FANG Yunhao

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EDUCATION

Zhejiang University (ZJU)

09/2018~06/2022

Electronic Engineering and Technology

- GPA: 3.92/4.0 1st/97
- Honors and Awards: China National Scholarship; Mathematical Contest in Modeling: Meritorious Winner; Huang Hong
 & Wu Xiaobei Scholarship (3 out of 2000); Rockchip Mobile and Innovative Contest 4th place

University of Illinois at Urbana-Champaign (UIUC)

07/12/2020~07/26/2020

Telecommunications & Engineering, Summer Course

- Wireless and Mobile IoT: From Algorithms to Applications (Romit Roy Choudhury) Final Grade: 99.1
- Wireless Communications: 5G / WiFi 6 & Low Power IoT (Haitham Hassanieh) Final Grade: 100

University of California, San Diego

09/2022~now

Computer Science and Engineering

• GPA: 4.0/4.0

RESEARCH EXPERIENCE

Distillation Large Vision-Language Model with Out-of-Distribution Generalizability

09/2022~03/2023

In submission to ICCV2023, Supervised by Prof. Hao Su

- Explore the constraints and behaviors of distilling Vision-Language model(e.g. CLIP) with light models
- Propose approaches to improve distillation by keeping vision feature spaces, relative relationships between vision and language feature space, as well as enrich the language feature space with informative description at the same time.

Deductive Verification of Chain-of-Thought Reasoning

03/2023~05/2023

In submission to NeurIPS2023, Supervised by Prof. Hao Su

- Explore the constraints and behaviors of distilling Vision-Language model(e.g. CLIP) with light models
- Propose approaches to improve distillation by keeping vision feature spaces, relative relationships between vision and language feature space, as well as enrich the language feature space with informative description at the same time.

Image Based Foreign Object Detection of High Speed Railway Catenary Network

05/01/2020~05/26/2021

Member, Supervised by: Prof. Jiming Chen IEEE Fellow

- Take real-time video of high speed train's front-loaded camera as input and search for foreign objects tangled on the catenary network using improved yolov5s mode designed with innovative preprocessing methods, loaded on a Nvidia Jetson Nano embedded system and accelerated the interfering progress by TensorRT
- Proposed a new method named horizon division to divide the input pictures along the horizon and improved the inference speed from 7ps to 37ps

Auto-irrigation System with Mobile Application

03/04/2021~05/07/2021

Leader-Fourth place in ISEE-Rockchip Mobile and Innovative Contest

- Designed a raspberry 4B based auto irrigation system and an auxiliary Android App
- Responsible for the work including the protective circuit and the amplifying circuit constructing by circuit elements to meet different voltage and current requirements
- Designed and wrote code for the App

A Touch Sensing Design with Microstrip Filter

07/10/2019~12/02/2019

- Proposed a sensing design based on electromagnetic induced EIT phenomenon and a mathematical measurement
- Describe the change of two EIT bands induced by the U-shape structure when electric objects are approaching, namely the change of the S-parameters, using the shifting vector and grids of the filter plane.
- Accomplished a 3x3mm precisely region locating of touching objects by utilizing the phase spectrum and the magnitude spectrum with correctness of 94.4%.

INTERNSHIPS

Shanghai Artificial Intelligence Laboratory.

11/2021~06/2022

- Maintain the opensource codebase mmtracking
- Doing research work about multiple object tracking

Hangzhou Humpback Whale Technology Co., Ltd.

01/09/2020~02/12/2020

- Algorithm Engineer Internship, Proposer of research project A Single RGB-camera Based Push-up Count and Attitude Rectification Method (patent)
- Proposed the idea of combing conventional method with fashionable neural network to detect whether procedure of push-up is completed
- Responsible for the geometry module, the HMM module, the initial recognition of 2D skeleton points and the connection of different parts