIQ				
IOOO OI I/O/I Griooo , Ioriwer, Oodoriwe	1038	31	I/O/T	GPI038, FSPIWP, SUBSPIWP

Cont'd on next page

Table 3 – cont'd from previous page

Name	No.	Type ^a	Function
1039	32	I/O/T	MTCK, GPIO39, CLK_OUT3, SUBSPICS1
1040	33	I/O/T	MTDO, GPIO40, CLK_OUT2
1041	34	I/O/T	MTDI, GPIO41, CLK_OUT1
1042	35	I/O/T	MTMS, GPIO42
RXDO	36	I/O/T	UORXD, GPIO44, CLK_OUT2
TXDO	37	I/O/T	UOTXD, GPIO43, CLK_OUT1
102	38	I/O/T	RTC_GPIO2, GPIO2, TOUCH2, ADC1_CH1
IO1	39	I/O/T	RTC_GPI01, GPI01, TOUCH1, ADC1_CH0
GND	40	Р	GND
EPAD	41	Р	GND

^a P: power supply; I: input; O: output; T: high impedance. Pin functions in bold font are the default pin functions. For pin 28 \sim 30, the default function is decided by eFuse bit.

^b For modules with Octal SPI PSRAM, i.e., modules embedded with ESP32-S3R8 or ESP32-S3R16V, pins IO35, IO36, and IO37 are connected to the Octal SPI PSRAM and are not available for other uses.

^c For modules embedded with ESP32-S3R16V, as the VDD_SPI voltage of the ESP32-S3R16V chip is set to 1.8 V, the working voltage for GPIO47 and GPIO48 is also 1.8 V, which is different from other GPIOs.

4 Boot Configurations

Note:

The content below is excerpted from <u>ESP32-S3 Series Datasheet</u> > Section Boot Configurations. For the strapping pin mapping between the chip and modules, please refer to Chapter 8 <u>Module Schematics</u>.

The chip allows for configuring the following boot parameters through strapping pins and eFuse bits at power-up or a hardware reset, without microcontroller interaction.

Chip boot mode

- Strapping pin: GPIOO and GPIO46

VDD_SPI voltage

- Strapping pin: GPIO45

- eFuse parameter: EFUSE_VDD_SPI_FORCE and EFUSE_VDD_SPI_TIEH

· ROM message printing

- Strapping pin: GPIO46

 eFuse parameter: EFUSE_UART_PRINT_CONTROL and EFUSE_DIS_USB_SERIAL_JTAG_ROM_PRINT

· JTAG signal source

- Strapping pin: GPIO3

- eFuse parameter: EFUSE_DIS_PAD_JTAG, EFUSE_DIS_USB_JTAG, and EFUSE_STRAP_JTAG_SEL

The default values of all the above eFuse parameters are 0, which means that they are not burnt. Given that eFuse is one-time programmable, once programmed to 1, it can never be reverted to 0. For how to program eFuse parameters, please refer to ESP32-S3 Technical Reference Manual > Chapter eFuse Controller.

The default values of the strapping pins, namely the logic levels, are determined by pins' internal weak pull-up/pull-down resistors at reset if the pins are not connected to any circuit, or connected to an external high-impedance circuit.

Table 4: Default Configuration of Strapping Pins

Strapping Pin	Default Configuration	Bit Value
GPI00	Weak pull-up	1
GPIO3	Floating	_
GPIO45	Weak pull-down	0
GPIO46	Weak pull-down	0

To change the bit values, the strapping pins should be connected to external pull-down/pull-up resistances. If the ESP32-S3 is used as a device by a host MCU, the strapping pin voltage levels can also be controlled by the host MCU.

All strapping pins have latches. At system reset, the latches sample the bit values of their respective strapping pins and store them until the chip is powered down or shut down. The states of latches cannot be changed in

any other way. It makes the strapping pin values available during the entire chip operation, and the pins are freed up to be used as regular IO pins after reset.

The timing of signals connected to the strapping pins should adhere to the setup time and hold time specifications in Table 5 and Figure 4.

Table 5: Description of Timing Parameters for the Strapping Pins

Parameter	Description	Min (ms)
+	Setup time is the time reserved for the power rails to stabilize be-	
t_{SU}	fore the CHIP_PU pin is pulled high to activate the chip.	
	Hold time is the time reserved for the chip to read the strapping	
t_H	pin values after CHIP_PU is already high and before these pins	3
	start operating as regular IO pins.	

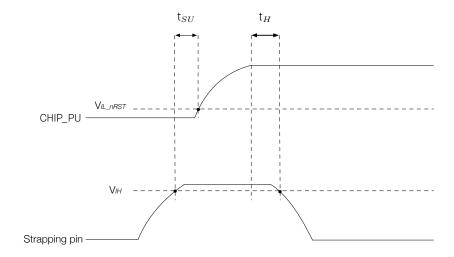


Figure 4: Visualization of Timing Parameters for the Strapping Pins

Chip Boot Mode Control 4.1

GPIOO and GPIO46 control the boot mode after the reset is released. See Table 6 Chip Boot Mode Control.

Table 6: Chip Boot Mode Control

Boot Mode	GPIOO	GPIO46
SPI Boot	1	Any value
Joint Download Boot ²	0	0

¹ Bold marks the default value and configuration.

- USB Download Boot:
 - USB-Serial-JTAG Download Boot
 - USB-OTG Download Boot
- UART Download Boot

² Joint Download Boot mode supports the following download methods:

In SPI Boot mode, the ROM bootloader loads and executes the program from SPI flash to boot the system.

In Joint Download Boot mode, users can download binary files into flash using UARTO or USB interface. It is also possible to download binary files into SRAM and execute it from SRAM.

In addition to SPI Boot and Joint Download Boot modes, ESP32-S3 also supports SPI Download Boot mode. For details, please see *ESP32-S3 Technical Reference Manual* > Chapter *Chip Boot Control*.

4.2 VDD_SPI Voltage Control

Depending on the value of EFUSE_VDD_SPI_FORCE, the voltage can be controlled in two ways.

Table 7: VDD_SPI Voltage Control

VDD_SPI power source ²	Voltage	EFUSE_VDD_SPI_FORCE	GPIO45	EFUSE_VDD_SPI_TIEH
VDD3P3_RTC via R_{SPI}	3.3 V	0	0	Ignored
Flash Voltage Regulator	1.8 V	U	1	ignored
Flash Voltage Regulator	1.8 V	1	lanorod	0
VDD3P3_RTC via R _{SPI}	3.3 V	l	Ignored	1

¹ **Bold** marks the default value and configuration.

4.3 ROM Messages Printing Control

During boot process the messages by the ROM code can be printed to:

- (Default) UARTO and USB Serial/JTAG controller
- USB Serial/JTAG controller
- UARTO

The ROM messages printing to UART or USB Serial/JTAG controller can be respectively disabled by configuring registers and eFuse. For detailed information, please refer to <u>ESP32-S3 Technical Reference Manual</u> > Chapter Chip Boot Control.

4.4 JTAG Signal Source Control

The strapping pin GPIO3 can be used to control the source of JTAG signals during the early boot process. This pin does not have any internal pull resistors and the strapping value must be controlled by the external circuit that cannot be in a high impedance state.

As Table 8 shows, GPIO3 is used in combination with EFUSE_DIS_PAD_JTAG, EFUSE_DIS_USB_JTAG, and EFUSE_STRAP_JTAG_SEL.

² See ESP32-S3 Series Datasheet > Section Power Scheme.

Table 8: JTAG Signal Source Control

JTAG Signal Source	EFUSE_DIS_PAD_JTAG	EFUSE_DIS_USB_JTAG	EFUSE_STRAP_JTAG_SEL	GPIO3
	0	0	0	Ignored
USB Serial/JTAG Controller	0	0	1	1
	1	0	Ignored	Ignored
JTAG pins ²	0	0	1	0
	0	1	Ignored	Ignored
JTAG is disabled	1	1	Ignored	Ignored

 $^{^{\}rm 1}$ Bold marks the default value and configuration.

 $^{^{\}rm 2}$ JTAG pins refer to MTDI, MTCK, MTMS, and MTDO.

5 Peripherals

5.1 Peripheral Overview

ESP32-S3 integrates a rich set of peripherals including SPI, LCD, Camera interface, UART, I2C, I2S, remote control, pulse counter, LED PWM, USB Serial/JTAG, MCPWM, SD/MMC host controller, TWAI® controller (compatible with ISO 11898-1, i.e., CAN Specification 2.0), ADC, touch sensor, and temperature sensor. It also includes a full-speed USB 2.0 On-The-Go (OTG) interface to enable USB communication.

To learn more about on-chip components, please refer to <u>ESP32-S3 Series Datasheet</u> > Section Functional Description.

