

Chapter 1: Basic Concepts of Probability

DEFINITION 1 (EXPERIMENT, SAMPLE SPACE, EVENT)

A **statistical experiment** is any procedure that produces data or observations.

The **sample space**, denoted by S , is the set of **all possible outcomes of a statistical experiment**. The sample space depends on the problem of interest!

A **sample point** is an **outcome (element) in the sample space**.

An **event** is a **subset of the sample space**.

Union: $A \cup B = x : x \in A \vee x \in B$

Union of n events: $\cup_{i=1}^n = x : x \in A_1 \vee x \in A_2 \dots$

Union: $A \cap B = x : x \in A \wedge x \in B$

Intersection of n events: $\cap_{i=1}^n = x : x \in A_1 \wedge x \in A_2 \dots$

Complement: $A' = x : x \in S \wedge x \notin A$

Mutually Exclusive: $A \cap B = \emptyset$

MORE EVENT OPERATIONS

(a) $A \cap A' = \emptyset$ (b) $A \cap \emptyset = \emptyset$

(c) $A \cup A' = S$ (d) $(A')' = A$

(e) $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$

(f) $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$

(g) $A \cup B = A \cup (B \cap A')$

(h) $A = (A \cap B) \cup (A \cap B')$

DE MORGAN'S LAW

For any n events A_1, A_2, \dots, A_n ,

(i) $(A_1 \cup A_2 \cup \dots \cup A_n)' = A_1' \cap A_2' \cap \dots \cap A_n'$

A special case: $(A \cup B)' = A' \cap B'$

(j) $(A_1 \cap A_2 \cap \dots \cap A_n)' = A_1' \cup A_2' \cup \dots \cup A_n'$

A special case: $(A \cap B)' = A' \cup B'$

Multiplication

Sequential experiments
 $n_1 * n_2 * \dots * n_r$
outcomes

Addition

Independent experiments
 $n_1 + n_2 + \dots + n_r$
outcomes

Permutation: $P_r^n = \frac{n!}{(n-r)!} = n(n-1)\dots(n-(r-1))$

Selection and arrangement of r objects out of n . Order is considered.

Combination: $C_r^n = \frac{n!}{r!(n-r)!} = \frac{n(n-1)\dots(n-(r-1))}{r!}$

Selection of r objects out of n . Order is not considered.

$C_r^n = C_{n-r}^n$

Axioms and Properties of Probability

1 $0 \leq P(A) \leq 1$

2 $P(S)=1$

3 $P(A \cup B) = P(A) + P(B)$ if A and B are **mutex** (not to be confused with independence)

4 $P(\emptyset)=0$

5 $P(A_1 \cup A_2 \cup \dots \cup A_n) = \sum_{i=1}^n P(A_i)$

6 $P(A') = 1 - P(A)$

7 $P(A \cup B) = P(A) + P(B) - P(AB)$

8 $P(A) = P(A \cap B) + P(A \cap B')$

9 $A \subset B \rightarrow P(A) \leq P(B)$

10 $P(A_1) = P(A_2) = \dots = P(A_k) \rightarrow \text{for } B \subset$

$$S, P(B) = \frac{|B|}{|S|}$$

Conditional Probability (B occurs given A):

$$P(B|A) = \frac{P(A \cap B)}{P(A)}$$

Multiplication rules

$P(A \cap B) = P(A)P(B|A)$ if $P(A) \neq 0$

$P(A \cap B) = P(B)P(A|B)$ if $P(B) \neq 0$

Inverse Probability Formula: $P(A|B) = \frac{P(B|A)P(A)}{P(B)}$

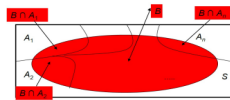
Independence $A \perp B$ if $P(A \cap B) = P(A)P(B)$ This implies $P(A|B) = P(A)$ and $P(B|A) = P(B)$

Partition A_1, A_2, \dots, A_r are mutually exclusive and $\sum_{i=1}^n A_i = S$

THEOREM 11 (LAW OF TOTAL PROBABILITY)

Suppose A_1, A_2, \dots, A_n is a partition of S . Then for any event B , we have

$$P(B) = \sum_{i=1}^n P(B \cap A_i) = \sum_{i=1}^n P(A_i)P(B|A_i).$$



$$P(B) = P(A)P(B|A) + P(A')P(B|A')$$

Bayes' theorem

$$P(A_k|B) = \frac{P(B|A_k)P(A_k)}{P(A)P(B|A) + P(A')P(B|A')}$$

$$\text{Bayes' Theorem}(n=2) P(A|B) = \frac{P(B|A)P(A)}{\sum_{i=1}^n P(A_i)P(B|A_i)}$$

