

## 01. COMPUTATIONAL MODELS

- algorithm** → a well-defined procedure for finding the correct solution to the input
- correctness**
  - worst-case correctness** → correct on every valid input
  - other types of correctness: correct on random input/with high probability/approximately correct
- efficiency / running time** → measures the number of steps executed by an algorithm as a function of the *input size* (depends on computational model used)
  - number input: typically the length of binary representation
  - worst-case** running time → *max* number of steps executed when run on an input of size  $n$

### adversary argument →

inputs are decided such that they have different solutions

## Comparison Model

- algorithm can **compare** any two elements in one time unit ( $x > y, x < y, x = y$ )
- running time = number of pairwise comparisons made
- array can be manipulated at no cost

## Decision Tree

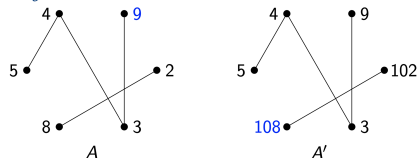
- each comparison represents the relationship between two elements
- each node is a comparison
- each branch is an outcome of the comparison
- log base is determined by the number of branches per node
- each leaf is a class label (decision after *all* comparisons)
- lower bound of worst-case** runtime = height of tree
- # of leaves = # of permutations →  $\lg(n!) = \Theta(n \lg n)$
- any decision tree that can sort  $n$  elements must have height  $\Omega(n \lg n)$ .

## Max Problem

*problem:* find largest element in array  $A$  of  $n$  distinct elements

*Proof.*  $n - 1$  comparisons are needed

fix an algorithm  $M$  that solves the Max problem on all inputs using  $< n - 1$  comparisons. construct graph  $G$  where nodes  $i$  and  $j$  are adjacent iff  $M$  compares  $i$  &  $j$ .

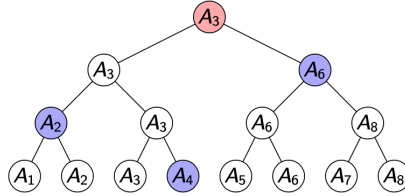


$M$  cannot differentiate  $A$  and  $A'$ .

## Second Largest Problem

*problem:* find the second largest element in  $< 2n - 3$  comparisons ( $2 \times \text{Maximum} \Rightarrow (n-1) + ((n-1)-1) = 2n-3$ )

- solution: knockout tournament** →  $n + \lceil \lg n \rceil - 2$



- bracket system:  $n - 1$  matches
  - every non-winner has lost exactly once
- then compare the elements that have lost to the largest
  - the 2nd largest element must have lost to the winner
  - compares  $\lceil \lg n \rceil$  elements that have lost to the winner using  $\lceil \lg n \rceil - 1$  comparisons

## Sorting

*Claim.* there is a sorting algorithm that requires  $\leq n \lg n - n + 1$  comparisons.

*Proof.* every sorting algorithm must make  $\geq \lg(n!)$  comparisons.

- let set  $\mathcal{U}$  be the set of all permutations of the set  $\{1, \dots, n\}$  that the adversary could choose as array  $A$ .  $|\mathcal{U}| = n!$
- for each query "is  $A_i > A_j$ ?", if  $\mathcal{U}_{yes} = \{A \in \mathcal{U} : A_i > A_j\}$  is of size  $\geq |\mathcal{U}|/2$ , set  $\mathcal{U} := \mathcal{U}_{yes}$ . else:  $\mathcal{U} := \mathcal{U} \setminus \mathcal{U}_{yes}$
- the size of  $\mathcal{U}$  decreases by at most half with each comparison
- with  $< \lg(n!)$  comparisons,  $\mathcal{U}$  will still contain at least 2 permutations

$$\begin{aligned} n! &\geq \left(\frac{n}{e}\right)^n \\ \Rightarrow \lg(n!) &\geq n \lg\left(\frac{n}{e}\right) = n \lg n - n \lg e \\ &\approx n \lg n - 1.44n \end{aligned}$$

⇒ roughly  $n \lg n$  comparisons are **required** and **sufficient** for sorting  $n$  numbers

## String Model

input	string of $n$ bits
each query	find out <b>one bit</b> of the string

- $n$  queries are **necessary** and **sufficient** to check if the input string is all 0s.
- query complexity** → number of bits of the input string queried by the algorithm
- evasive** → a problem requiring  $n$  query complexity

## Graph Model

input	(symmetric) adjacency matrix of an $n$ -node undirected graph
each query	find out if an edge is present between two chosen nodes (one entry of $G$ )

- evasive** → requires  $\binom{n}{2}$  queries

- Proof.* determining whether the graph is connected is evasive (requires  $\binom{n}{2}$  queries)
  - suppose  $M$  is an algorithm making  $\leq \binom{n}{2}$  queries.
  - whenever  $M$  makes a query, the algorithm tries not adding this edge, but adding all remaining unqueried edges.
    - if the resulting graph is connected,  $M$  replies 0 (i.e. edge does not exist)
    - else: replies 1 (edge exists)
  - after  $< \binom{n}{2}$  queries, at least one entry of the adjacency matrix is unqueried.

## 02. ASYMPTOTIC ANALYSIS

- algorithm** → a *finite* sequence of well-defined instructions to solve a given computational problem
- word-RAM model** → runtime is the total number of instructions executed
  - operators, comparisons, if, return, etc
  - each instruction operates on a *word* of data (limited size) ⇒ fixed constant amount of time

## Asymptotic Notations

**upper bound ( $\leq$ ):**  $f(n) = O(g(n))$

if  $\exists c > 0, n_0 > 0$  such that  $\forall n \geq n_0$ ,  
 $0 \leq f(n) \leq cg(n)$

**lower bound ( $\geq$ ):**  $f(n) = \Omega(g(n))$

if  $\exists c > 0, n_0 > 0$  such that  $\forall n \geq n_0$ ,  
 $0 \leq cg(n) \leq f(n)$

**tight bound:**  $f(n) = \Theta(g(n))$

if  $\exists c_1, c_2, n_0 > 0$  such that  $\forall n \geq n_0$ ,  
 $0 \leq c_1g(n) \leq f(n) \leq c_2g(n)$

**$o$ -notation ( $<$ ):**  $f(n) = o(g(n))$

if  $\forall c > 0, \exists n_0 > 0$  such that  $\forall n \geq n_0$ ,  
 $0 \leq f(n) < cg(n)$

**$\omega$ -notation ( $>$ ):**  $f(n) = \omega(g(n))$

if  $\forall c > 0, \exists n_0 > 0$  such that  $\forall n \geq n_0$ ,  
 $0 \leq cg(n) < f(n)$

*Proof.*  $(n+1)! \neq O(n!)$  since  $\frac{(n+1)!}{n!} = (n+1) > c$

## Limits

Assume  $f(n), g(n) > 0$ .

$$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0 \Rightarrow f(n) = o(g(n))$$

$$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} < \infty \Rightarrow f(n) = O(g(n))$$

$$0 < \lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} < \infty \Rightarrow f(n) = \Theta(g(n))$$

$$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} > 0 \Rightarrow f(n) = \Omega(g(n))$$

$$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = \infty \Rightarrow f(n) = \omega(g(n))$$

*Proof.* 1. Since  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$ , we have for all  $\epsilon > 0$ , there exists  $\delta > 0$  s.t.  $\frac{f(n)}{g(n)} < \epsilon$  for  $n > \delta$

2. Set  $c = \epsilon$  and  $n_0 = \delta$

3.  $\forall n \geq n_0, \frac{f(n)}{g(n)} < c$

4.  $\forall n \geq n_0, f(n) < cg(n)$

5. By definition,  $f(n) = o(g(n))$

## Properties of Big O

$$\Theta(g(n)) = O(g(n)) \cap \Omega(g(n))$$

- transitivity** - applies for  $O, \Omega, \Theta, o, \omega$   
 $f(n) = O(g(n)) \wedge g(n) = O(h(n)) \Rightarrow f(n) = O(h(n))$
- reflexivity** - for  $O, \Omega, \Theta, f(n) = O(f(n))$
- symmetry** -  $f(n) = \Theta(g(n)) \iff g(n) = \Theta(f(n))$
- complementarity** -
  - $f(n) = O(g(n)) \iff g(n) = \Omega(f(n))$
  - $f(n) = o(g(n)) \iff g(n) = \omega(f(n))$
- misc**
  - if  $f(n) = \omega(g(n))$ , then  $f(n) = \Omega(g(n))$
  - if  $f(n) = o(g(n))$ , then  $f(n) = O(g(n))$

$$\log \log n < \log n < (\log n)^k < n^k < (n+1)! < k^n$$

insertion sort:  $O(n^2)$  with worst case  $\Theta(n^2)$

## 03. ITERATION, RECURSION, DIVIDE-AND-CONQUER

### Iterative Algorithms

- iterative** → loop(s), sequentially processing input elements
- loop invariant** implies correctness if
  - initialisation* - true before the first iteration of the loop
  - maintenance* - if true before an iteration, it remains true at the beginning of the next iteration
  - termination* - true when the algorithm terminates

