



Technische Universität Berlin

Fakultät IV – Elektrotechnik und Informatik

Probabilistic and Bayesian Modelling in Machine Learning and Artificial Intelligence

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Problem Sheet 1

Solutions

Problem 1 – Random experiments

A dice is thrown repeatedly until it shows a 6. Let T be the number of throws for this to happen. Obviously, T is a random variable. Compute the expectation value $E[T]$ and the variance $\text{Var}(T)$ of T .

The probability for t throws is given by the geometric distribution

$$P(T = t) = (1 - q)q^{t-1}$$

with parameter $q = 5/6$. The expectation value of T can be calculated using its definition:

$$E[T] = \sum_{t=1}^{\infty} t P(T = t) = \sum_{t=1}^{\infty} (1 - q) t q^{t-1} = \sum_{t=1}^{\infty} (1 - q) \frac{d}{dq} q^t$$

As the geometric series converges absolutely, we can exchange summation and derivation:

$$E[T] = (1 - q) \frac{d}{dq} \sum_{t=0}^{\infty} q^t = (1 - q) \frac{d}{dq} \frac{1}{1 - q} = (1 - q) \frac{1}{(1 - q)^2} = \frac{1}{1 - q}$$

In order to obtain the variance we need the expectation value of T^2 , too:

$$E[T^2] = \sum_{t=1}^{\infty} t^2 P(T = t) = \sum_{t=1}^{\infty} (1 - q) t^2 q^{t-1}$$

Here $t^2 q^{t-1}$ is very similar to the second derivative of q^{t+1} :

$$E[T^2] = \sum_{t=1}^{\infty} (1 - q) t(t + 1) q^{t-1} - \sum_{t=1}^{\infty} (1 - q) t q^{t-1} = -E[T] + \sum_{t=1}^{\infty} (1 - q) \frac{d^2}{dq^2} q^{t+1}$$

Further simplifications

$$\mathbb{E}[T^2] = -\frac{1}{1-q} + (1-q) \frac{d^2}{dq^2} \sum_{t=0}^{\infty} q^t = -\frac{1}{1-q} + (1-q) \frac{d^2}{dq^2} \frac{1}{1-q}$$

lead to

$$\mathbb{E}[T^2] = -\frac{1}{1-q} + (1-q) \frac{2}{(1-q)^3} = \frac{1+q}{(1-q)^2}$$

so that the variance of T is given by

$$\text{Var}(T) = \mathbb{E}[T^2] - \mathbb{E}[T]^2 = \frac{1+q}{(1-q)^2} - \frac{1}{(1-q)^2} = \frac{q}{(1-q)^2}$$

By substituting $q = 5/6$ we finally find $\mathbb{E}[T] = 6$ and $\text{Var}(T) = 30$.

Problem 2 – Addition of variances

Let X and Y be independent random variables. Show that

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y),$$

where the variance is defined as

$$\text{Var}(X) = \mathbb{E}[(X - \mathbb{E}[X])^2].$$

Hint: Use the fact that for independent U and V , $\mathbb{E}[UV] = \mathbb{E}[U]\mathbb{E}[V]$.

$$\begin{aligned} & \text{Var}(X + Y) \\ &= \mathbb{E}[(X + Y - \mathbb{E}[X + Y])^2] \\ &= \mathbb{E}[X^2 + Y^2 + \mathbb{E}[X + Y]^2 + 2XY - 2X\mathbb{E}[X + Y] - 2Y\mathbb{E}[X + Y]] \\ &= \mathbb{E}[X^2] + \mathbb{E}[Y^2] + \mathbb{E}[X + Y]^2 + 2\mathbb{E}[XY] \\ &\quad - 2\mathbb{E}[X]\mathbb{E}[X + Y] - 2\mathbb{E}[Y]\mathbb{E}[X + Y] \\ &= \mathbb{E}[X^2] + \mathbb{E}[Y^2] + \mathbb{E}[X]^2 + 2\mathbb{E}[X]\mathbb{E}[Y] + \mathbb{E}[Y]^2 + 2\mathbb{E}[X]\mathbb{E}[Y] \\ &\quad - 2\mathbb{E}[X]^2 - 2\mathbb{E}[X]\mathbb{E}[Y] - 2\mathbb{E}[X]\mathbb{E}[Y] - 2\mathbb{E}[Y]^2 \\ &= \mathbb{E}[X^2] - \mathbb{E}[X]^2 + \mathbb{E}[Y^2] - \mathbb{E}[Y]^2 \\ &= \text{Var}(X) + \text{Var}(Y) \end{aligned}$$

The last step uses the computational formula for the variance:

$$\begin{aligned} \text{Var}(X) &= \mathbb{E}[(X - \mathbb{E}[X])^2] \\ &= \mathbb{E}[X^2 - 2X\mathbb{E}[X] + \mathbb{E}[X]^2] \\ &= \mathbb{E}[X^2] - 2\mathbb{E}[X]\mathbb{E}[X] + \mathbb{E}[X]^2 \\ &= \mathbb{E}[X^2] - \mathbb{E}[X]^2 \end{aligned}$$

Problem 3 – Transformation of probability densities

Let X be uniformly distributed in $(0, 1)$:

$$p(x) = \begin{cases} 1 & \text{for } 0 < x < 1, \\ 0 & \text{otherwise.} \end{cases}$$

A second random variable Y is defined as

$$Y = \tan(\pi(X - 1/2)).$$

What is the probability density $q(y)$ of Y ?

