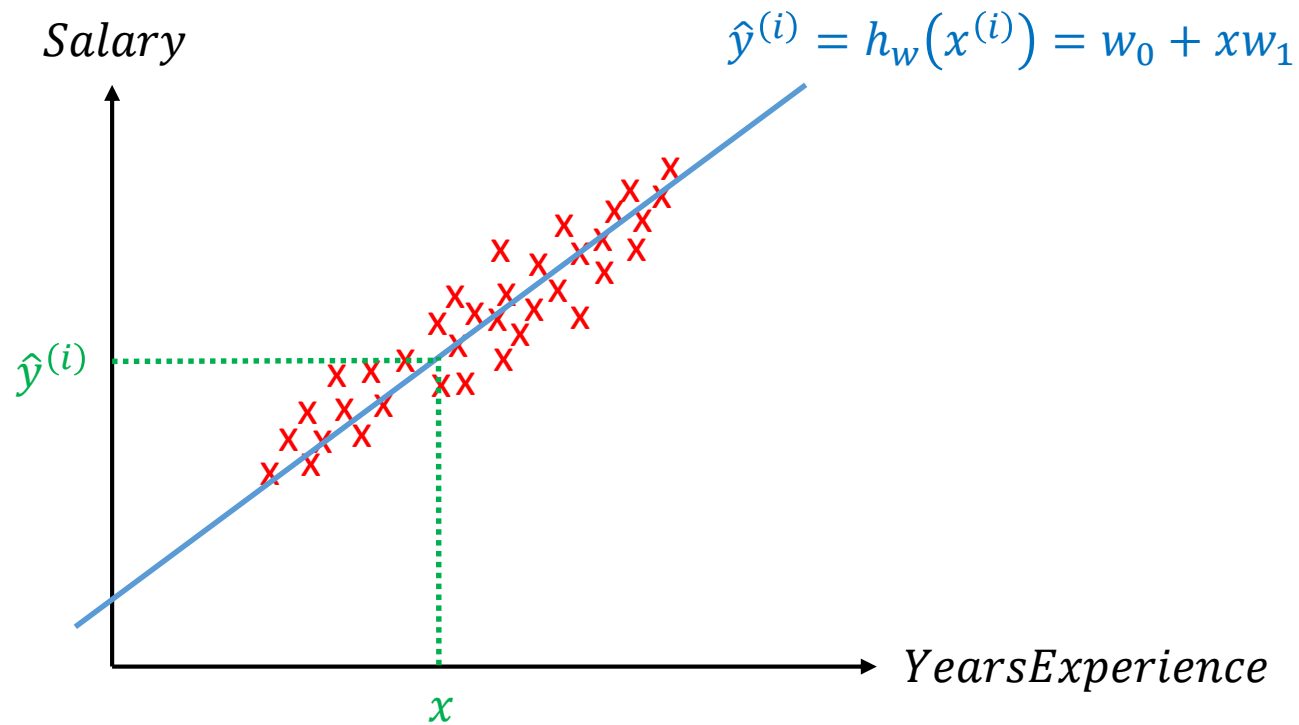


MAKİNE ÖĞRENMESİ

*Tek Değişkenli Lineer
Regresyon*

1. Model Gösterimi



(x, y) : toplam örnek sayısı

	YearsExperience	Salary
0	1.1	39343.0
1	1.3	46205.0
2	1.5	37731.0
3	2.0	43525.0
4	2.2	39891.0

$$x^{(0)} = 1.1$$

$$x^{(1)} = 1.3$$

$$x^{(2)} = 1.5$$

$$y^{(1)} = 46205$$

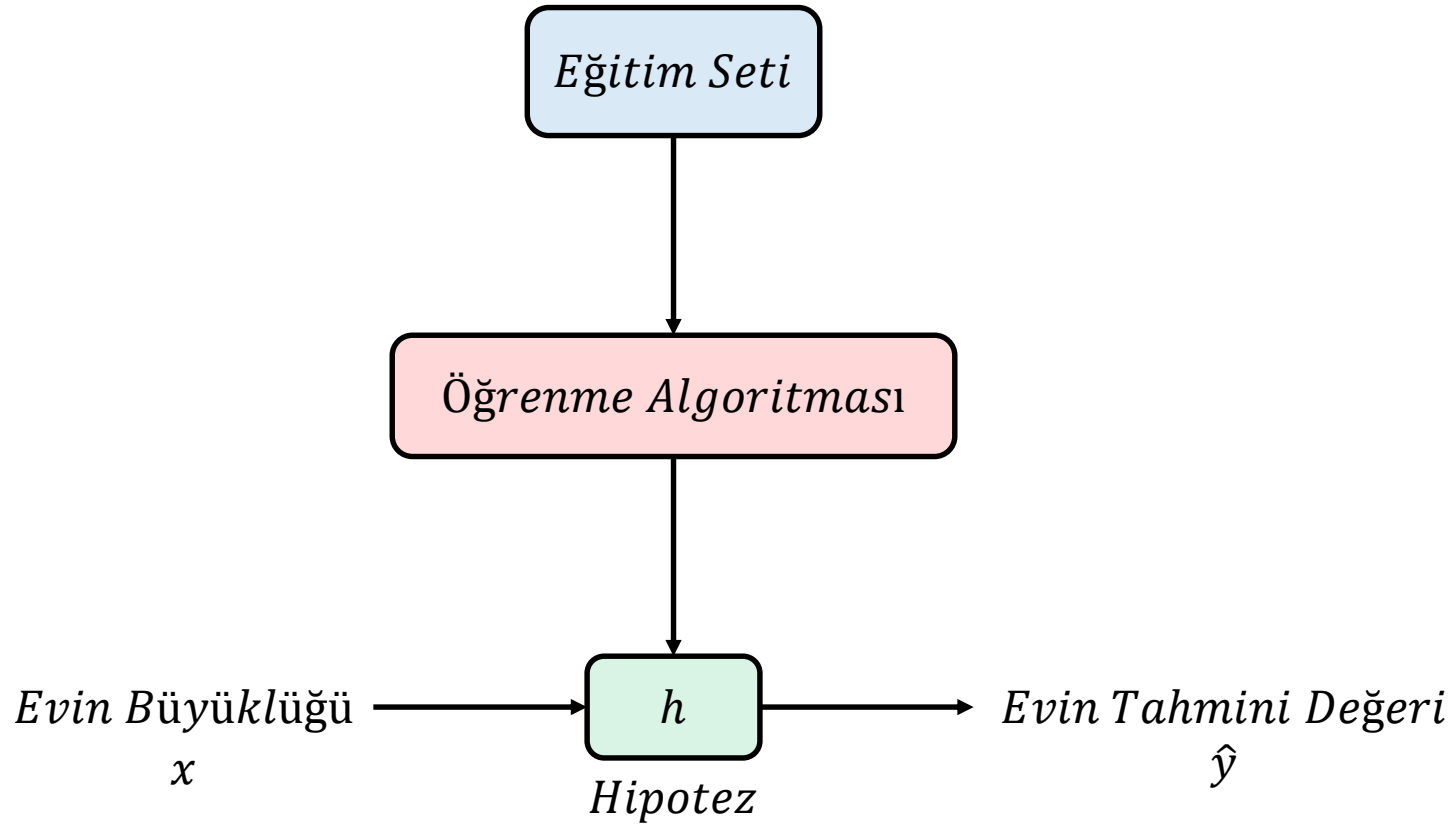
m : Örnek Sayısı

n : Özellik Sayısı

x : girdi(input) değişkenleri

y : çıktı(output) etiketleri

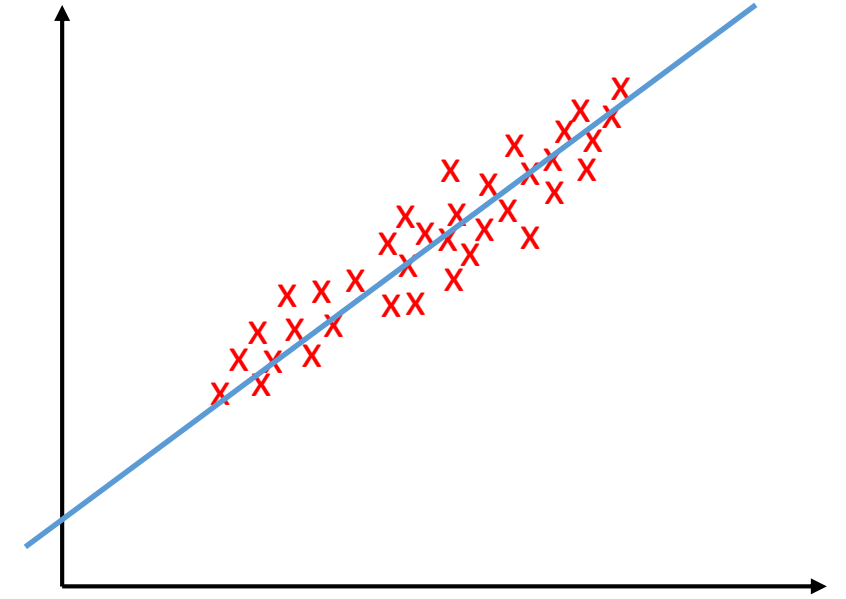
$(x^{(i)}, y^{(i)})$: i . örnek sayısı



h, x'ten y'ye haritalama yapar.

h(x) olarak da yazılabilir.

