ETH

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Task-Aware-Downscaling
Improving Super Resolution and Colorization
in Image and Video Domain

Semester Project

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Abstract

The abstract gives a concise overview of the work you have done. The reader shall be able to decide whether the work which has been done is interesting for him by reading the abstract. Provide a brief account on the following questions:

- What is the problem you worked on? (Introduction)

- How did you tackle the problem? (Materials and Methods)

- What were your results and findings? (Results)

- Why are your findings significant? (Conclusion)

The abstract should approximately cover half of a page, and does generally not contain citations.

Acknowledgements

Contents

List of Figures

1   Introduction

With the rise of deep learning in image processing super-resolution (SR) and image colorization (IC) in both the image and the video domain have received significant attention [20]. While SR aims to reconstruct a high-resolution (HR) image from a low-resolution (LR) image, image colorization deals with the transformation from an uncolored, grayscale (GR) image to a RGB colored (COL) image. However, in most of the recent works (e.g. [19], [18], [8], [17]) the problem of downscaling and upscaling or decolorization and colorization are regarded as seperate problems although upscaling often is preceded by downscaling, leading to a loss of information from the downscaling process which makes the inverse problem of SR highly ill-posed [9]. Despite of the large progress in SR in the last years ([20]) very specific details therefore often cannot be reconstructed, when interpolation is used for downsampling. However, as shown in Fig. 1 the downsampling method has a large impact on the performance of the subsequent upscaling task.

Figure 1: Comparison between an upscaled image based on bicubic downsampled (left) and task-aware downsampled (right) LR image applied on the same model with upscaling factor 4, for the image-domain, SET 14 dataset, and video domain, CALENDAR dataset.

As can be seen above a task-aware approach can dramatically improve the performance of existing super-resolution models. However, the research on task-aware downscaling methods is a very new field and therefore there still are a lot of unresolved issues such as the effect of noise or the feasibility of applying it in other domains.

1.1   Focus of this Work

For this reason this work focuses on Task-Aware-Downscaling (TAD) for several standard computer vision problems such as super-resolution or colorization in both the image and video domain, as recently purposed by Heewon Kim et. alt. ([9]) for the image domain only. Therefore the goals of this work are the following

- reimplement and evaluate the TAD framework purposed in ([9])

- improve the TAD framework especially with regards on accuracy (PSNR) and speed in the image domain

- evaluate the effect of external effects such as noise on the TAD framework

- extend the TAD framework to the video domain

By that to the best of our knowledge this work is the first one using deep learning for downscaling in the video domain.

1.2   Thesis Organization

After the problem statement Chapter 1 related works are introduced for both the image and video domain Chapter 2. Chapter 3 explains the methods that are used in order to achieve the goals described above and which are evaluated in Chapter 4. A final discussion of the results as well as an outlook on further work can be found in Chapter 5 and Chapter 6. Further visualization and experiments are shown in the abstract.

2 Related Work

In the following previous work in super-resolution, colorization and task-aware-downscaling are presented. At the end of each section the models used for comparison and evaluation of the the underlying approach are further explained in detail. Thereby the models were selected based on several criterias performance compared to the state-of-the-art, the use as benchmark in related papers and availability of (pretrained) models.

2.1 Super-Resolution in Image Domain

The problem of SR in the image domain is called Single-Image-Super-Resolution (SISR) and is shown in Fig. 2. A lot of approaches have been tried in order to cope with the SISR problem. While early approaches such as bicubic and Lanczos [5] tackle the problem using simple deterministic filters which are computational cheap but produce blurry results and lack in high frequency details, more recent approaches approach the problem using example-based methods such as sparse encoding or deep learning methods.
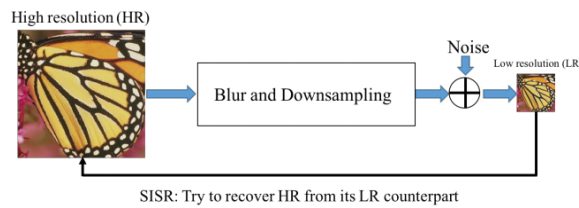

Figure 2: General SISR problem according to [22].

Sparsity-based techniques assumes the LR image to be transformable in another domain (usually a dictionary of image atoms [6]) and tries to find correspondences between the LR and HR patches in the transformed space, as implemented in [4]. However, these techniques usually are very computationally expensive. Among other learning based approaches such as the use of random forests [14], in-place example regression models [21] or adjusted anchored neighborhood regression [16], in terms of accuracy applying CNN based approaches have shown the largest success. [1] Dong et al. [2] trained a shallow CNN end-to-end to build the HR image based on a bicubicly upscaled LR image. This approach was improved by Kim et al. [10] (VDSR) using a deeper network (20 layers) and cascading small filters many times in a deep network structure to exploit contextual

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[1]An overview of various other deep learning based approaches for SISR can be found in [22].

information over large image regions in an efficient way. By advancing the network model VDSR was further improved by Lim et al. [11] which got the best results in the NTIRE2017 Super-Resolution Challenge [1].
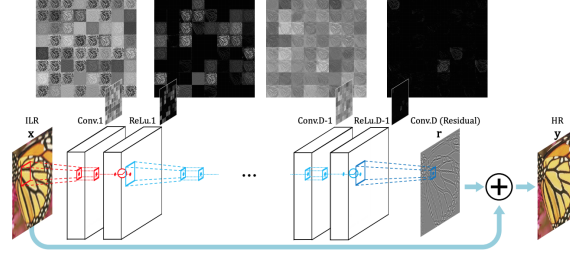

Figure 3: Overview of VDSR network design [10].

