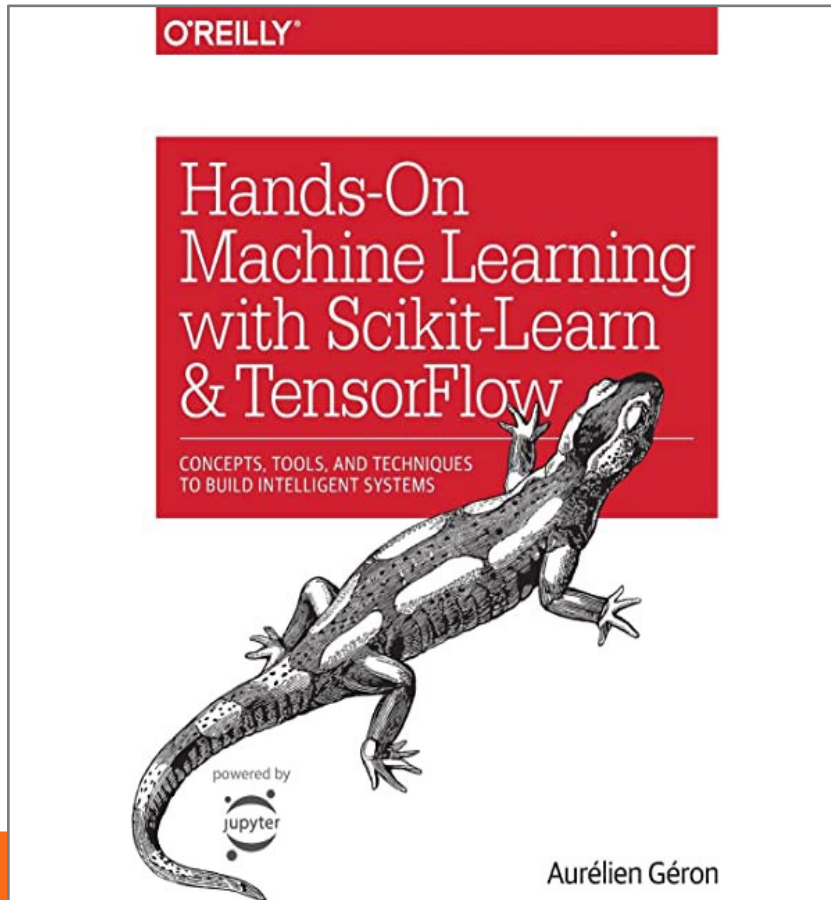


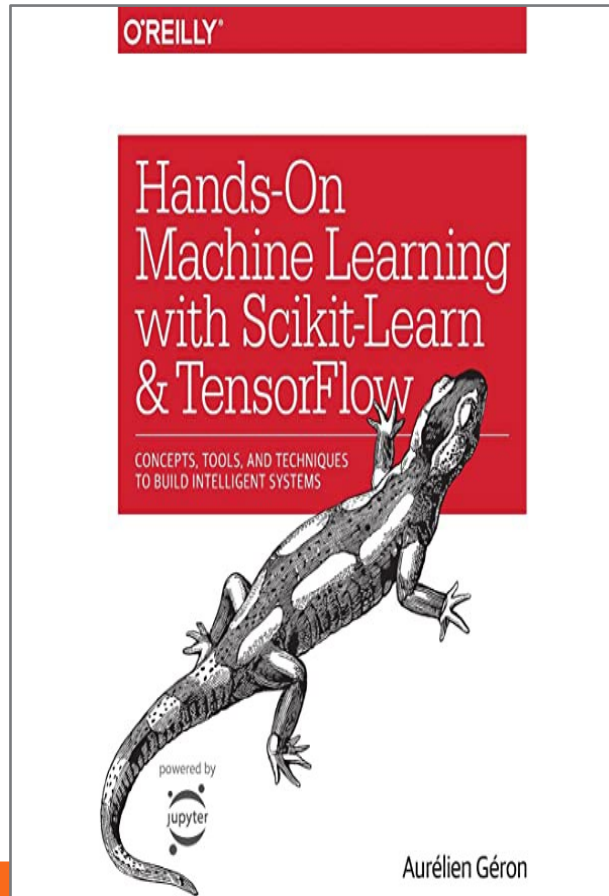
# Machine Learning



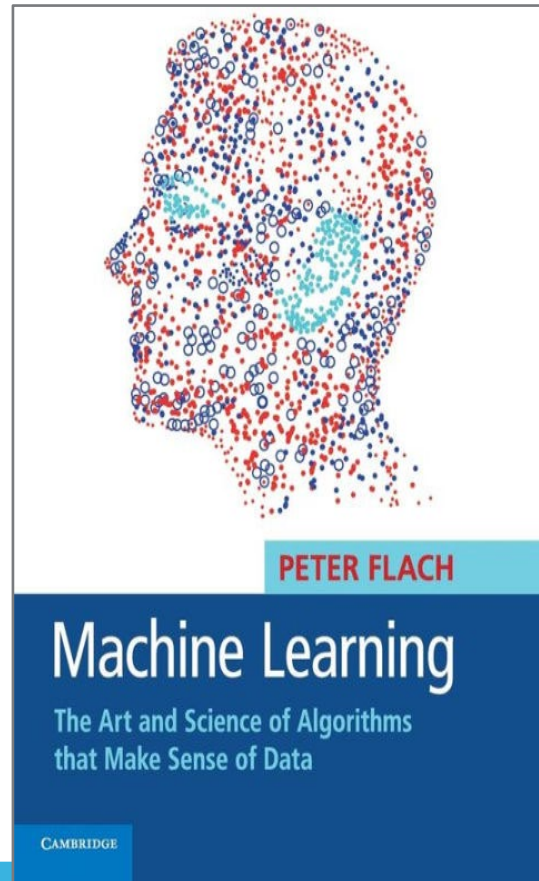
Introduced by  
**Dr. Ebtsam Adel**

DR. EBTSAM ADEL

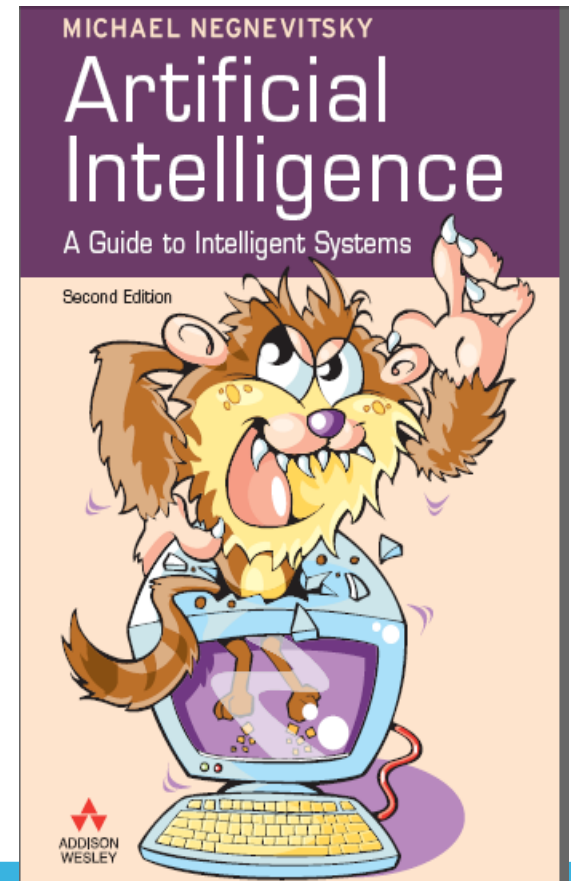
# Materials



**Aurélien Géron**



**PETER FLACH**



**Michael Negnevitskyt**

Introduced by  
**Dr. Ebtsam Adel**



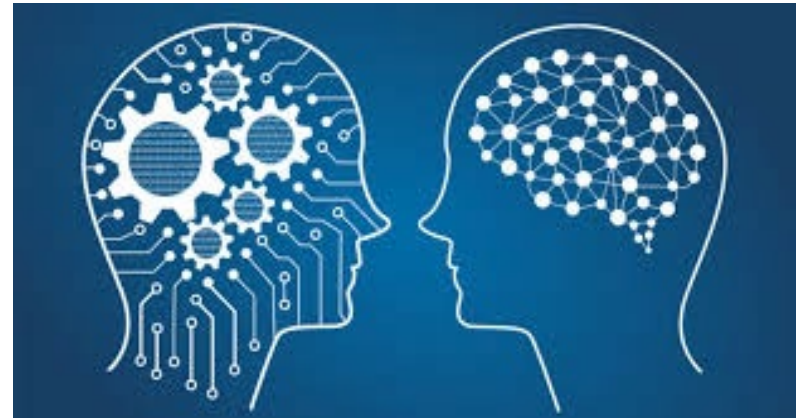
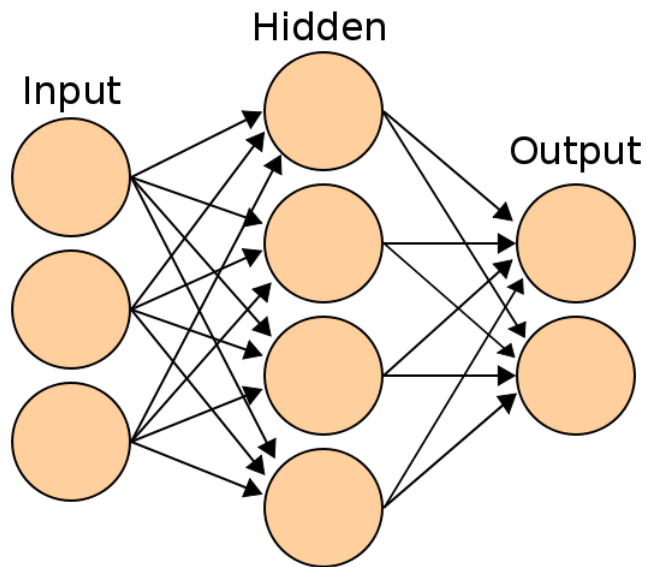
❖ Can you name four common unsupervised tasks?