$$h_w(x) = w_0 + xw_1$$



Tek değişkenli Doğrusal Regresyon

MAKİNE ÖĞRENMESİ

Tek Değişkenli Lineer Regresyon

2. Maliyet – Hata – Kayıp Fonksiyonu

	YearsExperience	Salary
0	1.1	39343.0
1	1.3	46205.0
2	1.5	37731.0
3	2.0	43525.0
4	2.2	39891.0

Hipotez

$$h_w(x) = w_0 + xw_1$$

Parametreler

w_i : Ağırlık Bileşenleri

$$m = 30, n = 1$$

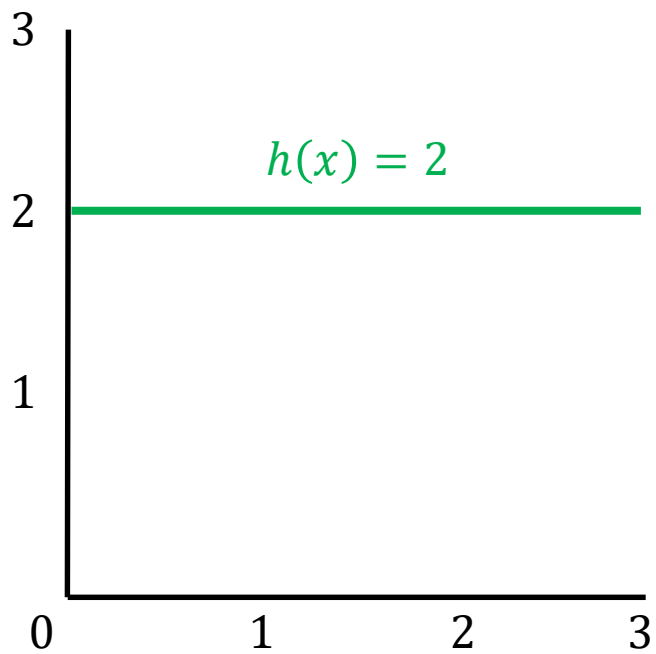
$$x_{m \times n} = x_{30 \times 1}$$

$$y_{m \times 1} = y_{30 \times 1}$$

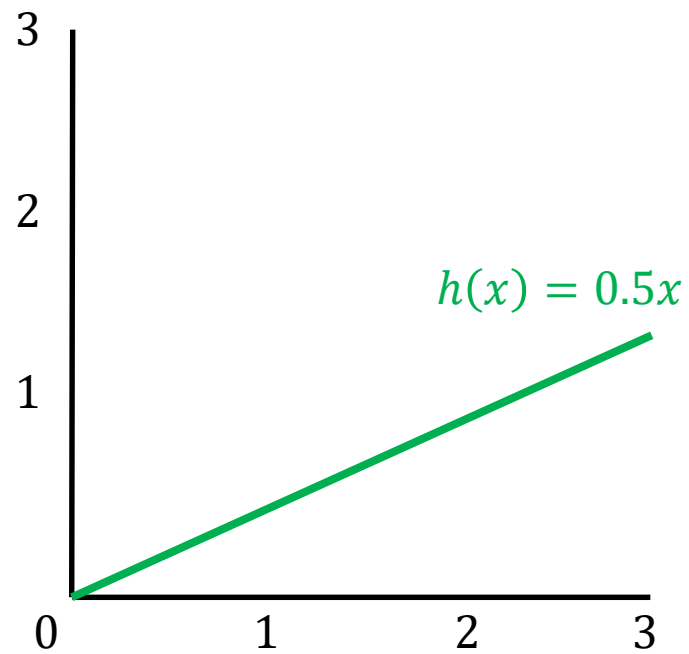
En uygun ağırlık bileşenlerini nasıl bulabiliriz ?



