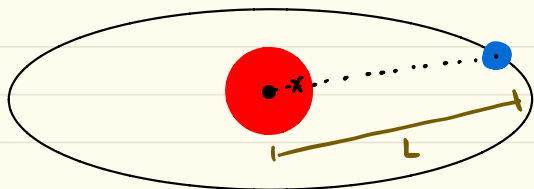


理论力学第二次作业

近似 $m_s \gg m_p$

1. 系外行星径向速度法

地球



$$V = 4.92 \text{ m/s}$$

$$T = 20.73 \text{ day}$$

$$M_s = 1.2 M_\odot$$

$$F = \frac{G M_s m_p}{L^2}$$

质心到行星距离 $d_p = \frac{m_s}{m_s + m_p} \cdot L$

... 恒 ... $d_s = \frac{m_p}{m_s + m_p} \cdot L$

$$\frac{G M_s m_p}{L^2} = m_s \omega^2 \cdot d_s$$

$$\omega = \frac{2\pi}{T}$$

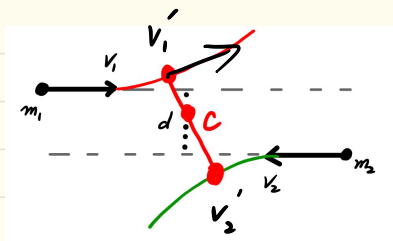
$$G \cancel{m_p} = \left(\frac{2\pi}{T}\right)^2 \cdot \frac{\cancel{m_p}}{m_s + m_p} \cdot L^3$$

$$\approx \left(\frac{2\pi}{T}\right)^2 \frac{L^3}{m_s}$$

解出 L.

另 $V = \omega \cdot d_s$

$$\frac{m_p}{m_s} L \cdot \omega = V \quad \text{解出 } m_p$$



$$F = k/r^2 \text{ 排斥力}$$

选质心静止参考系 (质心运动速 $v_c = \frac{m_1 v_1 - m_2 v_2}{m_1 + m_2}$)

在此参考系下, 1 质点速率 $v_1 - v_c$

质心位置位于距离 1 质点路径 $\frac{m_2}{m_1 + m_2} d$

最近点时速度方向与连线方向垂直. 角动量守恒

$$\cancel{m_1 v_1} \cdot \cancel{\frac{m_2}{m_1 + m_2} d} = \cancel{m_1 v_1'} \cdot \cancel{\frac{m_2}{m_1 + m_2} \cdot c}$$

1 质点受力 $F_1 = k/r^2$. 对 \int_{∞}^r 的势 $V = + \frac{k}{r}$

机械能 守恒 引入 $r_1 \dots$ 质心到 1 质点的距离. $F_1 = k \left(\frac{m_2}{m_1 + m_2} \right)^2 / r_1^2$

$$r_1 = \frac{m_2}{m_1 + m_2} \cdot r$$

$$V_1 = k \left(\frac{m_2}{m_1 + m_2} \right)^2 / r_1$$

$$\frac{1}{2} m_1 v_1^2 = \frac{1}{2} m_1 v_1'^2 + k \left(\frac{m_2}{m_1 + m_2} \right)^2 / \left(\frac{m_2}{m_1 + m_2} \cdot c \right)$$

$$\frac{1}{2} m_1 v_1'^2 = \frac{1}{2} m_1 v_1^2 + k \left(\frac{m_1 + m_2}{m_2} \right) / c$$

$$v_1' = \frac{v_1 d}{c}$$

代入并整理

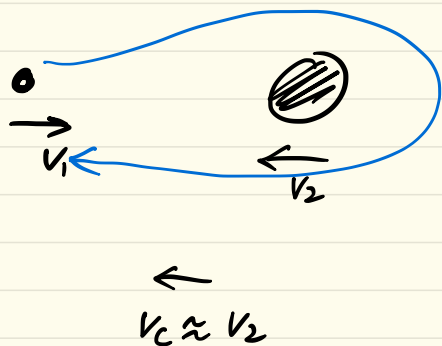
$$\frac{1}{2} m_1 v_1'^2 = \frac{1}{2} m_1 \frac{v_1^2 d^2}{c^2} + k \left(\frac{m_1 + m_2}{m_2} \right) / c$$

$$\frac{1}{2} m_1 v_1'^2 c^2 - k \left(\frac{m_1 + m_2}{m_2} \right) c - \frac{1}{2} m_1 v_1^2 d^2 = 0$$

$$c = \frac{k \left(\frac{m_1 + m_2}{m_2} \right) \pm \sqrt{k^2 \left(\frac{m_1 + m_2}{m_2} \right)^2 + m_1^2 v_1^4 d^2}}{m_1 v_1^2}$$

c 恒为正, 故取 "+" 号。

弹3效应



质心静止参考系下.