Denom is P(B)

$$P(A|B) = 1 - P(A'|B)$$

L2: Random Variables

Random variable X is a function from S to \mathbb{R}

Uppercase letters denote random variables

Lowercase letters denote observed values of random variables

variables

DEFINITION 3 (PROBABILITY MASS FUNCTION)

For a discrete random variable X, define

$$f(x) = \begin{cases} P(X=x), & \text{for } x \in R_X; \\ 0, & \text{for } x \notin R_X. \end{cases}$$

Then $f(x)$ is known as the **probability function (pf)**, or **probability mass function (pmf)** of X.

The collection of pairs $(x_i, f(x_i)), i = 1, 2, 3, \dots$, is called the **probability distribution** of X.

PROPERTIES OF THE PROBABILITY MASS FUNCTION

The probability mass function $f(x)$ of a discrete random variable **must** satisfy:

(1) $f(x_i) \geq 0$ for all $x_i \in R_X$;

(2) $f(x) = 0$ for all $x \notin R_X$;

(3) $\sum_{i=1}^{\infty} f(x_i) = 1$, or $\sum_{x_i \in R_X} f(x_i) = 1$.

For any set $B \subset \mathbb{R}$, we have

$$P(X \in B) = \sum_{x_i \in B \cap R_X} f(x_i).$$

DEFINITION 4 (PROBABILITY DENSITY FUNCTION)

The **probability density function** of a continuous random variable X, denoted by $f(x)$, is a function that satisfies:

(1) $f(x) \geq 0$ for all $x \in R_X$; and $f(x) = 0$ for $x \notin R_X$;

(2) $\int_{R_X} f(x) dx = 1$;

(3) For any a and b such that $a \leq b$,

$$P(a \leq X \leq b) = \int_a^b f(x) dx.$$

note: $P(a < X < b) = P(a \leq X \leq b)$

To check that a function is a PDF, check conditions 1 and 2

Cumulative Distribution Function: $F(x) = P(X \leq x)$

and

$$P(a \leq b) = P(X \leq b) - P(X \leq a) = F(b) - F(a-)$$

Deriving CDF from probability distribution

x	0	1	2
$f(x)$	1/4	1/2	1/4

We have

$$F(0) = f(0) = 1/4, F(1) = f(0) + f(1) = 3/4, F(2) = f(0) + f(1) + f(2) = 1.$$

Deriving probability distribution from cdf

$$f(x) = \begin{cases} 0, & x < 0 \\ 1/4, & 0 \leq x < 1 \\ 3/4, & 1 \leq x < 2 \\ 1, & 2 \leq x \end{cases}$$

$$\begin{aligned} & \bullet f(1) = P(X=0) = F(0) - F(0-) = \frac{1}{4} - 0 = \frac{1}{4} \\ & \bullet f(2) = P(X=1) = F(1) - F(1-) = \frac{3}{4} - \frac{1}{4} = \frac{1}{2} \\ & \bullet f(3) = P(X=2) = F(2) - F(2-) = 1 - \frac{3}{4} = \frac{1}{4} \end{aligned}$$

CDF - Continuous Random Variable

• $F(X)$ assumes different values in R_X when $F(X) \neq 0$

• $F(X)$ is always non-decreasing (for discrete variable too)
 $x_1 < x_2 \rightarrow F(x_1) < F(x_2)$

• Probability function and CDF is one-to-one and uniquely determined

• $0 < F(x) < 1$

• (discrete), $0 < f(x) < 1$

• (continuous), $f(x) \geq 0$ but $f(x)$ is not necessarily ≤ 1 .

While the PDF itself cannot exceed 1, there are points within its range that are greater than 1

CDF: CONTINUOUS RANDOM VARIABLE

If X is a **continuous random variable**,

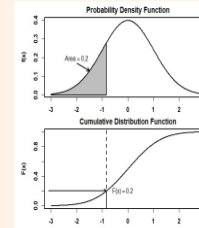
$$F(x) = \int_{-\infty}^x f(t) dt,$$

and

$$f(x) = \frac{dF(x)}{dx}.$$

Further

$$P(a \leq X \leq b) = P(a < X < b) = F(b) - F(a).$$



Find CDF of a continuous random variable

$$f(x) = \begin{cases} \frac{x}{\theta^2} e^{-x^2/(2\theta^2)}, & \text{for } x > 0, \\ 0, & \text{otherwise.} \end{cases}$$

$$F(x) = P(X \leq x) = \int_{-\infty}^x f(t) dt = \int_0^x \frac{t}{\theta^2} e^{-t^2/(2\theta^2)} dt = \left[-e^{-t^2/(2\theta^2)} \right]_{t=0}^x = 1 - e^{-x^2/(2\theta^2)}.$$