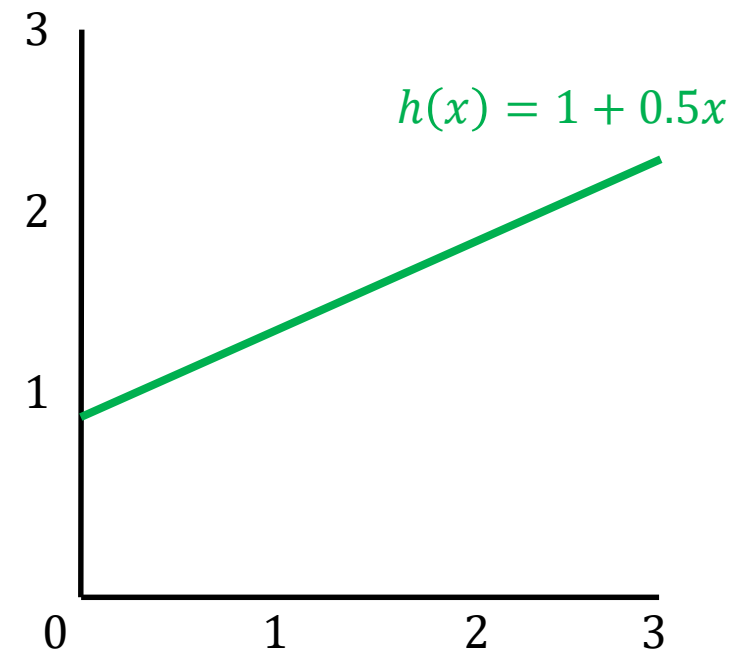
$$h_w(x) = w_0 + xw_1$$



$$w_0 = 2, w_1 = 0$$

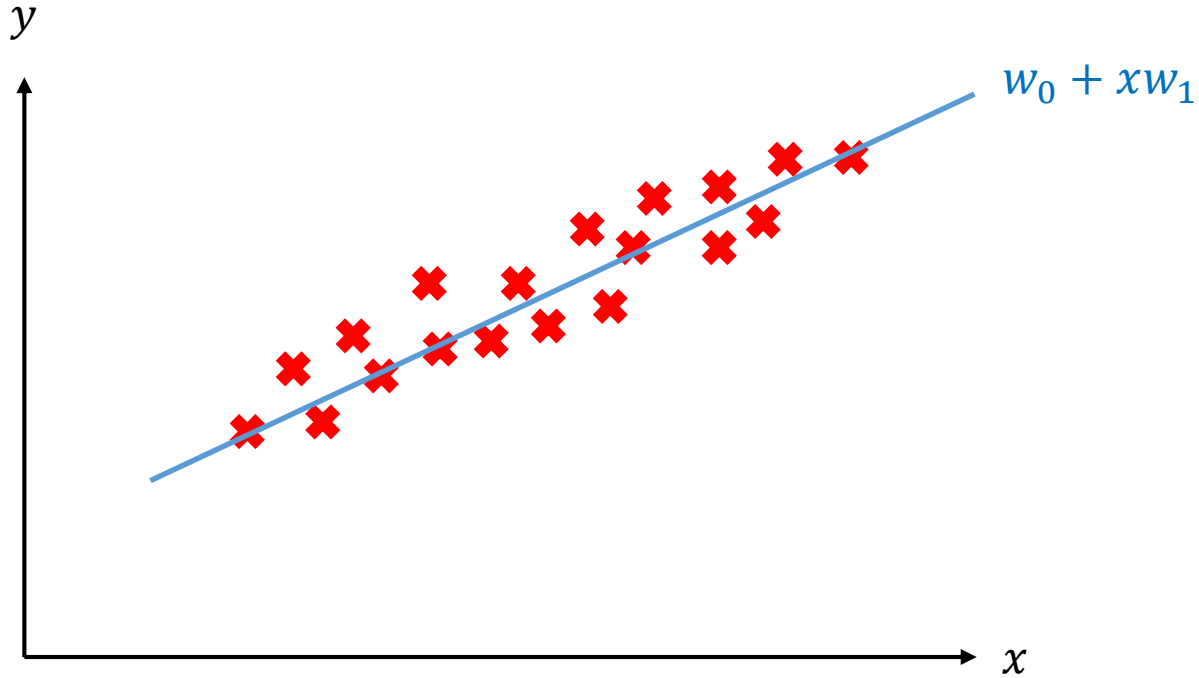


$$w_0 = 0, w_1 = 0.5$$



$$w_0 = 1, w_1 = 0.5$$





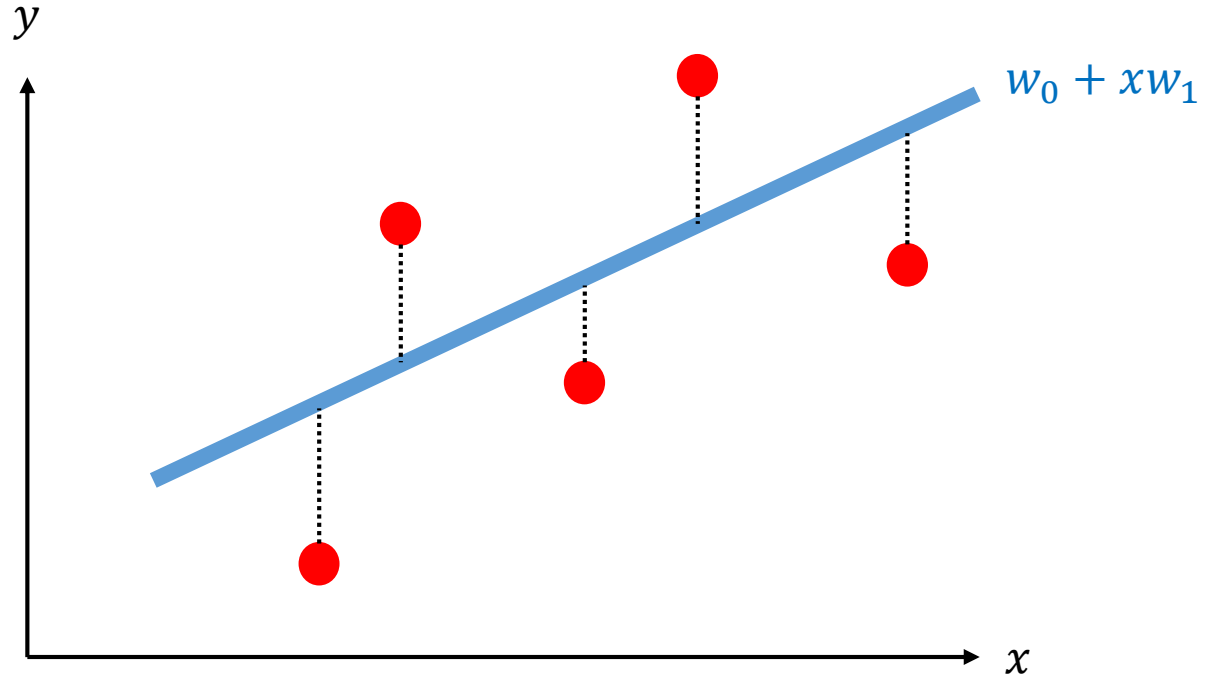
$$\text{Kayıp(Cost)} : J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))^2$$

$$\text{Kayıp(Cost)} : J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - \hat{y}^{(i)})^2$$

$$\hat{y}^{(i)} = h_w(x^{(i)}) = w_0 + xw_1$$

Amacımız kaybı minimize etmek

Öyle bir w_0 ve w_1 seçki $h_w(x)$, y' ye çok yakın olsun.



$$\text{Kayıp(Cost)} : J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))^2$$

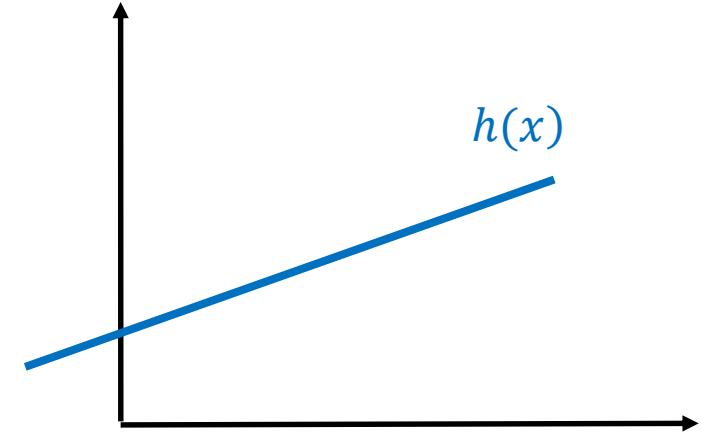
*Hata kare fonksiyonu
(squared error function)*

Hipotez

$$h_w(x^{(i)}) = w_0 + xw_1$$

Parametreler

$$w_0, w_1$$

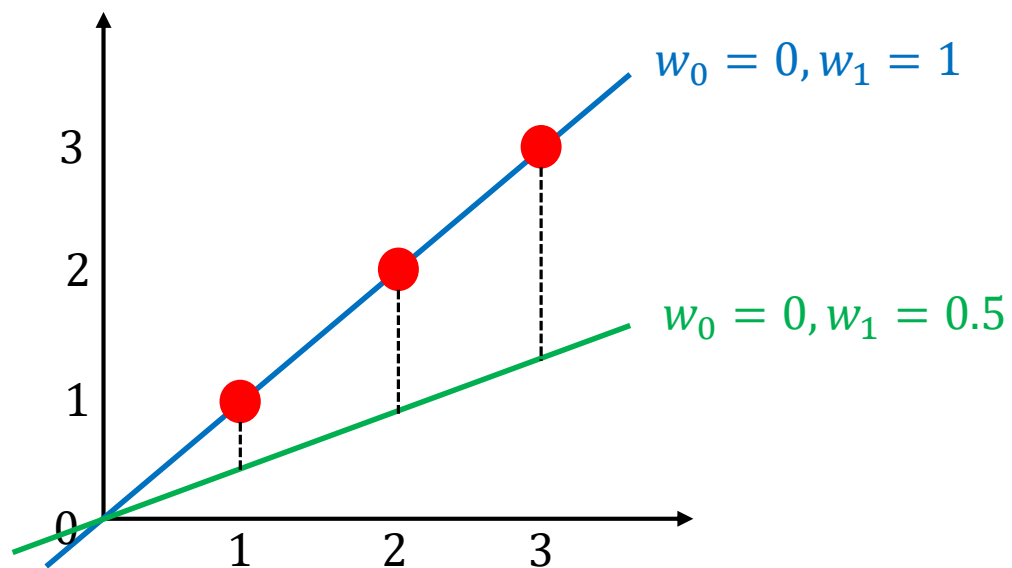


Kayıp (Maliyet) Fonksiyonu

$$\text{Kayıp(Cost)} : J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))^2$$

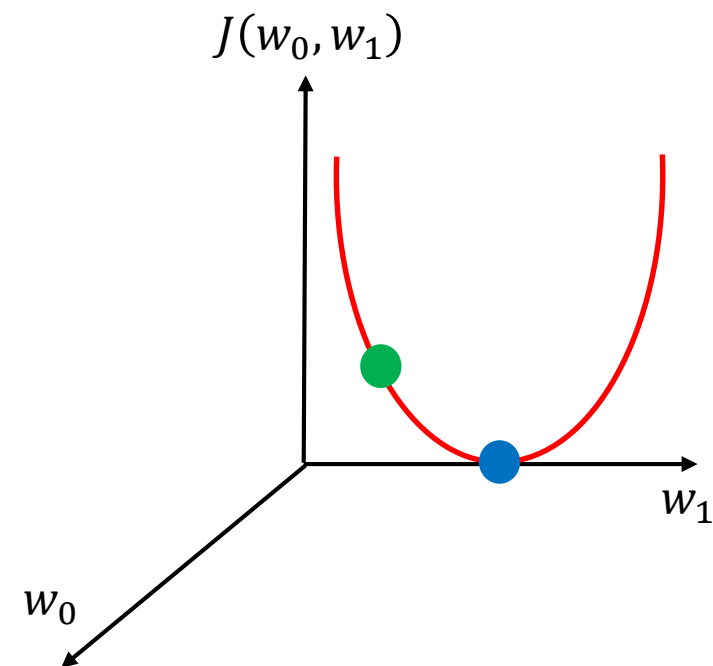
Amacımız kaybı minimize etmek

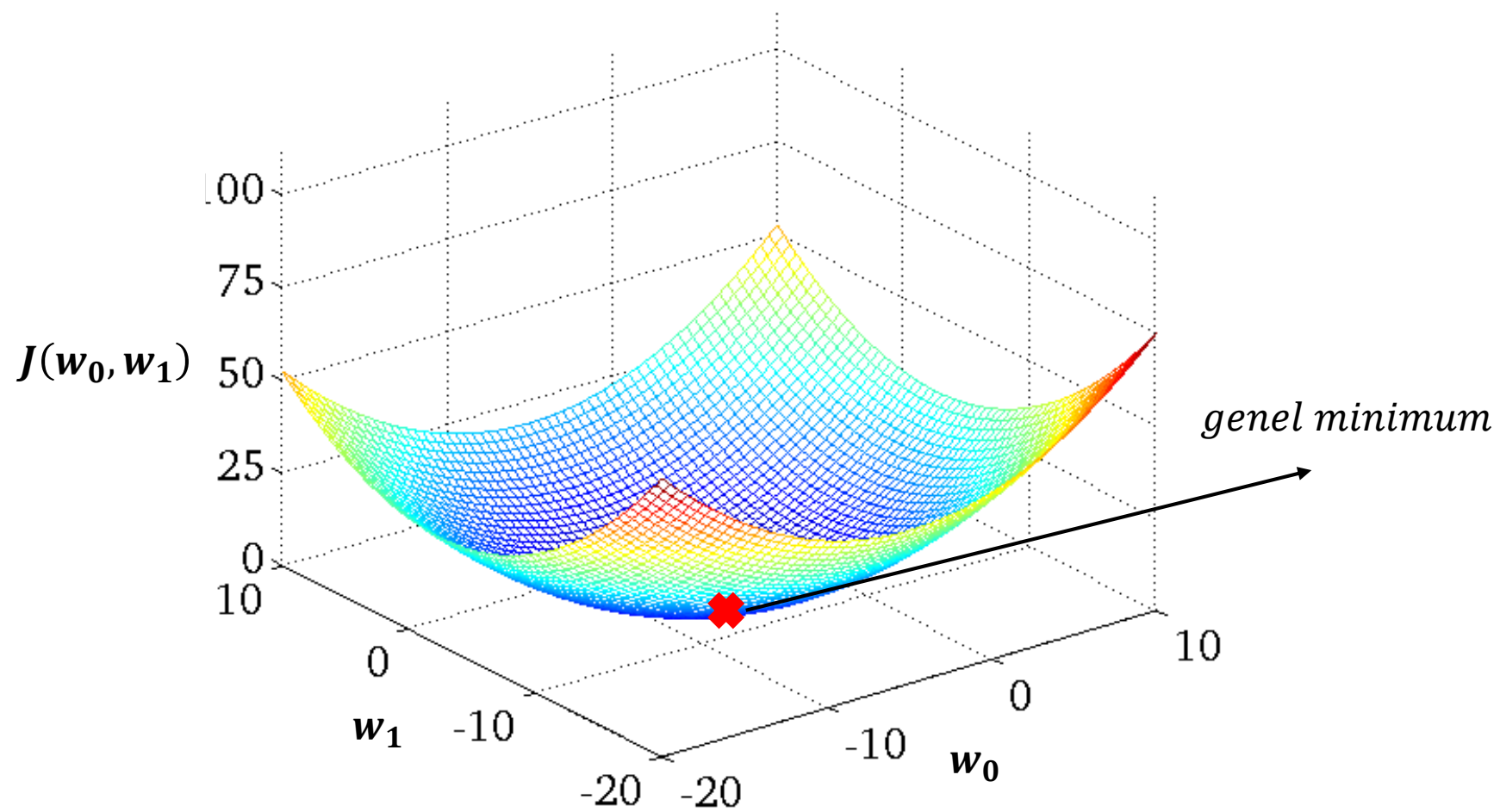
$$J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))^2$$