Note:

The content below is sourced from <u>ESP32-S3 Series Datasheet</u> > Section *Peripherals*. Some information may not be applicable to ESP32-S3-WROOM-1 and ESP32-S3-WROOM-1U as not all the IO signals are exposed on the module. To learn more about peripheral signals, please refer to <u>ESP32-S3 Technical Reference Manual</u> > Section *Peripheral Signals via GPIO Matrix*.

5.2 Peripheral Description

This section describes the chip's peripheral capabilities, covering connectivity interfaces and on-chip sensors that extend its functionality.

5.2.1 Connectivity Interface

This subsection describes the connectivity interfaces on the chip that enable communication and interaction with external devices and networks.

5.2.1.1 UART Controller

ESP32-S3 has three UART (Universal Asynchronous Receiver Transmitter) controllers, i.e., UARTO, UART1, and UART2, which support IrDA and asynchronous communication (RS232 and RS485) at a speed of up to 5 Mbps.

Feature List

- Three clock sources that can be divided
- Programmable baud rate
- 1024 x 8-bit RAM shared by TX FIFOs and RX FIFOs of the three UART controllers
- Full-duplex asynchronous communication
- Automatic baud rate detection of input signals
- Data bits ranging from 5 to 8
- Stop bits of 1, 1.5, 2, or 3 bits
- Parity bit

- Special character AT_CMD detection
- RS485 protocol
- IrDA protocol
- High-speed data communication using GDMA
- UART as wake-up source
- Software and hardware flow control

Pin Assignment

- UARTO
 - The pins UOTXD and UORXD that are connected to transmit and receive signals are multiplexed with GPIO43 ~ GPIO44 via IO MUX, and can also be connected to any GPIO via the GPIO Matrix.
 - The pins UORTS and UOCTS that are connected to hardware flow control signals are multiplexed with GPI015 ~ GPI016, RTC_GPI015 ~ RTC_GPI016, XTAL_32K_P and XTAL_32K_N, and SAR ADC2 interface via IO MUX, and can also be connected to any GPIO via the GPIO Matrix.
 - The pins UODTR and UODSR that are connected to hardware flow control signals can be chosen from any GPIO via the GPIO Matrix.

• UART1

- The pins U1TXD and U1RXD that are connected to transmit and receive signals are multiplexed with GPI017 ~ GPI018, RTC_GPI017 ~ RTC_GPI018, and SAR ADC2 interface via IO MUX, and can also be connected to any GPIO via the GPIO Matrix.
- The pins U1RTS and U1CTS that are connected to hardware flow control signals are multiplexed with GPI019 ~ GPI020, RTC_GPI019 ~ RTC_GPI020, USB_D- and USB_D+ pins, and SAR ADC2 interface via IO MUX, and can also be connected to any GPIO via the GPIO Matrix.
- The pins U1DTR and U1DSR that are connected to hardware flow control signals can be chosen from any GPIO via the GPIO Matrix.
- UART2: The pins used can be chosen from any GPIO via the GPIO Matrix.

For more information about the pin assignment, see ESP32-S3 Series Datasheet > Section IO Pins and ESP32-S3 Technical Reference Manual > Chapter IO MUX and GPIO Matrix.

5.2.1.2 I2C Interface

ESP32-S3 has two I2C bus interfaces which are used for I2C master mode or slave mode, depending on the user's configuration.

Feature List

- Standard mode (100 kbit/s)
- Fast mode (400 kbit/s)
- Up to 800 kbit/s (constrained by SCL and SDA pull-up strength)
- 7-bit and 10-bit addressing mode

• Double addressing mode (slave addressing and slave register addressing)

The hardware provides a command abstraction layer to simplify the usage of the I2C peripheral.

Pin Assignment

For I2C, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.1.3 I2S Interface

ESP32-S3 includes two standard I2S interfaces. They can operate in master mode or slave mode, in full-duplex mode or half-duplex communication mode, and can be configured to operate with an 8-bit, 16-bit, 24-bit, or 32-bit resolution as an input or output channel. BCK clock frequency, from 10 kHz up to 40 MHz, is supported.

The I2S interface has a dedicated DMA controller. It supports TDM PCM, TDM MSB alignment, TDM LSB alignment, TDM Phillips, and PDM interface.

Pin Assignment

For I2S, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.1.4 LCD and Camera Controller

The LCD and Camera controller of ESP32-S3 consists of a LCD module and a camera module.

The LCD module is designed to send parallel video data signals, and its bus supports 8-bit ~ 16-bit parallel RGB, I8080, and MOTO6800 interfaces. These interfaces operate at 40 MHz or lower, and support conversion among RGB565, YUV422, YUV420, and YUV411.

The camera module is designed to receive parallel video data signals, and its bus supports an 8-bit ~ 16-bit DVP image sensor, with clock frequency of up to 40 MHz. The camera interface supports conversion among RGB565, YUV422, YUV420, and YUV411.

Pin Assignment

For LCD and Camera controller, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.1.5 Serial Peripheral Interface (SPI)

ESP32-S3 has the following SPI interfaces:

- SPIO used by ESP32-S3's GDMA controller and cache to access in-package or off-package flash/PSRAM
- SPI1 used by the CPU to access in-package or off-package flash/PSRAM

- SPI2 is a general purpose SPI controller with access to a DMA channel allocated by the GDMA controller
- SPI3 is a general purpose SPI controller with access to a DMA channel allocated by the GDMA controller

Feature List

- SPIO and SPI1:
 - Supports Single SPI, Dual SPI, Quad SPI, Octal SPI, QPI, and OPI modes
 - 8-line SPI mode supports single data rate (SDR) and double data rate (DDR)
 - Configurable clock frequency with a maximum of 120 MHz for 8-line SPI SDR/DDR modes
 - Data transmission is in bytes

• SPI2:

- Supports operation as a master or slave
- Connects to a DMA channel allocated by the GDMA controller
- Supports Single SPI, Dual SPI, Quad SPI, Octal SPI, QPI, and OPI modes
- Configurable clock polarity (CPOL) and phase (CPHA)
- Configurable clock frequency
- Data transmission is in bytes
- Configurable read and write data bit order: most-significant bit (MSB) first, or least-significant bit (LSB) first
- As a master
 - * Supports 2-line full-duplex communication with clock frequency up to 80 MHz
 - * Full-duplex 8-line SPI mode supports single data rate (SDR) only
 - * Supports 1-, 2-, 4-, 8-line half-duplex communication with clock frequency up to 80 MHz
 - * Half-duplex 8-line SPI mode supports both single data rate (up to 80 MHz) and double data rate (up to 40 MHz)
 - * Provides six SPI_CS pins for connection with six independent SPI slaves
 - * Configurable CS setup time and hold time
- As a slave
 - * Supports 2-line full-duplex communication with clock frequency up to 60 MHz
 - * Supports 1-, 2-, 4-line half-duplex communication with clock frequency up to 60 MHz
 - * Full-duplex and half-duplex 8-line SPI mode supports single data rate (SDR) only

SPI3:

- Supports operation as a master or slave
- Connects to a DMA channel allocated by the GDMA controller
- Supports Single SPI, Dual SPI, Quad SPI, and QPI modes

- Configurable clock polarity (CPOL) and phase (CPHA)
- Configurable clock frequency
- Data transmission is in bytes
- Configurable read and write data bit order: most-significant bit (MSB) first, or least-significant bit (LSB) first
- As a master
 - * Supports 2-line full-duplex communication with clock frequency up to 80 MHz
 - * Supports 1-, 2-, 4-line half-duplex communication with clock frequency up to 80 MHz
 - * Provides three SPI_CS pins for connection with three independent SPI slaves
 - * Configurable CS setup time and hold time
- As a slave
 - * Supports 2-line full-duplex communication with clock frequency up to 60 MHz
 - * Supports 1-, 2-, 4-line half-duplex communication with clock frequency up to 60 MHz

Pin Assignment

Note:

Please refer to ESP32-S3 Series Datasheet > Section IO MUX Function > Table IO MUX Pin Functions for the corresponding SPI interface details.

- SPIO/1
 - Via IO MUX:
 - * Interface 4a is multiplexed with GPIO26 ~ GPIO32 via IO MUX. When used in conjunction with 4b, it can operate as the lower 4 bits data line interface and the CLK, CSO, and CS1 interfaces in 8-line SPI mode.
 - * Interface 4b is multiplexed with GPIO33 ~ GPIO37 and SPI interfaces 4e and 4f via IO MUX. When used in conjunction with 4a, it can operate as the higher 4 bits data line interface and DQS interface in 8-line SPI mode.
 - * Interface 4d is multiplexed with GPIO8 ~ GPIO14, RTC_GPIO8 ~ RTC_GPIO14, Touch Sensor interface, SAR ADC interface, and SPI interfaces 4c and 4g via IO MUX. Note that the fast SPI2 interface will not be available.
 - * Interface 4e is multiplexed with GPIO33 ~ GPIO39, JTAG MTCK interface, and SPI interfaces 4b and 4f via IO MUX. It is an alternative group of signal lines that can be used if SPIO/1 does not use 8-line SPI connection.
 - Via GPIO Matrix: The pins used can be chosen from any GPIOs via the GPIO Matrix.
- SPI2
 - Via IO MUX:
 - * Interface 4c is multiplexed with GPIO9 ~ GPIO14, RTC_GPIO9 ~ RTC_GPIO14, Touch Sensor interface, SAR ADC interface, and SPI interfaces 4d and 4g via IO MUX. It is the SPI2 main interface for fast SPI connection.

