Neural Machine Translation

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Seminar: Natural Language Processing

• Introduction to Machine Translation

- Introduction to Machine Translation
- Statistical Phrase-Based Translation

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- Statistical Phrase-Based Translation
- Introduction to Deep Learning

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- Neural Machine Translation

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- Why do we need it?
- Do I need to convince that we need machine translation?

Machine Translation

In a probabilistic perspective, machine translation can be formulated the problem of finding a target sentence y that maximizes the conditional probability of y from a given source sentence x.

$$arg max_y p(x|y)$$

Introduction to Deep Learning

Machine Learning (Supervised)

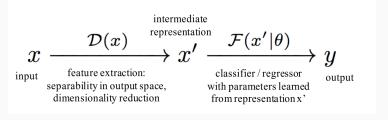


Figure: Traditional Supervised learning

Deep Learning (Supervised)

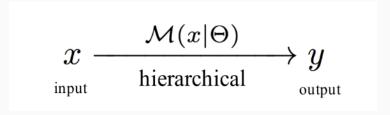


Figure: Deep learning

• Hierarchical representations of features.

Deep Learning (Supervised)

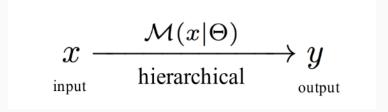


Figure: Deep learning

- Hierarchical representations of features.
- Joint learning of representation.

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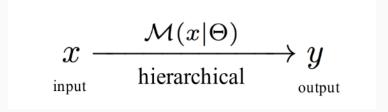


Figure: Deep learning

- Hierarchical representations of features.
- Joint learning of representation.
- Increased levels of abstraction.

Perceptron

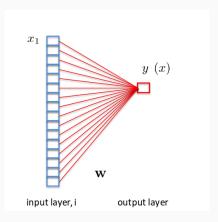


Figure: A perceptron (close to a biological neuron)

$$y(x) = f(W^T x)$$

Logistic Regression

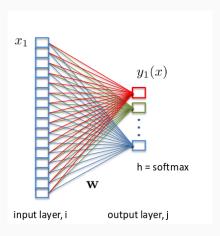


Figure: A perceptron (A collection of perceptrons)

Logistic Regression

Binary classification:

$$P(y = 1|x) = h_w(x) = \frac{1}{1 + exp(-W^T x)}$$
$$P(y = 0|x) = 1 - h_w(x) = 1 - P(y = 1|x)$$

Logistic Regression

Cost function:

$$J(w) = -\sum_{i} (y^{i} log(h_{w}(x^{i})) + (1 - y^{i}) log(1 - h_{w}(x^{i})))$$

Learning Weights: Gradient Descent

$$\nabla_w J(w) = \frac{\partial J(w)}{\partial w_j} = \sum_i x_j^i (h_w(x^i) - y^i)$$

Gradient Descent

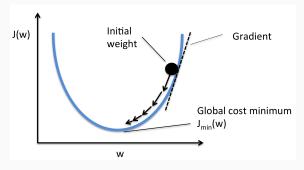


Figure: Update weights in the direction of negative gradient.

Multi Layer Perceptron

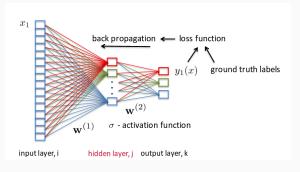


Figure: Multiple layers of perceptron

Learning weights: Same as before but apply chain rule.

$$\frac{\partial x}{\partial y} = \frac{\partial x}{\partial z} * \frac{\partial z}{\partial y}$$

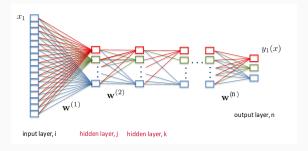


Figure: Deep Neural Networks

• Simply adding layers won't work.

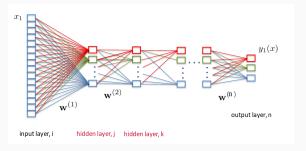


Figure: Deep Neural Networks

- Simply adding layers won't work.
- Too many parameters to train.

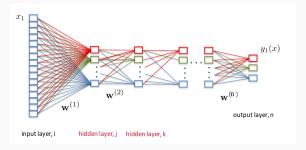


Figure: Deep Neural Networks

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- Too many parameters to train.
- Need smart architectures to capture additional priors.