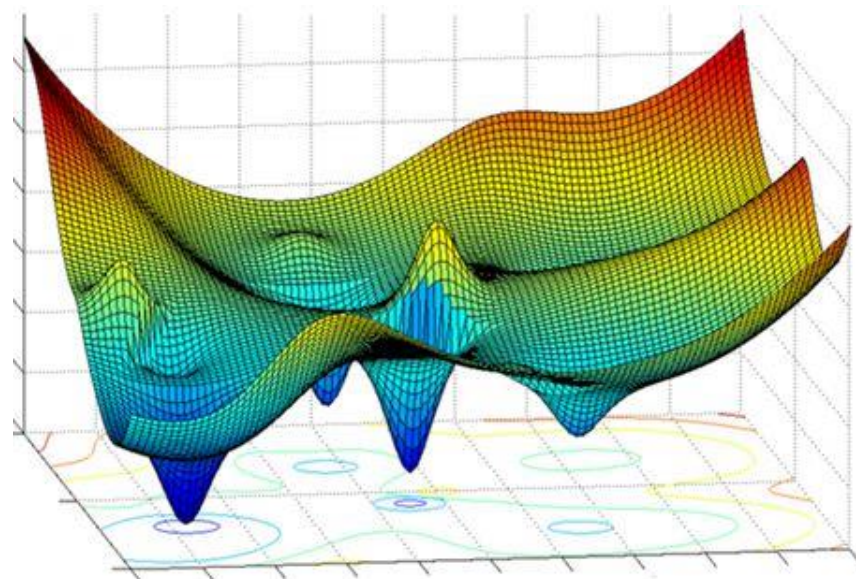


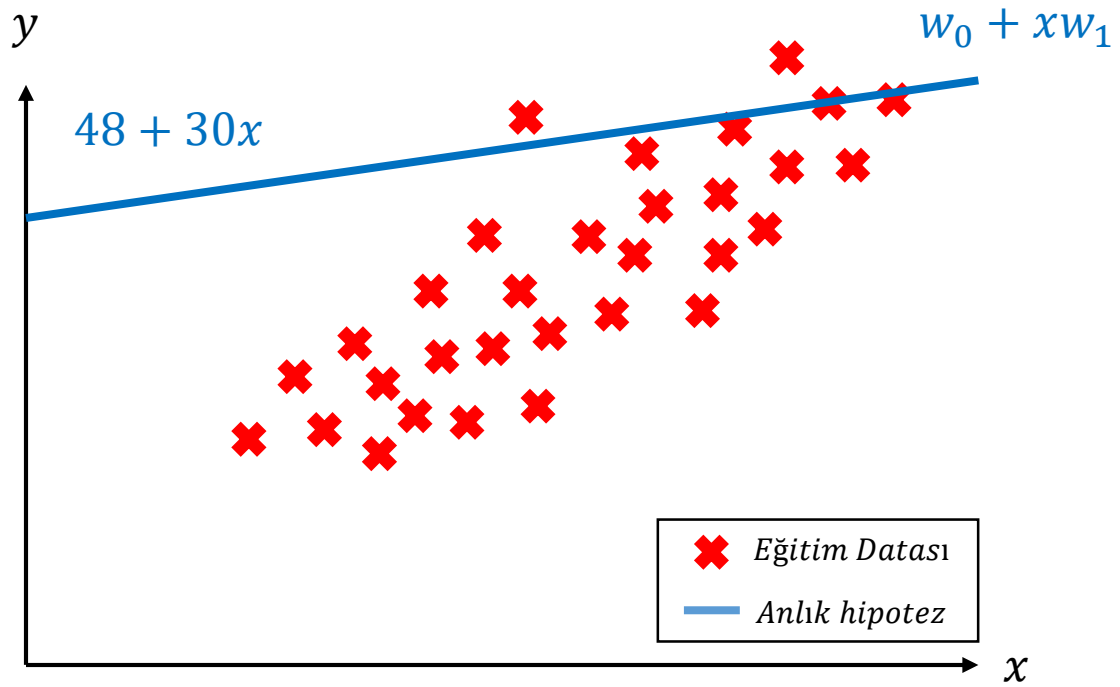
$$J(1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - x^{(i)} w_1)^2 = \frac{1}{2m} (0^2 + 0^2 + 0^2) = 0^2 = 0$$

$$J(0.5) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - x^{(i)} w_1)^2 = \frac{1}{2m} ((1 - 0.5)^2 + (2 - 1)^2 + (3 - 1.5)^2) = \frac{3.5}{6}$$

