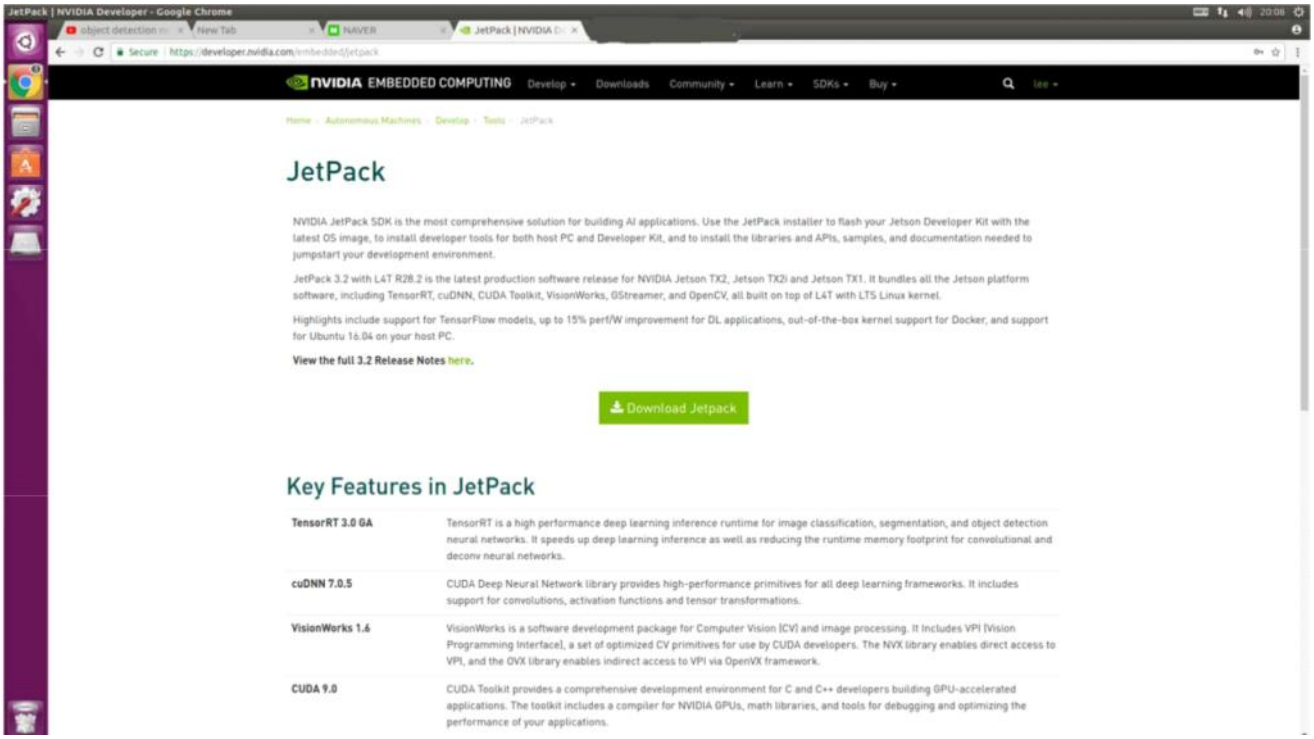
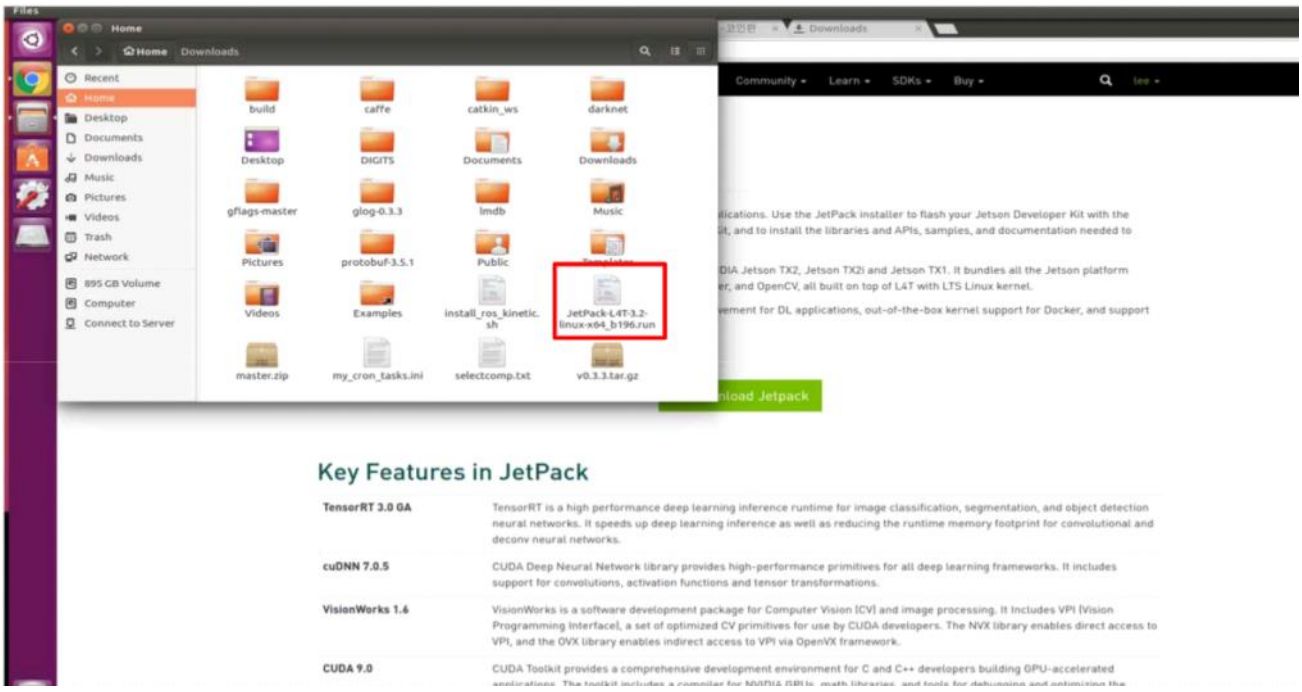
Jetpack 설치

Wednesday, August 15, 2018 9:18 AM

- 설치용 노트북 환경 : 우분투 16.04
- 사이트 가입 및 최종버번 다운받는다
  - https://developer.nvidia.com/embedded/jetpack