### examples

- insertionSort:** with loop variable as  $j, A[1..j-1]$  is sorted.
  - $A[1..j] = A[1..j]$ . Elements not considered are unaffected.
  - $A[i+2..j] = A[i+1..j-1]$ . Relative order of shifted elements is preserved.
  - $A[i+2..j] > \text{key}$ . Elements to its right are sorted and greater.
- selectionSort:** with loop variable as  $j$ , the array  $A[1..j-1]$  is sorted and contains the  $j-1$  smallest elements of  $A$ .
- Dijkstra's:**

*Proof.* 1. **invariant**  $\forall x \in R: \text{dist}[x] = \sigma(s, x)$

2. **invariant**  $\forall y$  neighbouring  $x \in R$ :  
 $\text{dist}[y] = \min_{x \in R} \sigma(s, x) + W(x, y)$

## Recursive Algorithm

- recursive** → solves sub problems
- Correctness is proven using **mathematical induction** on size of problem
- Use strong induction, prove base case, show algorithm works assuming it works for all smaller cases

Examples

**BINARY-SEARCH** ( $A, a, b, x$ )  $\triangleright A[a \dots b]$   
if  $a > b$  then  
    return *false*  
else  $mid = \lfloor (a+b)/2 \rfloor$   
if  $x == A[mid]$  then  
    return *true*  
if  $x < A[mid]$  then  
    return **BINARY-SEARCH** ( $A, a, mid-1, x$ )  
else  
    return **BINARY-SEARCH** ( $A, mid+1, b, x$ )

- **binary search**(A,a,b,x) returns the correct answer when b-a+1=n
- Base case: n=b-a+1=0, since a=b+1, A[a..b] is empty and the answer is false
- Inductive step:  $n = b - a + 1 > 0$
- By strong induction, assume (A,a',b',x) returns the correct answer for all j s.t  $0 \leq j \leq n-1$  where  $j = b' - a' + 1$
- By the algorithm,  $mid = \lfloor \frac{a+b}{2} \rfloor$  and  $a \leq mid \leq b$
- If  $x == A[mid]$  then  $x \in A[a..b]$  and the algorithm returns true correctly
- If  $x < A[mid]$  then  $x \in A[a..mid-1]$  if  $x \in A[a..b]$
- By the inductive hypothesis, (A,a,mid-1,x) is correct since  $0 \leq (mid-1) - a + 1 = mid - a \leq n-1$
- The  $x > A[mid]$  is similar

Divide-and-Conquer

powering a number

*problem:* compute  $f(n, m) = a^n \pmod m$  for all  $n, m \in \mathbb{Z}$

- observation:  $f(x + y, m) = f(x, m) * f(y, m) \pmod m$
- **naive solution:** recursively compute and combine  $f(n-1, m) * f(1, m) \pmod m$ 
  - $T(n) = T(n-1) + T(1) + \Theta(1) \Rightarrow T(n) = \Theta(n)$
- **better solution:** divide and conquer (only one sub problem computed)
  - divide: trivial
  - conquer: recursively compute  $f(\lfloor n/2 \rfloor, m)$
  - combine:
    - $f(n, m) = f(\lfloor n/2 \rfloor, m)^2 \pmod m$  if n is even
    - $f(n, m) = f(1, m) * f(\lfloor n/2 \rfloor, m)^2 \pmod m$  if odd
  - $T(n) = T(n/2) + \Theta(1) \Rightarrow \Theta(\log n)$

Peak finding

*problem:* Find the peak element (no neighbours are greater) in 2D array

- **Naive** O(mn)
  - for the middle column, find the maximum element
  - return if it is peak
  - p1=Find2DPeak(left)
  - p2=Find2DPeak(right)
  - return p1 or p2 if one is a peak
- **Divide and conquer** O(mlogn),  $T(n) = T(n/2) + O(1)$  n is number of columns
- find the middle column, find the maximum element
  - if it is a peak, return it
  - if not, recurse on the side with a larger element
- **Optimised** O(m+n)

- find the middle column, find the maximum element
- recurse on the quarter with the larger element

Solving Recurrences

for  $a$  sub-problems of size  $\frac{n}{b}$  where  $f(n)$  is the time to divide and combine,  
$$T(n) = aT(\frac{n}{b}) + f(n)$$

Telescoping

Express  $\frac{T(n)}{g(n)}$  as  $\frac{T(\frac{n}{b})}{g(\frac{n}{b})} + h(n)$

Choose the poly(n) part of f(n) as  $\frac{f(n)}{b}$

1. Example:  $T(n) = 2T(n/2) + n$

2.  $\frac{T(n)}{n} = \frac{T(n/2)}{n/2} + 1$

...

$$\log n \left[ \begin{aligned} \frac{T(n)}{n} &= \frac{T(n/2)}{n/2} + 1 \\ \frac{T(n/2)}{n/2} &= \frac{T(n/4)}{n/4} + 1 \\ \frac{T(n/4)}{n/4} &= \frac{T(n/8)}{n/8} + 1 \\ &\dots \\ \frac{T(2)}{2} &= \frac{T(1)}{1} + 1 \end{aligned} \right] \Rightarrow \frac{T(n)}{n} = \frac{T(1)}{1} + \log n$$

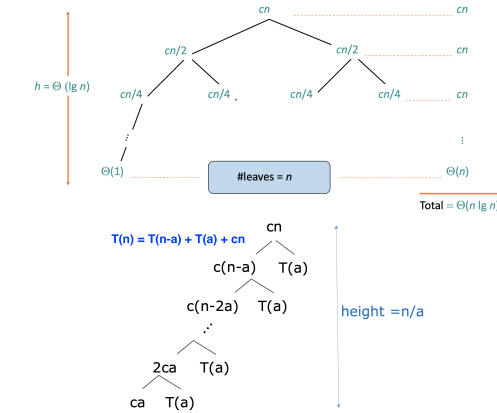
Hence,  $T(n) = O(n \log n)$ .

If g(n)=n, we need a=b since g(n) =  $n^{\log_b(a)}$

Recursion tree

total = height  $\times$  number of leaves

- each node represents the cost of a single subproblem
- height of the tree = longest path from root to leaf



Master method

- $a \geq 1, b > 1$ , and  $f$  is asymptotically positive.
- $a$  (number of sub problems),  $b$ (size of sub problems),  $f$ (time to divide and combine)

$T(n) = aT(\frac{n}{b}) + f(n) =$

$\Theta(n^{\log_b a})$	if $f(n) < n^{\log_b a}$ polynomially
$\Theta(n^{\log_b a} \log n)$	if $f(n) = n^{\log_b a}$
$\Theta(f(n))$	if $f(n) > n^{\log_b a}$ polynomially

three common cases

1. If  $f(n) = O(n^{\log_b a - \epsilon})$  for some constant  $\epsilon > 0$ ,
- $f(n)$  grows polynomially slower than  $n^{\log_b a}$  by  $n^\epsilon$  factor.
  - then  $T(n) = \Theta(n^{\log_b a})$ .

- This is when overhead at leaf  $>$  overhead at root
2. If  $f(n) = \Theta(n^{\log_b a} \log^k n)$  for some  $k \geq 0$ ,
- $f(n)$  and  $n^{\log_b a}$  grow at similar rates.
  - then  $T(n) = \Theta(n^{\log_b a} \log^{k+1} n)$
3. If  $f(n) = \Omega(n^{\log_b a + \epsilon})$  for some constant  $\epsilon > 0$ ,
- and  $f(n)$  satisfies the **regularity condition**
    - $af(n/b) \leq cf(n)$  for some constant  $c < 1$  and all sufficiently large  $n$
    - this guarantees that the sum of subproblems is smaller than  $f(n)$ .
  - $f(n)$  grows polynomially faster than  $n^{\log_b a}$  by  $n^\epsilon$  factor
  - then  $T(n) = \Theta(f(n))$ .
  - This is when the root (splitting)  $>$  leaf

Substitution method

1. guess that  $T(n) = O(f(n))$ .
2. verify by induction:
- 2.1. to show that for  $n \geq n_0$ ,  $T(n) \leq c \cdot f(n)$
- 2.2. set  $c = \max\{2, q\}$  and  $n_0 = 1$
- 2.3. verify base case(s):  $T(n_0) = q$
- 2.4. recursive case ( $n > n_0$ ):
- by strong induction, assume  $T(k) \leq c \cdot f(k)$  for  $n > k \geq n_0$
  - $T(n) = \text{recurrence}_i \dots \leq c \cdot f(n)$
- 2.5. hence  $T(n) = O(f(n))$ .