- * (not recommended) Interface 4f is multiplexed with GPIO33 ~ GPIO38, SPI interfaces 4e and 4b via IO MUX. It is the alternative SPI2 interface if the main SPI2 is not available. Its performance is comparable to SPI2 via GPIO matrix, so use the GPIO matrix instead.
- * (not recommended) Interface 4q is multiplexed with GPIO10 ~ GPIO14, RTC GPIO10 ~ RTC GPIO14, Touch Sensor interface, SAR ADC interface, and SPI interfaces 4c and 4d via IO MUX. It is the alternative SPI2 interface signal lines for 8-line SPI connection.
- Via GPIO Matrix: The pins used can be chosen from any GPIOs via the GPIO Matrix.
- SPI3: The pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see ESP32-S3 Series Datasheet > Section IO Pins and ESP32-S3 Technical Reference Manual > Chapter IO MUX and GPIO Matrix.

5.2.1.6 Two-Wire Automotive Interface (TWAI®)

The Two-Wire Automotive Interface (TWAI®) is a multi-master, multi-cast communication protocol with error detection and signaling as well as inbuilt message priorities and arbitration.

Feature List

- Compatible with ISO 11898-1 protocol (CAN Specification 2.0)
- Standard frame format (11-bit ID) and extended frame format (29-bit ID)
- Bit rates from 1 Kbit/s to 1 Mbit/s
- Multiple modes of operation:
 - Normal
 - Listen Only
 - Self-Test (no acknowledgment required)
- 64-byte receive FIFO
- Acceptance filter (single and dual filter modes)
- Error detection and handling:
 - Error counters
 - Configurable error interrupt threshold
 - Error code capture
 - Arbitration lost capture

Pin Assignment

For TWAI, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see ESP32-S3 Series Datasheet > Section IO Pins and ESP32-S3 Technical Reference Manual > Chapter IO MUX and GPIO Matrix.

5.2.1.7 USB 2.0 OTG Full-Speed Interface

ESP32-S3 features a full-speed USB OTG interface along with an integrated transceiver. The USB OTG interface complies with the USB 2.0 specification.

General Features

- FS and LS data rates
- HNP and SRP as A-device or B-device
- Dynamic FIFO (DFIFO) sizing
- Multiple modes of memory access
 - Scatter/Gather DMA mode
 - Buffer DMA mode
 - Slave mode
- Can choose integrated transceiver or external transceiver
- Utilizing integrated transceiver with USB Serial/JTAG by time-division multiplexing when only integrated transceiver is used
- Support USB OTG using one of the transceivers while USB Serial/JTAG using the other one when both integrated transceiver or external transceiver are used

Device Mode Features

- Endpoint number 0 always present (bi-directional, consisting of EPO IN and EPO OUT)
- Six additional endpoints (endpoint numbers 1 to 6), configurable as IN or OUT
- Maximum of five IN endpoints concurrently active at any time (including EPO IN)
- All OUT endpoints share a single RX FIFO
- Each IN endpoint has a dedicated TX FIFO

Host Mode Features

- Eight channels (pipes)
 - A control pipe consists of two channels (IN and OUT), as IN and OUT transactions must be handled separately. Only Control transfer type is supported.
 - Each of the other seven channels is dynamically configurable to be IN or OUT, and supports Bulk, Isochronous, and Interrupt transfer types.
- All channels share an RX FIFO, non-periodic TX FIFO, and periodic TX FIFO. The size of each FIFO is configurable.

Pin Assignment

When using the on-chip PHY, the differential signal pins USB_D- and USB_D+ of the USB OTG are multiplexed with GPIO19 ~ GPIO20, RTC GPIO19 ~ RTC GPIO20, UART1 interface, and SAR ADC2 interface via IO MUX.

When using external PHY, the USB OTG pins are multiplexed with GPIO21, RTC_GPIO21, GPIO38 ~ GPIO42, and SPI interface via IO MUX:

- VP signal connected to MTMS pin
- VM signal connected to MTDI pin
- RCV signal connected to GPIO21
- OEN signal connected to MTDO pin
- VPO signal connected to MTCK pin
- VMO signal connected to GPIO38

For more information about the pin assignment, see ESP32-S3 Series Datasheet > Section IO Pins and ESP32-S3 Technical Reference Manual > Chapter IO MUX and GPIO Matrix.

5.2.1.8 USB Serial/JTAG Controller

ESP32-S3 integrates a USB Serial/JTAG controller.

Feature List

- USB Full-speed device.
- Can be configured to either use internal USB PHY of ESP32-S3 or external PHY via GPIO matrix.
- Fixed function device, hardwired for CDC-ACM (Communication Device Class Abstract Control Model) and JTAG adapter functionality.
- Two OUT Endpoints, three IN Endpoints in addition to Control Endpoint 0; Up to 64-byte data payload size.
- Internal PHY, so no or very few external components needed to connect to a host computer.
- CDC-ACM adherent serial port emulation is plug-and-play on most modern OSes.
- JTAG interface allows fast communication with CPU debug core using a compact representation of JTAG instructions.
- CDC-ACM supports host controllable chip reset and entry into download mode.

Pin Assignment

When using the on-chip PHY, the differential signal pins USB_D- and USB_D+ of the USB Serial/JTAG controller are multiplexed with GPIO19 ~ GPIO20, RTC_GPIO19 ~ RTC_GPIO20, UART1 interface, and SAR ADC2 interface via IO MUX.

When using external PHY, the USB Serial/JTAG controller pins are multiplexed with GPIO38 ~ GPIO42 and SPI interface via IO MUX:

- VP signal connected to MTMS pin
- VM signal connected to MTDI pin
- OEN signal connected to MTDO pin
- VPO signal connected to MTCK pin
- VMO signal connected to GPIO38

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and ESP32-S3 Technical Reference Manual > Chapter IO MUX and GPIO Matrix.

5.2.1.9 SD/MMC Host Controller

ESP32-S3 has an SD/MMC Host controller.

Feature List

- Secure Digital (SD) memory version 3.0 and version 3.01
- Secure Digital I/O (SDIO) version 3.0
- Consumer Electronics Advanced Transport Architecture (CE-ATA) version 1.1
- Multimedia Cards (MMC version 4.41, eMMC version 4.5 and version 4.51)
- Up to 80 MHz clock output
- Three data bus modes:
 - 1-bit
 - 4-bit (supports two SD/SDIO/MMC 4.41 cards, and one SD card operating at 1.8 V in 4-bit mode)
 - 8-bit

Pin Assignment

For SD/MMC Host, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see ESP32-S3 Series Datasheet > Section IO Pins and ESP32-S3 Technical Reference Manual > Chapter IO MUX and GPIO Matrix.

5.2.1.10 LED PWM Controller

The LED PWM controller can generate independent digital waveforms on eight channels.

Feature List

- Can generate a digital waveform with configurable periods and duty cycle. The duty cycle resolution can be up to 14 bits within a 1 ms period
- Multiple clock sources, including APB clock and external main crystal clock
- Can operate when the CPU is in Light-sleep mode
- Gradual increase or decrease of duty cycle, useful for the LED RGB color-fading generator

Pin Assignment

For LED PWM, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.1.11 Motor Control PWM (MCPWM)

ESP32-S3 integrates two MCPWMs that can be used to drive digital motors and smart light. Each MCPWM peripheral has one clock divider (prescaler), three PWM timers, three PWM operators, and a capture module. PWM timers are used for generating timing references. The PWM operators generate desired waveform based on the timing references. Any PWM operator can be configured to use the timing references of any PWM timers. Different PWM operators can use the same PWM timer's timing references to produce related PWM signals. PWM operators can also use different PWM timers' values to produce the PWM signals that work alone. Different PWM timers can also be synchronized together.

Pin Assignment

For MCPWM, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.1.12 Remote Control Peripheral (RMT)

The Remote Control Peripheral (RMT) is designed to send and receive infrared remote control signals.