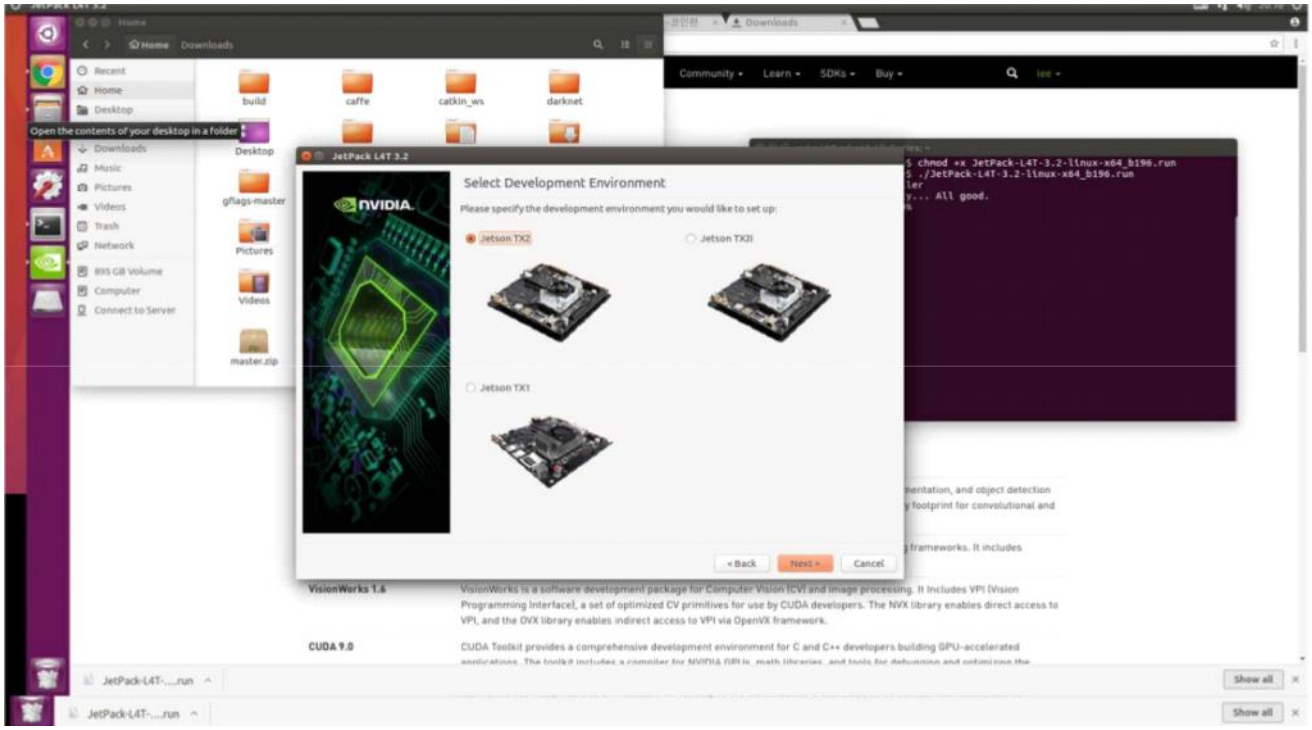
- $CD 다운받은폴더



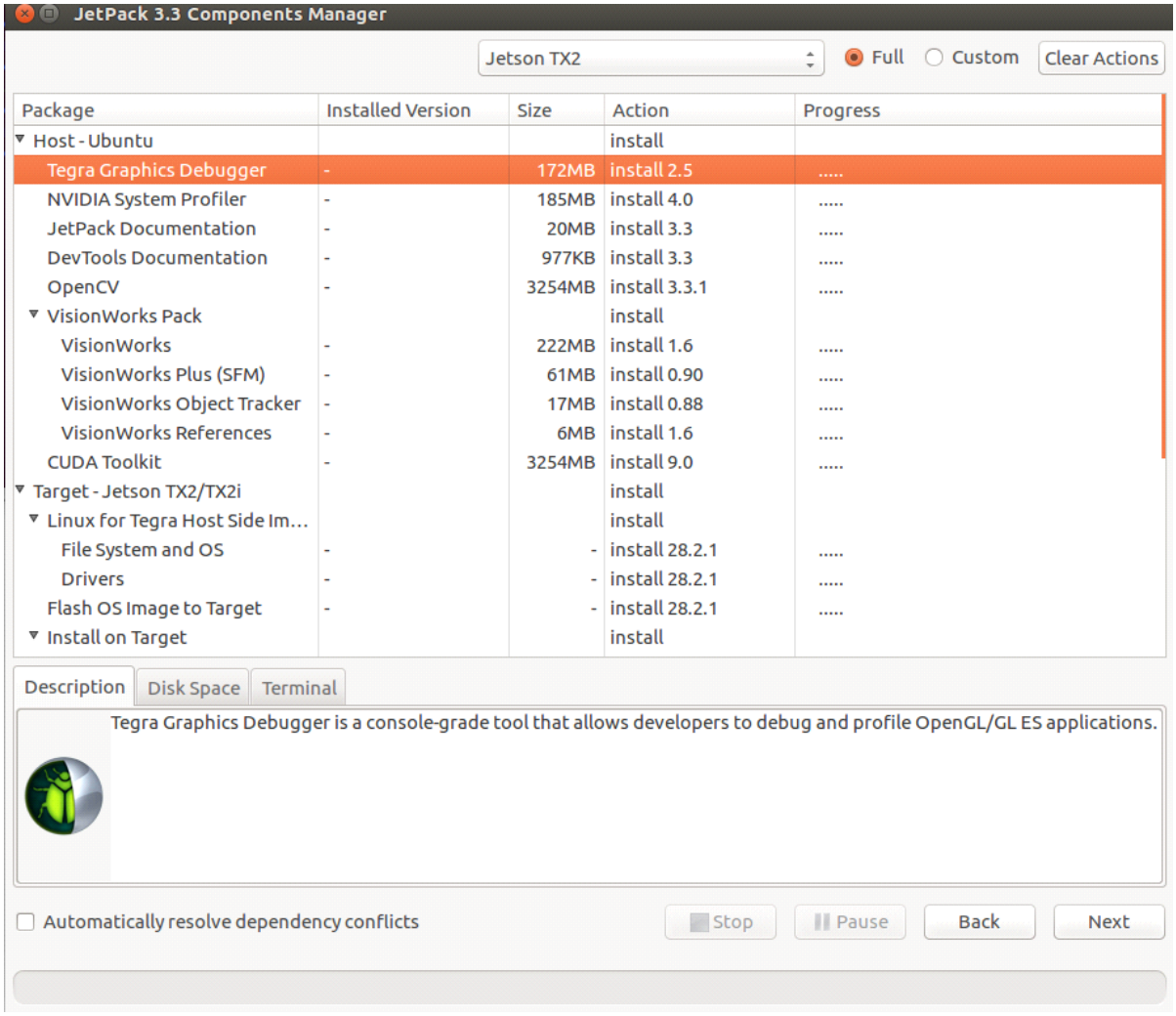
- $chmod +x JetPack이름.run ==> 실행권한 부여

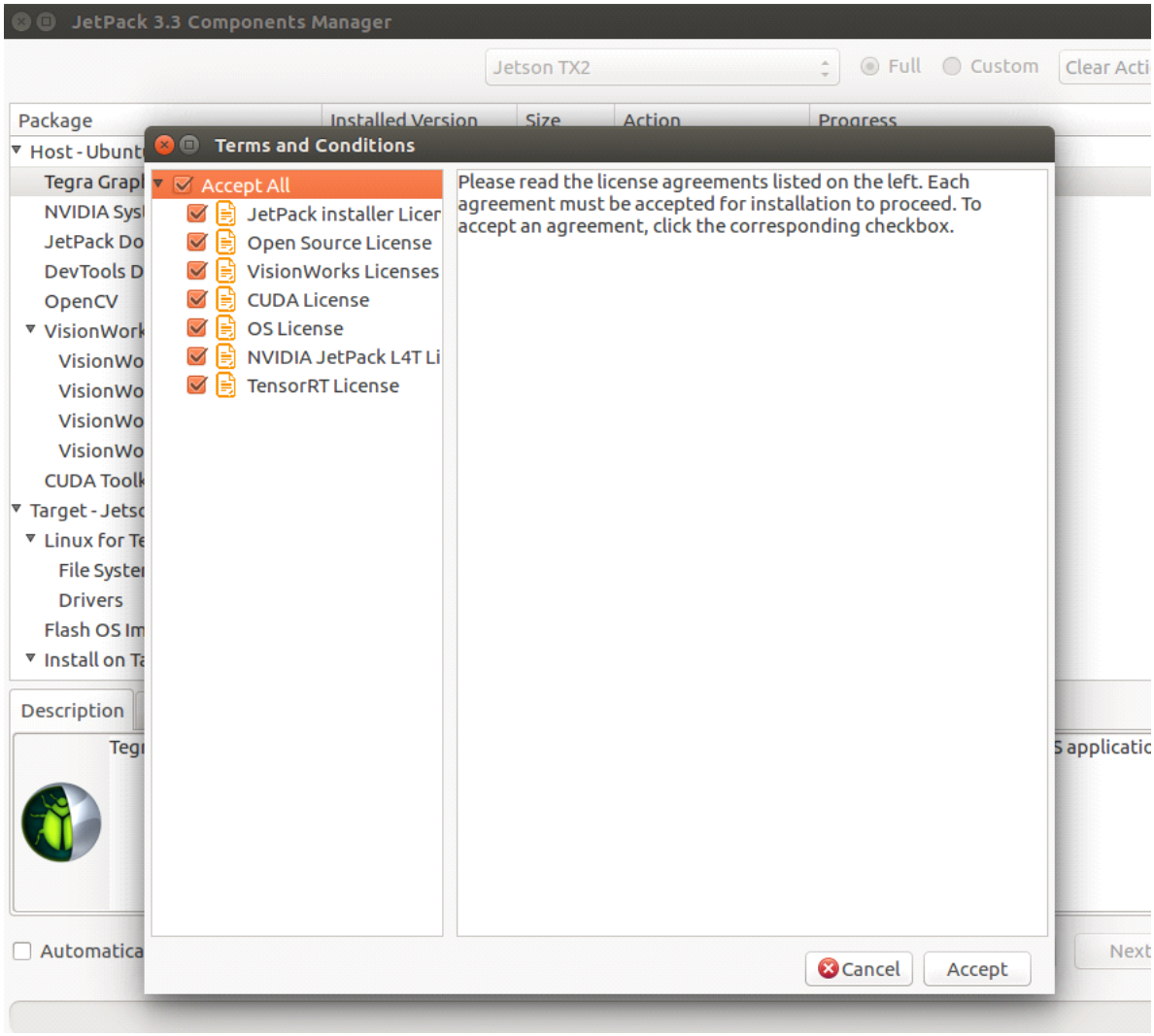
- $./JetPack이름.run ==> 실행

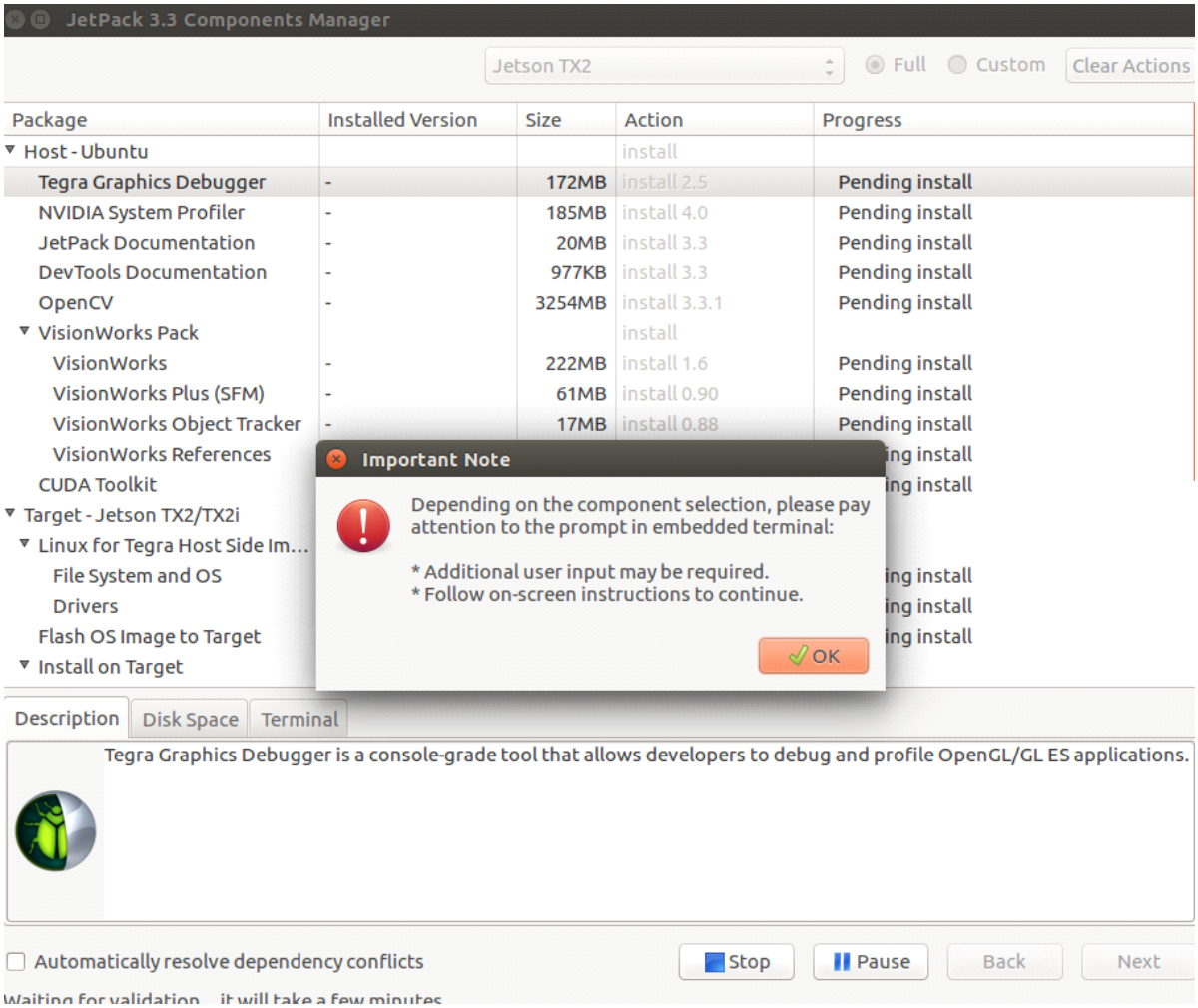
- 자신의 Jetson 보드에 맞게 선택



- 진행중 화면


JetPack 3.3 Components Manager
Jetson TX2
Full
Custom
Clear Actions
Package
Installed Version
Size
Action
Progress
Host - Ubuntu
install
Tegra Graphics Debugger
-
172MB
install 2.5
.....
NVIDIA System Profiler
-
185MB
install 4.0
.....
JetPack Documentation
-
20MB
install 3.3
.....
DevTools Documentation
-
977KB
install 3.3
.....
OpenCV
-
3254MB
install 3.3.1
.....
VisionWorks Pack
install
VisionWorks
-
222MB
install 1.6
.....
VisionWorks Plus (SFM)
-
61MB
install 0.90
.....
VisionWorks Object Tracker
-
17MB
install 0.88
.....
VisionWorks References
-
6MB
install 1.6
.....
CUDA Toolkit
-
3254MB
install 9.0
.....
Target - Jetson TX2/TX2i
install
Linux for Tegra Host Side Im...
install
File System and OS
-
-
install 28.2.1
.....
Drivers
-
-
install 28.2.1
.....
Flash OS Image to Target
-
-
install 28.2.1
.....
Install on Target
install
Description
Disk Space
Terminal
Tegra Graphics Debugger is a console-grade tool that allows developers to debug and profile OpenGL/GL ES applications.
Automatically resolve dependency conflicts
Stop
Pause
Back
Next