❖ If your model performs great on the training data but generalizes poorly to new instances, what is happening?  
Can you name three possible solutions?



# Artificial Neural Networks (P1)



Introduced by  
**Dr.Ebtsam Adel**

# AGENDA

Biological Background  
Artificial Neurons  
Activation Functions  
A Simple Perceptron  
Neural Network Characteristics

# AGENDA

## Biological Background

Artificial Neurons

Activation Functions

A Simple Perceptron

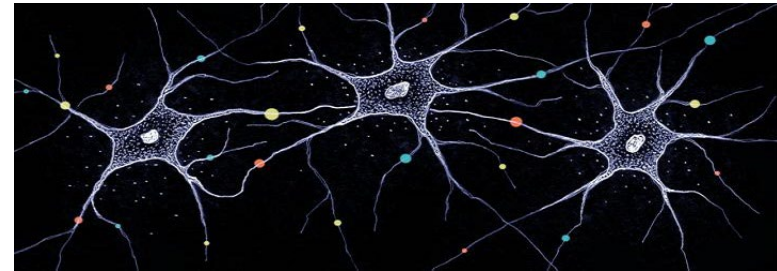
Neural Network Characteristics



# BIOLOGICAL BACKGROUND

## Neuron

- ❑ The basic element of the brain is a natural neuron. a **neuron** is the **basic** building block for all types of **neural networks**.
- ❑ The human brain incorporates nearly **10 billion** neurons and **60 trillion** connections, **synapses**, between them.

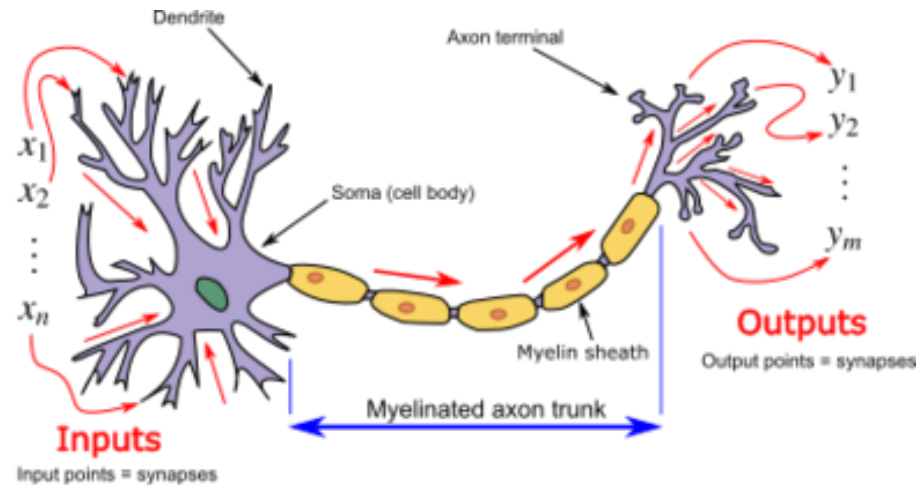




# BIOLOGICAL BACKGROUND

## ❖ Neuron consists of:

- ❑ **Dendrites:** Carry signals in.
- ❑ **Cell body:** processing.
- ❑ **Axon:** carry signals away
- ❑ **Synapses:** Size changes in response to learning. The synapse resistance to the incoming signal can be changed during a "learning" process.



Each neuron receives a **number** of **input signals** through its **connections**; and always produce **single output**.

# AGENDA

Biological Background

**Artificial Neurons**

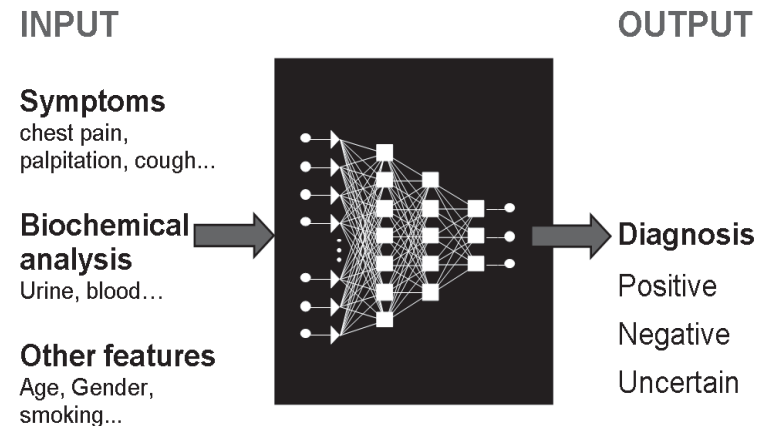
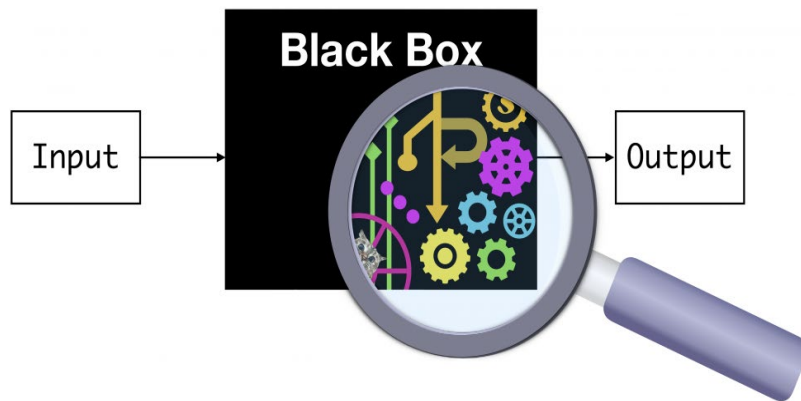
Activation Functions

A Simple Perceptron

Neural Network Characteristics

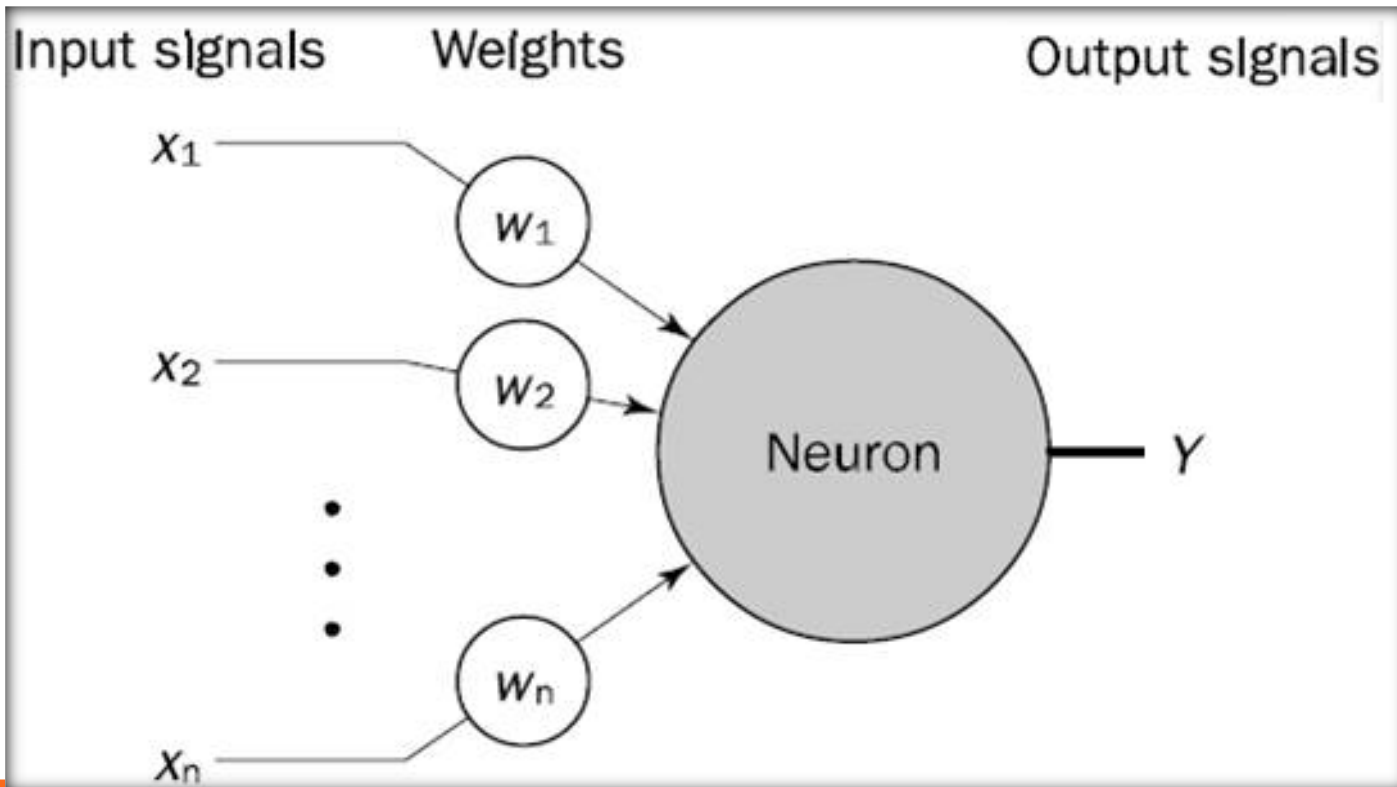
# NEURAL NETWORKS INTRO.