Feature List

- Four TX channels
- Four RX channels
- Support multiple channels (programmable) transmitting data simultaneously
- Eight channels share a 384 x 32-bit RAM
- Support modulation on TX pulses
- Support filtering and demodulation on RX pulses
- Wrap TX mode
- Wrap RX mode
- Continuous TX mode
- DMA access for TX mode on channel 3
- DMA access for RX mode on channel 7

Pin Assignment

For RMT, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.1.13 Pulse Count Controller (PCNT)

The pulse count controller (PCNT) captures pulse and counts pulse edges through multiple modes.

Feature List

- Four independent pulse counters (units) that count from 1 to 65535
- Each unit consists of two independent channels sharing one pulse counter
- All channels have input pulse signals (e.g. sig_ch0_un) with their corresponding control signals (e.g. ctrl_ch0_un)
- Independently filter glitches of input pulse signals (sig_ch0_un and sig_ch1_un) and control signals (ctrl_ch0_un and ctrl_ch1_un) on each unit
- Each channel has the following parameters:
 - 1. Selection between counting on positive or negative edges of the input pulse signal
 - Configuration to Increment, Decrement, or Disable counter mode for control signal's high and low states

Pin Assignment

For pulse count controller, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.2 Analog Signal Processing

This subsection describes components on the chip that sense and process real-world data.

5.2.2.1 SAR ADC

ESP32-S3 integrates two 12-bit SAR ADCs and supports measurements on 20 channels (analog-enabled pins). For power-saving purpose, the ULP coprocessors in ESP32-S3 can also be used to measure voltage in sleep modes. By using threshold settings or other methods, we can awaken the CPU from sleep modes.

Pin Assignment

The pins for the SAR ADC are multiplexed with GPIO1 ~ GPIO20, RTC_GPIO1 ~ RTC_GPIO20, Touch Sensor interface, SPI interface, UART interface, and USB_D- and USB_D+ pins via IO MUX.

For more information about the pin assignment, see <u>ESP32-S3 Series Datasheet</u> > Section *IO Pins* and <u>ESP32-S3 Technical Reference Manual</u> > Chapter *IO MUX and GPIO Matrix*.

5.2.2.2 **Temperature Sensor**

The temperature sensor generates a voltage that varies with temperature. The voltage is internally converted via an ADC into a digital value.

The temperature sensor has a range of -20 °C to 110 °C. It is designed primarily to sense the temperature changes inside the chip. The temperature value depends on factors such as microcontroller clock frequency or I/O load. Generally, the chip's internal temperature is higher than the ambient temperature.

5.2.2.3 **Touch Sensor**

ESP32-S3 has 14 capacitive-sensing GPIOs, which detect variations induced by touching or approaching the GPIOs with a finger or other objects. The low-noise nature of the design and the high sensitivity of the circuit allow relatively small pads to be used. Arrays of pads can also be used, so that a larger area or more points can be detected. The touch sensing performance can be further enhanced by the waterproof design and digital filtering feature.

Note:

ESP32-S3 touch sensor has not passed the Conducted Susceptibility (CS) test for now, and thus has limited application scenarios.

Pin Assignment

The pins for touch sensor are multiplexed with GPIO1 ~ GPIO14, RTC_GPIO1 ~ RTC_GPIO14, SAR ADC interface, and SPI interface via IO MUX.

For more information about the pin assignment, see ESP32-S3 Series Datasheet > Section IO Pins and ESP32-S3 Technical Reference Manual > Chapter IO MUX and GPIO Matrix.

Electrical Characteristics

Absolute Maximum Ratings 6.1

Stresses above those listed in Table 9 Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under Table 10 Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

Table 9: Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit
VDD33	Power supply voltage	-0.3	3.6	V
T_{STORE}	Storage temperature	-40	105	°C

Recommended Operating Conditions

Table 10: Recommended Operating Conditions

Symbol	Parameter		Min	Тур	Max	Unit
VDD33	Power supply voltage		3.0	3.3	3.6	V
$ V_{VDD} $	Current delivered by external power supply		0.5	_	_	Α
		65 °C version			65	
T_A	Operating ambient temperature	85 °C version	-40	_	85	°C
		105 °C version			105	

DC Characteristics (3.3 V, 25 °C) 6.3

Table 11: DC Characteristics (3.3 V, 25 °C)

Symbol	Parameter	Min	Тур	Max	Unit
C_{IN}	Pin capacitance	_	2	_	pF
V_{IH}	High-level input voltage	0.75 × VDD ¹	_	VDD ¹ + 0.3	V
V_{IL}	Low-level input voltage	-0.3	_	0.25 × VDD ¹	V
$ I_{IH} $	High-level input current	_	_	50	nA
$ I_{IL} $	Low-level input current	_	_	50	nA
V_{OH}^2	High-level output voltage	0.8 × VDD ¹	_	_	V
V_{OL}^2	Low-level output voltage	_	_	0.1 × VDD ¹	V
	High-level source current (VDD ¹ = 3.3 V, V_{OH}		40		mA
OH	>= 2.64 V, PAD_DRIVER = 3)	_	40	_	IIIA
	Low-level sink current (VDD ¹ = 3.3 V, V_{OL} =		28		mA
$ _{OL}$	0.495 V, PAD_DRIVER = 3)	_	20	_	IIIA
R_{PU}	Internal weak pull-up resistor	_	45	_	kΩ
R_{PD}	Internal weak pull-down resistor	_	45	_	kΩ

Cont'd on next page

Table 11 - cont'd from previous page

Symbol	Parameter	Min	Тур	Max	Unit
V	Chip reset release voltage (EN voltage is	0.75 × VDD ¹		VDD ¹ + 0.3	\/
V_{IH_nRST}	within the specified range)	0.73 ^ VDD	_	VUU + 0.3	V
V	Chip reset voltage (EN voltage is within the	0.3		0.25 × VDD ¹	\/
V_{IL_nRST}	specified range)	-0.3 - 0.		0.25 ^ VDD	V

¹ VDD is the I/O voltage for pins of a particular power domain.

6.4 Current Consumption Characteristics

6.4.1 Current Consumption in Active Mode

With the use of advanced power-management technologies, the module can switch between different power modes. For details on different power modes, please refer to Section *Power Management Unit* in *ESP32-S3 Series Datasheet*.

The current consumption measurements are taken with a 3.3 V supply at 25 °C ambient temperature.

TX current consumption is rated at a 100% duty cycle.

RX current consumption is rated when the peripherals are disabled and the CPU idle.

Table 12: Current Consumption in Avtice Mode

Work mode	Desc	Description	
		802.11b, 1 Mbps, @20.5 dBm	355
	TX	802.11g, 54 Mbps, @18 dBm	297
Active (RF working)	RX	802.11n, HT20, MCS 7, @17.5 dBm	286
		802.11n, HT40, MCS 7, @17 dBm	285
		802.11b/g/n, HT20	95
K		802.11n, HT40	97

Note:

The content below is excerpted from Section Power Consumption in Other Modes in ESP32-S3 Series Datasheet.

6.4.2 Current Consumption in Other Modes

Please note that if the chip embedded has in-package PSRAM, the current consumption of the module might be higher compared to the measurements below.

 $^{^{2}}$ V_{OH} and V_{OL} are measured using high-impedance load.

Table 13: Current Consumption in Modem-sleep Mode

Work mode	Frequency (MHz)	Description	Typ ¹ (mA)	Typ ² (mA)
		WAITI (Dual core in idle state)	13.2	18.8
		Single core running 32-bit data access instructions, the other core in idle state	16.2	21.8
	40	Dual core running 32-bit data access instructions	18.7	24.4
		Single core running 128-bit data access instructions, the other core in idle state	19.9	nA) (mA) 13.2 18.8 16.2 21.8 18.7 24.4 19.9 25.4 23.0 28.8 22.0 36.1 28.4 42.6 33.1 47.3 35.1 49.6 41.8 56.3 27.6 42.3 39.9 54.6 49.6 64.1 54.4 69.2 66.7 81.1 32.9 47.6 51.2 65.9 36.2 81.3 72.4 87.9
		Dual core running 128-bit data access instructions	23.0	28.8
		WAITI	22.0	36.1
		Single core running 32-bit data access instructions, the other core in idle state	28.4	42.6
	80	Dual core running 32-bit data access instructions	33.1	47.3
		Single core running 128-bit data access instructions, the other core in idle state	35.1	(mA) 2 18.8 2 18.8 2 21.8 .7 24.4 9 25.4 0 28.8 0 36.1 4 42.6 .1 47.3 .1 49.6 8 56.3 6 42.3 9 54.6 6 64.1 4 69.2 .7 81.1 9 47.6 2 65.9 2 81.3 4 87.9
Modem-sleep ³		Dual core running 128-bit data access instructions	41.8	56.3
Modern-sieep		WAITI	27.6	42.3
	Single core running 32-bit data access instructions, to other core in idle state	Single core running 32-bit data access instructions, the other core in idle state	39.9	54.6
	160	Dual core running 32-bit data access instructions	49.6	64.1
	Single core running 128-bit data access instructions, the other core in idle state	54.4	69.2	
		Dual core running 128-bit data access instructions	ta access instructions, the 13.2	81.1
		WAITI	32.9	47.6
		Single core running 32-bit data access instructions, the other core in idle state	51.2	65.9
	240	Dual core running 32-bit data access instructions	66.2	(mA) 18.8 21.8 24.4 25.4 28.8 36.1 42.6 47.3 49.6 56.3 42.3 54.6 64.1 69.2 81.1 47.6 65.9 81.3 87.9
		Single core running 128-bit data access instructions, the other core in idle state	72.4	87.9
		Dual core running 128-bit data access instructions	91.7	107.9

¹ Current consumption when all peripheral clocks are **disabled**.