JetPack 3.3 Components Manager
Jetson TX2
Full
Custom
Package
Installed Version
Size
Action
Progress
Terms and Conditions
Accept All
JetPack installer Licer
Open Source License
VisionWorks Licenses
CUDA License
OS License
NVIDIA JetPack L4T Li
TensorRT License
Please read the license agreements listed on the left. Each agreement must be accepted for installation to proceed. To accept an agreement, click the corresponding checkbox.
Description
Cancel
Accept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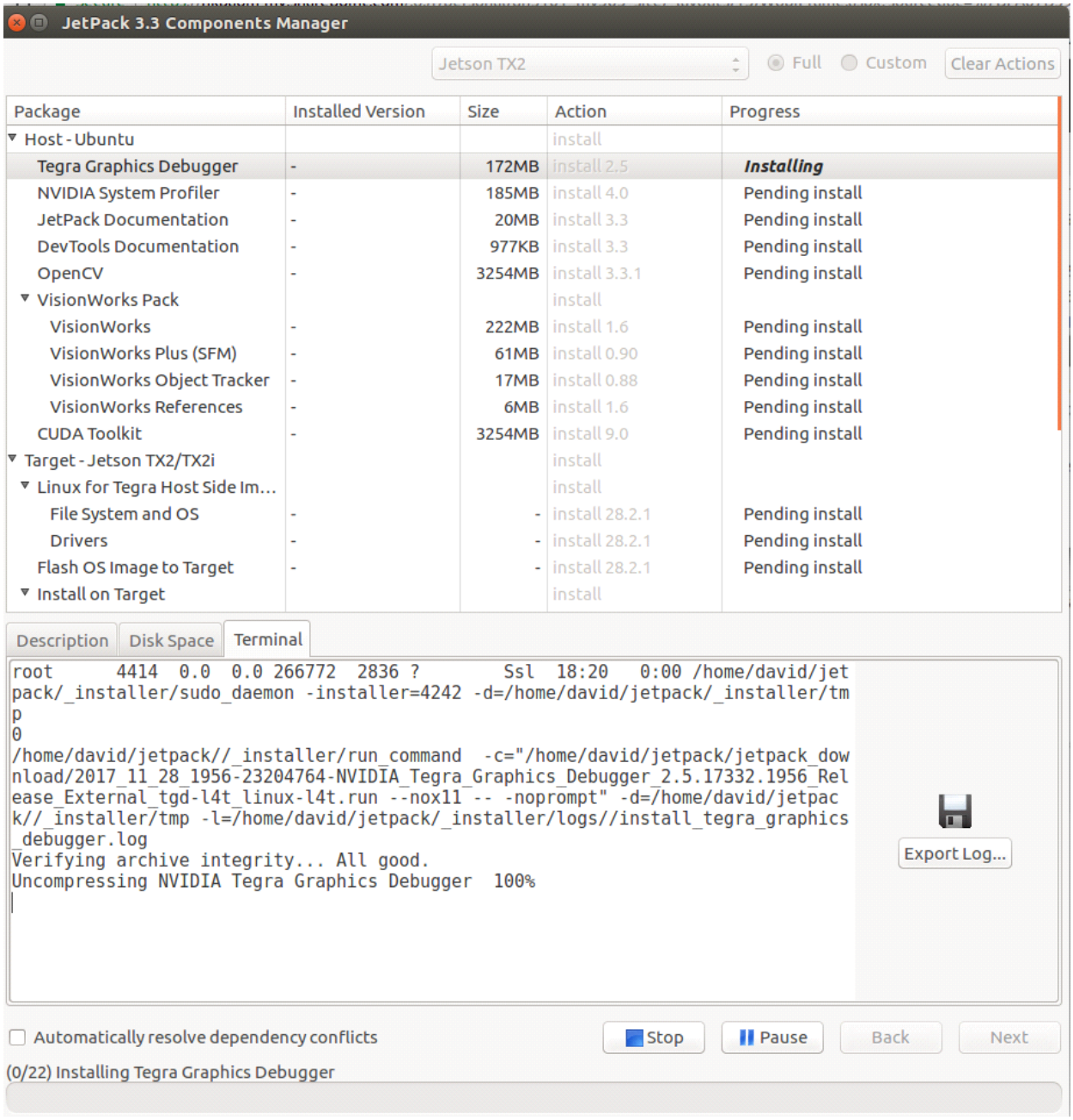
File System and OS
Drivers
Flash OS Image to Target
Install on Target
Important Note
Depending on the component selection, please pay attention to the prompt in embedded terminal:
* Additional user input may be required.
* Follow on-screen instructions to continue.
OK
Description
Disk Space
Terminal
Tegra Graphics Debugger is a console-grade tool that allows developers to debug and profile OpenGL/GL ES applications.
Automatically resolve dependency conflicts
Stop
Pause
Back
Next