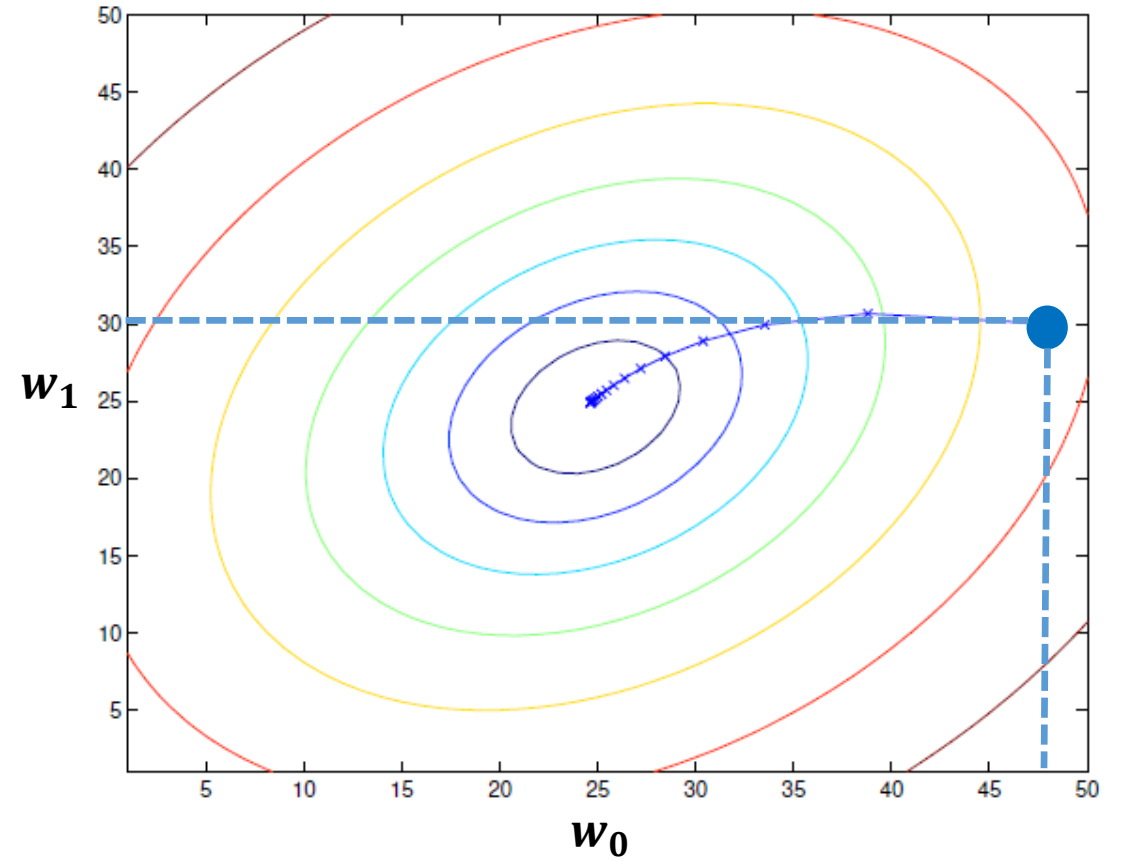


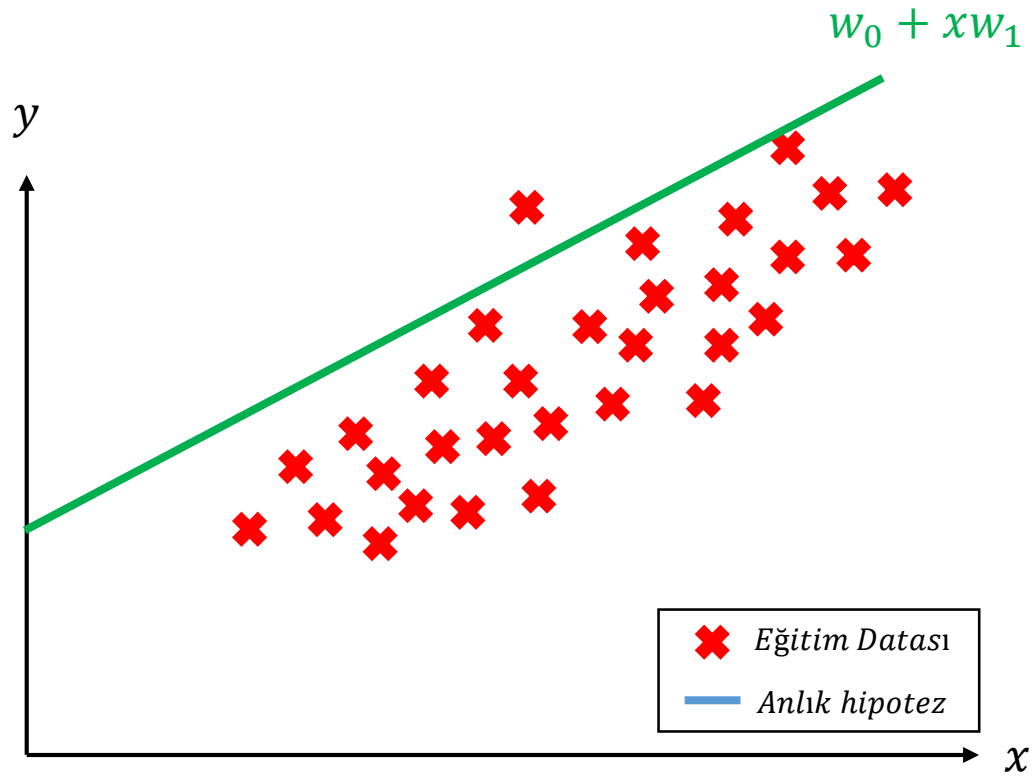




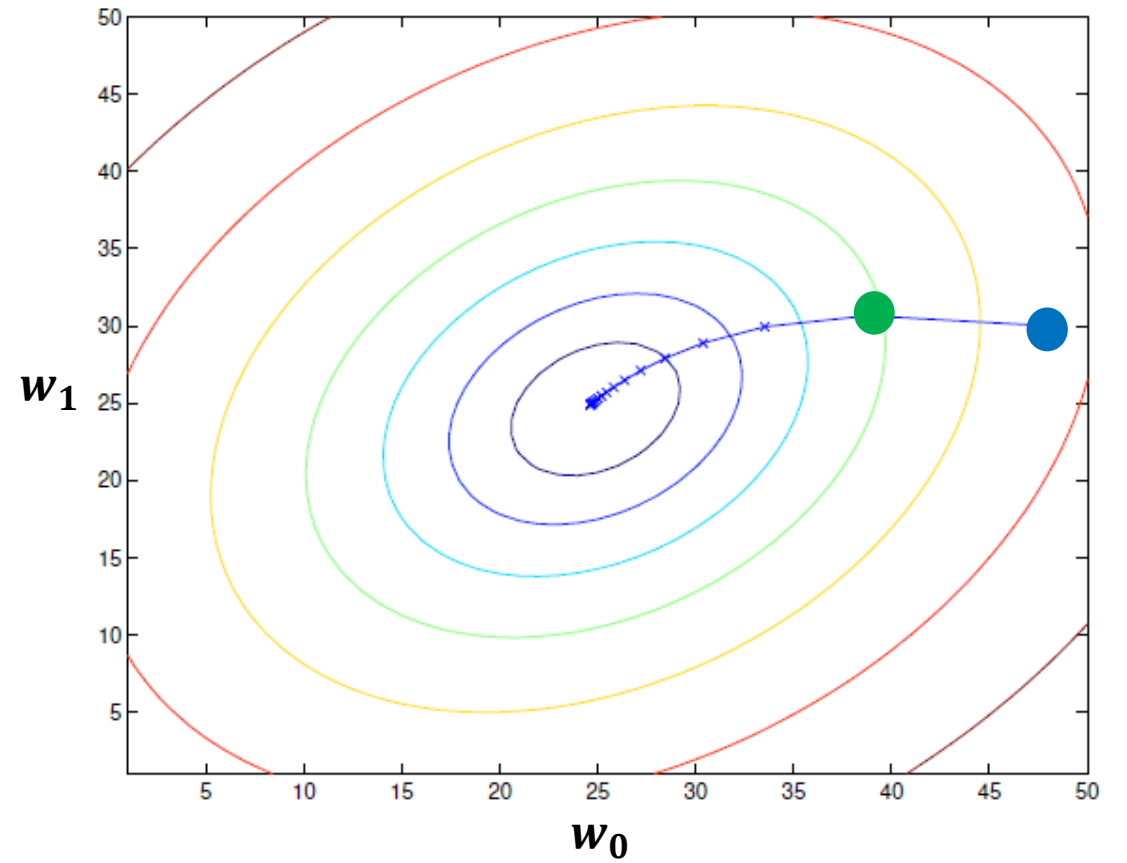


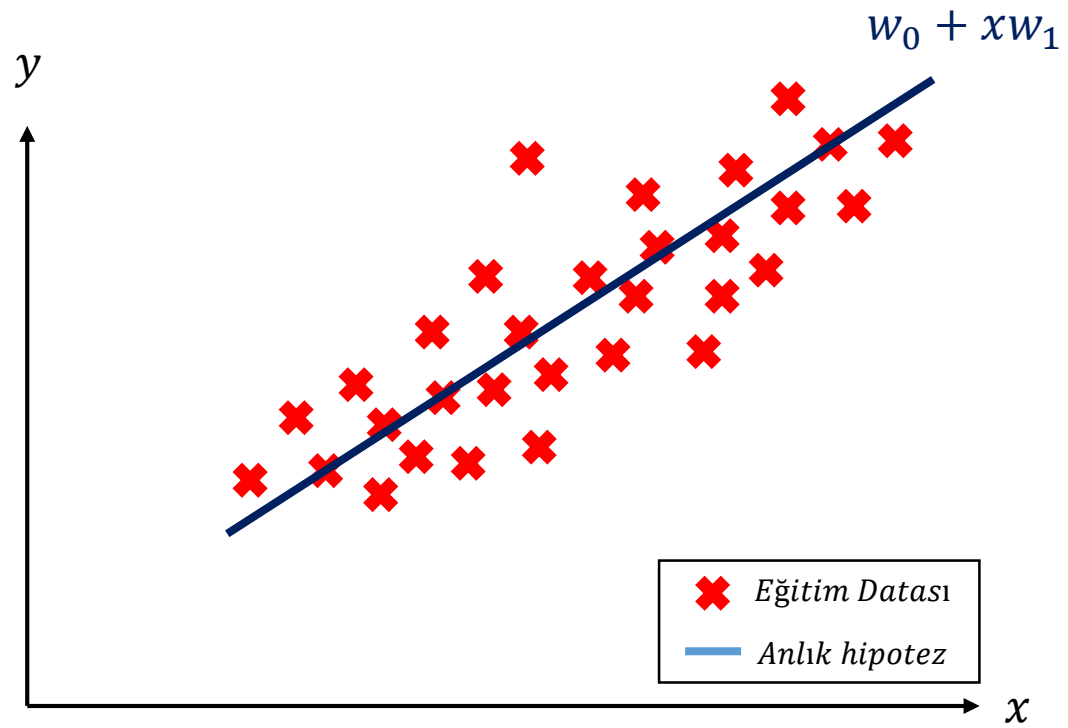
Contour plots



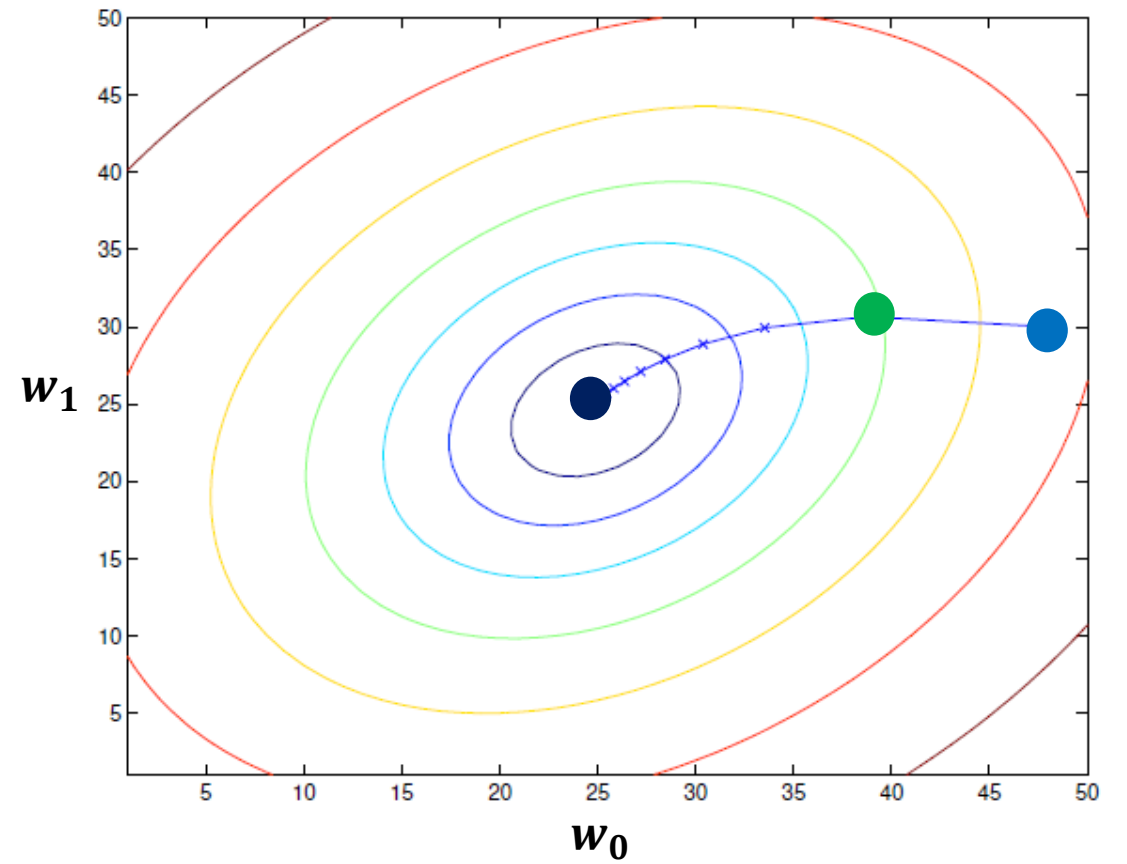


Contour plots





