Sejal Sanas

Task - 4

```
In [1]: import warnings
        warnings.filterwarnings('ignore')
        import keras
        import matplotlib.pyplot as plt # for plotting
        import os # provides a way of using operating system dependent functionality
        import cv2 #Image handling library
        import numpy as np
In [2]: from keras.layers import Conv2D, Activation, MaxPool2D, Dense, Flatten, Dropout
In [3]:
        CATEGORIES = ["01_palm", '02_l','03_fist','04_fist_moved','05_thumb','06_index','07_ok','08_palm_moved
        IMG_SIZE = 50
        # paths for dataset
        data_path = "C:/Users/Shejal Sanas/Downloads/archive/leapGestRecog/leapGestRecog"
In [4]: image_data = []
        for dr in os.listdir(data_path):
            for category in CATEGORIES:
                class_index = CATEGORIES.index(category)
                path = os.path.join(data_path, dr, category)
                for img in os.listdir(path):
                    try:
                         img_arr = cv2.imread(os.path.join(path, img), cv2.IMREAD_GRAYSCALE)
                         image_data.append([cv2.resize(img_arr, (IMG_SIZE, IMG_SIZE)), class_index])
                    except Exception as e:
                         pass
        image_data[0]
Out[4]: [array([[5, 4, 4, ..., 3, 4, 2],
                [5, 4, 5, \ldots, 3, 3, 3],
                [4, 5, 4, \ldots, 4, 5, 3],
                 [4, 5, 5, \ldots, 5, 5, 5],
                [5, 5, 6, \ldots, 5, 7, 4],
                [4, 7, 5, ..., 5, 4, 4]], dtype=uint8),
         0]
In [5]: import random
        random.shuffle(image_data)
In [6]: |input_data = []
        label = []
        for X, y in image_data:
            input_data.append(X)
            label.append(y)
In [7]: |label[:10]
```

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Out[7]: [9, 1, 3, 7, 5, 7, 6, 4, 0, 9]

```
In [8]: plt.figure(1, figsize=(10,10))
for i in range(1,10):
    plt.subplot(3,3,i)
    plt.imshow(image_data[i][0], cmap='hot')
    plt.xticks([])
    plt.yticks([])
    plt.title(CATEGORIES[label[i]][3:])
plt.show()
```

```
fist_moved
  I
                                                        palm_moved
index
                           palm_moved
                                                             ok
thumb
                                                            down
                              palm
```

```
In [9]: # Normalizing the data
         input_data = np.array(input_data)
         label = np.array(label)
         input_data = input_data/255.0
         input_data.shape
Out[9]: (20000, 50, 50)
In [10]:
         label = keras.utils.to_categorical(label, num_classes=10)
         label[0]
Out[10]: array([0., 0., 0., 0., 0., 0., 0., 0., 1.])
In [11]: # reshaping the data
         input_data.shape = (-1, IMG_SIZE, IMG_SIZE, 1)
In [12]:
         # splitting the input_data to train and test data
         from sklearn.model_selection import train_test_split
         X_train, X_test, y_train, y_test = train_test_split(input_data, label, test_size = 0.3, random_state=0
```

