CRAN packages comparison

1 DiffusionRgqd

Uses the cumulant truncation procedure developed by Varughese (2013), whereby the transition density can be approximated over arbitrarily large transition horizons for a suitably general class of non-linear diffusion models.

Generalized quadratic diffusions (GQD) are the specific class of SDEs with quadratic drift and diffusion terms:

$$dX_{t} = \mu(X_{t}, t)dt + \sigma(X_{t}, t)dW_{t}, \text{ where}$$

$$\mu(X_{t}, t) = G_{0}(t) + G_{1}(t)X_{t} + G_{2}(t)X_{t}^{2}, \text{ and}$$

$$\sigma(X_{t}, t) = Q_{0}(t) + Q_{1}(t)X_{t} + Q_{2}(t)X_{t}^{2}$$

For purposes of inference the drift and diffusion terms - and consequently the transitional density - are assumed to be dependent on a vector of parameters, θ . For example, an Ornstein-Uhlenbeck model with SDE:

$$dX_t = \theta_1(\theta_2 - X_t) + \sqrt{\theta_3^2} dW_t \tag{1}$$

```
G0=function(t){theta[1]*theta[2]}
G1=function(t){-theta[1]}
Q0=function(t){theta[3]*theta[3]}
```

For a constant drift, diffusion SDE, with given initial condition X_s :

$$dX_t = \mu dt + \sigma dW_t \tag{2}$$

The distribution at time t of the process X_t is $\mathcal{N}(X_t, X_s + \mu(t-s), \sigma^2(t-s))$

```
# Initial state
Xt <- seq(-3/2,3/2,1/50) # Possible future states
s <- 0
                      # Starting time
t <- 1
                        # Final time
mu <- 0.5
                        # Drift parameter
sigma <- 0.25
                        # Diffusion coefficient
library(DiffusionRgqd)
# Remove any existing coefficients:
GQD.remove()
## [1] "Removed : GO G1 QO"
# Define the model coefficients:
GO <- function(t){mu}
Q0 <- function(t){sigma^2}
# Calculate the transitional density:
BM <- GQD.density(Xs,Xt,s,t)
```

```
##
## -----
##
      Generalized Quadratic Diffusion (GQD)
## _____ Drift Coefficients _____
## GO : mu
## G1
## G2
## _____ Diffusion Coefficients _____
## Q0 : sigma^2
## Q1
## Q2
## _____ Distribution Approximant _____
## Density approx. : Saddlepoint
## P
## alpha
## Trunc. Order : 4
## Dens. Order : 4
```