Table 14: Current Consumption in Low-Power Modes

Work mode	Description	Typ (μ A)
Light-sleep ¹	VDD_SPI and Wi-Fi are powered down, and all GPIOs	240
Light-Sieep	are high-impedance.	240
Doop aloop	RTC memory and RTC peripherals are powered up.	8
Deep-sleep	RTC memory is powered up. RTC peripherals are	7
	powered down.	/

² Current consumption when all peripheral clocks are **enabled**. In practice, the current consumption might be different depending on which peripherals are enabled.

³ In Modem-sleep mode, Wi-Fi is clock gated, and the current consumption might be higher when accessing flash. For a flash rated at 80 Mbit/s, in SPI 2-line mode the consumption is 10 mA.

Power off	CHIP_PU is set to low level. The chip is shut down.	1
-----------	---	---

¹ In Light-sleep mode, all related SPI pins are pulled up. For chips embedded with PSRAM, please add corresponding PSRAM consumption values, e.g., 140 $\mu \rm A$ for 8 MB Octal PSRAM (3.3 V), 200 $\mu \rm A$ for 8 MB Octal PSRAM (1.8 V) and 40 μ A for 2 MB Quad PSRAM (3.3 V).

7 RF Characteristics

This section contains tables with RF characteristics of the Espressif product.

The RF data is measured at the antenna port, where RF cable is connected, including the front-end loss. The external antennas used for the tests on the modules with external antenna connectors have an impedance of 50Ω . Devices should operate in the center frequency range allocated by regional regulatory authorities. The target center frequency range and the target transmit power are configurable by software. See <u>ESP RF Test</u> Tool and Test Guide for instructions.

Unless otherwise stated, the RF tests are conducted with a 3.3 V (±5%) supply at 25 °C ambient temperature.

7.1 Wi-Fi Radio

Table 15: Wi-Fi RF Characteristics

Name	Description
Center frequency range of operating channel	2412 ~ 2484 MHz
Wi-Fi wireless standard	IEEE 802.11b/g/n

7.1.1 Wi-Fi RF Transmitter (TX) Characteristics

Table 16: TX Power with Spectral Mask and EVM Meeting 802.11 Standards

Rate	Min (dBm)	Typ (dBm)	Max (dBm)
802.11b, 1 Mbps	_	20.5	_
802.11b, 11 Mbps	_	20.5	_
802.11g, 6 Mbps	_	20.0	_
802.11g, 54 Mbps	_	18.0	_
802.11n, HT20, MCS 0	_	19.0	_
802.11n, HT20, MCS 7	_	17.5	_
802.11n, HT40, MCS 0	_	18.5	_
802.11n, HT40, MCS 7	_	17.0	_

Table 17: TX EVM Test¹

Rate	Min (dB)	Typ (dB)	Limit (dB)
802.11b, 1 Mbps, @20.5 dBm	_	-24.5	-10
802.11b, 11 Mbps, @20.5 dBm	_	-24.5	-10
802.11g, 6 Mbps, @20 dBm	_	-23.0	-5
802.11g, 54 Mbps, @18 dBm	_	-29.5	-25
802.11n, HT20, MCS 0, @19 dBm	_	-24.0	-5

Cont'd on next page

Table 17 - cont'd from previous page

Rate	Min (dB)	Typ (dB)	Limit (dB)
802.11n, HT20, MCS 7, @17.5 dBm	_	-30.5	-27
802.11n, HT40, MCS 0, @18.5 dBm	_	-25.0	-5
802.11n, HT40, MCS 7, @17 dBm	_	-30.0	-27

¹ EVM is measured at the corresponding typical TX power provided in Table 16 *TX Power with Spectral Mask and EVM Meeting 802.11 Standards* above.

7.1.2 Wi-Fi RF Receiver (RX) Characteristics

For RX tests, the PER (packet error rate) limit is 8% for 802.11b, and 10% for 802.11g/n.

Table 18: RX Sensitivity

D-t-	Min	Тур	Max
Rate	(dBm)	(dBm)	(dBm)
802.11b, 1 Mbps	_	-98.2	_
802.11b, 2 Mbps	_	-95.6	_
802.11b, 5.5 Mbps	_	-92.8	_
802.11b, 11 Mbps	_	-88.5	_
802.11g, 6 Mbps	_	-93.0	_
802.11g, 9 Mbps	_	-92.0	_
802.11g, 12 Mbps	_	-90.8	_
802.11g, 18 Mbps	_	-88.5	_
802.11g, 24 Mbps	_	-85.5	_
802.11g, 36 Mbps	_	-82.2	_
802.11g, 48 Mbps	_	-78.0	_
802.11g, 54 Mbps	_	-76.2	_
802.11n, HT20, MCS 0	_	-93.0	_
802.11n, HT20, MCS 1	_	-90.6	_
802.11n, HT20, MCS 2	_	-88.4	_
802.11n, HT20, MCS 3	_	-84.8	_
802.11n, HT20, MCS 4	_	-81.6	_
802.11n, HT20, MCS 5	_	-77.4	_
802.11n, HT20, MCS 6	_	-75.6	_
802.11n, HT20, MCS 7	_	-74.2	_
802.11n, HT40, MCS 0	_	-90.0	_
802.11n, HT40, MCS 1	_	-87.5	_
802.11n, HT40, MCS 2	_	-85.0	_
802.11n, HT40, MCS 3	_	-82.0	_
802.11n, HT40, MCS 4		-78.5	
802.11n, HT40, MCS 5		-74.4	
802.11n, HT40, MCS 6	_	-72.5	_

Cont'd on next page

Table 18 – cont'd from previous page

Rate	Min	Typ	Max
	(dBm)	(dBm)	(dBm)
802.11n, HT40, MCS 7	_	-71.2	_

Table 19: Maximum RX Level

Rate	Min	Тур	Max
Rate	(dBm)	(dBm)	(dBm)
802.11b, 1 Mbps	_	5	_
802.11b, 11 Mbps	_	5	_
802.11g, 6 Mbps	_	5	_
802.11g, 54 Mbps	_	0	_
802.11n, HT20, MCS 0	_	5	_
802.11n, HT20, MCS 7	_	0	_
802.11n, HT40, MCS 0	_	5	_
802.11n, HT40, MCS 7	_	0	_

Table 20: RX Adjacent Channel Rejection

Rate	Min (dB)	Typ (dB)	Max (dB)
802.11b, 1 Mbps	_	35	_
802.11b, 11 Mbps	_	35	_
802.11g, 6 Mbps	_	31	_
802.11g, 54 Mbps	_	14	_
802.11n, HT20, MCS 0	_	31	_
802.11n, HT20, MCS 7	_	13	_
802.11n, HT40, MCS 0	_	19	_
802.11n, HT40, MCS 7	_	8	_

7.2 Bluetooth LE Radio

Table 21: Bluetooth LE RF Characteristics

Name	Description
Center frequency range of operating channel	2402 ~ 2480 MHz
RF transmit power range	-24.0 ~ 20.0 dBm

7.2.1 Bluetooth LE RF Transmitter (TX) Characteristics

Table 22: Bluetooth LE - Transmitter Characteristics - 1 Mbps

Parameter	Description	Min	Тур	Max	Unit
Carrier frequency offset and drift	$ Max _{n=0,\;1,\;2,\;k}$	_	2.50		kHz
	$Max \mid f_0 = f_m \mid$	_	2.00	_	kHz
	$Max f_{n-} f_{n-5} $	_	1.40		kHz
	$ f_1 - f_0 $	_	1.00	_	kHz
Modulation characteristics	$\Deltaf1_{ ext{avg}}$	_	249.00		kHz
	Min Δ $f2_{\rm max}$ (for at least	_	198.00	_	kHz
Woodiation Characteristics	99.9% of all Δ $f2_{\text{max}}$)				KIIZ
	$\Delta~f2_{ m avg}/\Delta~f1_{ m avg}$	l	0.86	l	_
In-band spurious emissions	±2 MHz offset	_	-37.00		dBm
	±3 MHz offset	_	-42.00	_	dBm
	>±3 MHz offset	_	-44.00	_	dBm