Discrete: Expectation (mean) and Variance

$$\bullet E(X) = \sum_{x \in R_X} x_i f(x_i) = \mu_x$$

Random: Expectation (mean) and Variance

$$\bullet E(X) = \mu_x = \int_{-\infty}^{\infty} x f(x) dx = \int_{-\infty}^{\infty} x f(x) dx$$

• The mean of X is not necessarily a possible value

Properties of Expectation

$$1 E(aX + b) = aE(X) + b$$

$$2 E(X + Y) = E(X) + E(Y)$$

$$3 \text{ (discrete)} E|g(x)| = \sum_{x \in R_X} g(x) f(x)$$

$$3 \text{ (continuous)} E|g(x)| = \int_{-\infty}^{\infty} g(x) f(x) dx$$

• Using properties 1, 2 we have

$$E(a_1 X_1 + a_2 X_2 + \dots + a_k X + k) = a_1 E(X_1) + \dots + a_k E(X_k)$$

Variance

$$\bullet Var(X) = \sigma_x^2 = E(X - \mu_x)^2 = E(X^2) - E(X)^2$$

$$\bullet \text{ (discrete)} Var(X) = \sum_{x \in R_X} (x - \mu_x)^2 f(x)$$

$$\bullet \text{ (continuous)} Var(X) = \int_{-\infty}^{\infty} (x - \mu_x)^2 f(x) dx$$

• $V(X) \leq 0$ for any X, $V(X)=0$ when X is a constant

Joint Probability Distribution

DEFINITION 5 (DISCRETE JOINT PROBABILITY FUNCTION)

Let (X, Y) be a 2-dimensional **discrete random variable**. Its **joint probability (mass) function** is defined by

$$f_{X,Y}(x,y) = P(X=x, Y=y),$$

for $(x,y) \in R_{X,Y}$.

PROPERTIES OF THE DISCRETE JOINT PROBABILITY FUNCTION

The joint probability mass function has the following properties:

(1) $f_{X,Y}(x,y) \geq 0$ for any $(x,y) \in R_{X,Y}$.

(2) $f_{X,Y}(x,y) = 0$ for any $(x,y) \notin R_{X,Y}$.

$$(3) \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} f_{X,Y}(x_i, y_j) = \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} P(X=x_i, Y=y_j) = 1.$$

Equivalently, $\sum \sum_{(x,y) \in R_{X,Y}} f_{X,Y}(x,y) = 1$.

(4) Let A be any subset of $R_{X,Y}$, then

$$P((X,Y) \in A) = \sum \sum_{(x,y) \in A} f_{X,Y}(x,y).$$

DEFINITION 6 (CONTINUOUS JOINT PROBABILITY FUNCTION)
Let (X,Y) be a 2-dimensional **continuous** random variable. Its **joint probability (density) function** is a function $f_{X,Y}(x,y)$ such that

$$P((X,Y) \in D) = \iint_{(x,y) \in D} f_{X,Y}(x,y) dy dx,$$

for any $D \subset \mathbb{R}^2$. More specifically,

$$P(a \leq X \leq b, c \leq Y \leq d) = \int_a^b \int_c^d f_{X,Y}(x,y) dy dx.$$

PROPERTIES OF THE CONTINUOUS JOINT PROBABILITY FUNCTION
The joint probability density function has the following properties:

- $f_{X,Y}(x,y) \geq 0$, for any $(x,y) \in R_{X,Y}$.
- $f_{X,Y}(x,y) = 0$, for any $(x,y) \notin R_{X,Y}$.
- $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx dy = 1$.

Equivalently: $\iint_{(x,y) \in R_{X,Y}} f_{X,Y}(x,y) dx dy = 1$.

Marginal Probability Distribution

DEFINITION 7 (MARGINAL PROBABILITY DISTRIBUTION)
Let (X,Y) be a two-dimensional random variable with joint probability function $f_{X,Y}(x,y)$. We define the **marginal distribution** of X as follows.