Contour plots



MAKİNE ÖĞRENMESİ

Tek Değişkenli Lineer Regresyon

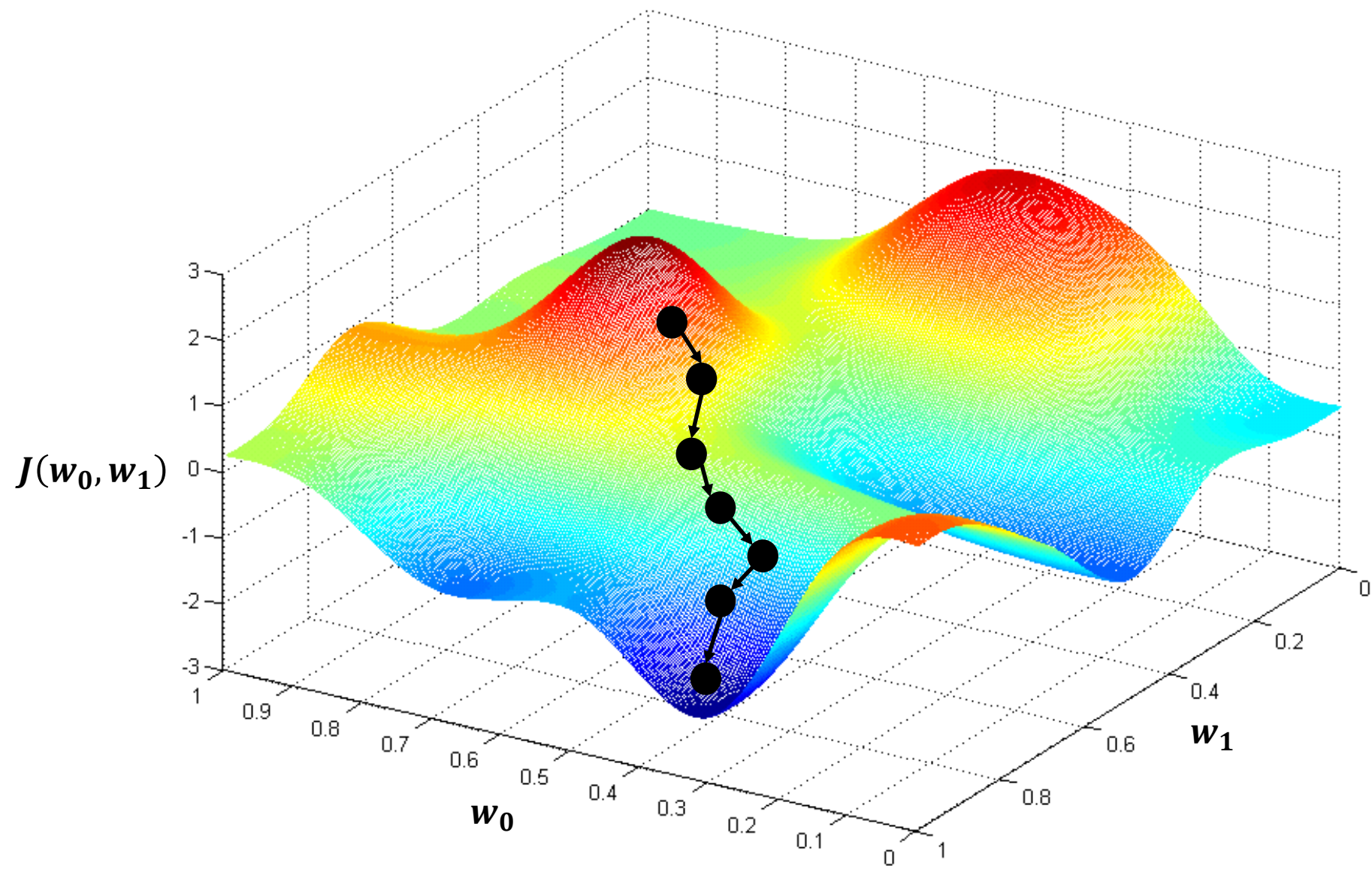
3. Gradyenik Alçalma (Gradient Descent)

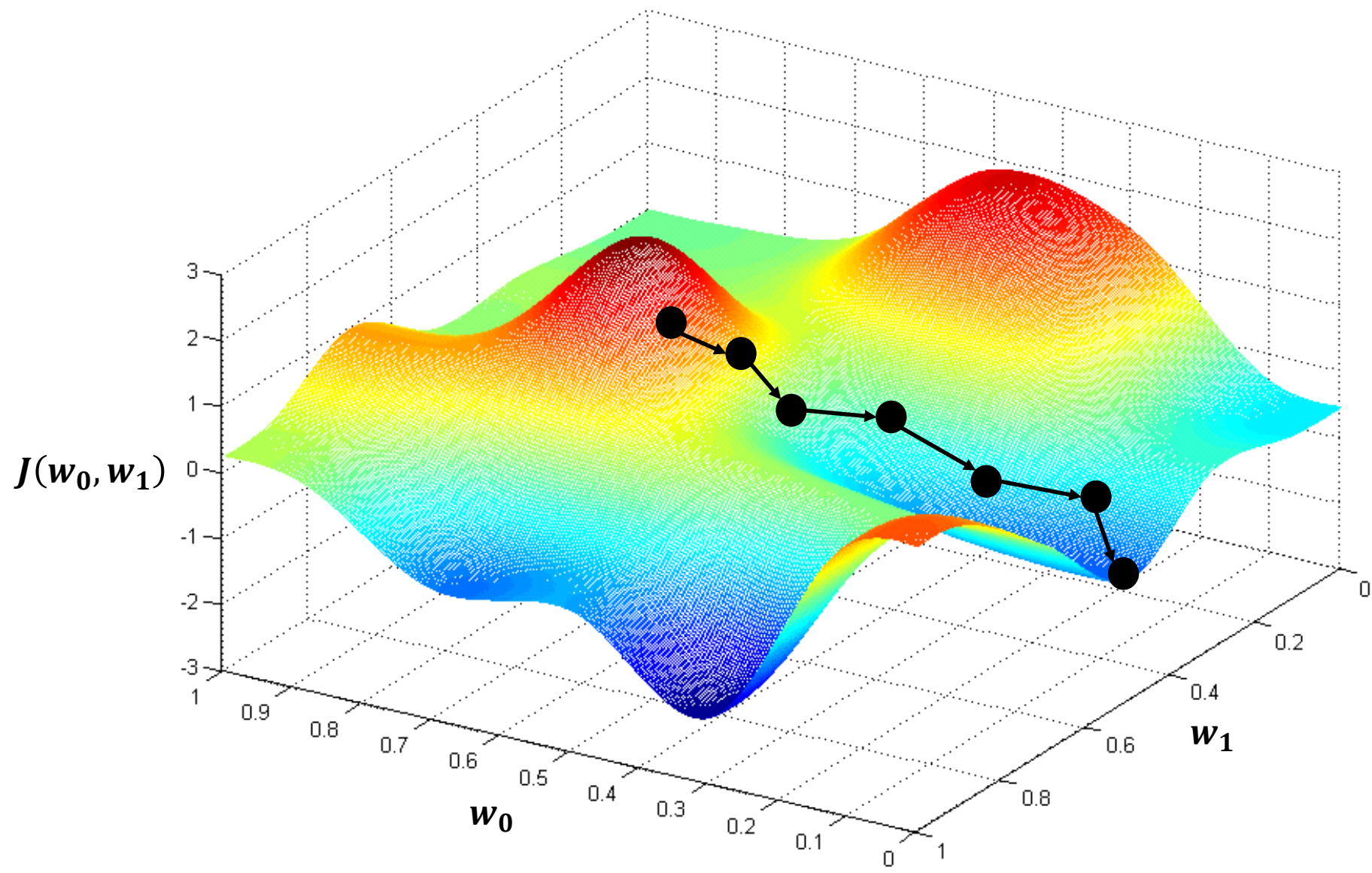
Elimizde bir $J(w_0, w_1)$ fonksiyonu var.