地球速率 $v_1 + v_2$

如弹性碰撞. 后速率 $v_1 + v_2$
但方向相反.

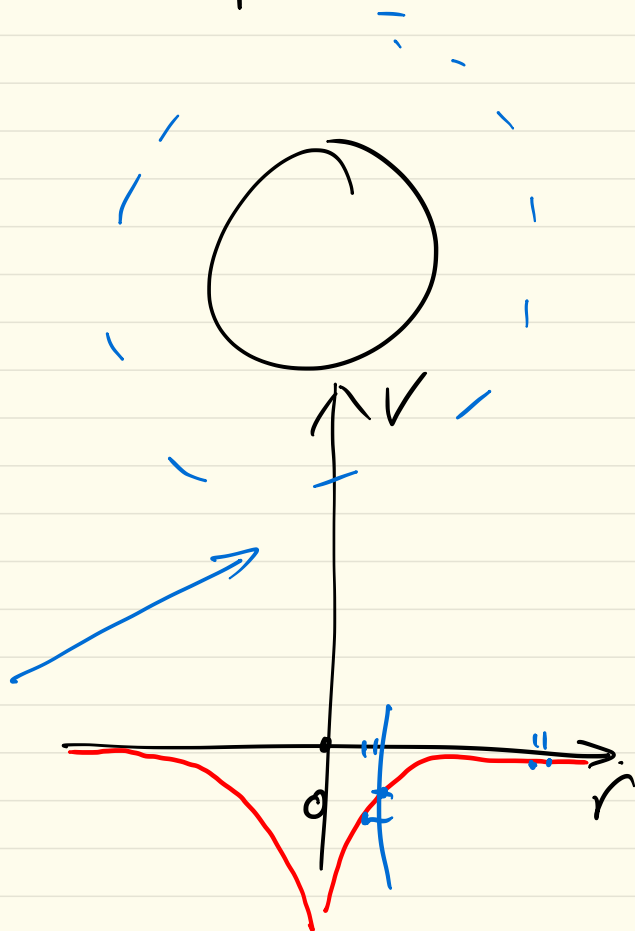
$$v_1 + v_2 + v_2 = v_1 + 2v_2$$

静止参考系下.

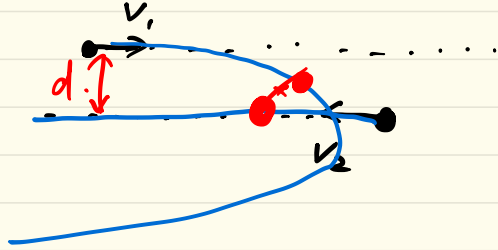
地球 $v_1 \rightarrow v_1 + 2v_2$

洛希极限.

$$V = - \frac{G m_0}{r}$$



$\vec{r}_i: C$



$$m_J \gg m_\oplus$$

$$y < \frac{\lambda t}{g}$$

$$\frac{d[(m - \lambda t) \cdot V]}{dt} + \lambda \cdot (V - u_0) = -(m - \lambda t)g$$

$$m \frac{dV}{dt} - \frac{d(\lambda t \cdot V)}{dt} + \lambda V - \lambda u_0 = (m - \lambda t)g$$

$$m \frac{dV}{dt} - \cancel{\lambda V} - \lambda t \frac{dV}{dt} + \cancel{\lambda V} - \lambda u_0 = (m - \lambda t)g$$

$$\frac{dV}{dt} = \frac{\lambda u_0 + (m - \lambda t)g}{m - \lambda t}$$

$$\text{积分得 } V = \dots$$