! may not be a tight bound!

example

*Proof.*  $T(n) = 4T(n/2) + n^2 / \lg n \Rightarrow \Theta(n^2 \lg \lg n)$

$$\begin{aligned} T(n) &= 4T(n/2) + \frac{n^2}{\lg n} \\ &= 4(4T(n/4) + \frac{(n/2)^2}{\lg n - \lg 2}) + \frac{n^2}{\lg n} \\ &= 16T(n/4) + \frac{n^2}{\lg n - \lg 2} + \frac{n^2}{\lg n} \\ &= \sum_{k=1}^{\lg n} \frac{n^2}{\lg n - k} \\ &= n^2 \lg \lg n \text{ by approx. of harmonic series } (\sum \frac{1}{k}) \end{aligned}$$

Can also be solved via telescoping using  $g(n)=n^2$

*Proof.*  $T(n) = 4T(n/2) + n \Rightarrow O(n^2)$

To show that for all  $n \geq n_0$ ,  $T(n) \leq c_1 n^2 - c_2 n$

1. Set  $c_1 = q + 1, c_2 = 1, n_0 = 1$ .
2. Base case ( $n = 1$ ): subbing into  $c_1 n^2 - c_2 n$ ,  $T(1) = q \leq (q + 1)(1)^2 - (1)(1)$
3. Recursive case ( $n > 1$ ):

- by strong induction, assume  $T(k) \leq c_1 \cdot k^2 - c_2 \cdot k$  for all  $n > k \geq 1$
- $T(n) = 4T(n/2) + n$ 
  - $= 4(c_1(n/2)^2 - c_2(n/2)) + n$
  - $= c_1 n^2 - 2c_2 n + n$
  - $= c_1 n^2 - c_2 n + (1 - c_2)n$
  - $= c_1 n^2 - c_2 n$  since  $c_2 = 1 \Rightarrow 1 - c_2 = 0$

Non-comparison sort

Counting sort

Set  $C[i]$  be the number of elements equal  $i$ .

Set  $C[i]$  be the number of elements smaller than or equal  $i$ .

Move elements equal  $i$  to  $B[C[i-1]+1..C[i]]$ .

for  $i \leftarrow 1$  to  $k$   
    do  $C[i] \leftarrow 0$   
for  $j \leftarrow 1$  to  $n$   
    do  $C[A[j]] \leftarrow C[A[j]] + 1 \triangleright C[i] = |\{\text{key} = i\}|$   
for  $i \leftarrow 2$  to  $k$  *prefix sum*  
    do  $C[i] \leftarrow C[i] + C[i-1] \triangleright C[i] = |\{\text{key} \leq i\}|$   
for  $j \leftarrow n$  downto 1  
    do  $B[C[A[j]]] \leftarrow A[j]$   
    do  $C[A[j]] \leftarrow C[A[j]] - 1$

- $O(n+k)$ , where k is the number of elements
- Stable

Radix sort

Suppose there are T digits.

for  $i \leftarrow 1$  to  $T$   
    do sort by the  $i^{\text{th}}$  least significant digit using a **stable** sorting algorithm;

Example: We can use counting sort as the stable sorting algorithm.

- Each pass processes r digits at  $O(n + 2^r)$
- $T(n, b) = \theta(\frac{b}{2} (n + 2^r))$  where  $b$  is the number of bits in the key
- Optimal  $r = \lg n$   $T(n, b) = \theta(\frac{bn}{\lg n})$
- Fast when the number of passes ( $\frac{b}{r}$ ) is small
- Little locality of reference, not cache friendly

04. AVERAGE-CASE ANALYSIS & RANDOMISED ALGORITHMS

- **average case**  $A(n) \rightarrow$  expected running time when the input is chosen uniformly at random from the set of all  $n!$  permutations
  - $A(n) = \frac{1}{n!} \sum_{\pi} Q(\pi)$  where  $Q(\pi)$  is the time complexity when the input is permutation  $\pi$ .
  - $A(n) = \mathbb{E}_{x \sim \mathcal{D}_n} [\text{Runtime of Alg on } x]$ 
    - $\mathbb{E}_{x \sim \mathcal{D}_n}$  is a probability distribution on  $U$  restricted to inputs of size  $n$ .

Quicksort Analysis

- divide & conquer, linear-time  $\Theta(n)$  partitioning subroutine
- assume we select the first array element as pivot
- $T(n) = T(j) + T(n-j-1) + \Theta(n)$ 
  - if the pivot produces subarrays of size  $j$  and  $(n-j-1)$
- **worst-case:**  $T(n) = T(0) + T(n-1) + \Theta(n) \Rightarrow \Theta(n^2)$

*Proof.* for quicksort,  $A(n) = O(n \log n)$

let  $P(i)$  be the set of all those permutations of elements  $\{e_1, e_2, \dots, e_n\}$  that begins with  $e_i$ .

Let  $G(n, i)$  be the average running time of quicksort over  $P(i)$ . Then  
$$\begin{aligned} G(n) &= A(i-1) + A(n-i) + (n-1). \\ A(n) &= \frac{1}{n} \sum_{i=1}^n G(n, i) \\ &= \frac{1}{n} \sum_{i=1}^n (A(i-1) + A(n-i) + (n-1)) \\ &= \frac{2}{n} \sum_{i=1}^n A(i-1) + n-1 \end{aligned}$$

=  $O(n \log n)$  by taking it as area under integration

quicksort vs mergesort

	average	best	worst
quicksort	$1.39n \lg n$	$n \lg n$	$n(n-1)$
mergesort	$n \lg n$	$n \lg n$	$n \lg n$

- disadvantages of mergesort:
  - overhead of temporary storage
  - cache misses
- advantages of quicksort
  - in place
  - reliable (as  $n \uparrow$ , chances of deviation from avg case  $\downarrow$ )
- issues with quicksort
  - distribution-sensitive**  $\rightarrow$  time taken depends on the initial (input) permutation. Resolved with median pivot or randomised partitions

Randomised Algorithms

- randomised algorithms**  $\rightarrow$  output and running time are **functions** of the **input** and **random bits chosen**
  - vs non-randomised: output & running time are functions of the *input only*
- expected running time = worst-case running time =  $E(n) = \max_{\text{input } x \text{ of size } n} \mathbb{E}[\text{Runtime of RandAlg on } x]$
- randomised quicksort**: choose pivot at random
  - probability that the runtime of *randomised* quicksort exceeds average by  $x\%$  =  $n^{-\frac{x}{100} \ln \ln n}$
  - P(time takes at least double of the average) =  $10^{-15}$
  - distribution insensitive

Balls into bins - Indicator Random Variable

There are  $n$  balls and  $m$  bins. Each ball is placed into a bin at random. How many empty bins?

- $X_i = 1$  if ball  $i$  is in bin  $j$ , 0 otherwise
- $E(X_i) = 1 * P(i^{th} bin \text{ empty}) + 0 * P(\dots) = (1 - \frac{1}{n})^m$
- $E(X) = E(X_1) + E(X_2) + \dots + E(X_n) = n(1 - \frac{1}{n})^m$

Randomised Quicksort Analysis

$T(n) = n - 1 + T(q - 1) + T(n - q)$   
Let  $A(n) = \mathbb{E}[T(n)]$  where the expectation is over the randomness in expectation.  
Taking expectations and applying linearity of expectation:  
 $A(n) = n - 1 + \frac{1}{n} \sum_{q=1}^n (A(q - 1) + A(n - q))$   
 $= n - 1 + \frac{2}{n} \sum_{q=1}^{n-1} A(q)$

$A(n) = n \log n \Rightarrow$  same as average case quicksort

Randomised Quickselect

- $O(n)$  to find the  $k^{th}$  smallest element
- randomisation: unlikely to keep getting a bad split

Types of Randomised Algorithms

- randomised **Las Vegas** algorithms
  - output is always correct
  - runtime is a *random variable*
  - e.g. randomised quicksort, randomised quickselect
- randomised **Monte Carlo** algorithms

- output may be incorrect with some small probability
- runtime is *deterministic*

Examples

- smallest enclosing circle**: given  $n$  points in a plane, compute the smallest radius circle that encloses all  $n$  points
  - best **deterministic** algorithm:  $O(n)$ , but complex
  - Las Vegas: average  $O(n)$ , simple solution
- minimum cut**: given a connected graph  $G$  with  $n$  vertices and  $m$  edges, compute the smallest set of edges whose removal would disconnect  $G$ .
  - best **deterministic** algorithm:  $O(mn)$
  - Monte Carlo**:  $O(m \log n)$ , error probability  $n^{-c}$  for any  $c$
- primality testing**: determine if an  $n$  bit integer is prime
  - best **deterministic** algorithm:  $O(n^6)$
  - Monte Carlo**:  $O(kn^2)$ , error probability  $2^{-k}$  for  $k$  checks

Geometric Distribution

Let  $X$  be the number of trials repeated until success.  $X$  is a random variable and follows a geometric distribution with probability  $p$ .