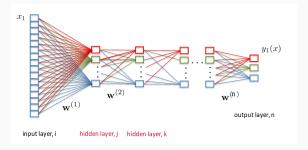


Figure: Deep Neural Networks

- Simply adding layers won't work.
- Too many parameters to train.
- Need smart architectures to capture additional priors.
- Two most commonly used architectures are CNNs and RNNs.

Convolutional Neural Networks

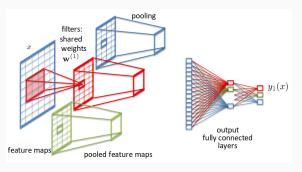


Figure: Convolutional Neural Networks

• Each layers learns a set of convolution kernels.

Convolutional Neural Networks

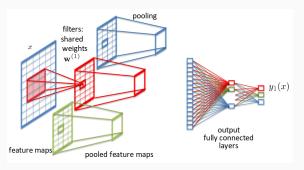


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- Captures a very important prior –smoothness prior– known to computer vision community for a very long time.

Convolutional Neural Networks

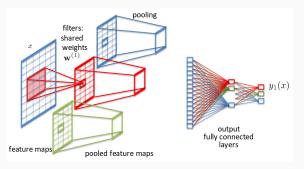


Figure: Convolutional Neural Networks

- Each layers learns a set of convolution kernels.
- Captures a very important prior –smoothness prior– known to computer vision community for a very long time.
- Much less number of parameters.

Recurrent Neural Networks

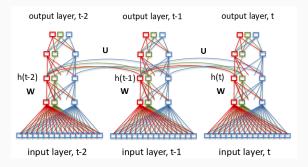


Figure: Recurrent Neural Networks

Used for predicting sequential data

Recurrent Neural Networks

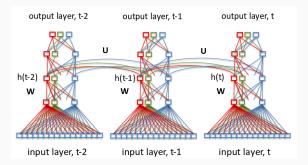


Figure: Recurrent Neural Networks

- Used for predicting sequential data
- Captures dependences across time frames.

Recurrent Neural Networks

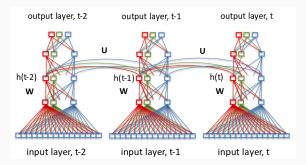


Figure: Recurrent Neural Networks

- Used for predicting sequential data
- Captures dependences across time frames.
- Usually harder to train (Vanishing Gradients).

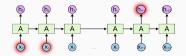


Figure: Recurrent Neural Networks

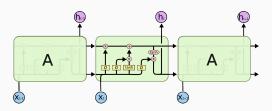


Figure: Long Short Term Memory

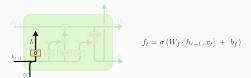


Figure: LSTM Forget gate

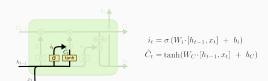


Figure: LSTM new content

LSTM

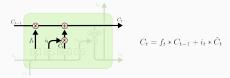


Figure: LSTM Add gate

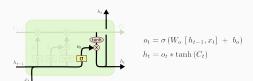


Figure: LSTM Output Gate

Neural Machine Translation

Neural Machine Translation

$$arg max_y p(x|y)$$

In Neural Machine Translation, a parameterized model (a neural network) is trained to maximize the conditional probability of the sentence pairs given parallel training corpus.

NMT - A historic perspective

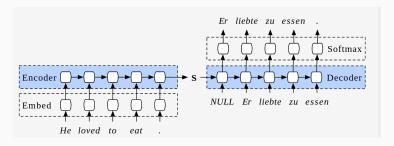


Figure: Encoder-Decoder model for Machine Translation

- Fixed size encodings.
- Each language typically required an Encoder and Decoder.

Jointly learning to Align and translate

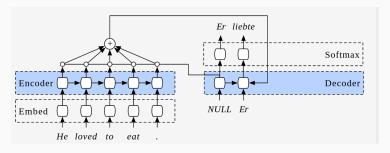


Figure: Encoder-Decoder model with context

Jointly learning to Align and translate

For a input sentence, $X=(x_1,\cdots,x_{T_x})$. The NMT¹ system consists of,

- Encoder and Decoder are multi-layer recurrent neural networks (RNNs).
- Encoder RNN, at each input step t, generates hidden state, $h_t = f(x_t, h_{t-1})$.
- Context vector encodes the input sequence as, $c = q(\{h_1, \cdots, h_{T_x}\}).$

 $^{^1 \}mbox{NEURAL}$ MACHINE TRANSLATION BY JOINTLY LEARNING TO ALIGN AND TRANSLATE. Dzmitry Bahdanau, KyungHyun Cho, Yoshua Bengio, ICLR, 2015.