2.2   Super-Resolution in Video Domain

Video Super-Resolution combines information from multiple adjacent LR frames to take temporal information into account, leading to higher quality results. Takeda et al. [15] apply a 3D kernel regression on a patch of adjacent LR frames to implicitly encounter temporal information. Since purposed by Caballero et al. [3] end-to-end approaches including motion compensation such as the CNN framework from [3] have large success in the VSR area. Liu et al. [12] added temporal addaptivity to the framework to be able to aggregate the resulting HR frame based on a weighted sum of several estimates as well as a varying number of input LR frames. Sajjadi et al. [13] purposed a frame-recurrent architecture iteratively using the previously inferred HR frames for the subsequent prediction. Wang et al. [17] (SOFVSR) implemented an end-to-end trainable approach to predict both, the HR frame as well as the HR optical flow. Therefore, first the HR optical flow is inferred in a coarse-to-fine manner, then motion compensation is performed according to the HR optical flows and finally, the compensated LR inputs are fed to a super-resolution network to generate the HR frame estimate (comp. Fig. 4).
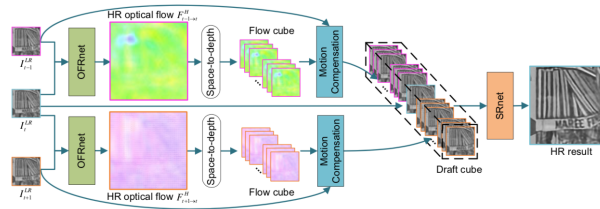

Figure 4: Overview of SOFVSR pipeline [17].

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2.3 Colorization

Image colorization methods can be categorized in two categories: Non-parametric approaches, such as [7], model the correspondence between the grayscale and the colored image by finding analogeous regions in reference image(s), while parameteric models learns this correspondence from large datasets, transforming the colorization problem into a regression problem. Zhang et al. [23] (CIC) purpose posing colorization as a classification task and use class-rebalancing at training time to increase the diversity of colors in the result, using the CNN shown in Fig. 5 and not requiring any user-interaction.
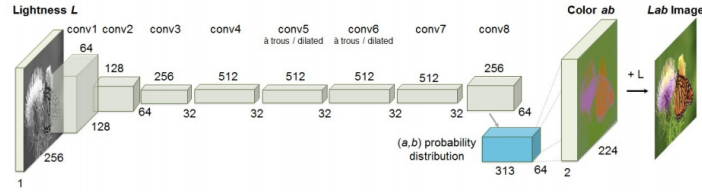

Figure 5: Overview of CIC network design [23].

2.4 Task-Aware-Downscaling

Over all of the problems stated above most of the approaches merely take into account one side of the process, e.g. by fixing the transformation HR to LR to bicubic interpolation in order to large amount of training data and focusing on estimating the inverse transformation. Kim et al. [9] (TAID) purpose taking into account the downscaling method in order to improve the upscaling performance, by training an autoencoder in an end-to-end manner while the latent space representation again is an image of same size as the LR image. The loss function thereby contains both the difference between the decoded SHR and the original HR image as well as the difference between the encoded SLR and the bicubic interpolated LR image, such that the SLR image is a humanly understandable representation. Next to SISR the approach is shown to be applicable for large scale factor up to 128 as well as for colorization.
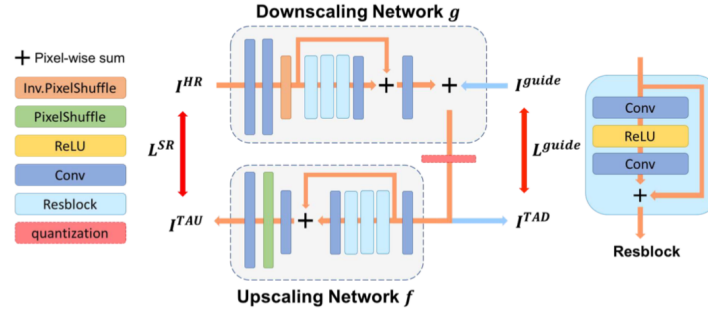
3   Approach

Figure 6: Overview of TAID autoencoder network design [9].

4   Experiments and Results

- PSNR for different scales

- Noise vs performance

- time vs network size

- colorization, video sr, image sr

- approaches of video scaling, i.e. flow, direct external

5   Discussion

6   Conclusion

List the conclusions of your work and give evidence for these. Often, the discussion and the conclusion sections are fused.

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A   Appendix

In the appendix, list the following material:

- Data (evaluation tables, graphs etc.)

- Program code

- Further material