Expected number of trials,  $E[X] = \frac{1}{p}$   
 $Pr[X = k] = q^{k-1}p$

Linearity of Expectation

For any two events  $X, Y$  and a constant  $a$ ,  
 $E[X + Y] = E[X] + E[Y]$   
 $E[aX] = aE[X]$

Coupon Collector Problem

- $n$  types of coupon are put into a box and randomly drawn with replacement. What is the expected number of draws needed to collect at least one of each type of coupon?
- let  $T_i$  be the time to collect the  $i$ -th coupon after the  $i - 1$  coupon has been collected.
    - Probability of collecting a new coupon,  $p_i = \frac{(n-(i-1))}{n}$
    - $T_i$  has a **geometric distribution**
    - $E[T_i] = 1/p_i$

- total number of draws,  $T = \sum_{i=1}^n T_i$
- $E[T] = E[\sum_{i=1}^n T_i] = \sum_{i=1}^n E[T_i]$  by linearity of expectation  
 $= \sum_{i=1}^n \frac{n}{n-(i-1)} = n \cdot \sum_{i=1}^n \frac{1}{i} = \Theta(n \log n)$

05. HASHING

Dictionary ADT

- different types:
  - static** - fixed set of inserted items; only care about queries
  - insertion-only** - only insertions and queries
  - dynamic** - insertions, deletions, queries
- implementations
  - sorted list (static) -  $O(\log N)$  query
  - balanced search tree (dynamic) -  $O(\log N)$  all operations
  - direct access table

- $\times$  needs items to be represented as non-negative integers (**prehashing**)
- $\times$  huge space requirement
- using  $\mathcal{H}$  for dictionaries: need to store both the hash table and the matrix  $A$ .
  - additional storage overhead =  $\Theta(\log N \cdot \log |U|)$ , if  $M = \Theta(N)$
  - other universal hashing constructions may have more efficient hash function evaluation
- associative array** - has both key and value (dictionary in this context has only key)

Hashing

- hash function**,  $h : U \rightarrow \{1, \dots, M\}$  gives the location of where to store in the hash table
  - notation:  $[M] = \{1, \dots, M\}$   $[M] = \{1, \dots, M\}$
  - storing  $N$  items in hash table of size  $M$
- collision**  $\rightarrow$  for two different keys  $x$  and  $y$ ,  $h(x) = h(y)$ 
  - resolve by **chaining**, **open addressing**, etc
- desired properties
  - $\checkmark$  minimise collisions - `query(x)` and `delete(x)` take time  $\Theta(|h(x)|)$
  - $\checkmark$  minimise storage space - aim to have  $M = O(N)$
  - $\checkmark$  function  $h$  is easy to compute (assume constant time)
- if  $|U| \geq (N - 1)M + 1$ , for any  $h : U \rightarrow [M]$ , there is a set of  $N$  elements having the same hash value.
  - Proof**: pigeonhole principle
- use **randomisation** to overcome the adversary
  - e.g. randomly choose between two *deterministic* hash functions  $h_1$  and  $h_2$   
 $\Rightarrow$  for any pair of keys, with probability  $\geq \frac{1}{2}$ , there will be no collision

Universal Hashing

Suppose  $\mathcal{H}$  is a set of hash functions mapping  $U$  to  $[M]$ .

$\mathcal{H}$  is **universal** if  $\forall x \neq y, \frac{|h \in \mathcal{H} : h(x) = h(y)|}{|\mathcal{H}|} \leq \frac{1}{M}$   
or  $Pr_{h \sim \mathcal{H}} [h(x) = h(y)] \leq \frac{1}{M}$

- aka: for any  $x \neq y$ , if  $h$  is chosen uniformly at random from a universal  $\mathcal{H}$ , then there is at most  $\frac{1}{M}$  probability that  $h(x) = h(y)$
- probability where  $h$  is sampled uniformly from  $\mathcal{H}$
- aka: for any  $x \neq y$ , the fraction of hash functions with collisions is at most  $\frac{1}{M}$ .

Properties of universal hashing

Collision Analysis

- for any  $N$  elements  $x_1, \dots, x_N \in U$ , the **expected number of collisions** between  $x_N$  and other elements is  $< N/M$ .
  - it follows that for  $K$  operations, the expected cost of the last operation is  $< K/M = O(1)$  if  $M > K$ .

**Proof.** by definition of Universal Hashing, each element  $x_1, \dots, x_{N-1} \in U$  has at most  $\frac{1}{M}$  probability of collision with  $x_N$  (over random choice of  $h$ ).  
by indicator r.v.,  $E[A_i] = P(A_i = 1) \leq \frac{1}{M}$ . expected number of collisions =  $(N - 1) \cdot \frac{1}{M} < \frac{N}{M}$ .

- if  $x_1, \dots, x_N$  are added to the hash table, and  $M > N$ , the expected **number of pairs**  $(i, j)$  with collisions is  $< 2N$ .

**Proof.** let  $A_{ij}$  be an indicator r.v. for collision.

$$\mathbb{E}[\sum_{1 \leq i, j \leq N} A_{ij}] = \sum_{i=1}^N \mathbb{E}[A_{ii}] + \sum_{i \neq j} \mathbb{E}[A_{ij}]$$
$$\leq N \cdot 1 + N(N - 1) \cdot \frac{1}{M} < 2N$$

Expected Cost

- for any sequence of  $N$  operations, if  $M > N$ , then the **expected total cost** for executing the sequence is  $O(N)$ .

**Proof.** linearity of expectation; sum up expected costs

Construction of Universal Family

Obtain a universal family of hash functions with  $M = O(N)$ .

- Suppose  $U$  is indexed by  $u$ -bit strings and  $M = 2^m$ .
- For any  $m \times u$  binary matrix  $A$ ,  $h_A(x) = Ax \pmod{2}$ 
  - each element  $x \Rightarrow x \% 2$
  - $x$  is a  $u \times 1$  matrix  $\Rightarrow Ax$  is  $m \times 1$
- Claim**:  $\{h_A : A \in \{0, 1\}^{m \times u}\}$  is universal
- e.g.  $U = \{00, 01, 10, 11\}$ ,  $M = 2$ 
  - $h_{ab}$  means  $A = \begin{bmatrix} a & b \end{bmatrix}$

	00	01	10	11
$h_{00}$	0	0	0	0
$h_{01}$	0	1	0	1
$h_{10}$	0	0	1	1
$h_{11}$	0	1	1	0

**Proof.** Let  $x \neq y$ . Let  $z = x - y$ . We know  $z \neq 0$ .

Collision:  $P(Ax = Ay) = P[A(x - y) = 0] = P(Az = 0)$ .

To show  $P(Az = 0) \leq \frac{1}{M}$ .

**Special case** - Suppose  $z$  is 1 at the  $i$ -th coordinate but 0 everywhere else. Then  $Az$  is the  $i$ -th column of  $A$ . Since the  $i$ -th column is uniformly random,  $P(Az = 0) = \frac{1}{2^m} = \frac{1}{M}$ .

**General case** - Suppose  $z$  is 1 at the  $i$ -th coordinate. Let  $z = [z_1 \ z_2 \ \dots \ z_u]^T$ .  $A = [A_1 \ A_2 \ \dots \ A_u]$  hence  $Az_k$  is the  $k$ -th column of  $A$ .  
Then  $Az = z_1 A_1 + z_2 A_2 + \dots + z_u A_u$ .  
 $Az = 0 \Rightarrow z_1 A_1 = -(z_2 A_2 + \dots + z_u A_u)$  (\*)  
We fix  $z_1 A_1$  to be an arbitrary  $m \times 1$  matrix of 1s and 0s. The probability that (\*) holds is  $\frac{1}{2^m}$ .

Perfect Hashing

**static case** -  $N$  fixed items in the dictionary  $x_1, x_2, \dots, x_N$   
To perform Query in  $O(1)$  worst-case time.

**Quadratic Space:**  $M = N^2$

if  $\mathcal{H}$  is universal and  $M = N^2$ , and  $h$  is sampled uniformly from  $\mathcal{H}$ , then the expected number of collisions is  $< 1$ .

**Proof.** for  $i \neq j$ , let indicator r.v.  $A_{ij}$  be equal to 1 if  $h(x_i) = h(x_j)$ , or 0 otherwise.  
By universality,  $E[A_{ij}] = P(A_{ij} = 1) \leq 1/N^2$   
 $E[\# \text{ collisions}] = \sum_{i < j} E[A_{ij}] \leq \binom{N}{2} \frac{1}{N^2} < 1$

It follows that there exists  $h \in \mathcal{H}$  causing no collisions (because if not,  $\mathbb{E}[\# \text{ collisions}]$  would be  $\geq 1$ ).



2-Level Scheme:  $M = N$

- No collision and less space needed

Construction

Choose  $h : U \rightarrow [N]$  from a universal hash family.

- Let  $L_k$  be the number of  $x_i$ 's for which  $h(x_i) = k$ .
- Choose  $h_1, \dots, h_N$  **second-level** hash functions  $h_k : [N] \rightarrow [(L_k)^2]$  s.t. there are no collisions among the  $L_k$  elements mapped to  $k$  by  $h$ .
  - quadratic second-level table  $\rightarrow$  ensures no collisions using quadratic space

Analysis

if  $\mathcal{H}$  is universal and  $h$  is sampled uniformly from  $\mathcal{H}$ , then

$$E \left[ \sum_k L_k^2 \right] < 2N$$

Proof. For  $i, j \in [1, N]$ , define indicator r.v.  $A_{ij} = 1$  if  $h(x_i) = h(x_j)$ , or 0 otherwise.

$$A_{ij} = \# \text{ possible collisions} = \# \text{ pairs} * 2 = L_k^2$$

$$\text{Hence } \sum_k L_k^2 = \sum_{i,j} A_{ij}$$

$$E[\sum_{i,j} A_{ij}] = \sum_i E[A_{ii}] + \sum_{i \neq j} E[A_{ij}]$$
$$\leq N \cdot 1 + N(N-1) \cdot \frac{1}{N}$$
$$< 2N$$

Hash Table Resizing

- when number of inserted items,  $N$  is not known
  - rehashing** - choose a new hash function of a larger size and re-hash all elements
  - costly but infrequent  $\Rightarrow$  amortize

06. FINGERPRINTING & STREAMING

String Pattern Matching

problem: does the pattern string  $P$  occur as a substring of the text string  $T$ ?