Waiting for validation... it will take a few minutes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-
-
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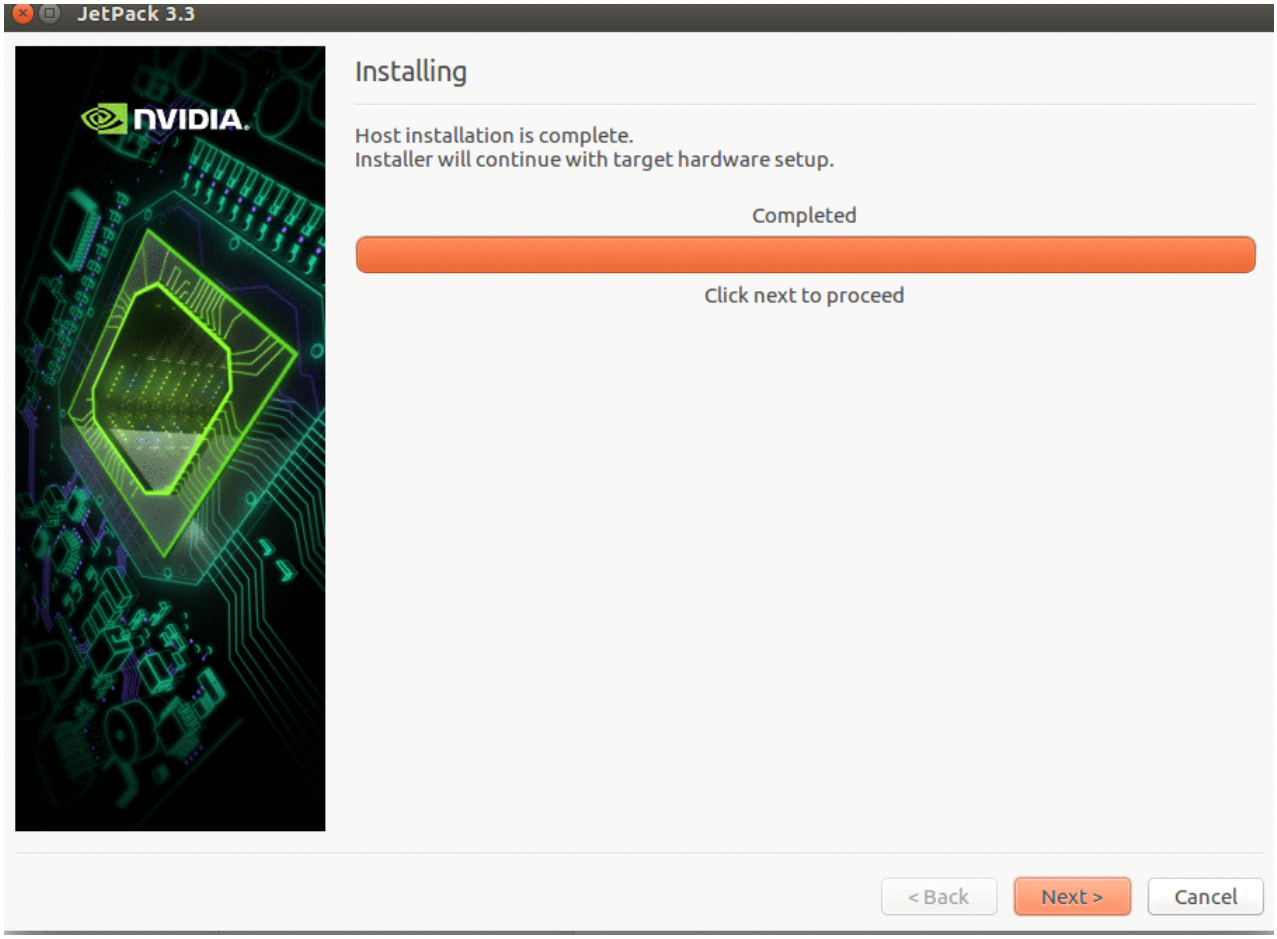
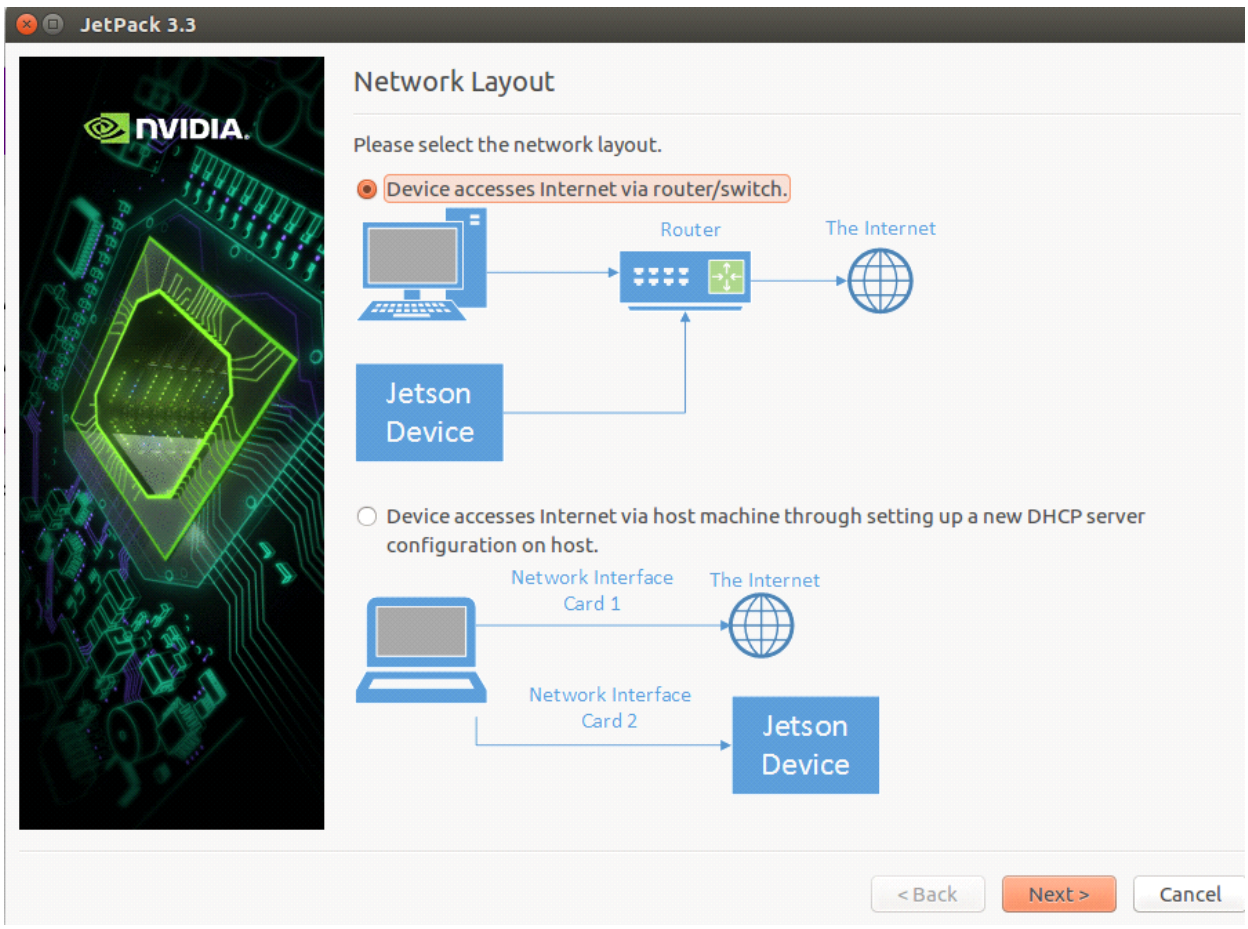
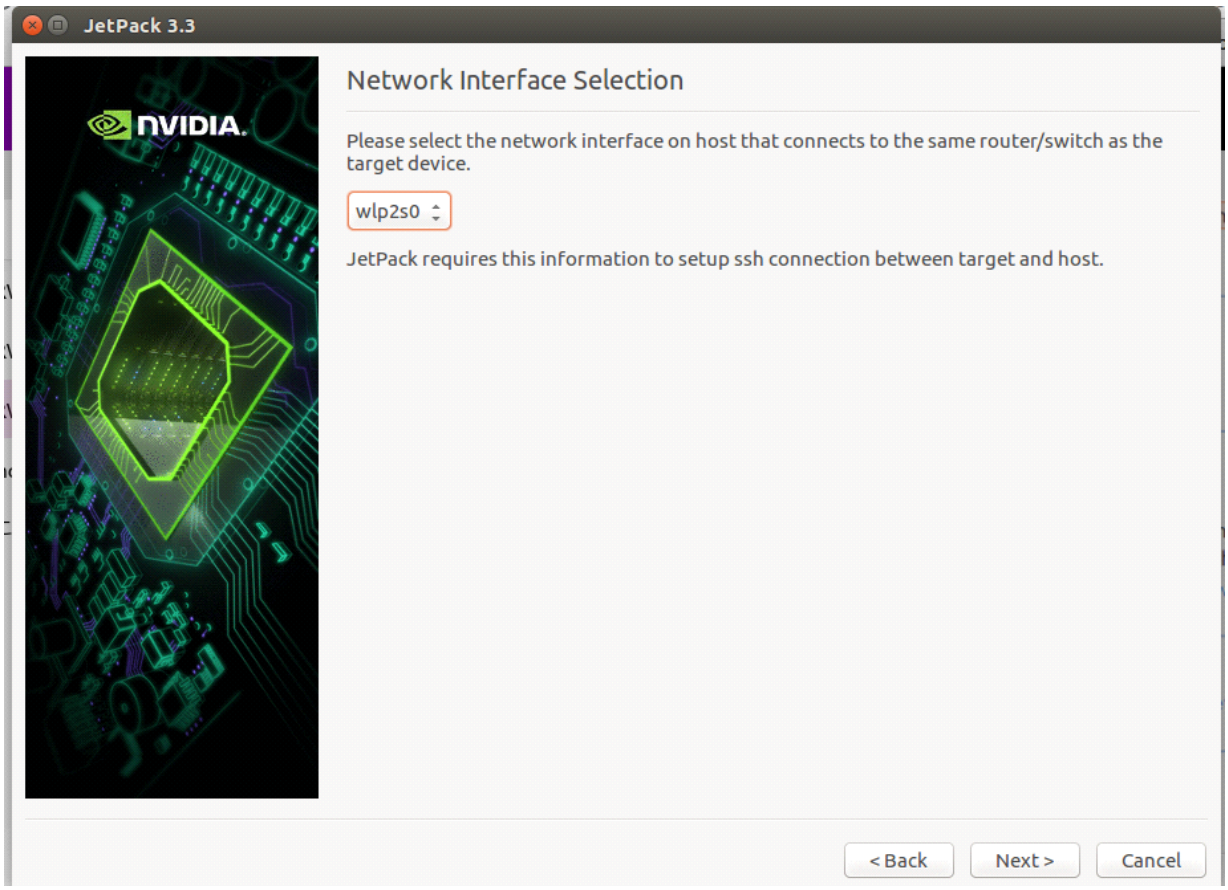
Pending install
Install on Target
install
Description
Disk Space
Terminal
root 4414 0.0 0.0 266772 2836 ? Ssl 18:20 0:00 /home/david/jetpack/_installer/sudo_daemon -installer=4242 -d=/home/david/jetpack/_installer/tmp
0
/home/david/jetpack//_installer/run_command -c="/home/david/jetpack/jetpack_download/2017_11_28_1956-23204764-NVIDIA_Tegra_Graphics_Debugger_2.5.17332.1956_Release_External_tgd-l4t_linux-l4t.run --nox11 -- -noprompt" -d=/home/david/jetpack//_installer/tmp -l=/home/david/jetpack/_installer/logs//install_tegra_graphics_debugger.log
Verifying archive integrity... All good.
Uncompressing NVIDIA Tegra Graphics Debugger 100%
Export Log...
Automatically resolve dependency conflicts
Stop
Pause
Back
Next
(0/22) Installing Tegra Graphics Debugger