If Y is a discrete random variable, then for any x ,

$$f_X(x) = \sum_y f_{X,Y}(x,y).$$

If Y is a continuous random variable, then for any x ,

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy.$$

x	y				Row Total
	0	1	2	3	
0	0	3/84	6/84	1/84	10/84
1	4/84	24/84	12/84	0	40/84
2	12/84	18/84	0	0	30/84
3	4/84	0	0	0	4/84
Column Total	20/84	45/84	18/84	1/84	1

- Each cell is $P(X = x, Y = y)$
- Column total represents $f_Y(y)$
- Row total represents $f_X(x)$

- Conditional Distribution**
 $f_{Y,X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)}, f_{X,Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$
- Only defined for $f_X(x) > 0$ and $f_Y(y) > 0$
 - the summation of the PDF is 1
 - $P(Y \leq y | X = x) = \int_{-\infty}^y f_{Y|X}(y|x) dy$
 - $E(Y|X = x) = \int_{-\infty}^{\infty} y f_{Y|X}(y|x) dy$
 - Replace bound with actual bounds

Normal Distribution

- $f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$
- $f(z) = \frac{1}{\sqrt{2\pi}} e^{-\frac{z^2}{2}}$
- Shape is identical if two curves share the same σ
- Curve flattens as σ increases
- $\Phi(x)$ is the CDF of the normal distribution
- $\Phi(x) = P(x < 2), \Phi(-x) = 1 - \Phi(x)$
- $P(|x| < 2) = 2\Phi(x) - 1 = p(-2 < x < 2)$
- $P(x_1 < x < x_2) = \Phi(\frac{x_2-\mu}{\sigma}) - \Phi(\frac{x_1-\mu}{\sigma})$
- $z = \frac{x-\mu}{\sigma}$
- $\phi(z) = f_Z(z)$

- $\Phi(z) = \int_{-\infty}^z (\phi(t)) dt = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z (e^{-\frac{t^2}{2}}) dt$

Normal apprximation to Binomial
As $n \rightarrow \infty, Z = \frac{X-np}{\sqrt{np(1-p)}}$

Continuity Correction

CONTINUITY CORRECTION
We apply **continuity correction** when approximating the binomial using the normal.

$$P(X = k) \approx P(k - 1/2 < X < k + 1/2)$$
$$P(a \leq X \leq b) \approx P(a - 1/2 < X < b + 1/2)$$
$$P(a < X \leq b) \approx P(a + 1/2 < X < b + 1/2)$$
$$P(a \leq X < b) \approx P(a - 1/2 < X < b - 1/2)$$
$$P(a < X < b) \approx P(a + 1/2 < X < b - 1/2)$$
$$P(X \leq c) = P(0 \leq X \leq c) \approx P(-1/2 < X < c + 1/2)$$
$$P(X > c) = P(c < X \leq n) \approx P(c + 1/2 < X < n + 1/2)$$

L-EXAMPLE 4.19
A system is made up of 100 components, and each of which has a reliability equal to 0.90. These components function independently of one another, and the entire system functions only when at least 80 components function. What is the probability that the system functioning?

Solution:
Let X be the number of components functioning. Then $X \sim \text{Bin}(100, 0.9)$.
Thus $E(X) = (100)(0.9) = 90$ and $V(X) = (100)(0.9)(0.1) = 9$.
The system is functioning if $80 \leq X \leq 100$, with probability

$$P(80 \leq X \leq 100) \approx P\left(\frac{79.5 - 90}{\sqrt{9}} < \frac{X - 90}{\sqrt{9}} \leq \frac{100.5 - 90}{\sqrt{9}}\right) = \Phi(3.5) - \Phi(-3.5) = 0.9995.$$

Properties of Independent Random Variables

DEFINITION 9 (INDEPENDENT RANDOM VARIABLES)
Random variables X and Y are **independent** if and only if for **any** x and y ,

$$f_{X,Y}(x,y) = f_X(x)f_Y(y).$$

Random variables X_1, X_2, \dots, X_n are **independent** if and only if for **any** x_1, x_2, \dots, x_n ,

$$f_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n) = f_{X_1}(x_1)f_{X_2}(x_2) \cdots f_{X_n}(x_n).$$

- $R_{x,y}$ must be a product space (not a square)
- Any zeroes in the table indicate that $R_{x,y}$ is not product space
- If $f(x,y)$ can be easily factorised to $c * g(x) * g(y)$, it is a product space
- Cov(x,y)=0, E(XY)=E(X)E(Y)** if X and Y are independent

PROPERTIES OF INDEPENDENT RANDOM VARIABLES
Suppose X, Y are independent random variables.

