

# 1. Structures and Theories

## 1.1. Language and Structures

### 1.1.1. Definition

a language  $\mathcal{L}$  is defined by the following data

1. a set of functions  $\mathcal{F}$  and positive integers  $n_f$  for each  $f \in \mathcal{F}$  which is the arity of each function
2. a set of relations  $\mathcal{R}$  and positive integers  $n_R$  for each  $R \in \mathcal{R}$  which is the arity of each relation
3. a set of constant symbols  $\mathcal{C}$

all sets can be empty

### 1.1.2. Examples

1. the language of rings  $\mathcal{L}_r = \{+, -, \cdot, 0, 1\}$
2. the language of ordered rings  $\mathcal{L}_{or} = \mathcal{L}_r \cup \{<\}$
3. the language of pure sets  $\mathcal{L} = \emptyset$
4. the language of graphs  $\mathcal{L} = \{R\}$  where  $R$  is a binary relation

**Remark:** Seems to me that it resembles a lot the concept of an abstract interface in programming languages like: Interfaces in Java, Traits in Rust, Typeclasses in Haskell, Concepts in C++

### 1.1.3. Definition

An  $\mathcal{L}$ -structure  $\mathcal{M}$  is given by the following data:

1. a non empty set  $M$  called universe/domain/underlying set of  $\mathcal{M}$
2. a function  $f^{\mathcal{M}} : M^{n_f} \rightarrow M$  for each  $f \in \mathcal{F}$
3. a set  $R^{\mathcal{M}} \subseteq M^{n_R}$  for each  $R \in \mathcal{R}$
4. an element  $c^{\mathcal{M}} \in M$  for each  $c \in \mathcal{C}$

the last 3 are called interpretations of their counterpart

$\mathcal{M}$  is generally given by a tuple of its components

#### 1.1.4. Examples

for example we have the language of groups being  $\mathcal{L}_g = \{\cdot, e\}$ . an  $\mathcal{L}$ -structure  $G = (\mathbb{R}, \cdot, 1)$  or even  $G = (\mathbb{Z}, +, 0)$

**Remark:** This in turn looks to me like the implementation of the structure in programming languages

#### 1.1.5. Definition

suppose  $\mathcal{M}, \mathcal{N}$  are structures of  $\mathcal{L}$  with universes  $M, N$ , an  $\mathcal{L}$ -embedding  $\eta : \mathcal{M} \rightarrow \mathcal{N}$  is a one-to-one embedding map  $\eta : M \rightarrow N$  that preserves structure as follows:

1.  $\eta(f^{\mathcal{M}}(a_1, \dots, a_n)) = f^{\mathcal{N}}(\eta(a_1), \dots, \eta(a_n))$
2.  $(a_1, \dots, a_m) \in R^{\mathcal{M}}$  iff  $(\eta(a_1), \dots, \eta(a_m)) \in R^{\mathcal{N}}$
3.  $\eta(c^{\mathcal{M}}) = c^{\eta(\mathcal{N})}$

some special cases:

- a bijective  $\mathcal{L}$ -embedding is called an  $\mathcal{L}$ -isomorphism.
- if  $M \subseteq N$  and inclusion map is an  $\mathcal{L}$ -embedding then  $\mathcal{M}$  is a substructure of  $\mathcal{N}$  and  $\mathcal{N}$  is an extension of  $\mathcal{M}$

#### 1.1.6. Examples

if  $\eta : \mathbb{Z} \rightarrow \mathbb{R}$  is  $\eta(x) = e^x$  then it is  $\mathcal{L}$ -embedding of  $(\mathbb{Z}, +, 0)$  into  $(\mathbb{R}, \cdot, 1)$

#### 1.1.7. Definition

$\mathcal{L}$ -terms is the smallest set  $\mathcal{T}$  such that

1.  $\forall c \in \mathcal{C}, c \in \mathcal{T}$
2. each variable symbol  $v_i \in \mathcal{T}$  for  $i \in \mathbb{N}^*$
3. if  $t_1, \dots, t_n \in \mathcal{T}$  and  $f \in \mathcal{F}$  then  $f(t_1, \dots, t_n) \in \mathcal{T}$

### 1.1.8. Examples

for  $\mathcal{L}_r$  (ring language) we have  $\cdot (v_1, -(v_3, 1))$  and  $+(1, +(1, +(1, 1)))$   
this example is written in S-expressions like lisp but it works with infix

***Remark:*** *this also is exactly the same thing as defining what is a valid term in programming languages*