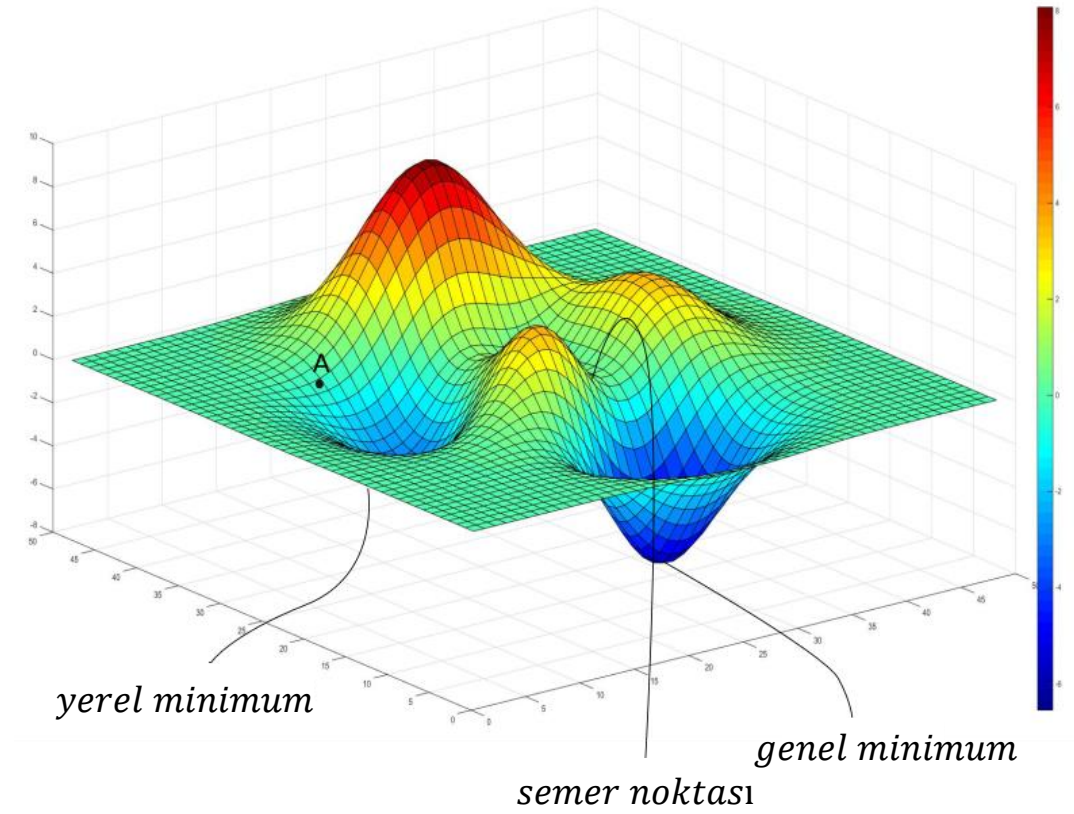
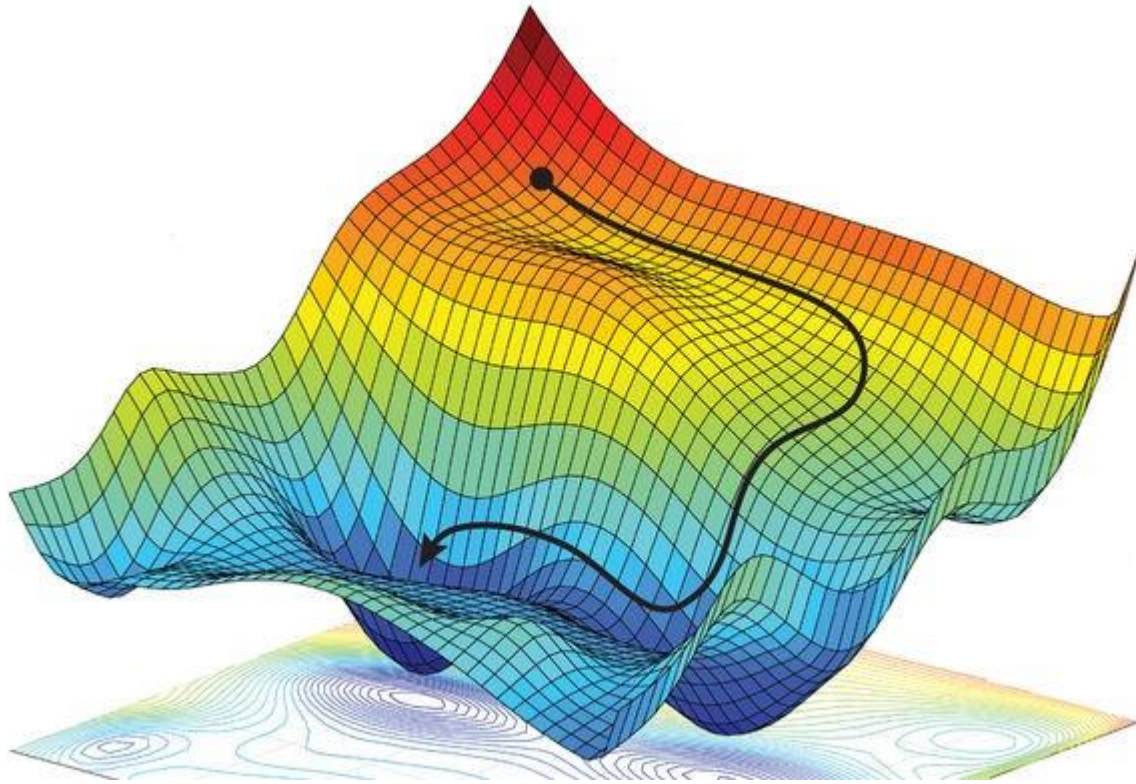
Amacımız bu fonksiyonu minimize etmek.

w_0, w_1 bileşenleri ile başlayalım. (0 ile 1 arası rastgele değerler atayalım.)

$J(w_0, w_1)$ fonksiyonunu azaltana kadar (minimum'u bulana kadar) bu bileşenleri değiştirelim.







Gradyenik Alçalma(Gradient Descent) algoritması

İterasyon {

$$w_j := w_j - \alpha \frac{\partial J(w_j)}{\partial w_j} \quad (j = 0 \text{ ve } j = 1 \text{ için})$$

}

Öğrenme oranı(Learning rate)

Eş zamanlı güncelleme yapılmalı !

$$temp0 := w_0 - \alpha \frac{\partial J(w_0, w_1)}{\partial w_0}$$

$$temp1 := w_1 - \alpha \frac{\partial J(w_0, w_1)}{\partial w_1}$$

$$w_0 := temp0$$

$$w_1 := temp1$$

DOĞRU !

$$temp0 := w_0 - \alpha \frac{\partial J(w_0, w_1)}{\partial w_0}$$

$$w_0 := temp0$$

$$temp1 := w_1 - \alpha \frac{\partial J(w_0, w_1)}{\partial w_1}$$

$$w_1 := temp1$$

YANLIŞ !



Gradyenik Alçalma(Gradient Descent) algoritması

İterasyon {

$$w_j := w_j - \alpha \frac{\partial J(w_j)}{\partial w_j}, \quad (j = 0 \text{ ve } j = 1 \text{ için})$$

}

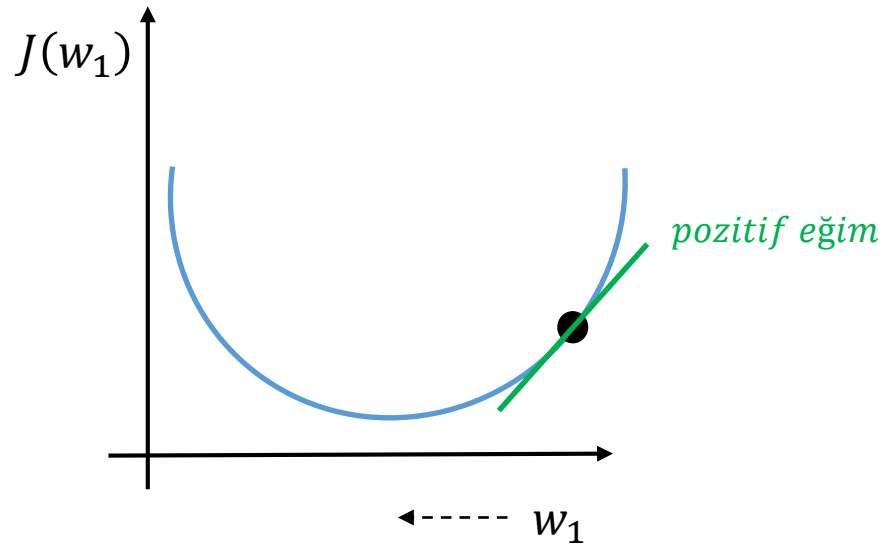
İterasyon {

$$w_j := w_j - \alpha \nabla J(w_j), \quad (j = 0 \text{ ve } j = 1 \text{ için})$$

}

Eş zamanlı güncelleme yapılmalı !

