# Arquitecturas Especializadas

# Práctica 3. Programación con directivas

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#### **Objetivos**

- Familiarizarse con la programación por medio de directivas con OpenACC
- Evaluar las mejoras/speedup

### OpenACC (I)

- Uso del compilador de PGI que soporta OpenACC
- GPU: nVIDIA Tesla M2070
  - Conocer características de la GPU

/opt/cuda-6.5/samples/1\_Utilities/deviceQuery/deviceQuery

- Wiki: <a href="http://en.wikipedia.org/wiki/CUDA">http://en.wikipedia.org/wiki/CUDA</a>
- Ejecución en gpuser@urbion.dacya.ucm.es
- Compilación en gpuser@speedy.dacya.ucm.es
  - Compilador de PGI

pgcc -Minfo -acc hello.c -o hello.pgi.exe

- Preparados makefiles:
  - CPU: make host → bin.host.exe
  - GPU: make pgi → bin.pgi.exe

```
#ifdef_OPENACC
                       24, Loop not fused: function call before adjacent loop
#include < openacc.h >
                             Generated vector sse code for the loop
#endif
                          28, Generating copy(b[:])
int main() {
                             Generating Tesla code
                          29, Loop is parallelizable
#ifdef_OPENACC
                             Accelerator kernel generated
                             29, #pragma acc loop gang, vector(128) /* blockIdx.x threadIdx.x */
  acc init(acc device r
                          32, Loop not vectorized/parallelized: potential early exits
  printf(" Compiling wi
#endif
 // Compute on the GPU if OpenACC support - host if not
 #pragma acc kernels copyout(b[0:N])
 for (int i = 0; i < N; i++) {
   b[i] = i;
#ifdef OPENACC
  acc shutdown(acc device not host);
#endif
 return 0;
```

#### Operación AXPY

```
#ifdef_OPENACC
#include < openacc.h >
#endif
int main() {
#ifdef _OPENACC
  acc_init(acc_device_not_host);
  printf(" Compiling with OpenACC support \n");
#endif
 for(i=0; i<n; i++)
      y_acc[i] = a*x_acc[i] + y_acc[i];
#ifdef_OPENACC
  acc_shutdown(acc_device_not_host);
#endif
 return 0;
```

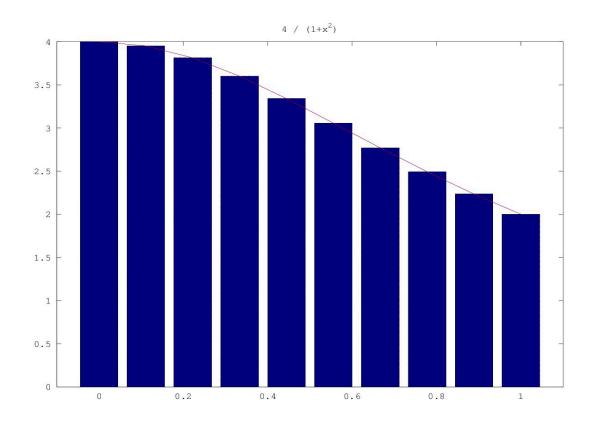
Jacobi

Dependencias

```
while (error > tol && iter < iter_max){
    error = 0.0;
    for( int j = 1; j < n-1; j++){
       for( int i = 1; i < m-1; i++){
         Anew[i][i] = 0.25 * (A[i][i+1] + A[i][i-1]
                      + A[i-1][i] + A[i+1][i];
         error = fmax( error, fabs(Anew[j][i] - A[j][i]));
    for( int j = 1; j < n-1; j++){
       for( int i = 1; i < m-1; i++)
         A[i][i] = Anew[i][i];
    if(iter % 100 == 0) printf("%5d, %0.6f\n", iter, error);
    iter++;
```

#### Cálculo de PI

$$\prod = \int_0^1 \frac{4}{1+x^2} dx$$



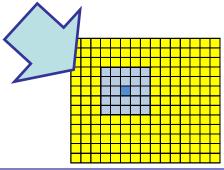
- Detección bordes → convolucion
  - ./imgprocess input\_image.bmp output\_image\_bmp [c,g]
    - c: código ejecutado en CPU
    - g: código ejecutado en CPU







■ Filtrado: convolución 2D



$$filt = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$