- We can think of a neuron as a sort of **black box**, receiving **input vector  $x$**  then producing a scalar **output  $y$** . The same output value  $y$  can be sent out through multiple edges emerging from the neuron.



# ARTIFICIAL NEURONS- FROM BIOLOGY TO SIMULATION

Neuron as a simple computing element:



# ARTIFICIAL NN VS. BIOLOGICAL NN

- ❑ Mapping between **artificial neural** network and **biological neural** network

<i>Biological Neural Network</i>	<i>Artificial Neural Network</i>
Soma	Neuron
Dendrite	Input
Axon	Output
Synapse	Weight

# ARTIFICIAL NEURONS- FROM BIOLOGY TO SIMULATION

- ❑ A **neural network (NN)** is an abstract **computer model** of the human brain. The human brain has an estimated  $10^{11}$  tiny units called **neurons**.
- ❑ network is viewed as a **graph**, neurons can be represented as **nodes** (or **vertices**), and **interconnections** as **edges**.
- ❑ In most cases an ANN is an **adaptive system** that changes its structure based on external or internal information that flows through the network during the **learning phase**.



# ARTIFICIAL NEURONS

- ❖ The **neural network** of the brain is considered to be the **fundamental functional source** of intelligence, which includes **perception**, **cognition**, and **learning** for humans as well as other living creatures.
- ❖ We have **inputs**  $x_1, x_2, \dots, x_m$  coming into the neuron. These inputs are the stimulation levels of a natural neuron. Each input  $x_i$  is multiplied by its **corresponding weight**  $w_i$ , then the **product**  $x_i w_i$  is **fed into the body** of the neuron.
- ❖ The **weights** represent the **biological synaptic strengths** in a natural neuron.

# ARTIFICIAL NEURONS- FROM BIOLOGY TO SIMULATION

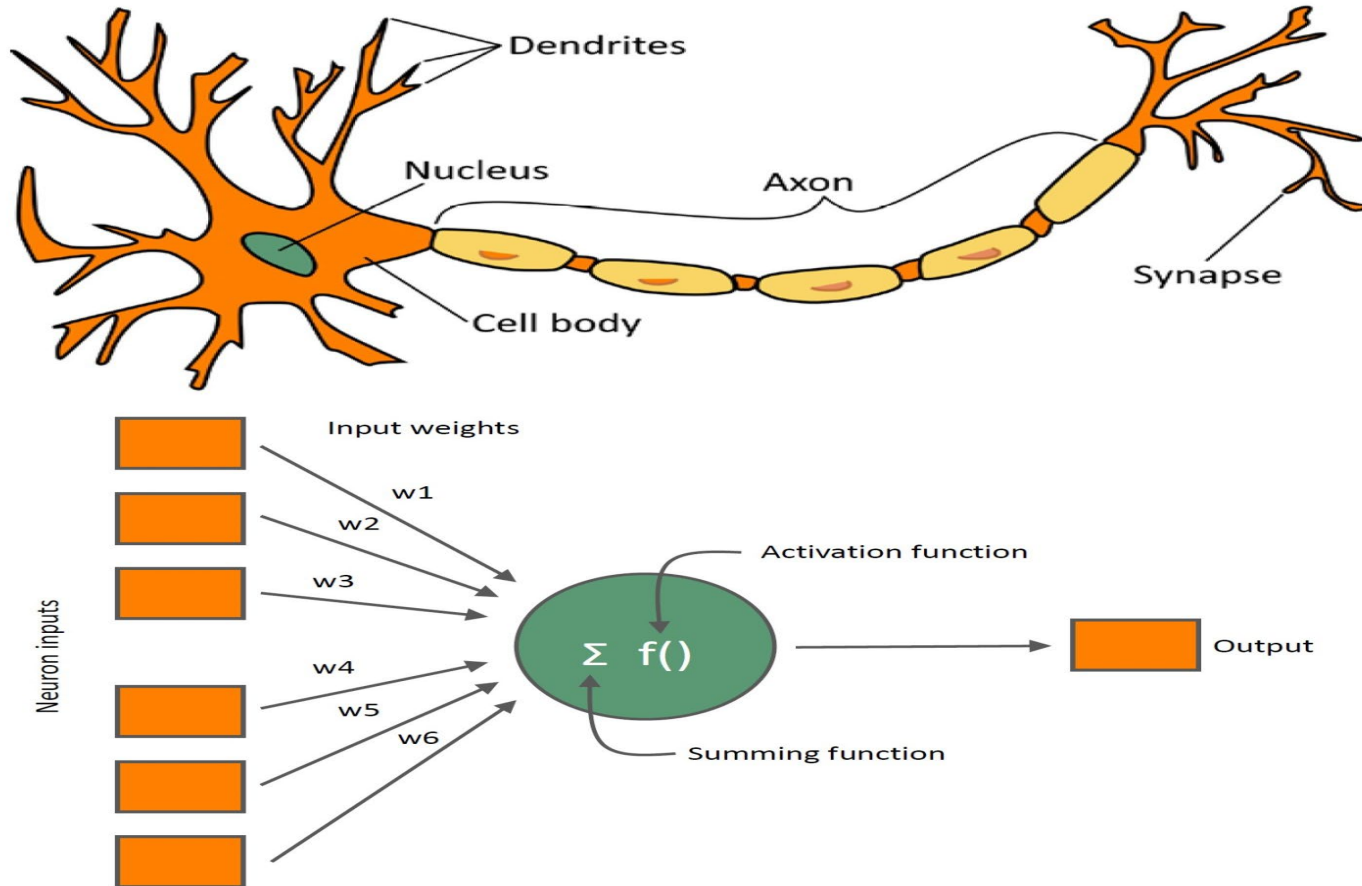
- ❑ The neuron computes the **weighted sum** of the input signals and compares the result with a **threshold** value.

$$X = \sum_{i=1}^n x_i w_i$$

- ❑ The **activation function** determine the response for the output of the neuron.

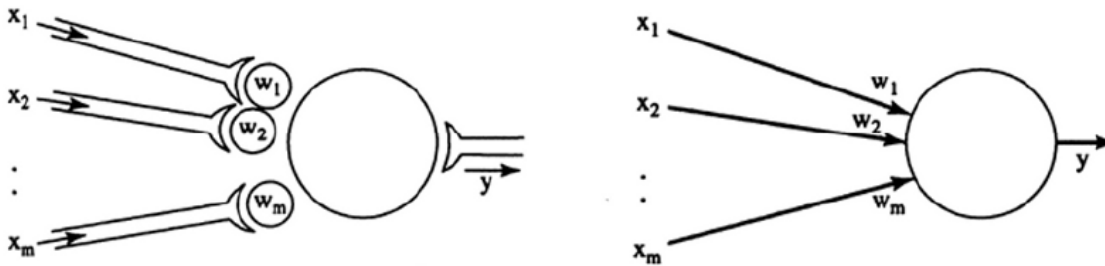
$$Y = f(X)$$

# ARTIFICIAL NEURONS



# ARTIFICIAL NEURONS

- ❑ The neuron **adds** up all the **products** for  $i = 1, m$ . The **weighted sum** of the products is usually denoted as **net**.



- ❑ The weighted sum of the products is usually denoted as **net**. Therefore, the neuron evaluates:

$$\text{net} = x_1w_1 + x_2w_2 + \dots + x_mw_m$$

# ARTIFICIAL NEURONS

In mathematical terms,

- Given two **vectors**  $x = (x_1; x_2; \dots ; x_m)$  and  $w = (w_1; w_2; \dots ; w_m)$ .
- **$\text{net} = x_1 w_1 + x_2 w_2 + \dots + x_m w_m$**
- Finally, the neuron computes its **output  $y$**  as a certain function of net, i.e.,  **$y = f(\text{net})$** . This function is called the **activation transfer function**.