- Inverse function:

$$\begin{aligned} y = \tan(\pi(x - 1/2)) &\iff \arctan y = \pi(x - 1/2) \\ &\iff x = \frac{1}{\pi} \arctan y + \frac{1}{2} \end{aligned}$$

- Transformation of probability densities:

$$q(y) = p(x) \cdot \frac{dx}{dy} = p(x) \cdot \frac{1}{\pi} \frac{1}{1 + y^2} = \frac{1}{\pi} \frac{1}{1 + y^2}$$

- This transformation together with a (pseudo-)random number generator can be used to generate (pseudo-)random numbers with a standard Cauchy distribution.

Problem 4 – Gaussian inference

Suppose we have two random variables V_1 and V_2 which are **jointly Gaussian** distributed with zero means $E[V_1] = E[V_2] = 0$ and variances $E[V_1^2] = 16.6$ and $E[V_2^2] = 6.8$. The covariance is $E[V_1 V_2] = 6.4$.

Assume that we observe a noisy estimate

$$Y = V_2 + \nu$$

of V_2 where ν is a Gaussian noise variable independent of V_1 and of V_2 with $E[\nu] = 0$ and $E[\nu^2] = 1$.

- Calculate the conditional (posterior) densities $p(V_1|Y)$ and $p(V_2|Y)$.
- What are the posterior mean predictions of V_1 and V_2 for an observation $Y = 1$ and what are the posterior uncertainties of these predictions.

The following formula could be helpful: The inverse of the matrix

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$

is given by

$$\mathbf{A}^{-1} = \frac{1}{\det \mathbf{A}} \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix}$$

- (a) We obtain the conditional densities $p(V|Y)$ from the joint densities $p(V, Y)$. (Here V can be either V_1 or V_2) !

$$p(V, Y) = \frac{1}{2\pi\sqrt{\det(\mathbf{S})}} \exp \left\{ -\frac{1}{2} (V, Y)^\top \mathbf{S}^{-1} (V, Y) \right\}$$

Note (V, Y) is a two dimensional vector and the covariance matrix is given by

$$\mathbf{S} = \begin{pmatrix} E[V^2] & E[VY] \\ E[VY] & E[Y^2] \end{pmatrix}$$

The expectations are

$$\begin{aligned} E[V_1 Y] &= E[V_1 V_2] \\ E[V_2 Y] &= E[V_2^2] \\ E[Y^2] &= E[V_2^2] + E[\nu^2] \end{aligned}$$

We set

$$\mathbf{S}^{-1} = \begin{pmatrix} (\mathbf{S}^{-1})_{vv} & (\mathbf{S}^{-1})_{vy} \\ (\mathbf{S}^{-1})_{vy} & (\mathbf{S}^{-1})_{yy} \end{pmatrix}$$

Then, from the joint density, we can write the conditional density as

$$p(V|Y) \propto \exp \left(-\frac{V^2}{2} (\mathbf{S}^{-1})_{vv} - V (\mathbf{S}^{-1})_{vy} Y \right)$$

- (b) This can be written in the standard notation as

$$p(V|Y) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(V-\mu)^2}{2\sigma^2}}$$

where

$$\begin{aligned} \mu &= E[V|Y] = -\frac{(\mathbf{S}^{-1})_{vy} Y}{(\mathbf{S}^{-1})_{vv}} \\ \sigma^2 &= \text{VAR}[V|Y] = \frac{1}{(\mathbf{S}^{-1})_{vv}} \end{aligned}$$

are the conditional mean and variance. We can use $E[V|Y]$ for prediction. $\text{VAR}[V|Y]$ would give us a measure for the error of such a prediction.

(c) Numerical example:

- For $p(V_1|Y)$ we have

$$\mathbf{S} = \begin{pmatrix} 16.6 & 6.4 \\ 6.4 & 7.8 \end{pmatrix}$$

and

$$\mathbf{S}^{-1} = \begin{pmatrix} 0.0881 & -0.0723 \\ -0.0723 & 0.1875 \end{pmatrix}$$

Hence $E[V_1|Y] = 0.8207$ and $\text{VAR}[V_1|Y] = 11.3507$.

- For $p(V_2|Y)$ we have

$$\mathbf{S} = \begin{pmatrix} 6.8 & 6.8 \\ 6.8 & 7.8 \end{pmatrix}$$

and

$$\mathbf{S}^{-1} = \begin{pmatrix} 1.1471 & -1.0000 \\ -1.0000 & 1.0000 \end{pmatrix}$$

Hence $E[V_2|Y] = 0.8718$ and $\text{VAR}[V_2|Y] = 0.8718$.