JetPack 3.3
NVIDIA.
Installing
Host installation is complete.
Installer will continue with target hardware setup.
Completed
Click next to proceed
< Back
Next >
Cancel

- 네트워 레이아웃 선택


JetPack 3.3
NVIDIA.
Network Layout
Please select the network layout.
Device accesses Internet via router/switch.
Router
The Internet
Jetson Device
Device accesses Internet via host machine through setting up a new DHCP server configuration on host.
Network Interface Card 1
The Internet
Network Interface Card 2
Jetson Device
< Back
Next >
Cancel

- 노트북의 인터넷 연결을 선택한다. 무선으로 선택함 (wire less ==> wlp2s0)



- 하드웨어 준비하기

  1.jetson 의 전원이 꺼져있는 상태로 만든다.

  2. Jetson을 Micro –B Type을 Host Pc와 연결

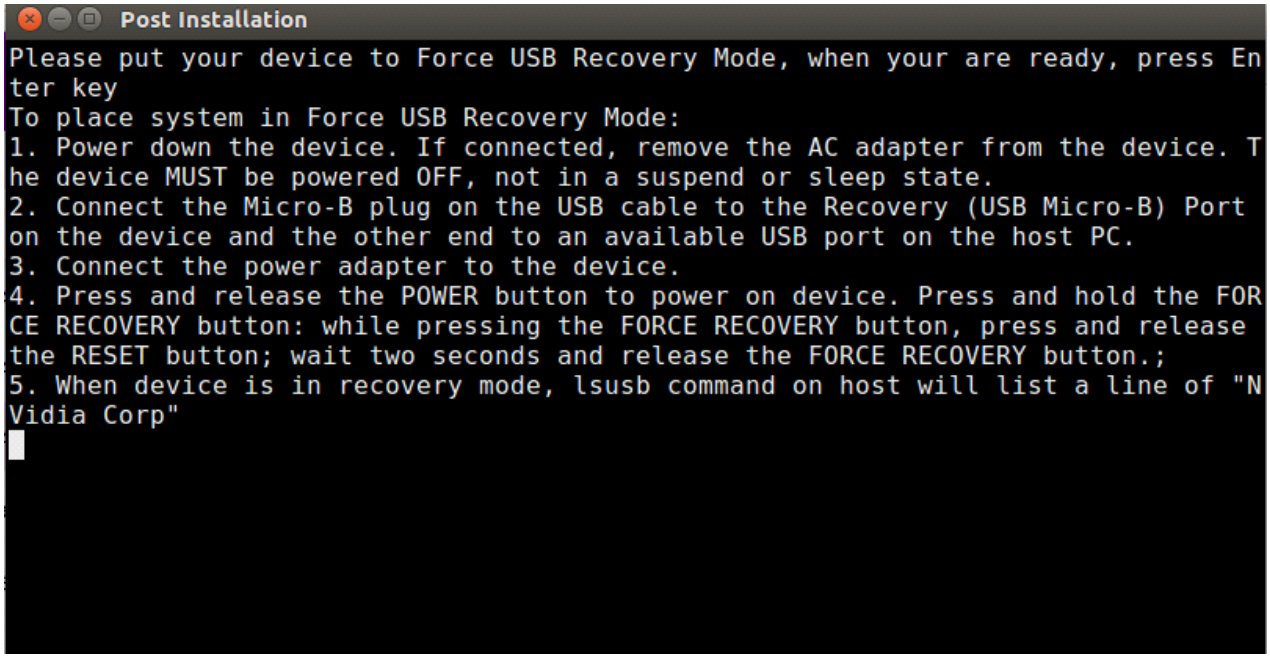
     Host Pc와 같은 Router를 쓰는 유선 랜을 Jetson에도 연결