- If A and B are arbitrary subsets of \mathbb{R} , the events $X \in A$ and $Y \in B$ are independent events in S . Thus

$$P(X \in A; Y \in B) = \boxed{P(X \in A)P(Y \in B)}.$$

In particular, for any real numbers x, y ,

$$P(X \leq x; Y \leq y) = P(X \leq x)P(Y \leq y).$$

- For arbitrary functions $g_1(\cdot)$ and $g_2(\cdot)$, $g_1(X)$ and $g_2(Y)$ are independent. For example,
 - X^2 and Y are independent.
 - $\sin(X)$ and $\cos(Y)$ are independent.
 - e^X and $\log(Y)$ are independent.
- Independence is connected with conditional distribution.
 - If $f_X(x) > 0$, then $f_{Y|X}(y|x) = f_Y(y)$.
 - If $f_Y(y) > 0$, then $f_{X|Y}(x|y) = f_X(x)$.

Uniform Distribution

MEAN AND VARIANCE OF THE UNIFORM
We derive $E(X)$ and $V(X)$ for the continuous uniform distribution.
The mean is given as

$$E(X) = \int_a^b x \cdot \frac{1}{b-a} dx = \frac{1}{b-a} \left[\frac{x^2}{2} \right]_a^b = \frac{1}{b-a} \cdot \frac{b^2 - a^2}{2} = \frac{a+b}{2}.$$

Recall that $V(X) = E(X^2) - [E(X)]^2$. So we compute

$$E(X^2) = \int_a^b x^2 \cdot \frac{1}{b-a} dx = \frac{1}{b-a} \left[\frac{x^3}{3} \right]_a^b = \frac{1}{b-a} \cdot \frac{b^3 - a^3}{3} = \frac{a^2 + ab + b^2}{3}.$$

Thus

$$V(X) = E(X^2) - [E(X)]^2 = \frac{a^2 + ab + b^2}{3} - \left(\frac{a+b}{2} \right)^2 = \frac{(a^2 - 2ab + b^2)}{12} = \frac{(b-a)^2}{12}.$$

CUMULATIVE DISTRIBUTION FUNCTION OF THE UNIFORM

We derive the cumulative distribution function of a continuous uniform distribution.

Take note that $F_X(x) = 0$ when $x < a$, and $F_X(x) = 1$ when $x > b$.

When $a \leq x \leq b$,

$$F_X(x) = \int_{-\infty}^x f_X(t) dt = \int_{-\infty}^a 0 dt + \int_a^x \frac{1}{b-a} dt = \frac{1}{b-a} (x - a).$$

Exponential Distribution

- Theorem 15** $\lambda > 0 P(X > (s + t) | X > s) = P(X > t)$ for positive values of s and t
- This is because exponential distribution is memoryless

MEAN AND VARIANCE OF THE EXPONENTIAL

We derive $E(X)$ and $V(X)$ for the exponential distribution.

The mean is given as

$$E(X) = \int_0^{\infty} x \lambda e^{-\lambda x} dx = \left[-x e^{-\lambda x} \right]_0^{\infty} - \int_0^{\infty} (-e^{-\lambda x}) dx = \int_0^{\infty} e^{-\lambda x} dx = \left[-\frac{1}{\lambda} e^{-\lambda x} \right]_0^{\infty} = \frac{1}{\lambda}.$$

Recall that $V(X) = E(X^2) - [E(X)]^2$. So we compute

$$E(X^2) = \int_0^{\infty} x^2 \lambda e^{-\lambda x} dx = \left[-x^2 e^{-\lambda x} \right]_0^{\infty} - \int_0^{\infty} (-2x e^{-\lambda x}) dx = \frac{2}{\lambda} \int_0^{\infty} x \lambda e^{-\lambda x} dx = \frac{2}{\lambda} \cdot \frac{1}{\lambda} = \frac{2}{\lambda^2}.$$

Thus

$$V(X) = \frac{2}{\lambda^2} - \left(\frac{1}{\lambda} \right)^2 = \frac{1}{\lambda^2}.$$

We derive the cumulative distribution function of the exponential distribution with parameter λ .

For $x \geq 0$,

$$F_X(x) = P(X \leq x) = \int_0^x \lambda e^{-\lambda t} dt = \left[-e^{-\lambda t} \right]_0^x = 1 - e^{-\lambda x}.$$

For $x < 0$, $F_X(x) = 0$.