Jointly learning to Align and translate

ullet The decoder is trained to predict the next work y_t given the context vector c and all previously predicted words $\{y_1,\cdots,y_{t-1}\}$

$$p(y) = \prod_{t=1}^{T} p(y_t | \{y_1, \cdots, y_{t-1}\}, c)$$

• With RNN, each conditional probability is modeled as,

$$p(y_t|\{y_1,\cdots,y_{t-1}\},c)=g(y_{t-1},s_t,c)$$

where s_t is the hidden state of the RNN.

Context Vector

The context vector for a input sentence i, is computed as a weighted sum of hidden states of the encoder (also known as **annotations**)

$$c_i = \sum_{j=1}^{T_x} \alpha_{ij} h_j$$

$$\alpha_{ij} = \frac{exp(e_{ij})}{\sum_{k=1}^{T_x} exp(e_{ik})}$$

where,

$$e_{ij} = a(s_{i-1}, h_j)$$

is the alignment model that scores how well the inputs around the j and the output at the position i match.

A feedforward neural network is used as the alignment model and is **jointly trained** with all the NMT system as a whole.

Bi-directional Encoder

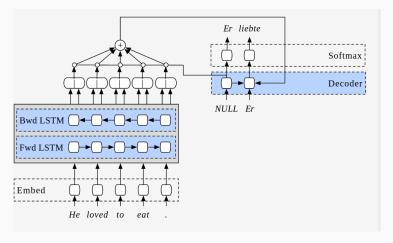
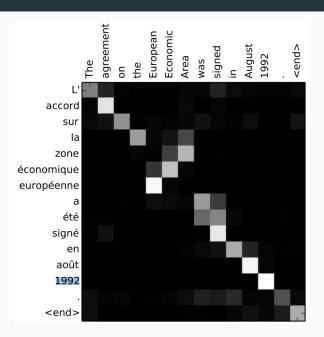


Figure: Bi-directional Encoder

- Recurrent connection in both directions.
- Two independent states, updated independently.

Visualization of the context



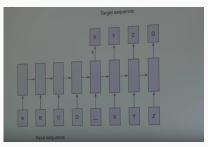
Seq2Seq Learning

Machine Translation is can treated as a special case of a more generic sequence to sequence modeling.

- 1. Idea is simple: Throw more power at the network.
- 2. Deep LSTM layers.
- 3. No special handling for Machine translation.
- 4. Trained with SGD.

$$p(y_1, \dots, y_T | x_1, \dots, x_T) = \prod_{t=1}^T p(y_t | v, y_1, \dots, y_{t-1})$$

Seq2Seq Learning



(b) More powerful model (a) Seq2Seq model

The model

Google NMT

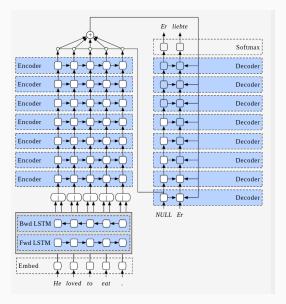


Figure: Simple Encoder-Decoder but more deeper as in Seq2Seq, and Context

Google NMT

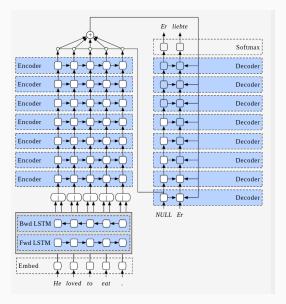
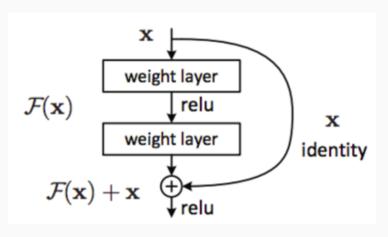


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Residual learning



²Deep Residual Learning for Image Recognition. Kaiming He, Xiangyu Zhang, Shaoqing Ren, & Jian Sun. CVPR, 2016.

Google NMT with Residual connection



Figure: GNMT with residual connections.

Conclusion

Neural Machine Translation systems,

- Are State of the Art in Machine translation.
- Greatly benefited from the Neural Network research by other communities.
- In production by companies like Google, Microsoft, Facebook, etc.

Referencee

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