Table 23: Bluetooth LE - Transmitter Characteristics - 2 Mbps

Parameter	Description	Min	Тур	Max	Unit
Carrier frequency offset and drift	$ Max _{n=0,\;1,\;2,\;k}$	_	2.50	_	kHz
	$Max \mid f_0 = f_m \mid$	_	2.00	_	kHz
	$Max f_{n-} f_{n-5} $	_	1.40	_	kHz
	$ f_1 - f_0 $	_	1.00	_	kHz
Modulation characteristics	$\Deltaf1_{ ext{avg}}$	_	499.00	_	kHz
	Min Δ $f2_{\rm max}$ (for at least	_	416.00	_	kHz
Woodiation Characteristics	99.9% of all Δ $f2_{\text{max}}$)				KI IZ
	$\Delta~f2_{\rm avg}/\Delta~f1_{\rm avg}$	_	0.89	_	_
In-band spurious emissions	±4 MHz offset	_	-42.00	_	dBm
	±5 MHz offset	_	-44.00	_	dBm
	>±5 MHz offset	_	-47.00	_	dBm

Table 24: Bluetooth LE - Transmitter Characteristics - 125 Kbps

Parameter	Description	Min	Тур	Max	Unit
Carrier frequency offset and drift	$ f_n _{n=0,\;1,\;2,\;k}$		0.80	_	kHz
	$Max \mid f_0 = f_m \mid$	_	1.00	_	kHz
	$ f_n - f_{n-3} $		0.30	_	kHz
	$ f_0 - f_3 $		1.00	_	kHz
Modulation characteristics	$\Deltaf1_{ ext{avg}}$	_	248.00	_	kHz
	Min $\Delta f1_{\text{max}}$ (for at least		222.00		kHz
	99.9% of all $\Delta f1_{\text{max}}$)		222.00		KIIZ
	±2 MHz offset	_	-37.00	_	dBm
In-band spurious emissions	±3 MHz offset	_	-42.00	_	dBm

Cont'd on next page

Table 24 – cont'd from previous page

Parameter	Description	Min	Тур	Max	Unit
	>±3 MHz offset	_	-44.00	_	dBm

Table 25: Bluetooth LE - Transmitter Characteristics - 500 Kbps

Parameter	Description	Min	Тур	Max	Unit
	$ Max _{n=0,\;1,\;2,\;k}$	_	0.80	_	kHz
Carrier frequency offset and drift	$Max \mid f_0 = f_m \mid$	_	1.00	_	kHz
Camer nequency onset and unit	$ f_n - f_{n-3} $	_	0.85	_	kHz
	$ f_0-f_3 $	_	0.34	_	kHz
Modulation characteristics	$\Delta~f2_{avg}$	_	213.00	_	kHz
	Min Δ $f2_{\rm max}$ (for at least	_	196.00	_	kHz
	99.9% of all Δ $f2_{\text{max}}$)				KIIZ
In-band spurious emissions	±2 MHz offset	_	-37.00	_	dBm
	±3 MHz offset	_	-42.00	_	dBm
	>±3 MHz offset	_	-44.00	_	dBm

7.2.2 Bluetooth LE RF Receiver (RX) Characteristics

Table 26: Bluetooth LE - Receiver Characteristics - 1 Mbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-96.5	_	dBm
Maximum received signal @30.8% PER	_	_	8	_	dBm
Co-channel C/I	F = FO MHz	_	8	_	dB
	F = FO + 1 MHz	_	4	_	dB
	F = FO – 1 MHz	_	4	_	dB
	F = F0 + 2 MHz	_	-23	_	dB
Adjacent channel calcotivity C/I	F = F0 - 2 MHz	_	-23	_	dB
Adjacent channel selectivity C/I	F = F0 + 3 MHz	_	-34	_	dB
	F = F0 - 3 MHz	_	-34	_	dB
	F > F0 + 3 MHz	_	-36	_	dB
	F > F0 - 3 MHz	_	-37	_	dB
Image frequency	_	_	-36		dB
Adiabant abangal ta imaga fraguagay	$F = F_{image} + 1 MHz$	_	-39		dB
Adjacent channel to image frequency	$F = F_{image} - 1 \text{ MHz}$	_	-34	_	dB
Out-of-band blocking performance	30 MHz ~ 2000 MHz	_	-12	_	dBm
	2003 MHz ~ 2399 MHz	_	-18	_	dBm
	2484 MHz ~ 2997 MHz	_	-16	_	dBm
	3000 MHz ~ 12.75 GHz	_	-10	_	dBm
Intermodulation	_	_	-29	_	dBm

Table 27: Bluetooth LE - Receiver Characteristics - 2 Mbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-92	_	dBm
Maximum received signal @30.8% PER	_	_	3	_	dBm
Co-channel C/I	F = FO MHz	_	8	_	dB
	F = F0 + 2 MHz	_	4	_	dB
	F = F0 - 2 MHz	_	4	_	dB
	F = F0 + 4 MHz	_	-27	_	dB
Adjacent channel selectivity C/I	F = F0 - 4 MHz	_	-27	_	dB
Adjacent channel selectivity 6/1	F = F0 + 6 MHz	_	-38	_	dB
	F = F0 - 6 MHz	_	-38	_	dB
	F > F0 + 6 MHz	_	-41	_	dB
	F > F0 - 6 MHz	_	-41	_	dB
Image frequency	_	_	-27		dB
Adjacent channel to image frequency	$F = F_{image} + 2 MHz$	_	-38	_	dB
	$F = F_{image} - 2 \text{ MHz}$	_	4	_	dB
Out-of-band blocking performance	30 MHz ~ 2000 MHz	_	-15	_	dBm
	2003 MHz ~ 2399 MHz	_	-21	_	dBm
	2484 MHz ~ 2997 MHz	_	-21	_	dBm
	3000 MHz ~ 12.75 GHz	_	-9	_	dBm
Intermodulation	_	_	-29	_	dBm

Table 28: Bluetooth LE - Receiver Characteristics - 125 Kbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-103.5		dBm
Maximum received signal @30.8% PER	_	_	8	_	dBm
Co-channel C/I	F = FO MHz	_	4		dB
	F = FO + 1 MHz	_	1	_	dB
	F = F0 – 1 MHz	_	2	_	dB
	F = F0 + 2 MHz	_	-26	_	dB
Adjacent channel selectivity C/I	F = FO - 2 MHz	_	-26		dB
Aujacent channel Selectivity C/1	F = F0 + 3 MHz	_	-36	_	dB
	F = FO - 3 MHz	_	-39		dB
	F > F0 + 3 MHz	_	-42	_	dB
	F > F0 - 3 MHz	_	-43		dB
Image frequency	_	_	-42	_	dB
Adjacent channel to image frequency	$F = F_{image} + 1 MHz$	_	-43	_	dB
Adjacent channel to image frequency	F = F _{image} – 1 MHz	_	-36	_	dB

Table 29: Bluetooth LE - Receiver Characteristics - 500 Kbps

Parameter	Description	Min	Тур	Max	Unit
Sensitivity @30.8% PER	_	_	-100	_	dBm
Maximum received signal @30.8% PER	_	_	8	_	dBm
Co-channel C/I	F = FO MHz	_	4	_	dB
	F = FO + 1 MHz	_	1	_	dB
	F = FO – 1 MHz	_	0	_	dB
	F = F0 + 2 MHz	_	-24	_	dB
Adjacent channel calcotivity C/I	F = FO - 2 MHz	_	-24	_	dB
Adjacent channel selectivity C/I	F = F0 + 3 MHz	_	-37	_	dB
	F = FO - 3 MHz	_	-39	_	dB
	F > F0 + 3 MHz	_	-38	_	dB
	F > FO - 3 MHz	_	-42	_	dB
Image frequency	_	_	-38	_	dB
Adjacent channel to image frequency	$F = F_{image} + 1 MHz$	_	-42	_	dB
Adjacent channel to image frequency	F = F _{image} – 1 MHz	_	-37	_	dB

 ∞

8 Module Schematics

This is the reference design of the module. For modules with PSRAM, the VDD_SPI voltage is fixed to 3.3 V or 1.8 V via eFuse, so their VDD_SPI voltage will not be affected by the GPIO45 level. However, for other modules, please ensure that GPIO45 is not pulled high when the module is powered up by the external circuit.