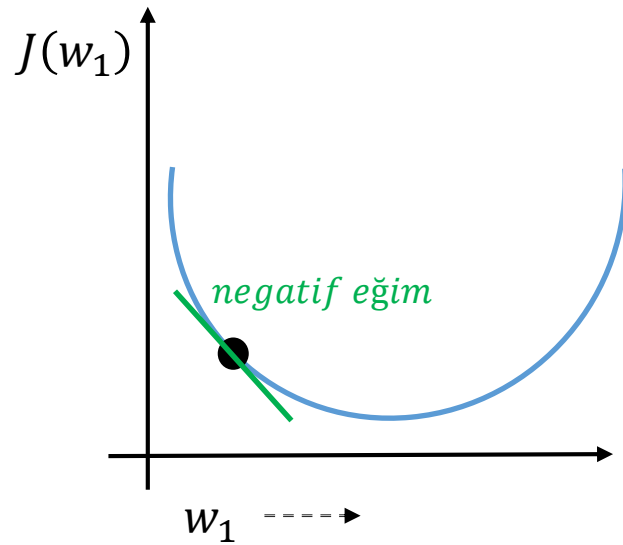
$$w_j := w_j - \alpha \frac{1}{2m} \nabla \left(\sum_{i=1}^m \left(y^{(i)} - h_w(x^{(i)}) \right)^2 \right)$$



$$w_1 := w_1 - \alpha \frac{\partial J(w_0, w_1)}{\partial w_1}$$

$$\frac{\partial J(w_0, w_1)}{\partial w_1} > 0$$

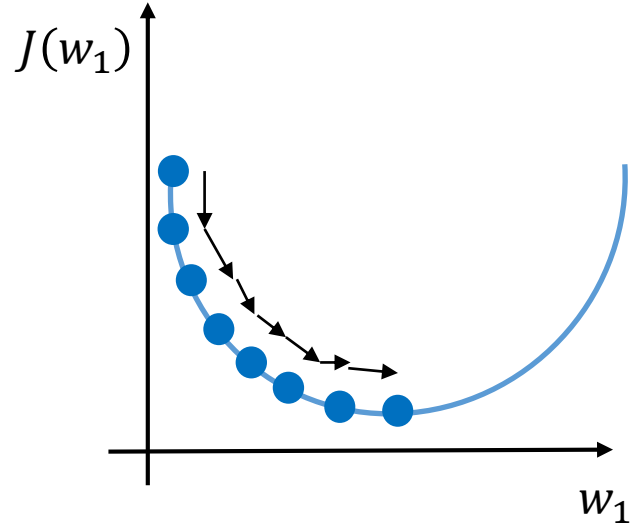
$$w_1 := w_1 - \alpha(\text{pozitif sayı})$$



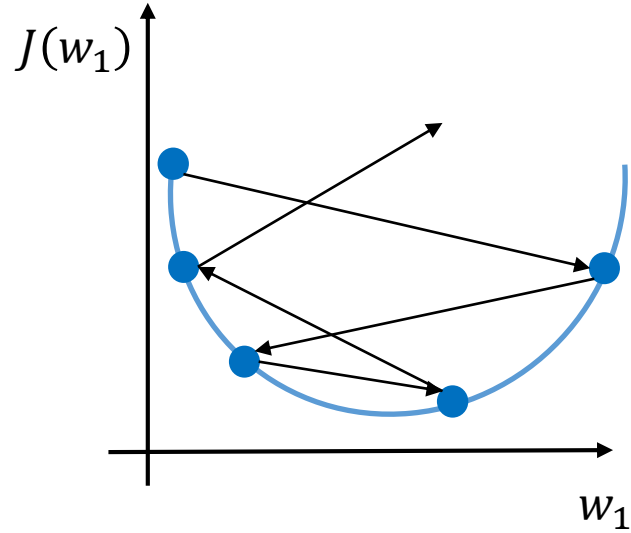
$$w_1 := w_1 - \alpha \frac{\partial J(w_0, w_1)}{\partial w_1}$$

$$\frac{\partial J(w_0, w_1)}{\partial w_1} < 0$$

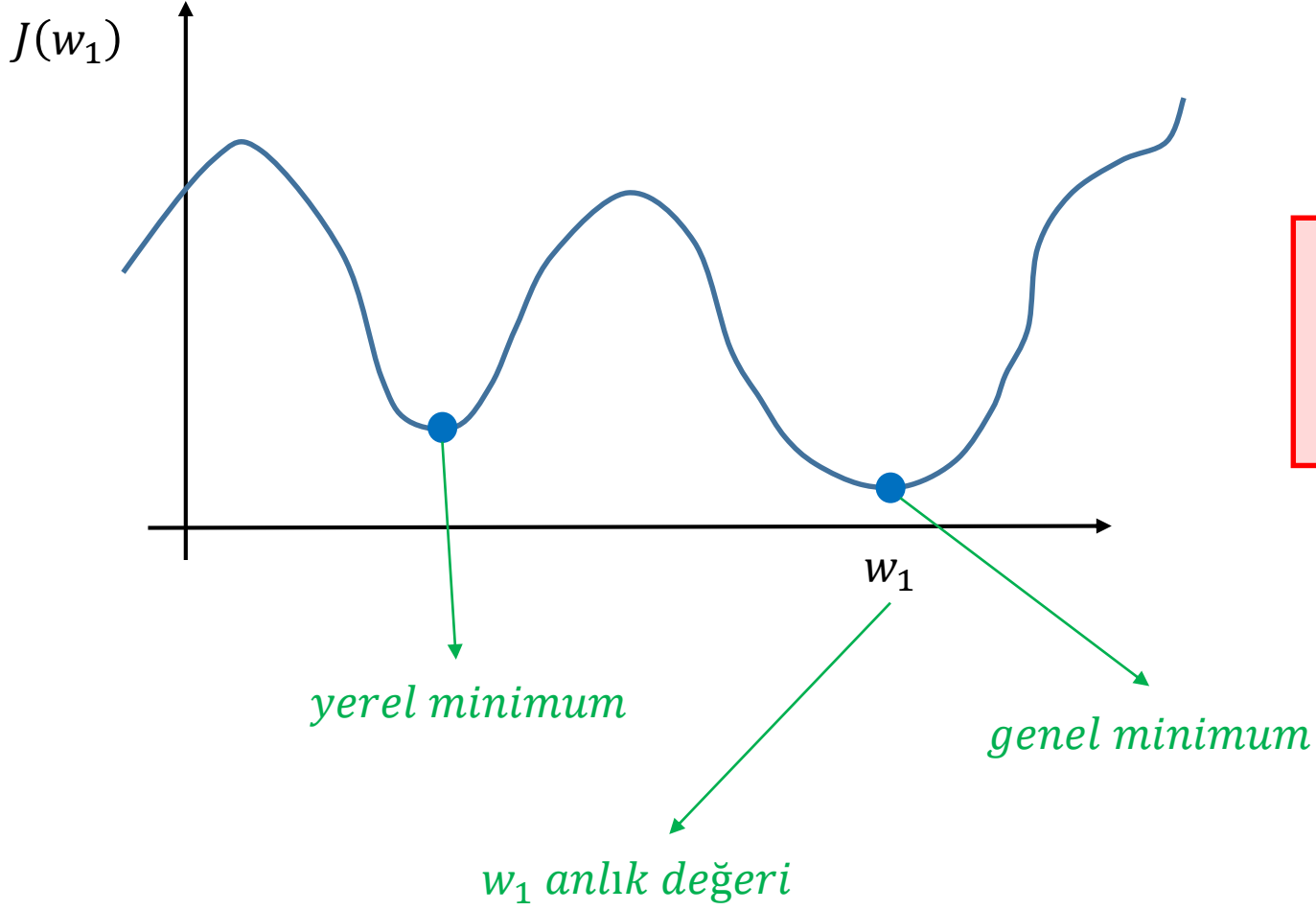
$$w_1 := w_1 - \alpha(\text{negatif sayı})$$



eğer α çok küçük olursa, gradyeni alçalma çok yavaş olabilir.



eğer α çok büyük olursa, gradyeni alçalma minimum değeri bölgesini aşırabilir.



$$w_1 := w_1 - \alpha \frac{\partial J(w_0, w_1)}{\partial w_1}$$

Lineer Regresyon Modeli

$$h_w(x) = w_0 + w_1x$$

$$J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))^2$$

$$\frac{\partial}{\partial w_j} J(w_0, w_1) = \frac{\partial}{\partial w_j} \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))^2$$

$$\frac{\partial}{\partial w_j} J(w_0, w_1) = \frac{\partial}{\partial w_j} \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - w_0 - w_1 x^{(i)})^2$$

$$j = 0 : \frac{\partial}{\partial w_0} J(w_0, w_1) = -\frac{1}{m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))$$

$$j = 1 : \frac{\partial}{\partial w_1} J(w_0, w_1) = -\frac{1}{m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)})) x^{(i)}$$

İterasyon {

$$w_0 := w_0 + \alpha \frac{1}{m} \sum_{i=1}^m (y^{(i)} - \hat{y}^{(i)})$$

$$w_1 := w_1 + \alpha \frac{1}{m} \sum_{i=1}^m (y^{(i)} - \hat{y}^{(i)}) x^{(i)}$$

}

Linear Regresyon Modeli

$$J(w_0, w_1) = \frac{1}{2m} \sum_{i=1}^m (y^{(i)} - h_w(x^{(i)}))^2$$
$$w_0 := w_0 + \alpha \frac{1}{m} \sum_{i=1}^m (y^{(i)} - \hat{y}^{(i)}) x_0^{(i)} \quad [1]_{m \times 1}$$
$$w_1 := w_1 + \alpha \frac{1}{m} \sum_{i=1}^m (y^{(i)} - \hat{y}^{(i)}) x^{(i)}$$