# AGENDA

Biological Background

Artificial Neurons

**Activation Functions**

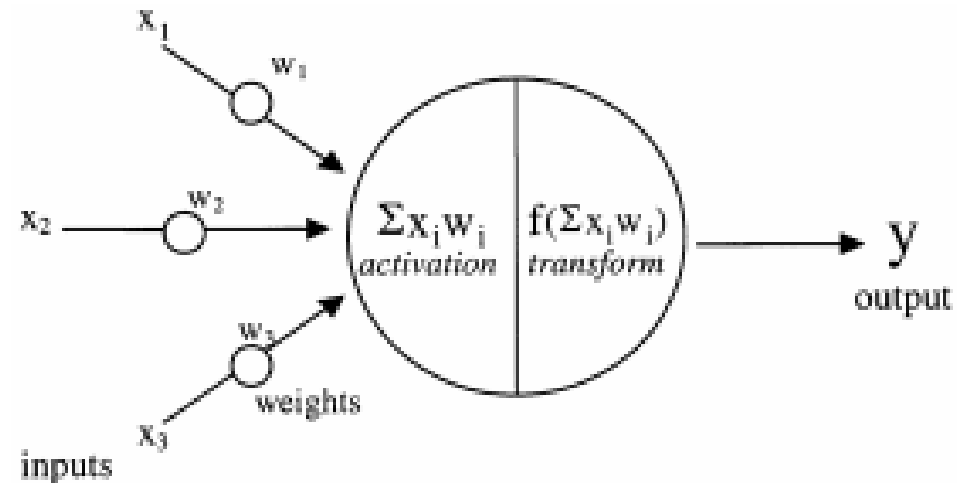
A Simple Perceptron

Neural Network Characteristics



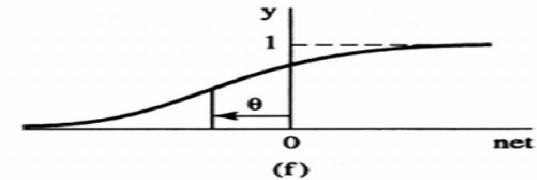
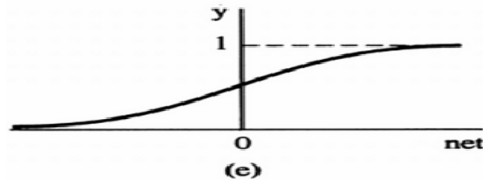
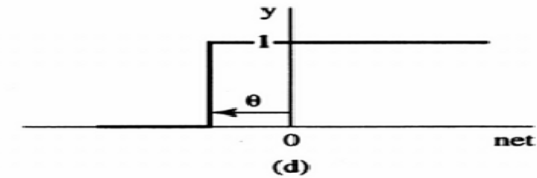
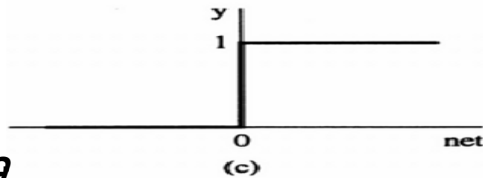
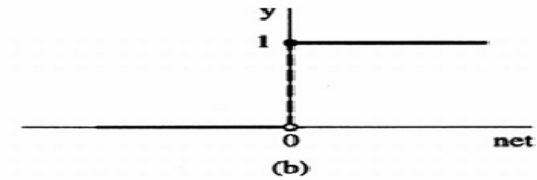
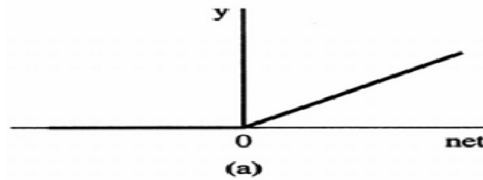
# ACTIVATION (TRANSFER) FUNCTIONS

- ❑ Activation functions are functions used in neural networks to **compute** the **weighted sum** of **input** and **biases**, of which is used to **decide** if a neuron can be **fired** or not.
- ❑ Activation functions of **linear**, **step**, **sigmoid**, etc.
- ❑ Various **forms** of activation functions can be defined depending on the **characteristics of applications**.



# ACTIVATION (TRANSFER) FUNCTIONS

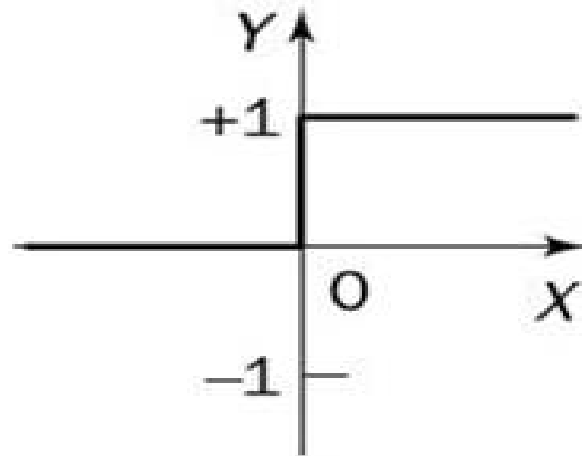
- (a) linear function,
- (b) step function,
- (c) step function,
- (d) step function with threshold  $\theta$
- (e) sigmoid function,
- (f) sigmoid function with threshold  $\theta$



# ACTIVATION (TRANSFER) FUNCTIONS

## Step Function

Step function

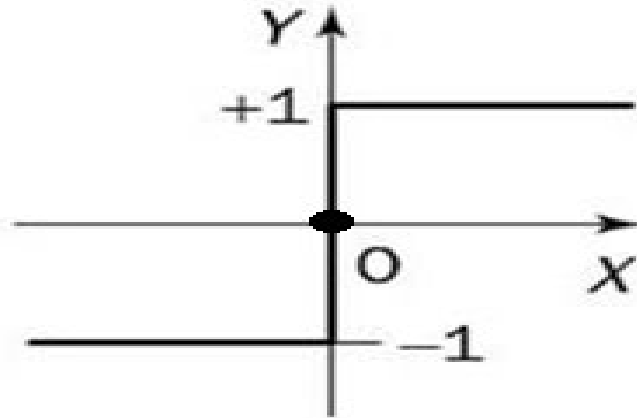


$$y_{step} = \begin{cases} 1, & \text{if } x \geq 0 \\ 0, & \text{if } x < 0 \end{cases}$$

# ACTIVATION (TRANSFER) FUNCTIONS

## Sign Function

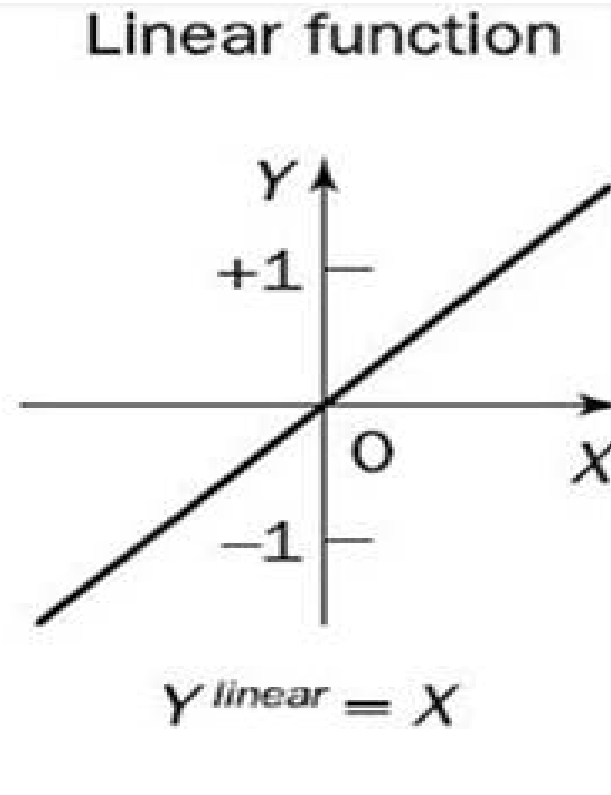
Sign function



$$Y^{sign} = \begin{cases} +1, & \text{if } X > 0 \\ 0, & \text{if } X = 0 \\ -1, & \text{if } X < 0 \end{cases}$$