$m$  = length of  $P$ ,  $n$  = length of  $T$ ,  $\ell$  = size of alphabet

- assumption: operations on strings of length  $O(\log n)$  can be executed in  $O(1)$  time. (word-RAM model)
- naive solution:  $\Theta(n^2)$

Fingerprinting approach (Karp-Rabin)

- faster string equality check:
  - for substring  $X$ , check  $h(X) == h(P)$  for a hash function  $h \Rightarrow \Theta(1)$  + cost of hashing instead of  $\Theta(|X|)$
- Rolling Hash**:  $O(m + n)$ 
  - update the hash from what we already have from the previous hash -  $O(1)$
  - compute  $n - m + 1$  hashes in  $O(n)$  time
  - Monte Carlo algorithm

Division Hash

Choose a random **prime** number  $p$  in the range  $\{1, \dots, K\}$ .  
For integer  $x$ ,  $h_p(x) = x \pmod p$

- if  $p$  is small and  $x$  is  $b$ -bits long in binary, hashing  $\Rightarrow O(b)$
- hash family  $\{h_p\}$  is approximately universal
- if  $0 \leq x < y < 2^b$ , then  $Pr_h[h_p(x) = h_p(y)] < \frac{b \ln K}{K}$

Proof.  $h_p(x) = h_p(y)$  when  $y - x = 0 \pmod p$ .

Let  $z = y - x$ .

Since  $z < 2^b$ , then  $z$  can have at most  $b$  distinct prime factors.

$p$  divides  $z$  if  $p$  is one of these  $\leq b$  prime factors.

number of primes in range  $\{1, \dots, K\}$  is  $> \frac{K}{\ln K}$ ,

hence the probability is  $b / \frac{K}{\ln K} = \frac{b \ln K}{K}$

values of K

- higher  $K$  = lower probability of false positive
  - for  $\delta = \frac{1}{100n}$ ,  $P(\text{false positive}) \leq 1\%$ .

$\forall \delta > 0$ , if  $X \neq Y$  and  $K = \frac{2m}{\delta} \cdot \lg \ell \cdot \lg(\frac{2m}{\delta} \lg \ell)$ , then  $Pr[h(X) = h(Y)] < \delta$

Streaming

problem: Consider a sequence of insertions or deletions of items from a large universe  $\mathcal{U}$ . At the end of the stream, the frequency  $f_i$  of item  $i$  is its net count.

Let  $M$  be the sum of all frequencies at the end of stream.

naive solutions

- direct access table -  $\Omega(U)$  space
- sorted list -  $\Omega(M)$  space, no  $O(1)$  update
- binary search tree -  $O(M)$  space

Frequency Estimation

an approximation  $\hat{f}_i$  is  **$\epsilon$ -approximate** if

$$f_i - \epsilon M \leq \hat{f}_i \leq f_i + \epsilon M$$

Using Hash Table

$$f_i \leq \mathbb{E}[\hat{f}_i] \leq f_i + M/k$$

- increment/decrement  $A[h(j)]$  on an empty table  $A$  of size  $k$
- collision  $\Rightarrow$  false positives  $\Rightarrow$  may give overestimate of  $f_i$ 
  - $A[h(i)] = \sum_{j:h(j)=h(i)} f_j \geq f_i$
- if  $h$  is drawn from a universal family, overestimate,  $\mathbb{E}[A[h(i)] - f_i] \leq M/k$
- space:  $O(\frac{1}{\epsilon} \cdot \lg M + \lg U \cdot \lg M)$

let  $k = \frac{1}{\epsilon}$  for some  $\epsilon > 0$ .

- number of rows =  $O(\frac{1}{\epsilon})$
- size of each row =  $O(\lg M)$
- size of hash function (using universal hash family from ch.05) =  $O(\lg U \cdot \lg M)$

- Count-Min Sketch**  $\rightarrow$  gives a bound on the probability

that  $\hat{f}_i$  deviates from  $f_i$  instead of a bound on the expectation of the gap

07. AMORTIZED ANALYSIS

- amortized analysis**  $\rightarrow$  guarantees the *average* performance of each operation in the *worst case*.
- total amortized cost provides an *upper bound* on the total true cost
- For a sequence of  $n$  operations  $o_1, o_2, \dots, o_n$ ,
  - let  $t(i)$  be the time complexity of the  $i$ -th operation  $o_i$
  - let  $f(n)$  be the *worst-case* time complexity for *any* of the  $n$  operations
  - let  $T(n)$  be the time complexity of all  $n$  operations

$$T(n) = \sum_{i=1}^n t(i) = nf(n)$$

Types of Amortized Analysis

Aggregate method

- look at the whole sequence, sum up the cost of operations and take the average - simpler but less precise
- e.g. binary counter - amortized  $O(1)$
- e.g. queues (with INSERT and EMPTY) - amortized  $O(1)$
- Find (a) The number of operations and (b) the upperbound of each operation
  - $a = n$
  - $b = \sum_{i=1}^n t(i) = nf(n)$

Accounting method

- charge the  $i$ -th operation a fictitious amortized cost  $c(i)$ 
  - amortized cost**  $c(i)$  is a fixed cost for each operation
  - true cost**  $t(i)$  depends on when the operation is called
- amortized cost  $c(i)$  must satisfy:

$$\sum_{i=1}^n t(i) \leq \sum_{i=1}^n c(i) \text{ for all } n$$

- take the extra amount for cheap operations early on as "credit" paid in advance for expensive operations
  - invariant**: bank balance never drops below 0
- the total amortized cost provides an **upper bound** on the total true cost

Potential method

- $\phi$ : potential function associated with the algo/DS
- $\phi(i)$ : potential at the end of the  $i$ -th operation
- $c_i$ : amortized cost of the  $i$ -th operation
- $t_i$ : true cost of the  $i$ -th operation

$$c_i = t_i + \phi(i) - \phi(i-1)$$
$$\sum_{i=1}^n c_i = \phi(n) - \phi(0) + \sum_{i=1}^n t_i$$

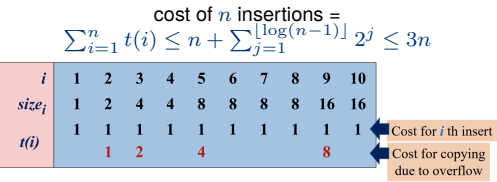
- hence as long as  $\phi(n) \geq 0$ , then amortized cost is an upper bound of the true cost.

$$\sum_{i=1}^n c_i \geq \sum_{i=1}^n t_i$$

- Validity**  $\phi(0) = 0$  and  $\phi(i) \geq 0$  for all  $i$
- e.g.** for queue:
  - let  $\phi(i)$  = # of elements in queue after the  $i$ -th operation
  - amortized cost for insert:
$$c_i = t_i + \phi(i) - \phi(i-1) = 1 + 1 = 2$$
  - amortized cost for empty (for  $k$  elements):
$$c_i = t_i + \phi(i) - \phi(i-1) = k + 0 - k = 0$$
- try to keep  $c(i)$  small: using  $c(i) = t(i) + \Delta\phi_i$ 
  - if  $t(i)$  is small, we want  $\Delta\phi_i$  to be positive and small
  - if  $t(i)$  is large, we want  $\Delta\phi_i$  to be negative and large

e.g. Dynamic Table (insertion only)

Aggregate method



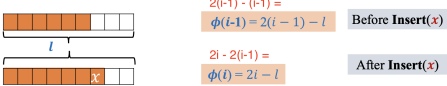
Accounting method

- charge \$3 per insertion
  - \$1 for insertion itself
  - \$1 for moving itself when the table expands

- \$1 for moving one of the existing items when the table expands

Potential method

let  $\phi(i) = 2i - size(T)$



Operation Insert(·)	Actual Cost	$\Delta\phi$	Amortized Cost
Case 1: when table is not full	1	2	3
Case 2: when table is already full	$i$	$3 - i$	3

Amortized cost of  $n$  insertions =  $3n = O(n)$

Actual cost of  $n$  insertions =  $O(n)$

- show that SUM of amortized cost  $\geq$  SUM of actual cost
- conclude that sum of amortized cost is  $O(f(n)) \Rightarrow$  sum of actual cost is  $O(f(n))$

08. DYNAMIC PROGRAMMING

- cut-and-paste proof**  $\rightarrow$  proof by contradiction - suppose you have an optimal solution. Replacing ("cut") subproblem solutions with this subproblem solution ("paste" in) should improve the solution. If the solution doesn't improve, then it's not optimal (contradiction).
- overlapping subproblems** - recursive solution contains a small number of distinct subproblems repeated many times
- optimal substructure** - optimal solution to a problem contains optimal solutions to subproblems

Longest Common Subsequence

- for sequence  $A : a_1, a_2, \dots, a_n$  stored in array
- $C$  is a **subsequence** of  $A \rightarrow$  if we can obtain  $C$  by removing zero or more elements from  $A$ .