  3. jetson에 전원을 연결한다

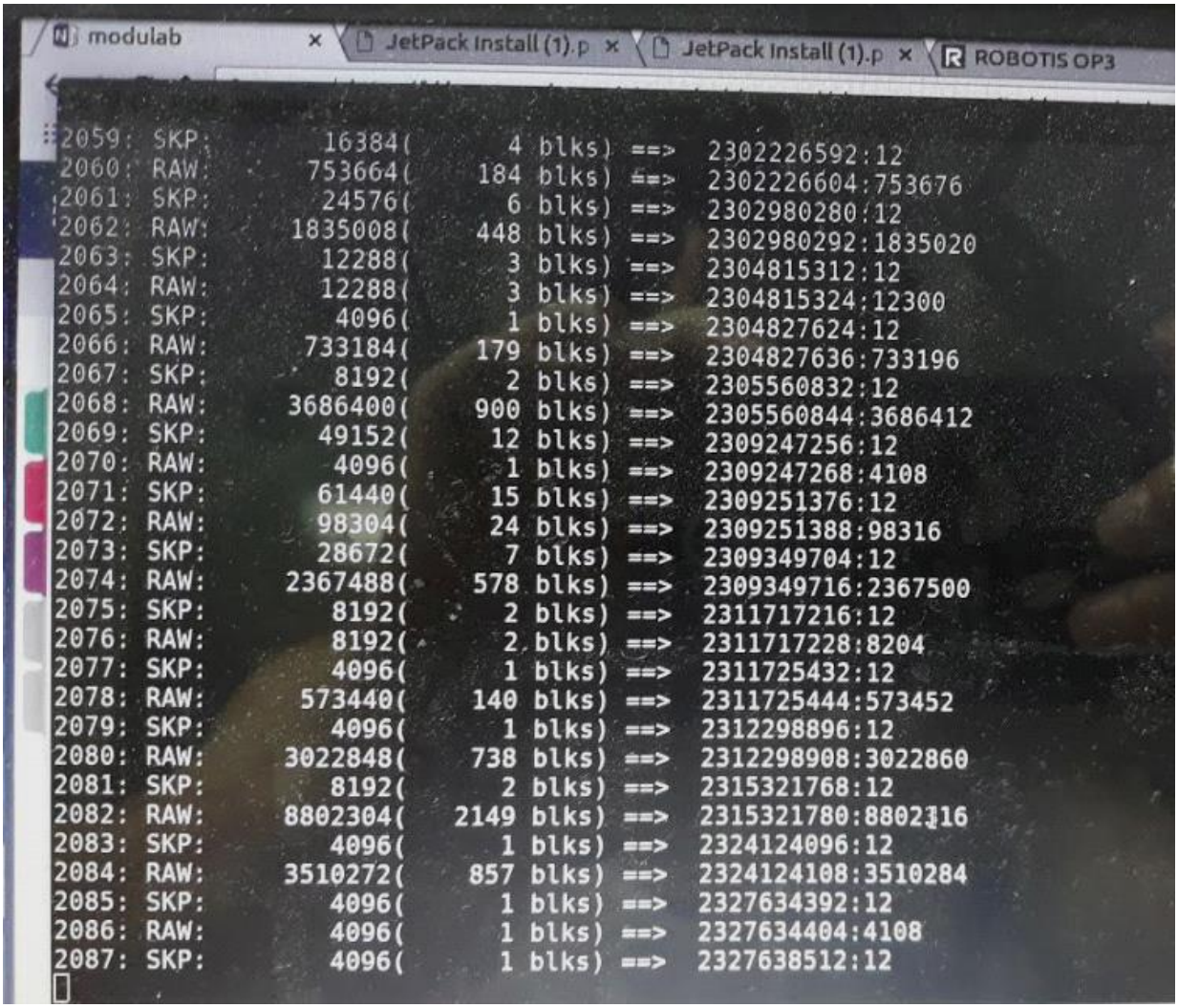
  4. jetson의 power on 한다

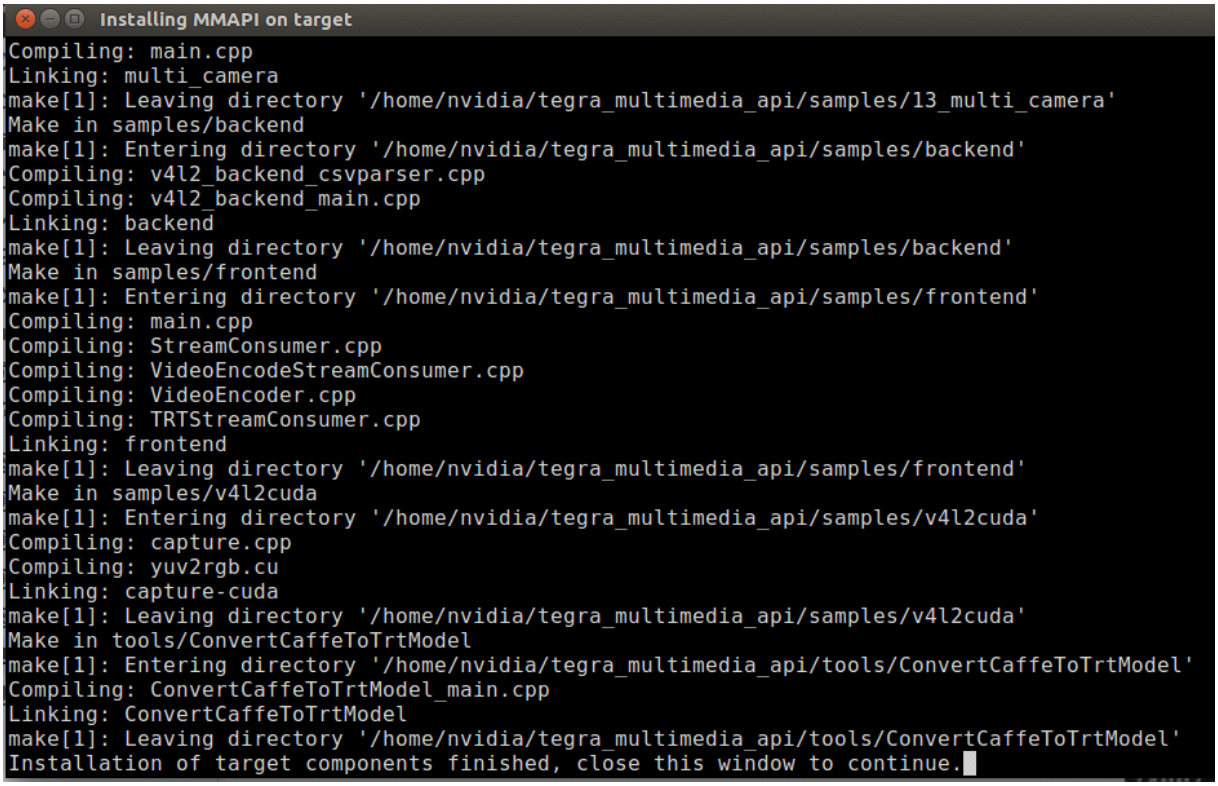
     REC 버튼을 누르면서 RST버튼을 2초간 눌렀다가 뗌

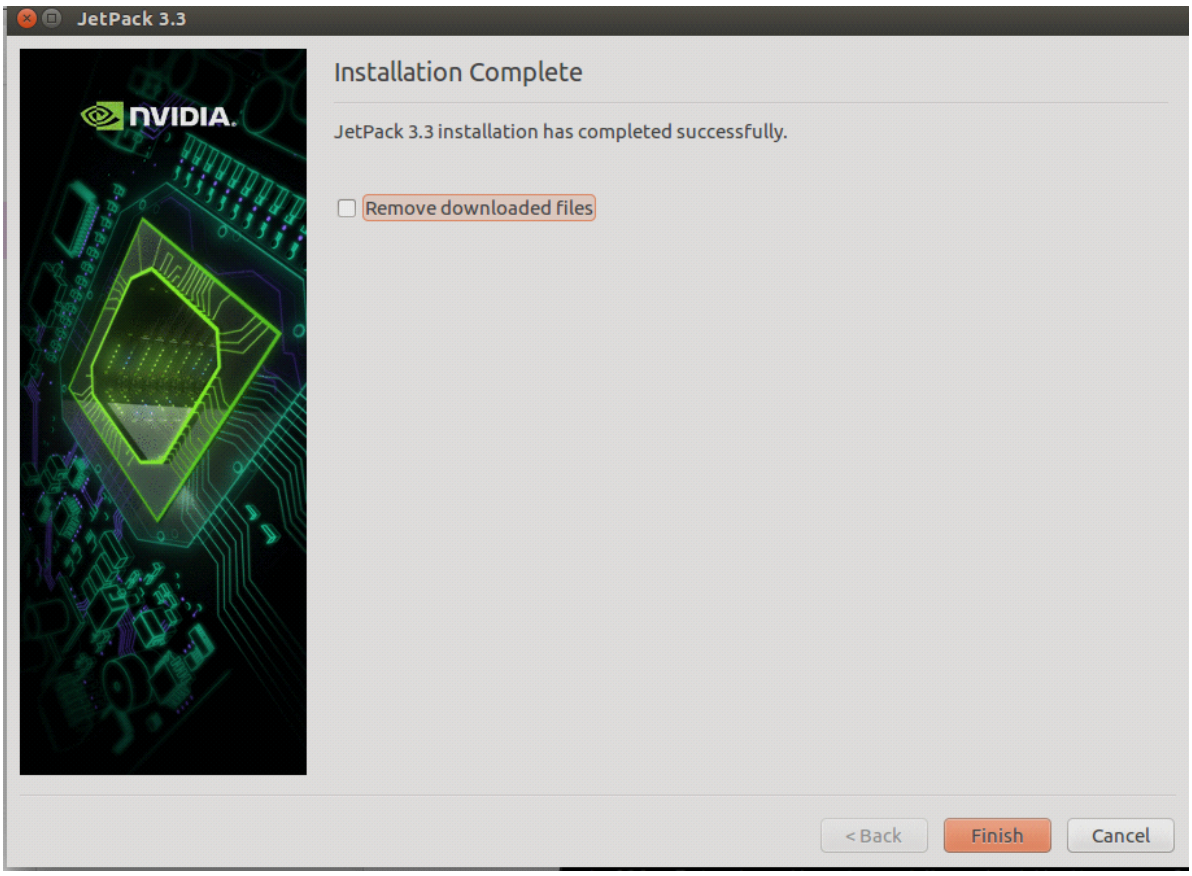
  5. Host Pc로와서 Enter를 눌러준다



- Host pc 에서 enter 후에 약 2분정도 화면이 멈춰있다가, 이후 아래 화면이 나오면서 진행이 됨.

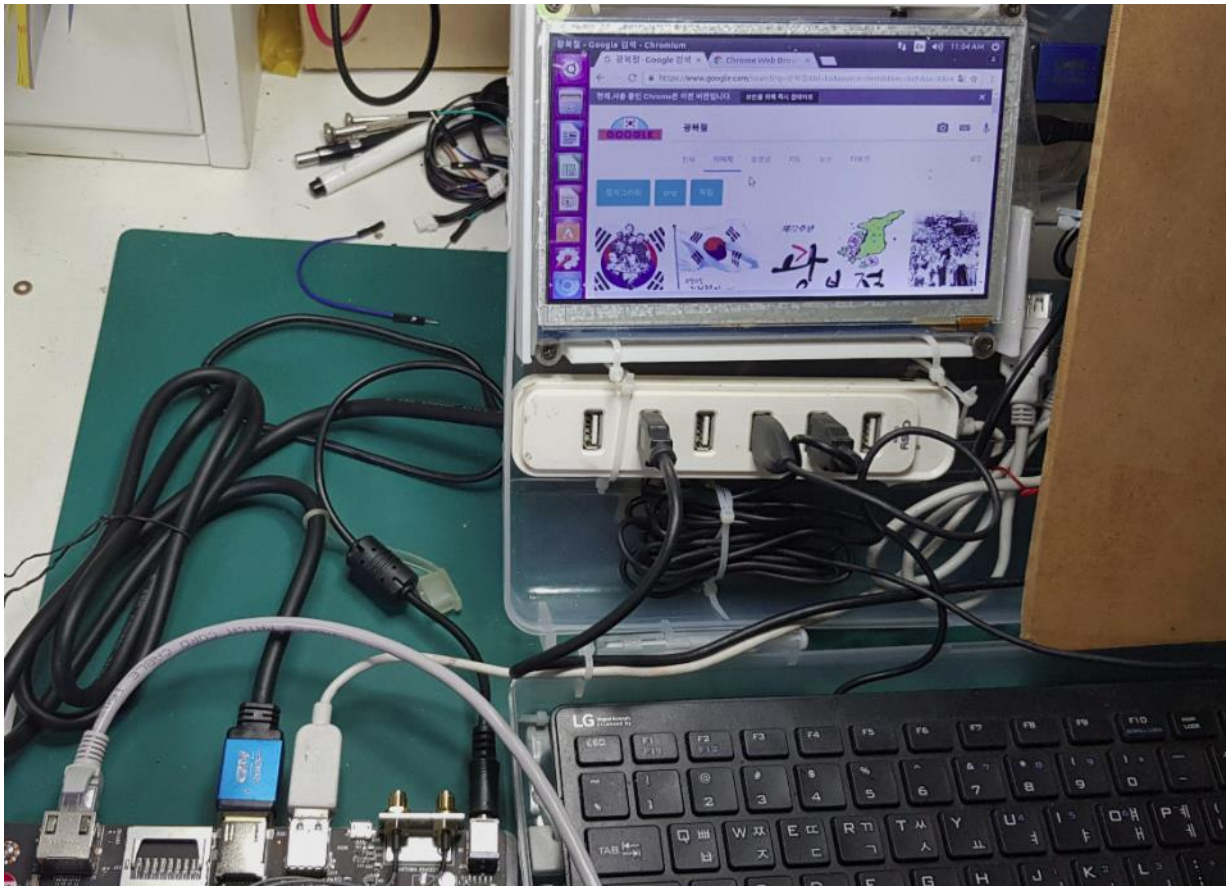






- HOST PC 에서 usb 연결 제거
  Jetson 에 디스플레이 장치 및 마우스 키보드 연결함 ==> JETSON에 USB 포트가 1개밖에 없으므로, 연결 소켓(6구)를 이용함
  Jetson 재부팅함

- 인터넷 연결 : 랜선



- 인터넷 연결 : 무선 (랜선제거후 무선으로 연결)

- 비밀번호

  Jetpack 설치를 하면 계정(사용자)이 2개(Ubuntu , nvidia)가 생긴다
  각각의 비밀번호는 Ubuntu => Ubuntu , nvidia==> nvidia 입니다.
  비밀번호를 설정한적이 없지만, 자동으로 위와같이 생성이 됩니다.

  추후에 각자 비밀번호를 변경하시면 됩니다.

- 문제점

  Jetson 보드의 휀 이 돌지 않음, 아래 명령어가 작동않됨

  ==> Sudo nvpmodel –m 0