# ACTIVATION (TRANSFER) FUNCTIONS

## Linear Function



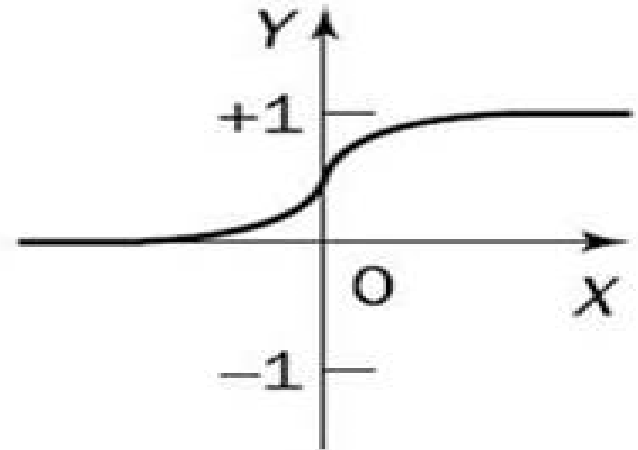
# ACTIVATION (TRANSFER) FUNCTIONS

## Sigmoid Function

$$f(x) = \left( \frac{1}{(1 + \exp^{-x})} \right)$$

e (exponential function)=2.7

## Sigmoid function

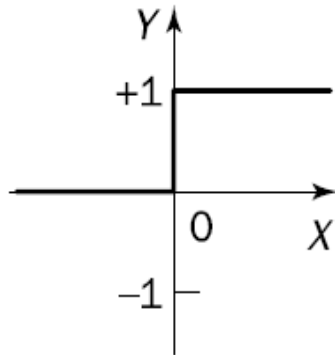


$$y^{\text{sigmoid}} = \frac{1}{1 + e^{-x}}$$



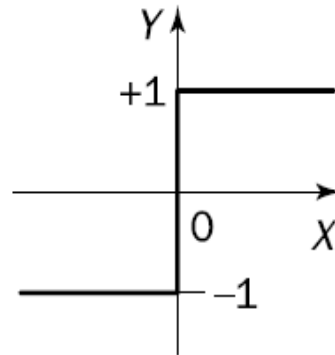
# ACTIVATION (TRANSFER) FUNCTIONS

Step function



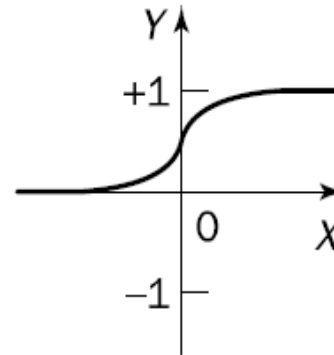
$$Y^{step} = \begin{cases} 1, & \text{if } X \geq 0 \\ 0, & \text{if } X < 0 \end{cases}$$

Sign function



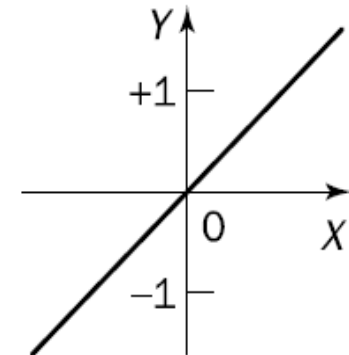
$$Y^{sign} = \begin{cases} +1, & \text{if } X \geq 0 \\ -1, & \text{if } X < 0 \end{cases}$$

Sigmoid function



$$Y^{sigmoid} = \frac{1}{1 + e^{-X}}$$

Linear function



$$Y^{linear} = X$$

❑ The **step** and **sign activation functions**, also called **hard limit functions**, are often used in **decision-making** neurons for **classification** and **pattern recognition** tasks.

# AGENDA

Biological Background

Artificial Neurons

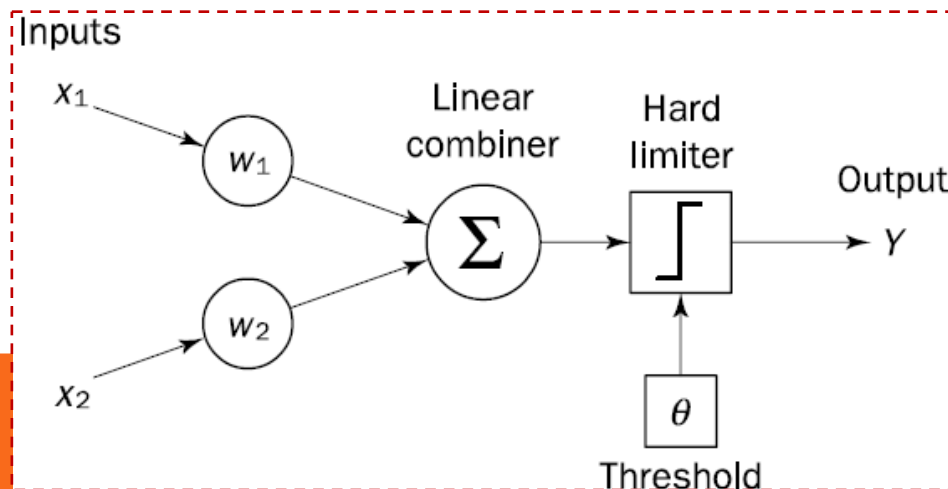
Activation Functions

**A Simple Perceptron**

Neural Network Characteristics

# A SIMPLE PERCEPTRON

- ❑ The operation of **Rosenblatt's** perceptron is based on the **McCulloch and Pitts** neuron model in **1958**.
- ❑ The model consists of a **linear combiner** followed by a **hard limiter**.
- ❑ The **weighted sum** of the **inputs** is applied to the **hard limiter**, which produces an **output equal** to +1 if its input is **positive** and -1 if it is **negative**.
- ❑ The hyperplane is defined by the **linearly separable** function.



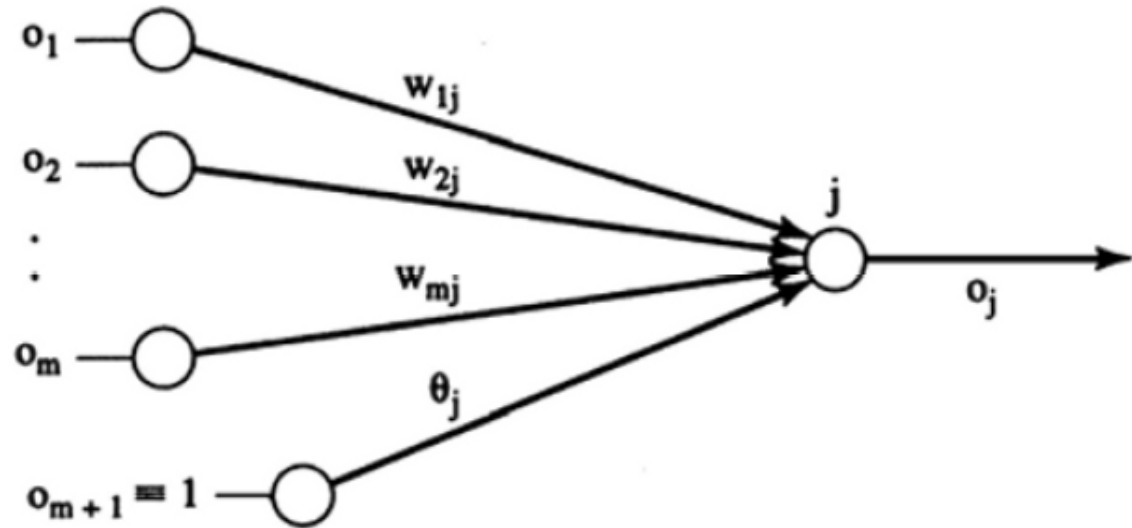
$$\sum_{i=1}^n x_i w_i - \theta = 0$$

# A SIMPLE PERCEPTRON

❑ Only an **input** layer and an **output** layer (**0-hidden layers**), is called a simple **perceptron**.

## Perception (brain)

1. Input
2. Processing
3. output



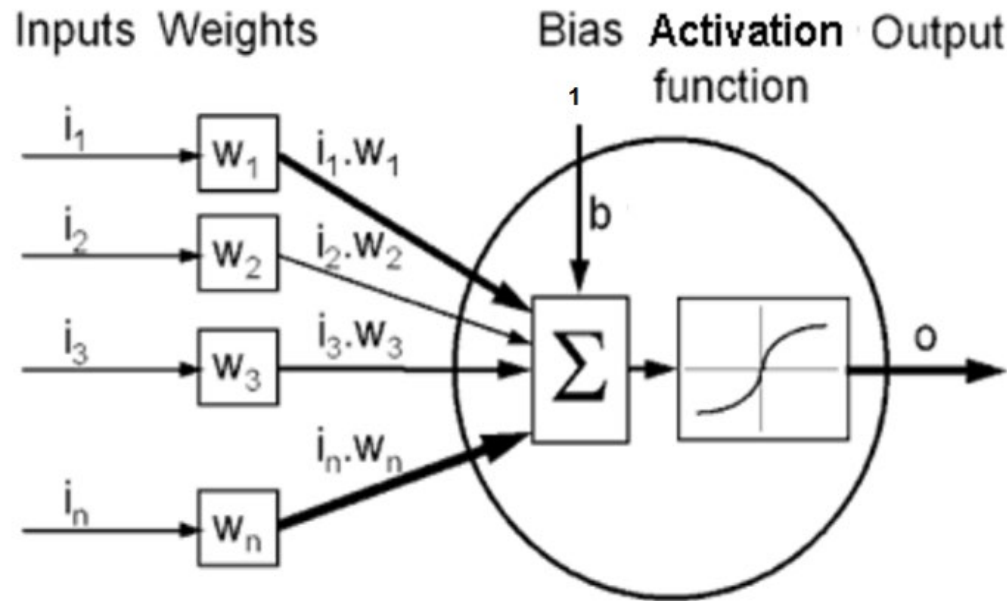
Example: attendance a training course

1. **Trainer**
2. **Time**
3. **cost**

# A SIMPLE PERCEPTRON

- ❑ **Representation** refers to whether a neural network is able to produce a particular function by **assigning appropriate weights**.
- ❑ Perceptron can **learn** anything it can **represent**.
- ❑ The activation function is **a step function with threshold**.