**problem**: given two sequences  $A[1..n]$  and  $B[1..m]$ , compute the *longest* sequence  $C$  such that  $C$  is a subsequence of  $A$  and  $B$ .

brute force solution

- check *all* possible subsequences of  $A$  to see if it is also a subsequence of  $B$ , then output the longest one.
- analysis:  $O(m2^n)$ 
  - checking each subsequence takes  $O(m)$
  - $2^n$  possible subsequences

recursive solution

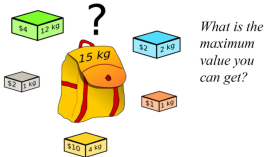
let  $LCS(i, j)$ : longest common subsequence of  $A[1..i]$  and  $B[1..j]$

- base case:  $LCS(i, 0) = \emptyset$  for all  $i$ ,  $LCS(0, j) = \emptyset$  for all  $j$
- general case:
  - if last characters of  $A, B$  are  $a_n = b_m$ , then  $LCS(n, m)$  must terminate with  $a_n = b_m$ 
    - the optimal solution will match  $a_n$  with  $b_m$
  - if  $a_n \neq b_m$ , then either  $a_n$  or  $b_m$  is not the last symbol
- optimal substructure**: (general case)
  - if  $a_n = b_m$ ,
$$LCS(n, m) = LCS(n-1, m-1) :: a_n$$
  - if  $a_n \neq b_m$ ,
$$LCS(n, m) = LCS(n-1, m) || LCS(n, m-1)$$

- simplified problem:**
  - $L(n, m) = 0$  if  $n = 0$  or  $m = 0$
  - if  $a_n = b_m$ , then  $L(n, m) = L(n - 1, m - 1) + 1$
  - if  $a_n \neq b_m$ , then  $L(n, m) = \max(L(n, m - 1), L(n - 1, m))$
- analysis**
  - number of distinct subproblems  $= (n + 1) \times (m + 1)$
  - to use  $O(\min\{m, n\})$  space: bottom-up approach, column by column
  - memoize for DP  $\Rightarrow$  makes it  $O(mn)$  instead of exponential time

### Knapsack Problem

- input:  $(w_1, v_1), (w_2, v_2), \dots, (w_n, v_n)$  and capacity  $W$
- output: subset  $S \subseteq \{1, 2, \dots, n\}$  that maximises  $\sum_{i \in S} v_i$  such that  $\sum_{i \in S} w_i \leq W$



- $2^n$  subsets  $\Rightarrow$  naive algorithm is costly
- recursive solution:**
  - let  $m[i, j]$  be the maximum value that can be obtained using a subset of items  $\{1, 2, \dots, i\}$  with total weight no more than  $j$ .
  - $m[i, j] = \begin{cases} 0, & \text{if } i = 0 \text{ or } j = 0 \\ \max\{m[i-1, j-w_i] + v_i, m[i-1, j]\}, & \text{if } w_i \leq j \\ m[i-1, j], & \text{otherwise} \end{cases}$
- analysis:**  $O(nW)$ 
  - $O(nW)$  is **not** a polynomial time algorithm
  - not polynomial in input bitsize
    - $W$  can be represented in  $O(\lg W)$  bits
    - $n$  can be represented in  $O(\lg n)$  bits
  - polynomial time is strictly in terms of the number of bits for the input

### Changing Coins

**problem:** use the fewest number of coins to make up  $n$  cents using denominations  $d_1, d_2, \dots, d_n$ . Let  $M[j]$  be the fewest number of coins needed to change  $j$  cents.

- optimal substructure:**

$$M[j] = \begin{cases} 1 + \min_{i \in [k]} M[j - d_i], & j > 0 \\ 0, & j = 0 \\ \infty, & j < 0 \end{cases}$$

*Proof.* Suppose  $M[j] = t$ , meaning  $j = d_{i_1} + d_{i_2} + \dots + d_{i_t}$  for some  $i_1, \dots, i_t \in \{1, \dots, k\}$ . Then, if  $j' = d_{i_1} + d_{i_2} + \dots + d_{i_{t-1}}$ ,  $M[j'] = t - 1$ , because otherwise if  $M[j'] < t - 1$ , by **cut-and-paste** argument,  $M[j] < t$ .

- runtime:  $O(nk)$  for  $n$  cents,  $k$  denominations

### Dijkstra’s Algorithm

- property 1:** The nearest neighbor is also the vertex nearest to  $s$
- Violated by **negative edges** since there can exist a shorter path to a vertex that is not the nearest neighbor
- property 2:** Optimal subpath property
- Violated when there are **negative cycles** since the final parth can consist of a subparth that is not the optimal subpath

## 09. GREEDY ALGORITHMS

- solve only one subproblem at each step
- beats DP and divide-and-conquer when it works
- greedy-choice property**  $\rightarrow$  a locally optimal choice is globally optimal
- Note:** This is not true for DP, a clear counter-example is that the LCS of a substring is not necessarily in the LCS of the entire string

### Examples

#### Fractional Knapsack

- $O(n \log n)$
- greedy-choice property:** let  $j^*$  be the item with *maximum value/kg*,  $v_j / w_i$ . Then there exists an optimal knapsack containing  $\min(w_{j^*}, W)$  kg of item  $j^*$ .
- optimal substructure:** if we remove  $w$  kg of item  $j$  from the optimal knapsack, then the remaining load must be the optimal knapsack weighing at most  $W - w$  kgs that one can take from  $n - 1$  original items and  $w_j - w$  kg of item  $j$ .

*Proof.* cut-and-paste argument

Suppose the remaining load after removing  $w$  kgs of item  $j$  was *not* the optimal knapsack weighing ... Then there is a knapsack of value  $> X - v_j \cdot \frac{w}{w_j}$  with weight ... Combining this knapsack with  $w$  kg of item  $j$  gives a knapsack of value  $> X \Rightarrow$  contradiction!

#### Minimum Spanning Trees

for a connected, undirected graph  $G = (V, E)$ , find a spanning tree  $T$  that connects all vertices with minimum weight. Weight of spanning tree  $T$ ,  $w(T) = \sum_{(u,v) \in T} w(u, v)$ .

- optimal substructure:** let  $T$  be a MST. remove any edge  $(u, v) \in T$ . then  $T$  is partitioned into  $T_1, T_2$  which are MSTs of  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$ .

*Proof.* cut-and-paste:  $w(T) = w(u, v) + w(T_1) + w(T_2)$  if  $w(T'_1) < w(T_1)$  for  $G_1$ , then  $T' = \{(u, v)\} \cup T'_1 \cup T_2$  would be a lower-weight spanning tree than  $T$  for  $G$ .  $\Rightarrow$  contradiction,  $T$  is the MST

- Prim’s algorithm** - at each step, add the least-weight edge from the tree to some vertex outside the tree
- Exchange Argument:

- Proof.* Let  $T'$  be the optimal solution without edge  $(u, v)$ . Swap  $(u, v)$  with the first edge along the simple path from  $u$  to  $v$  in  $T'$ . Clearly, a lighter weight spanning tree than  $T'$  results.
- Kruskal’s algorithm** - at each step, add the least-weight edge that does *not* cause a cycle to form

### Binary Coding

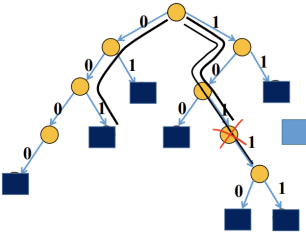
Given an alphabet set  $A : \{a_1, a_2, \dots, a_n\}$  and a text file  $F$  (sequence of alphabets), how many bits are needed to encode a text file with  $m$  characters?

- fixed length encoding:**  $m \cdot \lceil \log_2 n \rceil$ 
  - encode each alphabet to unique binary string of length  $\lceil \log_2 n \rceil$
  - total bits needed for  $m$  characters  $= m \cdot \lceil \log_2 n \rceil$
- variable length encoding**
  - different characters occur with different frequency  $\Rightarrow$  use fewer bits for *more frequent* alphabets
  - average bit length,  $ABL(\gamma) = \sum_{x \in A} f(x) \cdot |\gamma(x)|$
  - BUT overlapping prefixes cause indistinguishable characters
  - E.g. 0|10|10|111, 0|101|0|111

#### Prefix coding

**Problem:** Given a set  $A$  of  $n$  alphabets and their frequencies, compute coding  $\gamma$  such that:

- $\gamma$  is a prefix code
- $ABL(\gamma)$  is minimum
- a coding  $\gamma(A)$  is a **prefix coding** if  $\nexists x, y \in A$  such that  $\gamma(x)$  is a prefix of  $\gamma(y)$ .
- labelled binary tree:**  $\gamma(A) =$  label of path from root