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```
In [13]: model = keras.models.Sequential()
         model.add(Conv2D(filters = 32, kernel_size = (3,3), input_shape = (IMG_SIZE, IMG_SIZE, 1)))
         model.add(Activation('relu'))
         model.add(Conv2D(filters = 32, kernel_size = (3,3)))
         model.add(Activation('relu'))
         model.add(MaxPool2D(pool_size=(2,2)))
         model.add(Dropout(0.3))
         model.add(Conv2D(filters = 64, kernel_size = (3,3)))
         model.add(Activation('relu'))
         model.add(MaxPool2D(pool_size=(2,2)))
         model.add(Dropout(0.3))
         model.add(Flatten())
         model.add(Dense(256, activation='relu'))
         model.add(Dense(10, activation='softmax'))
         model.compile(loss='categorical_crossentropy',
                      optimizer = 'rmsprop',
                      metrics = ['accuracy'])
```

In [14]: | model.fit(X_train, y_train, epochs = 7, batch_size=32, validation_data=(X_test, y_test)) Epoch 1/7 438/438 -- 42s 89ms/step - accuracy: 0.6738 - loss: 0.9456 - val_accuracy: 0.9968 val_loss: 0.0132 Epoch 2/7 438/438 - 38s 88ms/step - accuracy: 0.9934 - loss: 0.0251 - val_accuracy: 0.9987 val_loss: 0.0041 Epoch 3/7 438/438 -- 39s 88ms/step - accuracy: 0.9964 - loss: 0.0116 - val_accuracy: 0.9992 val_loss: 0.0024 Epoch 4/7 438/438 -**- 40s** 91ms/step - accuracy: 0.9980 - loss: 0.0065 - val_accuracy: 0.9992 val loss: 0.0032 Epoch 5/7 438/438 - **42s** 97ms/step - accuracy: 0.9990 - loss: 0.0059 - val_accuracy: 0.9987 val_loss: 0.0070 Epoch 6/7 438/438 **43s** 99ms/step - accuracy: 0.9985 - loss: 0.0035 - val_accuracy: 0.9997 val_loss: 0.0032 Epoch 7/7 438/438 -**40s** 92ms/step - accuracy: 0.9990 - loss: 0.0027 - val_accuracy: 0.9993 val_loss: 0.0016

Out[14]: <keras.src.callbacks.history.History at 0x1fd63da5b50>

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In [15]: model.summary()

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 48, 48, 32)	320
activation (Activation)	(None, 48, 48, 32)	0
conv2d_1 (Conv2D)	(None, 46, 46, 32)	9,248
activation_1 (Activation)	(None, 46, 46, 32)	0
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 23, 23, 32)	0
dropout (Dropout)	(None, 23, 23, 32)	0
conv2d_2 (Conv2D)	(None, 21, 21, 64)	18,496
activation_2 (Activation)	(None, 21, 21, 64)	0
<pre>max_pooling2d_1 (MaxPooling2D)</pre>	(None, 10, 10, 64)	0
dropout_1 (Dropout)	(None, 10, 10, 64)	0
flatten (Flatten)	(None, 6400)	0
dense (Dense)	(None, 256)	1,638,656
dense_1 (Dense)	(None, 10)	2,570

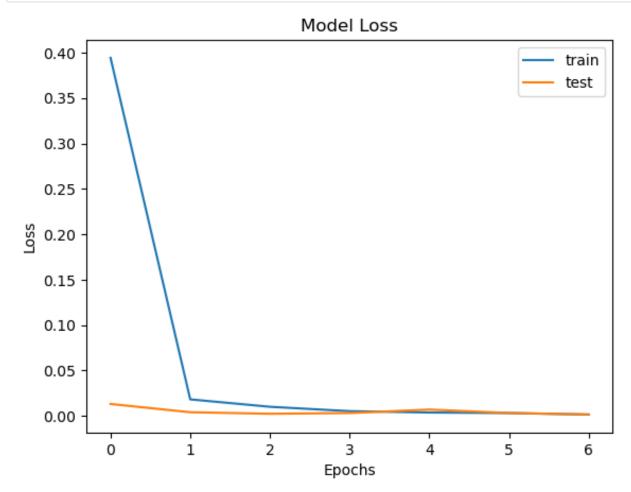
```
Total params: 3,338,582 (12.74 MB)

Trainable params: 1,669,290 (6.37 MB)

Non-trainable params: 0 (0.00 B)