# A SIMPLE PERCEPTRON

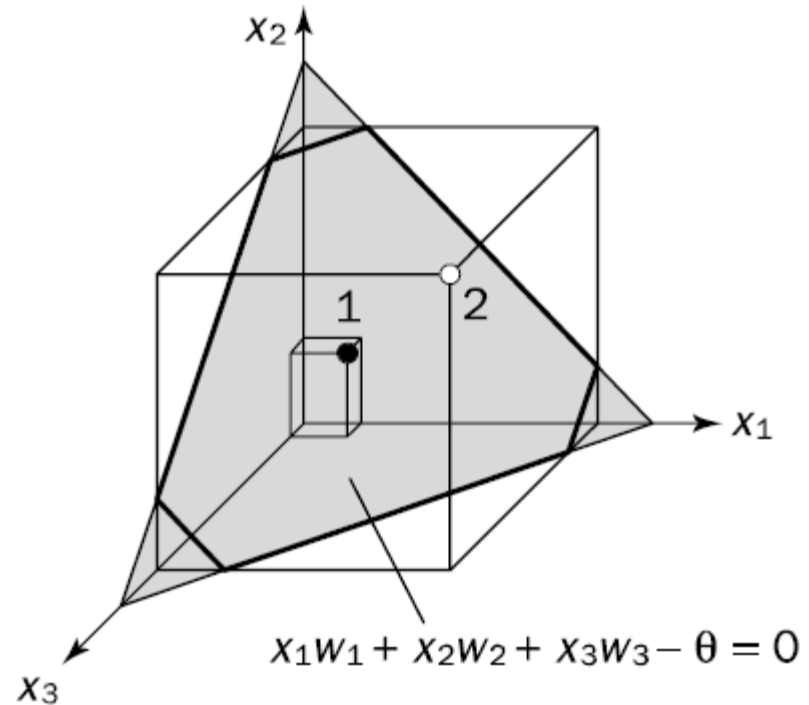
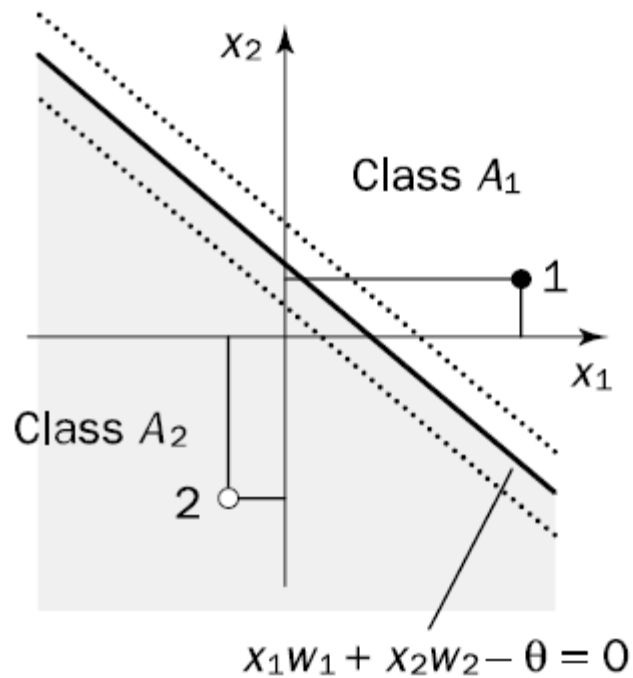


$$X = b + \sum_{i=1}^n i_i w_i$$

$$Y^{sign} = \begin{cases} +1, & \text{if } X > 0 \\ 0, & \text{if } X = 0 \\ -1, & \text{if } X < 0 \end{cases}$$



# Linear separability



Linear separability in the perceptron's

## HOW DOES THE PERCEPTRON LEARN ITS CLASSIFICATION TASKS?

- ❑ This is done by making small **adjustments** in the **weights** to **reduce** the **difference** between the **actual** and **desired** outputs of the perceptron.
- ❑ The **initial weights** are **randomly assigned**, usually in the range  $[-0.5; 0.5]$ , and then **updated** to obtain the output consistent with the training examples.
- ❑ If at iteration  $p$ , the actual output is  $Y(p)$  and the desired output is  $Y_d(p)$ , then the **error** is given by:

## HOW DOES THE PERCEPTRON LEARN ITS CLASSIFICATION TASKS?

- ❑ If at iteration  $p$ , the **actual output** is  $Y(p)$  and the **desired output** is  $Y_d(p)$ , then the **error** is given by:

$$e(p) = Y_d(p) - Y(p) \quad \text{where } p = 1, 2, 3, \dots$$

Iteration  $p$  here refers to the  $p$ th training example presented to the perceptron.

If the error,  $e(p)$ , is positive, we need to increase perceptron output  $Y(p)$ , but if it is negative, we need to decrease  $Y(p)$ . Taking into account that each perceptron input contributes  $x_i(p) \times w_i(p)$  to the total input  $X(p)$ , we find that if input value  $x_i(p)$  is positive, an increase in its weight  $w_i(p)$  tends to increase perceptron output  $Y(p)$ , whereas if  $x_i(p)$  is negative, an increase in  $w_i(p)$  tends to decrease  $Y(p)$ . Thus, the following **perceptron learning rule** can be established:

$$w_i(p + 1) = w_i(p) + \alpha \times x_i(p) \times e(p),$$

where  $\alpha$  is the **learning rate**, a positive constant less than unity.

# PERCEPTRON'S LEARNING ALGORITHM

## Step 1: *Initialisation*

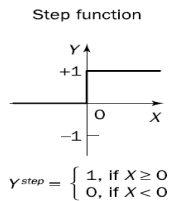
Set initial weights  $w_1, w_2, \dots, w_n$  and threshold  $\theta$  to random numbers in the range  $[-0.5, 0.5]$ .

## Step 2: *Activation*

Activate the perceptron by applying inputs  $x_1(p), x_2(p), \dots, x_n(p)$  and desired output  $Y_d(p)$ . Calculate the actual output at iteration  $p = 1$

$$Y(p) = \text{step} \left[ \sum_{i=1}^n x_i(p)w_i(p) - \theta \right], \quad (6.6)$$

where  $n$  is the number of the perceptron inputs, and *step* is a step activation function.



## PERCEPTRON'S LEARNING ALGORITHM CONT.

### Step 3: *Weight training*

Update the weights of the perceptron

$$w_i(p+1) = w_i(p) + \Delta w_i(p), \quad (6.7)$$

where  $\Delta w_i(p)$  is the weight correction at iteration  $p$ .

The weight correction is computed by the **delta rule**:

$$\Delta w_i(p) = \alpha \times x_i(p) \times e(p) \quad (6.8)$$

### Step 4: *Iteration*

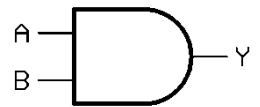
Increase iteration  $p$  by one, go back to Step 2 and repeat the process until convergence.

# Example

## EXAMPLE. X1 AND X2 (BOOLEAN AND)

This example illustrates that representation of the AND function is possible. The AND function,  $y = x_1 \text{ AND } x_2$  should produce the following:

$x_1$	$x_2$	$y$
0	0	0
0	1	0
1	0	0
1	1	1



# CAN WE TRAIN A PERCEPTRON TO PERFORM BASIC LOGICAL OPERATIONS

Epoch	Inputs		Desired output $Y_d$	Initial weights		Actual output $Y$	Error $e$	Final weights	
	$x_1$	$x_2$		$w_1$	$w_2$			$w_1$	$w_2$
1	0	0	0	0.3	-0.1	0	0	0.3	-0.1
	0	1	0	0.3	-0.1	0	0	0.3	-0.1
	1	0	0	0.3	-0.1	1	-1	0.2	-0.1
	1	1	1	0.2	-0.1	0	1	0.3	0.0

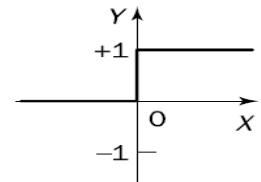
Threshold:  $\theta = 0.2$ ; learning rate:  $\alpha = 0.1$ .

$$e(p) = Y_d(p) - Y(p)$$

$$\begin{aligned} (0*0.3+0*-0.1)-0.2 &= -0.2 \implies Y=0 \\ (0*0.3+1*-0.1)-0.2 &= -0.3 \implies Y=0 \\ (1*0.3+0*-0.1)-0.2 &= 0.1 \implies Y=1 \\ (1*0.2+1*-0.1)-0.2 &= -0.1 \implies Y=0 \end{aligned}$$

$$Y(p) = \text{step} \left[ \sum_{i=1}^n x_i(p)w_i(p) - \theta \right]$$

Step function



$$Y^{\text{step}} = \begin{cases} 1, & \text{if } X \geq 0 \\ 0, & \text{if } X < 0 \end{cases}$$

❑ the sequence of four **input patterns** representing an **epoch**.