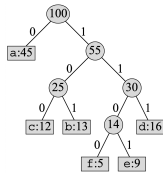


- for each prefix code  $A$  of  $n$  alphabets, there exists a binary tree  $T$  on  $n$  leaves such that there is a **bijective mapping (1-1)** between the alphabets and the leaves
- $ABL(\gamma) = \sum_{x \in A} f(x) \cdot |\gamma(x)| = \sum_{x \in A} f(x) \cdot \text{depth}_T(x)$
- the binary tree corresponding to an *optimal* prefix coding must be a **full binary tree**.
  - every internal node has degree exactly 2
  - multiple possible optimal trees - most optimal depends on alphabet frequencies
- accounting for alphabet **frequencies:**
  - let  $a_1, a_2, \dots, a_n$  be the alphabets of  $A$  in non-decreasing order of their frequencies.
  - $a_1$  must be a leaf node;  $a_2$  can be a sibling of  $a_1$ .
  - If  $a_1$  swapping  $a_1$  with a higher (frequency) none-leaf node results in a less optimal solution
  - there exists an optimal prefix coding in which  $a_1$  and  $a_2$  are siblings
- Greedy algorithm** for prefix coding:
  - $A = \{a_1, a_2, \dots, a_n\}$  in ascending order of freq

- $A' = \{a_3, a_4, \dots, a - i \dots a_n\}$  in ascending order of freq
- $f(a') = f(a_1) + f(a_2)$
- $OPT_{ABL}(A) = OPT_{ABL}(A') + f(a_1) + f(a_2)$
- derivation of optimal prefix coding: **Huffman’s algorithm**
  - keep merging the two least frequent items

Huffman(C):

```
Q = new PriorityQueue(C)
while Q:
    allocate a new node z
    z.left = x = extractMin(Q)
    z.right = y = extractMin(Q)
    z.val = x.val + y.val
    Q.add(z)
return extractMin(Q) // root
```

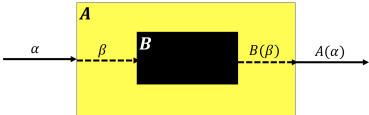


## 10. REDUCTIONS & INTRACTABILITY

### Reduction

Consider two problems  $A$  and  $B$ ,  $A$  can be solved as follows:

- convert instance  $\alpha$  of  $A$  to an instance of  $\beta$  in  $B$
- solve  $\beta$  to obtain a solution
- based on the solution of  $\beta$ , obtain the solution of  $\alpha$ .
- $\Rightarrow$  then we say  $A$  **reduces**  $B$ .



**instance**  $\rightarrow$  another word for input

#### e.g. Matrix Multiplication & Squaring

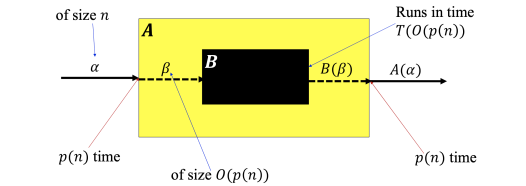
- MAT-MULT:** matrix multiplication
  - input:* two  $N \times N$  matrices  $A$  and  $B$ .
  - output:*  $A \times B$
- MAT-SQR:** matrix squaring
  - input:* one  $N \times N$  matrix  $C$ . *output:*  $C \times C$
- MAT-SQR can be reduced to MAT-MULT
  - Proof.* Given input matrix  $C$  for MAT-SQR, let  $A = C$  and  $B = C$  be inputs for MAT-MULT. Then  $AB = C^2$ .
- MAT-MULT can also be reduced to MAT-SQR!
  - Proof.* let  $C = \begin{bmatrix} 0 & A \\ B & 0 \end{bmatrix}$   
 $\Rightarrow C^2 = \begin{bmatrix} 0 & A \\ B & 0 \end{bmatrix} \begin{bmatrix} 0 & A \\ B & 0 \end{bmatrix} = \begin{bmatrix} AB & 0 \\ 0 & BA \end{bmatrix}$

#### T-Sum

- o-SUM:** given array  $A$ , output  $i, j \in (1, n)$  such that  $A[i] + A[j] = 0$
- T-SUM:** given array  $B$ , output  $i, j \in (1, n)$  such that  $B[i] + B[j] = T$
- reduce T-SUM to o-SUM:**
  - given array  $B$ , define array  $A$  s.t.  $A[i] = B[i] - T/2$ .
  - if  $i, j$  satisfy  $A[i] + A[j] = 0$ , then  $B[i] + B[j] = T$ .

p(n)-time Reduction

- p(n)-time Reduction** → if for any instance  $\alpha$  of problem  $A$  of size  $n$ ,
  - an instance  $\beta$  for  $B$  can be constructed in  $p(n)$  time
  - a solution to problem  $A$  for input  $\alpha$  can be recovered from a solution to problem  $B$  for input  $\beta$  in time  $p(n)$ .
- !  $n$  is in bits!**
- if there is a  $p(n)$ -time reduction from problem  $A$  to  $B$  and a  $T(n)$ -time algorithm to solve problem  $B$ , then there is a  $T(O(p(n))) + O(p(n))$  time algorithm to solve  $A$ .



- $A \leq_P B$**  → if there is a  $p(n)$ -time reduction from  $A$  to  $B$  for some polynomial function  $p(n) = O(n^c)$  for some constant  $c$ . (" $A$  is a special case of  $B$ ")
  - if  $B$  has a polynomial time algorithm, then so does  $A$
  - "polynomial time"  $\approx$  reasonably efficient
- $A \leq_P B, B \leq_P C \Rightarrow A \leq_P C$**

Polynomial Time

- polynomial time** → runtime is polynomial in the **length of the encoding** of the problem instance
- "standard" encodings**
  - binary encoding of integers
  - list of parameters enclosed in braces (graphs/matrices)
- pseudo-polynomial** algorithm → runs in time polynomial in the **numeric value** if the input but is **exponential** in the **length** of the input
  - e.g. DP algo for KNAPSACK since  $W$  is in numeric value
- KNAPSACK is NOT polynomial time:  $O(nW \log M)$  but  $W$  is not the number of bits
- FRACTIONAL KNAPSACK is polynomial time:  $O(n \log n \log W \log M)$

Decision Problems

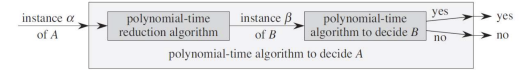
- decision problem** → a function that maps an instance space  $I$  to the solution set  $\{YES, NO\}$
- decision vs optimisation problem:
  - decision problem**: given a directed graph  $G$ , is there a path from vertex  $u$  to  $v$  of length  $\leq k$ ?
  - optimisation problem**: given ..., what is the *length* of the shortest path ... ?
  - convert from **decision** → **optimisation**: given an instance of the optimisation problem and a number  $k$ , is there a solution with value  $\leq k$ ?
- the decision problem is *no harder than* the optimisation problem.
  - given the optimal solution, check that it is  $\leq k$ .
  - if we cannot solve the decision problem quickly  $\Rightarrow$  then we cannot solve the optimisation problem quickly
- decision  $\leq_P$  optimisation

Reductions between Decision Problems

given two decision problems  $A$  and  $B$ , a polynomial-time reduction from  $A$  to  $B$  denoted  $A \leq_P B$  is a

**transformation** from instances  $\alpha$  of  $A$  and  $\beta$  of  $B$  such that

- $\alpha$  is a YES-instance of  $A \iff \beta$  is a YES-instance of  $B$
- the transformation takes polynomial time in the size of  $\alpha$



Examples

- INDEPENDENT-SET**: given a graph  $G = (V, E)$  and an integer  $k$ , is there a subset of  $\leq k$  vertices such that no 2 are adjacent?
- VERTEX-COVER**: given a graph  $G = (V, E)$  and an integer  $k$ , is there a subset of  $\leq k$  vertices such that each edge is incident to *at least one* vertex in this subset?
- INDEPENDENT-SET  $\leq_P$  VERTEX-COVER**
  - Reduction**: to check whether  $G$  has an independent set of size  $k$ , we check whether  $G$  has vertex cover of size  $n - k$ .

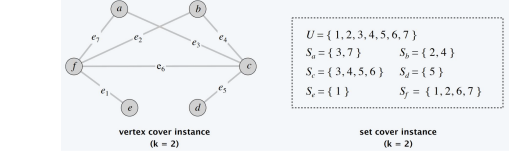
**Proof.** If INDEPENDENT-SET, then VERTEX-COVER.  
Suppose  $(G, k)$  is a YES-instance of INDEP-SET. Then there is subset  $S$  of size  $\geq k$  that is an independent set.  
 $V - S$  is a vertex cover of size  $\leq n - k$ . Proof: Let  $(u, v) \in E$ . Then  $u \notin S$  or  $v \notin S$ .  
So either  $u$  or  $v$  is in  $V - S$ , the vertex cover.

**Proof.** If VERTEX-COVER, then INDEPENDENT-SET.  
Same as above, but flip IS and VC

e.g. SET-COVER

Given integers  $k$  and  $n$ , and collection  $\mathcal{S}$  of subsets of  $\{1, \dots, n\}$ , are there  $\leq k$  of these subsets whose union equals  $\{1, \dots, n\}$ ?  
Claim: **VERTEX-COVER  $\leq_P$  SET-COVER**  
**Reduction**: given  $(G, k)$  instance of VERTEX-COVER, generate an instance  $(n, k', \mathcal{S})$  of SET-COVER.