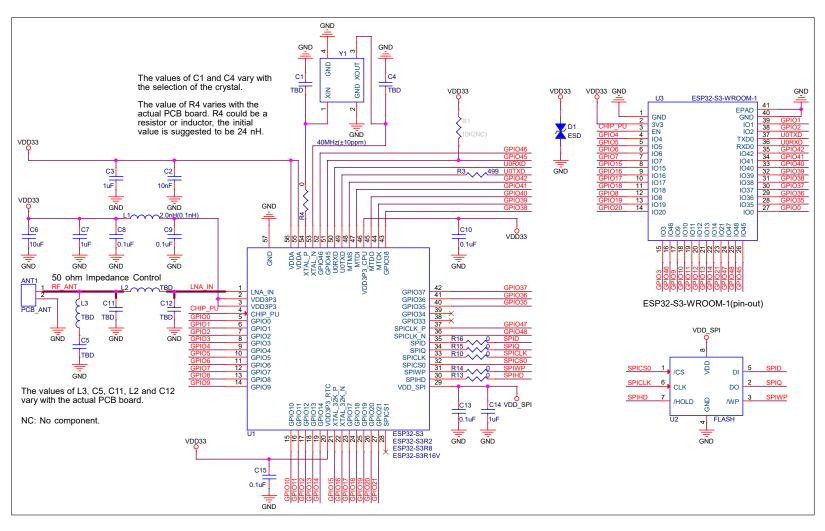


Figure 5: ESP32-S3-WROOM-1 Schematics

 $| \infty |$

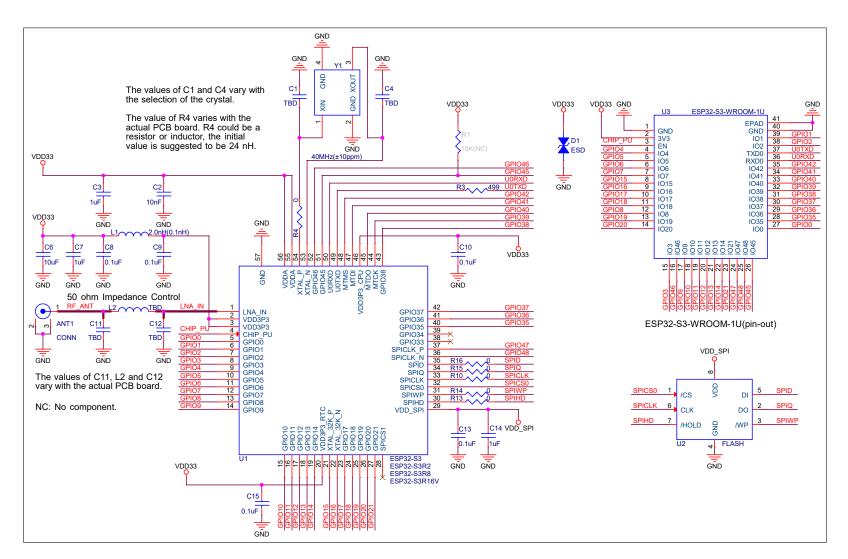


Figure 6: ESP32-S3-WROOM-1U Schematics

9 Peripheral Schematics

This is the typical application circuit of the module connected with peripheral components (for example, power supply, antenna, reset button, JTAG interface, and UART interface).

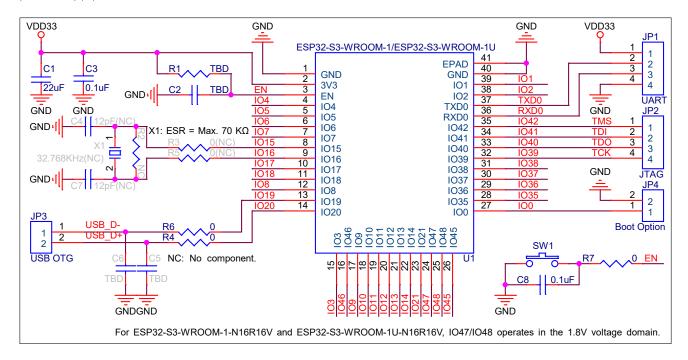


Figure 7: Peripheral Schematics

- Soldering the EPAD to the ground of the base board is not a must, however, it can optimize thermal performance. If you choose to solder it, please apply the correct amount of soldering paste. Too much soldering paste may increase the gap between the module and the baseboard. As result, the adhesion between other pins and the baseboard may be poor.
- To ensure that the power supply to the ESP32-S3 chip is stable during power-up, it is advised to add an RC delay circuit at the EN pin. The recommended setting for the RC delay circuit is usually R = 10 k Ω and C = 1 μ F. However, specific parameters should be adjusted based on the power-up timing of the module and the power-up and reset sequence timing of the chip. For ESP32-S3's power-up and reset sequence timing diagram, please refer to <u>ESP32-S3 Series Datasheet</u> > Section Power Supply.

10 Physical Dimensions

10.1 Module Dimensions

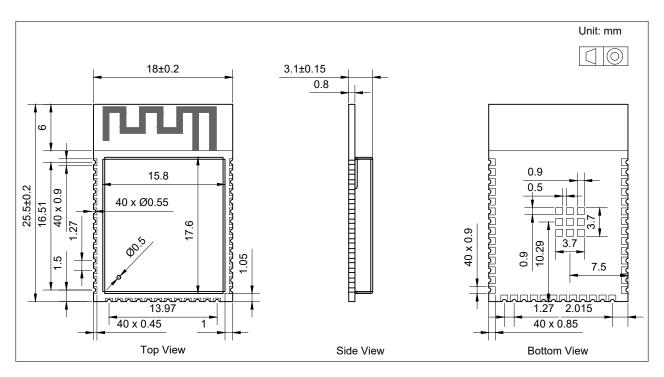


Figure 8: ESP32-S3-WROOM-1 Physical Dimensions

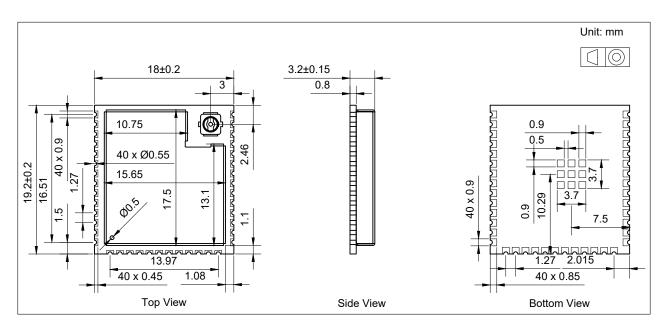


Figure 9: ESP32-S3-WROOM-1U Physical Dimensions

Note:

For information about tape, reel, and product marking, please refer to Espressif Module Packaging Information.

10.2 Dimensions of External Antenna Connector

ESP32-S3-WROOM-1U uses the first generation external antenna connector as shown in Figure 10 *Dimensions* of *External Antenna Connector*. This connector is compatible with the following connectors:

- U.FL Series connector from Hirose
- MHF I connector from I-PEX
- AMC connector from Amphenol

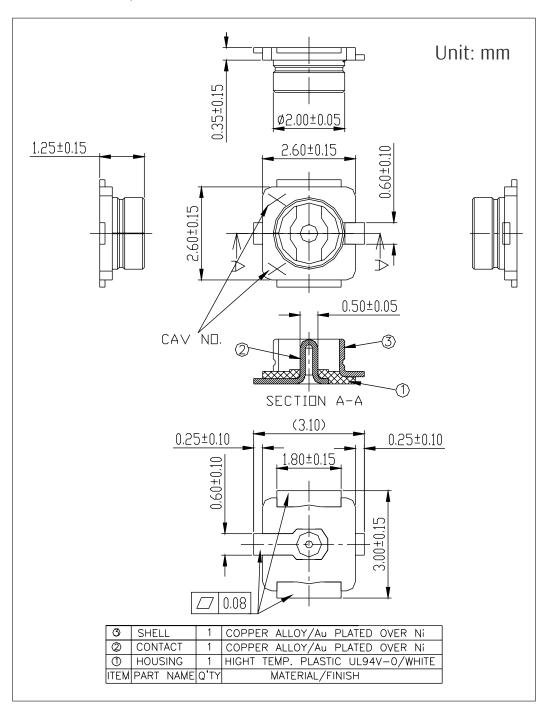


Figure 10: Dimensions of External Antenna Connector

11 PCB Layout Recommendations

11.1 PCB Land Pattern

This section provides the following resources for your reference:

- Figures for recommended PCB land patterns with all the dimensions needed for PCB design. See Figure 11 ESP32-S3-WROOM-1 Recommended PCB Land Pattern and Figure 12 ESP32-S3-WROOM-1U Recommended PCB Land Pattern.
- Source files of recommended PCB land patterns to measure dimensions not covered in Figure 11 and Figure 12. You can view the source files for ESP32-S3-WROOM-1 and ESP32-S3-WROOM-1 with Autodesk Viewer.
- 3D models of <u>ESP32-S3-WROOM-1</u> and <u>ESP32-S3-WROOM-1U</u>. Please make sure that you download the 3D model file in .STEP format (beware that some browsers might add .txt).