$$w_i(p+1) = w_i(p) + \alpha \times x_i(p) \times e(p)$$

$$W1 = 0.3 + 0.1 * -1 * 1 = 0.2$$

$$W2 = w2 = -0.1$$

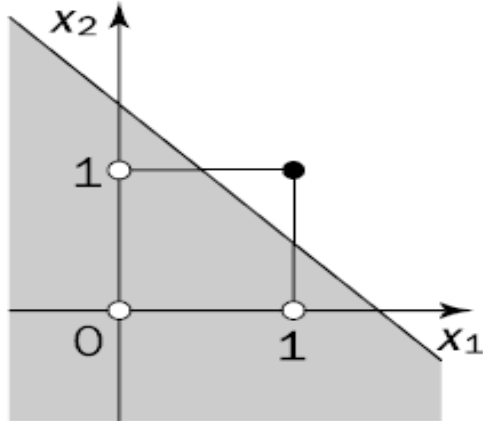


# CAN WE TRAIN A PERCEPTRON TO PERFORM BASIC LOGICAL OPERATIONS

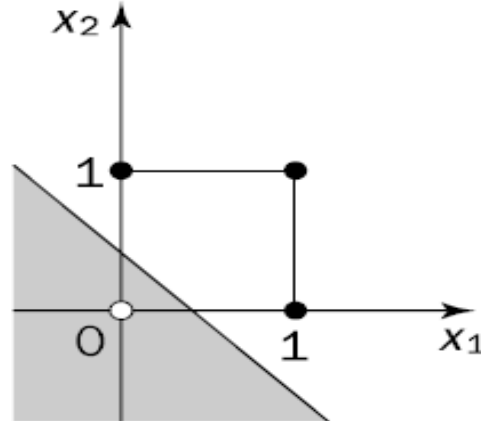
Epoch	Inputs		Desired output $Y_d$	Initial weights		Actual output $Y$	Error $e$	Final weights	
	$x_1$	$x_2$		$w_1$	$w_2$			$w_1$	$w_2$
1	0	0	0	0.3	-0.1	0	0	0.3	-0.1
	0	1	0	0.3	-0.1	0	0	0.3	-0.1
	1	0	0	0.3	-0.1	1	-1	0.2	-0.1
	1	1	1	0.2	-0.1	0	1	0.3	0.0
2	0	0	0	0.3	0.0	0	0	0.3	0.0
	0	1	0	0.3	0.0	0	0	0.3	0.0
	1	0	0	0.3	0.0	1	-1	0.2	0.0
	1	1	1	0.2	0.0	1	0	0.2	0.0
3	0	0	0	0.2	0.0	0	0	0.2	0.0
	0	1	0	0.2	0.0	0	0	0.2	0.0
	1	0	0	0.2	0.0	1	-1	0.1	0.0
	1	1	1	0.1	0.0	0	1	0.2	0.1
4	0	0	0	0.2	0.1	0	0	0.2	0.1
	0	1	0	0.2	0.1	0	0	0.2	0.1
	1	0	0	0.2	0.1	1	-1	0.1	0.1
	1	1	1	0.1	0.1	1	0	0.1	0.1
5	0	0	0	0.1	0.1	0	0	0.1	0.1
	0	1	0	0.1	0.1	0	0	0.1	0.1
	1	0	0	0.1	0.1	0	0	0.1	0.1
	1	1	1	0.1	0.1	1	0	0.1	0.1

Threshold:  $\theta = 0.2$ ; learning rate:  $\alpha = 0.1$ .

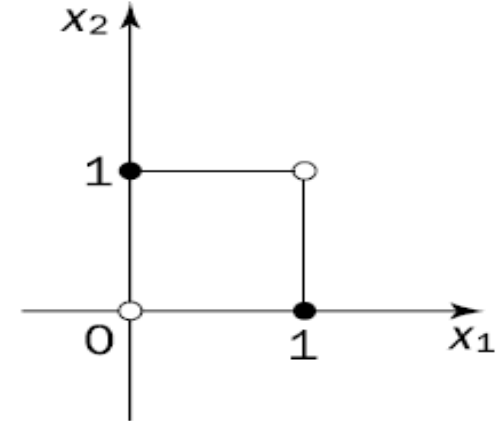
# CAN WE TRAIN A PERCEPTRON TO PERFORM BASIC LOGICAL OPERATIONS



(a) AND ( $x_1 \cap x_2$ )



(b) OR ( $x_1 \cup x_2$ )



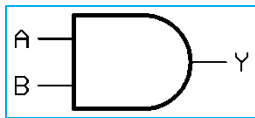
(c) Exclusive-OR  
( $x_1 \oplus x_2$ )

Two-dimensional plots of basic logical operations

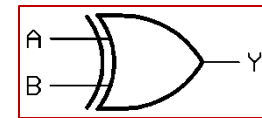
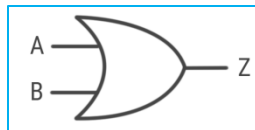
- Points in the input space where the function output is **1** are indicated by **black dots**, and points where the output is **0** are indicated by **white dots**.

## CAN WE TRAIN A PERCEPTRON TO PERFORM BASIC LOGICAL OPERATIONS

- ❑ the **perceptron** can **learn** the operation **OR**. However, a **single-layer perceptron cannot be trained** to perform the operation **Exclusive OR**.
- ❑ A perceptron is able to represent a function only if there is some **line** that **separates** all the black dots from all the white dots. Such functions are called **linearly separable**. Therefore, a perceptron can learn the operations **AND** and **OR**, but **not Exclusive-OR**.



**linear**

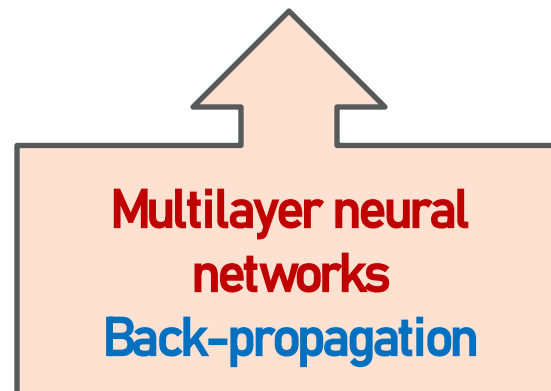


**Non- linear**

# CAN WE TRAIN A PERCEPTRON TO PERFORM BASIC LOGICAL OPERATIONS

**How do we cope with problems which are not linearly separable?**

To cope with such problems we need multilayer neural networks. In fact, history has proved that the limitations of Rosenblatt's perceptron can be overcome by advanced forms of neural networks, for example multilayer perceptrons trained with the back-propagation algorithm.



# AGENDA

Biological Background

Artificial Neurons

Activation Functions

A Simple Perceptron

**Neural Network Characteristics**

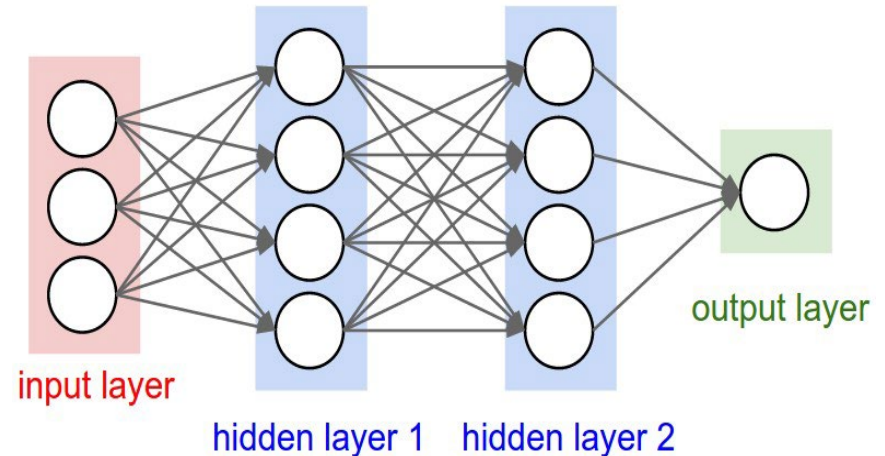
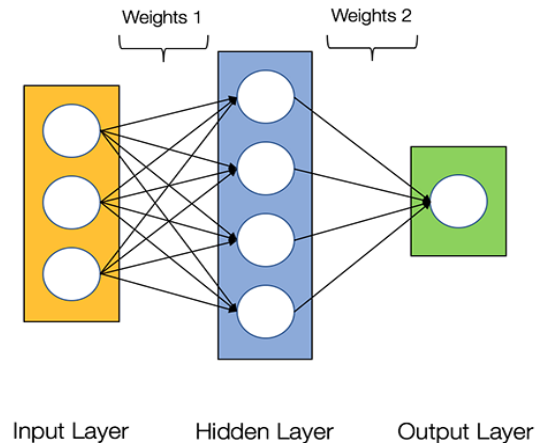
# NEURAL NETWORK CHARACTERISTICS

- ❑ There are various **characteristics** associated with the neural networks, and by selecting different **characteristic values**, we can come up many **different models**.