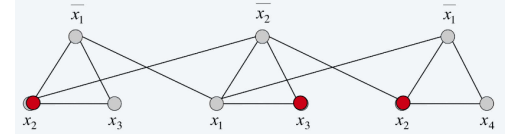
**Proof.** For each node  $v$  in  $G$ , construct a set  $S_v$  containing all its outgoing edges. (Number each edge)



e.g. 3-SAT

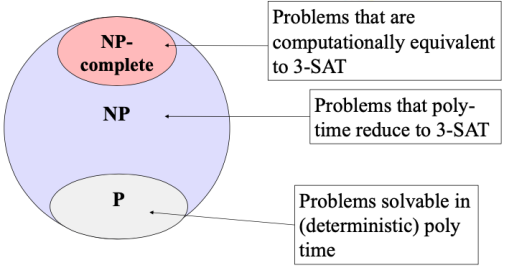
- SAT**: given a CNF formula  $\Phi$ , does it have a satisfying truth assignment?
  - literal: a boolean variable or its negation  $x, \bar{x}$
  - clause: a disjunction (OR) of literals
  - conjunctive normal form (CNF): formula  $\Phi$  that is a conjunction (AND) of clauses
- 3-SAT** → SAT where each clause contains exactly 3 literals
- 3-SAT  $\leq_P$  INDEPENDENT-SET**
  - Reduction**: Construct an instance  $(G, k)$  of INDEP-SET s.t.  $G$  has an independent set of size  $k \iff \Phi$  is satisfiable

- node: each literal term
- edge: connect 3 literals in a clause in a triangle
- edge: connect literal to all its negations
- reduction runs in polynomial time
- $\Rightarrow$  for  $k$  clauses, connecting  $k$  vertices form an independent set in  $G$ .



11. NP-COMPLETENESS

- P** → the class of *decision* problems solvable in (deterministic) polynomial time
- NP** → the class of *decision* problems for which polynomial-time verifiable **certificates** of YES-instances exist.
  - aka *non-deterministic polynomial*
  - i.e. no poly-time algo, but verification can be poly-time
  - certificate** → result that can be checked in poly-time to verify correctness
- $P \subseteq NP$** : any problem in **P** is in **NP**.
  - if  **$P = NP$** , then all these algos can be solved in poly time



NP-Hard and NP-Complete

- a problem  $A$  is said to be **NP-Hard** if for *every* problem  $B \in NP, B \leq_P A$ .
  - aka  $A$  is at least as hard as every problem in **NP**.
- a problem  $A$  is said to be **NP-Complete** if it is in **NP** and is also **NP-Hard**
  - aka the hardest problems in NP.
- Cook-Levin Theorem** → every problem in NP-Hard can be poly-time *reduced* to 3-SAT. Hence, **3-SAT is NP-Hard and NP-Complete**.
- NP-Complete problems can still be approximated in poly-time! (e.g. greedy algorithm gives a 2-approximation for VERTEX-COVER)

showing NP-Completeness

- show that  $X$  is in NP.  $\Rightarrow$  a YES-instance has a certificate that can be verified in polynomial time
- show that  $X$  is NP-hard
  - by giving a poly-time reduction from another NP-hard problem  $A$  to  $X$ .  $\Rightarrow X$  is at least as hard as  $A$
  - reduction should *not* depend on whether the instance of  $A$  is a YES- or NO-instance
- show that the reduction is valid
  - reduction runs in poly time

- if the instance of  $A$  is a YES-instance, then the instance of  $X$  is also a YES-instance
- if the instance of  $A$  is a NO-instance, then the instance of  $X$  is also a NO-instance

```
def INDEPENDENT-SET(G, k) -> bool:
1. G', k' = reduction(G, k)
2. yes_or_no: bool = CLIQUE(G', k') # magically given
3. return yes_or_no
```

- What to show for a **correct** reduction:
- $(G, k)$  is YES-instance  $\rightarrow (G', k')$  is also a YES-instance
  - $(G', k')$  is YES-instance  $\rightarrow (G, k)$  is also a YES-instance
  - The transformation takes polynomial time in the size of  $(G, k)$

showing NP-HARD

- take any **NP-Complete** problem  $A$
- show that  $A \leq_P X$

helpful approximations

stirling's approximation:  $T(n) = \sum_{i=0}^n \log(n-i) = \log \prod_{i=0}^n (n-i) = \Theta(n \log n)$

$\log\log(2) + \log\log(4) + \dots + \log\log(n) = \log(n)\log\log(n)$

harmonic number,  $H_n = \sum_{k=1}^n \frac{1}{k} = \Theta(\lg n)$

basel problem:  $\sum_{n=1}^N \frac{1}{n^2} \leq 2 - \frac{1}{N} \xrightarrow{N \rightarrow \infty} 2$

because  $\sum_{n=1}^N \frac{1}{N^2} \leq 1 + \sum_{x=2}^{\log_3 n} \frac{1}{(x-1)^x} = 1 + \sum_{n=2}^N (\frac{1}{n-1} - \frac{1}{n}) = 1 + 1 - \frac{1}{N} = 2 - \frac{1}{N}$

number of primes in range  $\{1, \dots, K\}$  is  $> \frac{K}{\ln K}$

asymptotic bounds

$1 < \log n < \sqrt{n} < n < n \log n < n^2 < n^3 < 2^n < 2^{2n}$

$\log_a n < n^a < a^n < n! < n^n$

for any  $a, b > 0$ ,  $\log_a n < n^b$

multiple parameters

for two functions  $f(m, n)$  and  $g(m, n)$ , we say that  $f(m, n) = O(g(m, n))$  if there exists constants  $c, m_0, n_0$  such that  $0 \leq f(m, n) \leq c \cdot g(m, n)$  for all  $m \geq m_0$  or  $n \geq n_0$ .

set notation

$O(g(n))$  is actually a *set of functions*.  $f(n) = O(g(n))$  means  $f(n) \in O(g(n))$

- $O(g(n)) = \{f(n) : \exists c, n_0 > 0 \mid \forall n \geq n_0, 0 \leq f(n) \leq cg(n)\}$
- $\Omega(g(n)) = \{f(n) : \exists c, n_0 > 0 \mid \forall n \geq n_0, 0 \leq cg(n) \leq f(n)\}$
- $\Theta(g(n)) = \{f(n) : \exists c_1, c_2, n_0 > 0 \mid \forall n \geq n_0, 0 \leq c_1 \cdot g(n) \leq f(n) \leq c_2 \cdot g(n)\} = O(g(n)) \cap \Omega(g(n))$
- $o(g(n)) = \{f(n) : \forall c > 0, \exists n_0 > 0 \mid \forall n \geq n_0, 0 \leq f(n) < cg(n)\}$
- $\omega(g(n)) = \{f(n) : \forall c > 0, \exists n_0 > 0 \mid \forall n \geq n_0, 0 \leq cg(n) < f(n)\}$

example proofs

*Proof.* that  $2n^2 = O(n^3)$

let  $f(n) = 2n^2$ . then  $f(n) = 2n^2 \leq n^3$  when  $n \geq 2$ .

set  $c = 1$  and  $n_0 = 2$ .

we have  $f(n) = 2n^2 \leq c \cdot n^3$  for  $n \geq n_0$ .

*Proof.*  $n = o(n^2)$

For any  $c > 0$ , use  $n_0 = 2/c$ .

*Proof.*  $n^2 - n = \omega(n)$

For any  $c > 0$ , use  $n_0 = 2(c + 1)$ .

*Example.* let  $f(n) = n$  and  $g(n) = n^{1+\sin(n)}$ .

Because of the oscillating behaviour of the sine function, there is no  $n_0$  for which  $f$  dominates  $g$  or vice versa.

Hence, we cannot compare  $f$  and  $g$  using asymptotic notation.

*Example.* let  $f(n) = n$  and  $g(n) = n(2 + \sin(n))$ .

Since  $\frac{1}{3}g(n) \leq f(n) \leq g(n)$  for all  $n \geq 0$ , then  $f(n) = \Theta(g(n))$ . (note that limit rules will not work here)

mentioned algorithms

- ch.3 - **Misra Gries** - space-efficient computation of the majority bit in array  $A$
- ch.3 - **Euclidean** - efficient computation of GCD of two integers
- ch.3 - **Tower of Hanoi** -  $T(n) = 2^n - 1$ 
  - move the top  $n - 1$  discs from the first to the second peg using the third as temporary storage.
  - move the biggest disc directly to the empty third peg.
  - move the  $n - 1$  discs from the second peg to the third using the first peg for temporary storage.
- ch.3 - **MergeSort** -  $T(n) = T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil) + \Theta(n)$
- ch.3 - **Karatsuba Multiplication** - multiply two  $n$ -digit numbers  $x$  and  $y$  in  $O(n^{\log_2 3})$ 
  - worst-case runtime:  $T(n) = 3T(\lceil n/2 \rceil) + \Theta(n)$

uncommon notations

- $\perp$  - false

# NP-Complete problems

- 1. Circuit-SAT
- 2. CNF-SAT
- 3. 3-SAT
- 4. Independent Set
- 5. Vertex Cover
- 6. Max-Clique
- 7. Hamiltonian Cycle (both directed and undirected)
- 8. Hamiltonian Path (undirected)
- 9. Traveling Sales Person
- 10. Subset Sum
- 11. Knapsack
- 12. Hitting Set