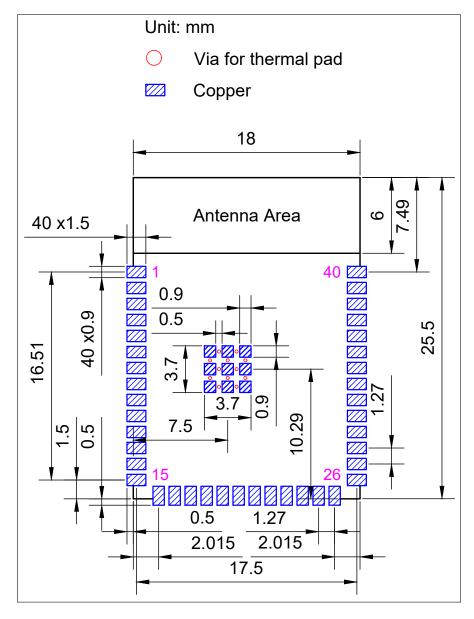


Figure 11: ESP32-S3-WROOM-1 Recommended PCB Land Pattern

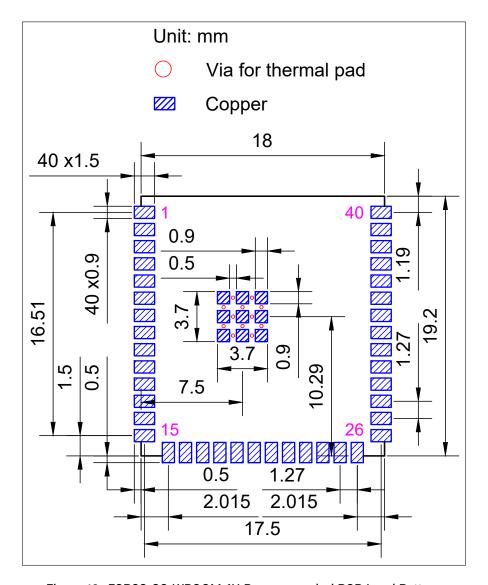


Figure 12: ESP32-S3-WROOM-1U Recommended PCB Land Pattern

11.2 Module Placement for PCB Design

If module-on-board design is adopted, attention should be paid while positioning the module on the base board. The interference of the base board on the module's antenna performance should be minimized.

For details about module placement for PCB design, please refer to ESP32-S3 Hardware Design Guidelines > Section Positioning a Module on a Base Board.

Product Handling 12

12.1 **Storage Conditions**

The products sealed in moisture barrier bags (MBB) should be stored in a non-condensing atmospheric environment of < 40 °C and 90%RH. The module is rated at the moisture sensitivity level (MSL) of 3.

After unpacking, the module must be soldered within 168 hours with the factory conditions 25±5 °C and 60%RH. If the above conditions are not met, the module needs to be baked.

Electrostatic Discharge (ESD) 12.2

• Human body model (HBM): ±2000 V • Charged-device model (CDM): ±500 V

Reflow Profile 12.3

Solder the module in a single reflow.

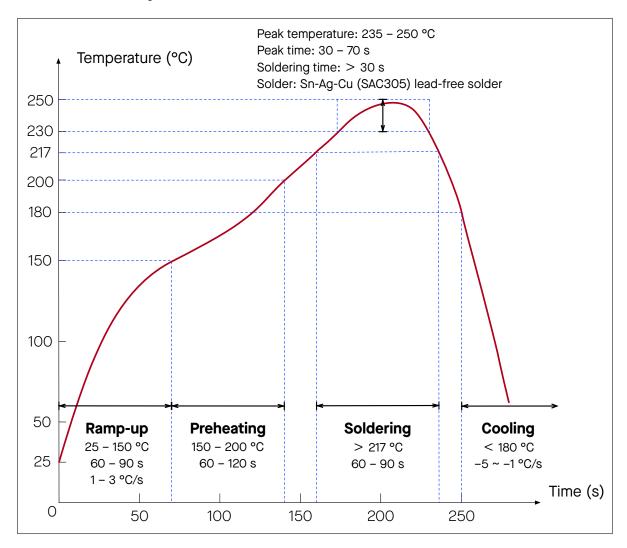


Figure 13: Reflow Profile

Ultrasonic Vibration 12.4

Avoid exposing Espressif modules to vibration from ultrasonic equipment, such as ultrasonic welders or ultrasonic cleaners. This vibration may induce resonance in the in-module crystal and lead to its malfunction or even failure. As a consequence, the module may stop working or its performance may deteriorate.

Related Documentation and Resources

Related Documentation

- ESP32-S3 Series Datasheet Specifications of the ESP32-S3 hardware.
- ESP32-S3 Technical Reference Manual Detailed information on how to use the ESP32-S3 memory and peripherals.
- ESP32-S3 Hardware Design Guidelines Guidelines on how to integrate the ESP32-S3 into your hardware product.
- ESP32-S3 Series SoC Errata Descriptions of known errors in ESP32-S3 series of SoCs.
- Certificates

https://espressif.com/en/support/documents/certificates

• ESP32-S3 Product/Process Change Notifications (PCN)

https://espressif.com/en/support/documents/pcns?keys=ESP32-S3

• ESP32-S3 Advisories - Information on security, bugs, compatibility, component reliability.

https://espressif.com/en/support/documents/advisories?keys=ESP32-S3

 Documentation Updates and Update Notification Subscription https://espressif.com/en/support/download/documents

Developer Zone

- ESP-IDF Programming Guide for ESP32-S3 Extensive documentation for the ESP-IDF development framework.
- ESP-IDF and other development frameworks on GitHub.

https://github.com/espressif

• ESP32 BBS Forum – Engineer-to-Engineer (E2E) Community for Espressif products where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.

https://esp32.com/

• The ESP Journal - Best Practices, Articles, and Notes from Espressif folks.

https://blog.espressif.com/

• See the tabs SDKs and Demos, Apps, Tools, AT Firmware.

https://espressif.com/en/support/download/sdks-demos

Products

• ESP32-S3 Series SoCs – Browse through all ESP32-S3 SoCs.

https://espressif.com/en/products/socs?id=ESP32-S3

• ESP32-S3 Series Modules - Browse through all ESP32-S3-based modules.

https://espressif.com/en/products/modules?id=ESP32-S3

• ESP32-S3 Series DevKits – Browse through all ESP32-S3-based devkits.

https://espressif.com/en/products/devkits?id=ESP32-S3

• ESP Product Selector – Find an Espressif hardware product suitable for your needs by comparing or applying filters. https://products.espressif.com/#/product-selector?language=en

Contact Us

 See the tabs Sales Questions, Technical Enquiries, Circuit Schematic & PCB Design Review, Get Samples (Online stores), Become Our Supplier, Comments & Suggestions.

https://espressif.com/en/contact-us/sales-questions

Revision History

Date	Version	Release notes
2024-11-14	V1.4	 Renamed module variants ESP32-S3-WROOM-1-N16R16V and ESP32-S3-WROOM-1U-N16R16VA to ESP32-S3-WROOM-1-N16R16VA and ESP32-S3-WROOM-1U-N16R16VA Added a reference to the chip revision information in the note in Section Section 1.2 Series Comparison Updated Section 1.3 Applications Restructured the previous Section Strapping Pins as Section 4 Boot Configurations Added Section 5.2 Peripheral Description Divided Section Electrical Characteristics into Section 6 Electrical Characteristics and Section 7 RF Characteristics with updated formatting and wording Divided Section Physical Dimensions and PCB Land Pattern into Section 10 Physical Dimensions and 11 PCB Layout Recommendations and added Section 11.2 Module Placement for PCB Design Added the 3D model link of ESP32-S3-WROOM-1U in Section 11.1 PCB Land Pattern Updated Figure 13 Reflow Profile Other minor updates to formatting and wording
2023-11-24	V1.3	 Added the new module variants ESP32-S3-WROOM-1-N16R16VA and ESP32-S3-WROOM-1U-N16R16VA, and updated the related information Updated table notes to Table 2 ESP32-S3-WROOM-1U Series Comparison Updated Section 4.1 Chip Boot Mode Control Updated the module schematics in Section 8 Module Schematics Updated the physical dimensions figure in Section 10.1 Module Dimensions Other minor updates
2023-03-07	V1.2	 Update Section Strapping Pins Update Section 6.4 Current Consumption Characteristics Update the minimum value of RF transmit power in Section 7.2.1 Bluetooth LE RF Transmitter (TX) Characteristics Update descriptions in Section 9 Peripheral Schematics Add descriptions in Section 11.1 PCB Land Pattern Update Section 12.4 Other minor changes

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Date	Version	Release notes
		Update Table 1 and Table 2
2022-07-22	V1.1	Other minor updates
		Update Bluetooth LE RF data
		Update power consumption data in Table 14
2022-04-21	v1.0	Add certification and test information
		Update Section Strapping Pins
2021-10-29	v0.6	Overall update for chip evision 1
2021-07-19	v0.5.1	Preliminary release, for chip revision 0



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