# TOPOLOGY OF THE NETWORK ARCHITECTURE

## ❑ Multilayered

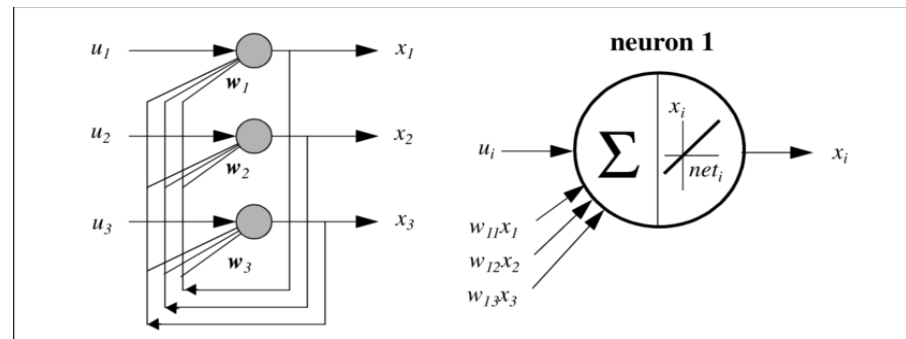
The **backpropagation** model has distinct layers such as **input**, **hidden**, and **output**. The neurons within each layer **are connected** with the neurons of the **adjacent layers** through directed edges. There are **no connections among the** neurons within the **same layer**.



# TOPOLOGY OF THE NETWORK ARCHITECTURE

## Non-multilayered

- We can also build neural network **without such distinct layers** as input, output, or hidden. Every neuron can be connected with **every other neuron** in the network through directed edges. Every neuron may input as well as output. A typical example is the **Hopfield** model.

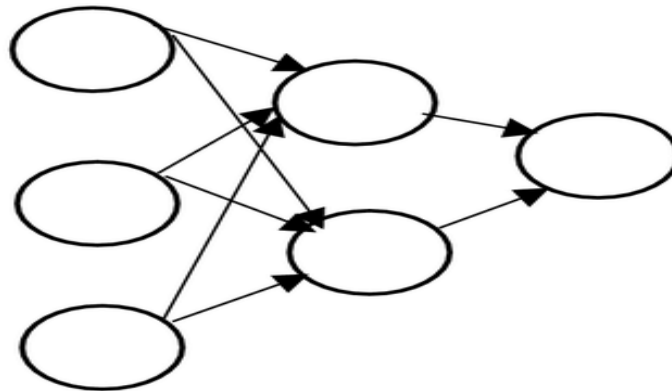




# DIRECTIONS OF OUTPUT

## ❑ Non-recurrent (feedforward only)

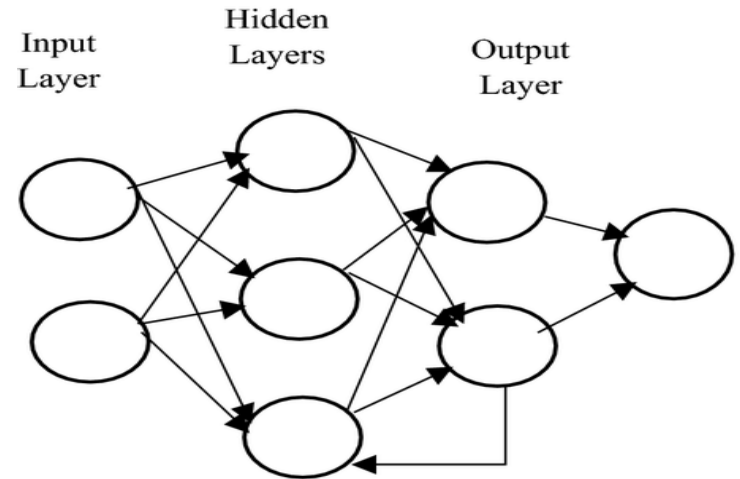
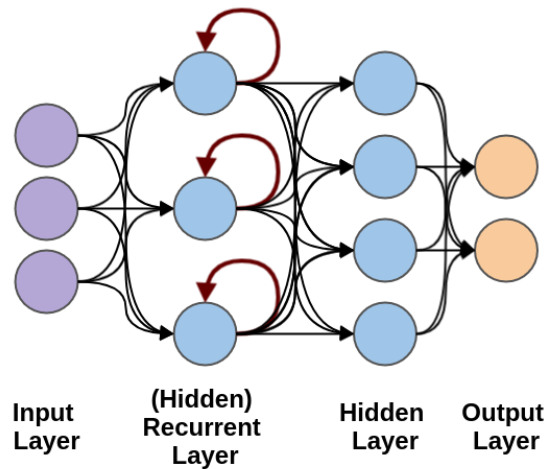
Neural network models with **feedforward only** are called **non-recurrent**. Incidentally, “backpropagation” in the **backpropagation** model should not be confused with feedbackward. The backpropagation is backward adjustments of the weights, not output movements from neurons.



# DIRECTIONS OF OUTPUT

## ❑ Recurrent (feedforward and feedbackward)

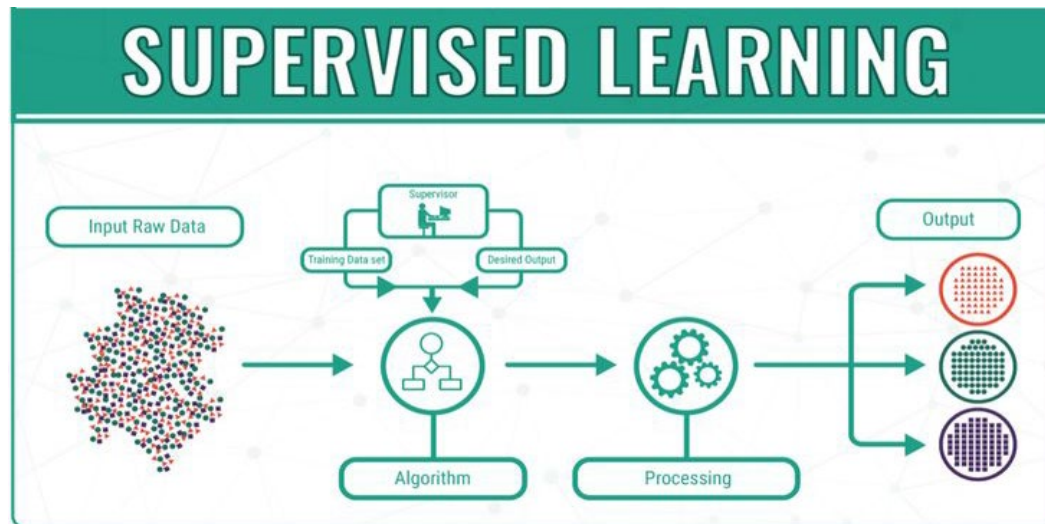
The outputs can also propagate **backward** (from right to left). This is called feedbackward. A neural network in which the outputs can propagate in **both directions, forward and backward**, is called a recurrent model.



# FORM OF LEARNING

## ❑ Supervised Learning

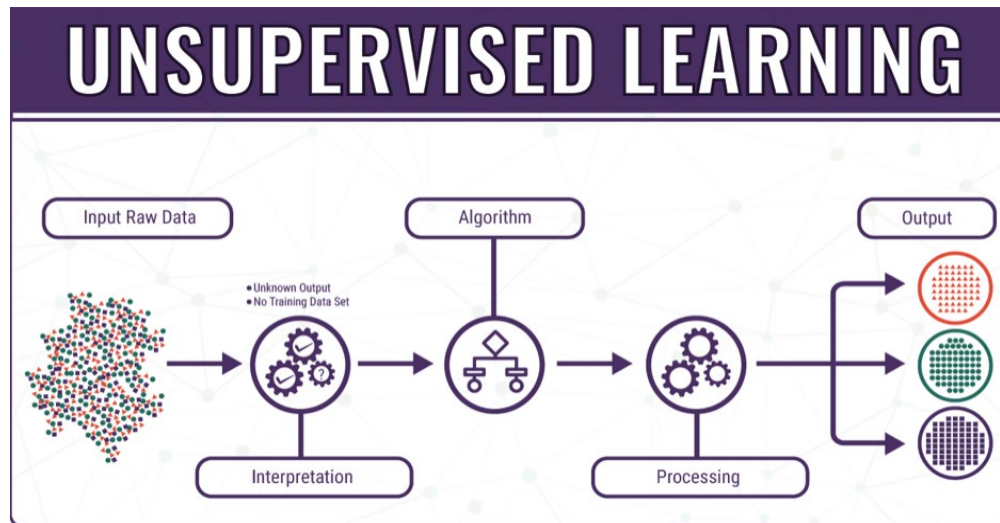
In supervised learning, a **teacher knows what should be the correct output** and this information is given to the neural network. The backpropagation model is such an example, assuming an existence of a teacher who knows what are correct patterns.



# FORM OF LEARNING

## ❑ Unsupervised Learning

In some models, neural networks can **learn by themselves** after being given some form of general **guidelines**. The neural network adjusts by itself internally using certain criteria or algorithms.



# TYPES OF INPUT VALUES

We can assume different **types** of **input values**. The most common types are:

- ✓ **Binary**: an input value is restricted to either 0 or 1.
- ✓ **Bipolar**: an input value is either -1 or 1.
- ✓ **Continuous**: Continuous real numbers in a certain range.

*Thank You!*

**Any questions?** 