

# Linear Regression

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## 1 Problem Formulation

**Input space:**

$$X \subseteq \mathbb{R}^d \setminus \mathcal{X} \subseteq \mathbb{R}^d$$

$$\text{Feature vector } x = (x_1, x_2, \dots, x_d) \quad x = (x_1, x_2, \dots, x_d)$$

**Output space:**

$$Y \subseteq \mathbb{R} \setminus \mathcal{Y} \subseteq \mathbb{R}$$

Continuous target variable

**Data distribution:**

Samples  $(x_i, y_i)$  drawn i.i.d. from unknown distribution  $P(X, Y)$

**Learning Objective (Expected Risk Minimization):**

$$R(w) = \mathbb{E}_{(X, Y)} [(Y - f_w(X))^2] \quad R(w) = \mathbb{E}_{(X, Y)} [(Y - f_w(X))^2]$$

Goal:

$$\min_w R(w)$$

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## 2 Model Specification

**Hypothesis function:**

$$f_w(x) = w^T x + b \quad f_w(x) = w^T x + b$$

**Parameter space:**

$$w \in \mathbb{R}^d, b \in \mathbb{R} \quad w \in \mathbb{R}^d, b \in \mathbb{R}$$

**Structural assumptions:**

- Linearity in parameters

- Additive noise
- Homoscedasticity
- No multicollinearity (ideal case)

### 3 Loss Function

**Explicit form (Squared Error Loss):**

$$L(y, \hat{y}) = (y - \hat{y})^2 \quad L(y, \hat{y}) = (y - \hat{y})^2$$

**Why this loss?**

- Corresponds to Gaussian noise assumption
- Maximum Likelihood Estimation under normal errors

**Convexity:**

- Convex
- Differentiable
- Global minimum exists

### 4 Objective Function

**Empirical Risk:**

$$J(w) = \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 \quad J(w) = \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2$$

**Regularized (Ridge example):**

$$J(w) = \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda \|w\|^2 \quad J(w) = \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda \|w\|^2$$

### 5 Optimization Method

**Closed-form solution (Normal Equation):**

$$w = (X^T X)^{-1} X^T y \quad w = (X^T X)^{-1} X^T y$$

**Gradient:**

$$\nabla J(w) = -2X^T(y - Xw)$$

**Convergence:**

- Convex  $\Rightarrow$  global optimum guaranteed

**Computational complexity:**

- Closed-form:  $O(d^3)$
- Gradient Descent:  $O(nd)$  per iteration

## 6 Statistical Interpretation

**MLE connection:**

Assume:

$$Y = w^T X + \epsilon, \epsilon \sim N(0, \sigma^2)$$

Then minimizing MSE = maximizing likelihood.

**Noise model:** Gaussian

**Probabilistic meaning:**

Predicts conditional mean:

$$E[Y|X]$$

## 7 Regularization & Generalization

**Bias–Variance Tradeoff:**

- No regularization  $\rightarrow$  low bias, high variance
- With Ridge  $\rightarrow$  slightly higher bias, lower variance

**Overfitting behavior:**

- High-degree polynomial features can overfit

**Capacity control:**

- L2 (Ridge)
  - L1 (Lasso)
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## 8 Theoretical Properties

- Convex optimization
  - Unique global minimum (if  $XTXX^T$  invertible)
  - Consistent estimator (under assumptions)
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## 9 Computational Complexity

Training:

- $O(nd^2)$  or  $O(d^3)$

Inference:

- $O(d)$  per prediction

Memory:

- $O(nd)$
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## 10 Limitations

- Sensitive to outliers
- Assumes linear relationship
- Requires homoscedasticity
- Multicollinearity issues