

Exercise 4: Task 5

1) $F(u, v) = \mathcal{F}\{f(x, y)\}$

$$\begin{aligned} \mathcal{F}\{f(x, y) e^{j2\pi(u_0 x/M + v_0 y/N)}\} &= \\ \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{j2\pi(u_0 x/M + v_0 y/N)} e^{-j2\pi(u x/M + v y/N)} &= \\ \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi[(u-u_0)x/M + (v-v_0)y/N]} &= \\ [F(u-u_0, v-v_0)] \end{aligned}$$

$$\begin{aligned} \mathcal{F}^{-1}\{F(u, v) e^{-j2\pi(x_0 u/M + y_0 v/N)}\} &= \\ \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} F(u, v) e^{-j2\pi(x_0 u/M + y_0 v/N)} e^{j2\pi(ux/M + vy/N)} &= \\ \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} F(u, v) e^{j2\pi[(x-x_0)u/M + (y-y_0)v/N]} &= \\ [f(x-x_0, y-y_0)] \end{aligned}$$

2)
$$\begin{aligned} x &= r \cos \theta & u &= \omega \cos \phi \\ y &= r \sin \theta & v &= \omega \sin \phi \end{aligned}$$

→ define rotated coordinates (x', y') in terms of x, y , and θ_0

$$\theta' = \theta + \theta_0$$

$$\begin{aligned} x &= r \cos(\theta' - \theta_0) \\ x &= r \cos \theta' \cos \theta_0 + r \sin \theta' \sin \theta_0 \\ x &= x' \cos \theta_0 + y' \sin \theta_0 \\ y &= r \sin(\theta' - \theta_0) \\ y &= r \sin \theta' \cos \theta_0 - r \cos \theta' \sin \theta_0 \\ y &= y' \cos \theta_0 - x' \sin \theta_0 \end{aligned}$$

→ find the 2D DFT of $f(x', y')$

$$\begin{aligned} \mathcal{F}\{f(x', y')\} &= \\ \sum_{x'} \sum_{y'} f(x', y') e^{-j2\pi(\frac{u}{M}x' + \frac{v}{N}y')} &= \\ \sum_{x'} \sum_{y'} f(x', y') e^{-j2\pi[\frac{u}{M}(x' \cos \theta_0 + y' \sin \theta_0) + \frac{v}{N}(y' \cos \theta_0 - x' \sin \theta_0)]} &= \\ \sum_{x'} \sum_{y'} f(x', y') e^{-j2\pi[\frac{x'}{M}(u \cos \theta_0 - v \sin \theta_0) + \frac{y'}{N}(v \cos \theta_0 + u \sin \theta_0)]} &= \end{aligned}$$

→ Recognize rotated coordinates (u', v')
$$\begin{aligned} u' &= u \cos \theta_0 - v \sin \theta_0 = r \cos(\phi + \theta_0) \\ v' &= v \cos \theta_0 + u \sin \theta_0 = r \sin(\phi + \theta_0) \end{aligned}$$

$$\sum_{x'} \sum_{y'} f(x', y') e^{-j2\pi(\frac{x'}{M}u' + \frac{y'}{N}v')} =$$

$$[F(u', v'), \text{ s.t. } (u', v') \text{ are the coordinates } (u, v) \text{ rotated by } \theta_0]$$