This is a handy result to remember:

$$P(X > x) = e^{-\lambda x}, \text{ for } x > 0.$$

ALTERNATIVE FORM OF THE EXPONENTIAL

The probability density function of the exponential distribution can be written in the following alternative form

$$f_X(x) = \begin{cases} \frac{1}{\mu} e^{-x/\mu}, & x \geq 0; \\ 0, & x < 0. \end{cases}$$

The parameters μ and λ have the relationship $\mu = 1/\lambda$.

We will then have

$$E(X) = \mu, \quad V(X) = \mu^2, \quad \text{and} \quad F_X(x) = 1 - e^{-x/\mu}, \text{ for } x \geq 0.$$

Central Limit Theorem

- Under CLT, sample mean approaches population mean as n increases
- Law of large numbers: $P(|\bar{x} - \mu_x| > \epsilon) \rightarrow 0$ as n increases
- Symmetric no outliers: 15-20
- Skewed: 30-50, heavily skewed: > 1000
- $\sigma_{\bar{x}} = \frac{\sigma}{\sqrt{n}} \rightarrow$ large n , higher accuracy

Margin of Error

DIFFERENT CASES						
	Population	σ	n	Statistic	E	n for desired E_0 and α
I	Normal	known	any	$Z = \frac{\bar{X} - \mu}{\sigma/\sqrt{n}}$	$z_{\alpha/2} \cdot \frac{\sigma}{\sqrt{n}}$	$\left(\frac{z_{\alpha/2} \cdot \sigma}{E_0} \right)^2$
II	any	known	large	$Z = \frac{\bar{X} - \mu}{\hat{\sigma}/\sqrt{n}}$	$z_{\alpha/2} \cdot \frac{\sigma}{\sqrt{n}}$	$\left(\frac{z_{\alpha/2} \cdot \sigma}{E_0} \right)^2$
III	Normal	unknown	small	$T = \frac{\bar{X} - \mu}{\hat{S}/\sqrt{n}}$	$t_{n-1, \alpha/2} \cdot \frac{s}{\sqrt{n}}$	$\left(\frac{t_{n-1, \alpha/2} \cdot s}{E_0} \right)^2$
IV	any	unknown	large	$Z = \frac{\bar{X} - \mu}{\hat{S}/\sqrt{n}}$	$z_{\alpha/2} \cdot \frac{s}{\sqrt{n}}$	$\left(\frac{z_{\alpha/2} \cdot s}{E_0} \right)^2$

Confidence Interval

CONFIDENCE INTERVALS FOR THE MEAN
The table below gives the $(1 - \alpha)$ **confidence** interval (formulas) for the population mean.

Case	Population	σ	n	Confidence Interval
I	Normal	known	any	$\bar{x} \pm z_{\alpha/2} \cdot \sigma/\sqrt{n}$
II	any	known	large	$\bar{x} \pm z_{\alpha/2} \cdot \sigma/\sqrt{n}$
III	Normal	unknown	small	$\bar{x} \pm t_{n-1, \alpha/2} \cdot s/\sqrt{n}$
IV	any	unknown	large	$\bar{x} \pm z_{\alpha/2} \cdot s/\sqrt{n}$

Note that n is considered large when $n \geq 30$.

Alternative pooled variance:

$$s_p^2 = \frac{\sum_{i=1}^n (x_i - \bar{x})^2 + \sum_{i=1}^n (y_i - \bar{y})^2}{n_1 + n_2 - 2}$$

Equal Variance Assumption: $\frac{1}{2} < \frac{s_1}{s_2} < 2$

Assumptions

- Normal population (esp for small samples)
- Random and independent sampling

	Do not reject H_0	Reject H_0
H_0 is true	Correct Decision	Type I error
H_0 is false	Type II error	Correct Decision

DEFINITION 1 (TYPE I VS TYPE II ERROR)

The rejection of H_0 when H_0 is true is called a **Type I error**.

Not rejecting H_0 when H_0 is false is called a **Type II error**.

DEFINITION 2 (SIGNIFICANCE LEVEL VS POWER)

The probability of making a **Type I** error is called the **level of significance**, denoted by α . That is,

$$\alpha = P(\text{Type I error}) = P(\text{Reject } H_0 \mid H_0 \text{ is true}).$$

Let

$$\beta = P(\text{Type II error}) = P(\text{Do not reject } H_0 \mid H_0 \text{ is false}).$$

We define $1 - \beta = P(\text{Reject } H_0 \mid H_0 \text{ is false})$ to be the **power of the test**.