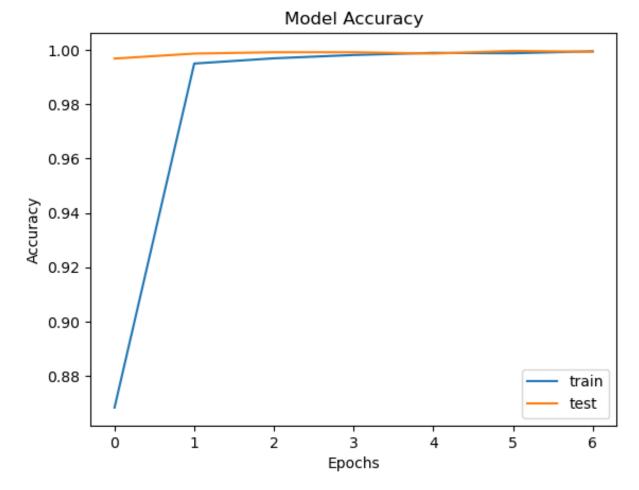
Optimizer params: 1,669,292 (6.37 MB)
```

```
In [16]: plt.plot(model.history.history['loss'])
    plt.plot(model.history.history['val_loss'])
    plt.title('Model Loss')
    plt.ylabel('Loss')
    plt.xlabel('Epochs')
    plt.legend(['train', 'test'])
    plt.show()
```



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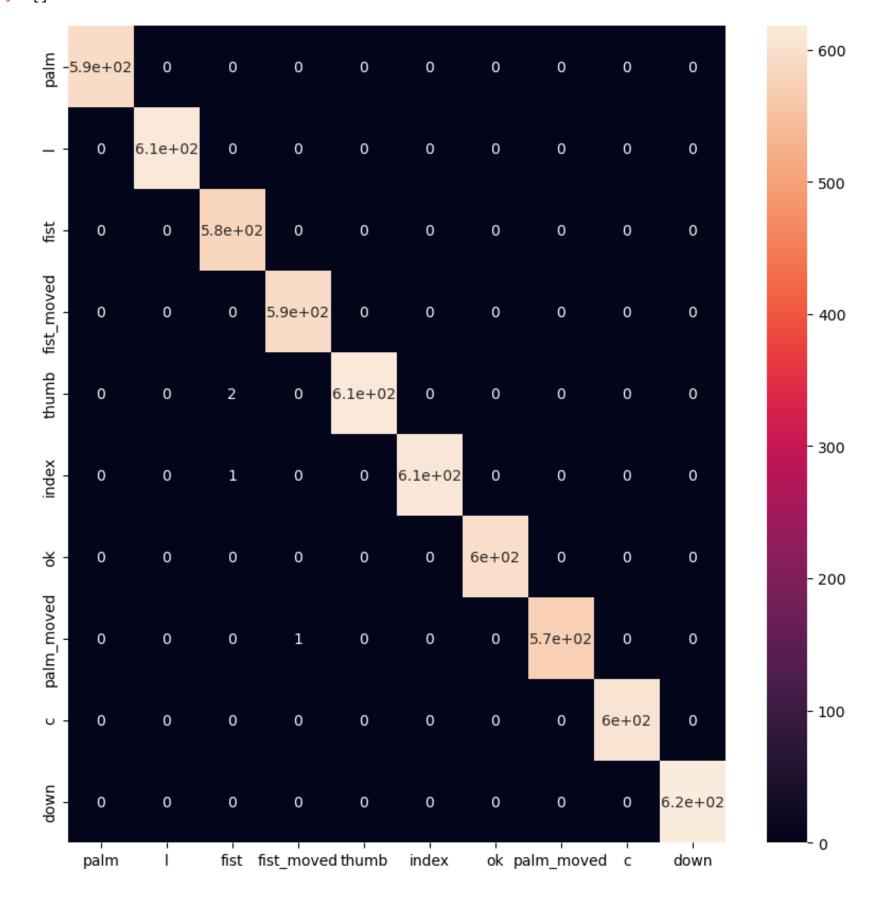
```
In [17]: plt.plot(model.history.history['accuracy'])
    plt.plot(model.history.history['val_accuracy'])
    plt.title('Model Accuracy')
    plt.ylabel('Accuracy')
    plt.xlabel('Epochs')
    plt.legend(['train', 'test'])
    plt.show()
```



Test accuracy: 99.93%

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Out[19]: []



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