Application of Machine Learning to Radar Automatic Target Recognition

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Presentation Overview

- > Technical Background
- > Data Discussion
- > Machine Learning Approaches
- > Observations/Results
- > Summary



Project Description

- Objective: Use machine learning to automatically identify targets in Synthetic Aperture Radar (SAR) Imagery
- > Approach:
 - Understand the technical domain
 - Study the problem
 - Find, Format, and Transform Data
 - Choose a machine learning approach
 - Program software and run the model
 - Analyze results/Fine tune the model/Evaluate Accuracy

Automatically Identify Targets in Radar Imagery



This Data Science Project Relied Upon Knowledege in Three Areas

- > Radar
 - Functionality
 - Signal Processing
 - Target Data (Image Formats)
- > Programming
 - Python
 - Programming Libraries
 - Tools
- > Mathematics
 - Linear Algebra
 - Statistics
 - Machine Learning

SAR Background

Cross Range

Why Synthetic Aperture Radar (SAR)?



Radar Image



Radar provides excellent range information

- Can resolve in range down to inches
- Not weather/cloud limited as visible and infrared sensors
- Good image resolution requires commensurate cross-range resolution
- Problem: The radar beam is far too wide and not matched to range resolution for good imaging of targets

Radar Parameters

Range = 100 km

Beamwidth = 0.2°

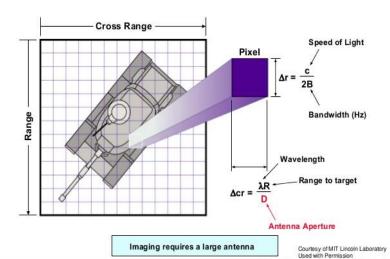
Bandwidth ≈ 500 MHz

Cross Range Resolution = R θ = 350m

Range Resolution = c/2 B ≈ 0.3 m

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View SAR as a Phased Array Antenna

· SAR Resolution

Separated radar positions

provide twice the phase shift

Passive Array Resolution

Antenna Aperture

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Solution:

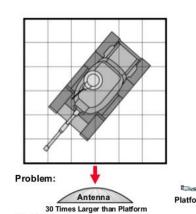
Synthetic Aperture Radar (SAR)

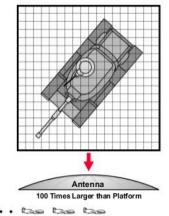
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Cross-Range Resolution with SAR



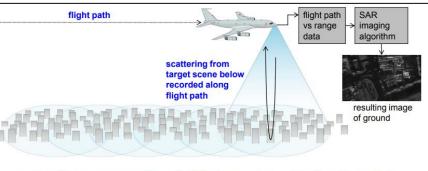




Positions Phased-Array Beam Pattern Cross-Range Resolution Target

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SAR Example



- Small antenna on aircraft illuminates large swaths of ground
- Range profiles recorded along flight path
- SAR algorithm processes data into image of ground [2]
 - thereby synthesizing an aperture the length of the aircraft flight
 - narrow beamwidth, high resolution and gain



Programming Knowledge



Programming Language



Array Manipulation



Machine Learning







Data Frames





Visualization



imageio - Python library for reading and writing image data

PIL: Python Image Library





Program Development

Image Processing



Data Source



Moving and Stationary Target Acquisition and Recognition (MSTAR) Database

- Publicly Released collection of radar imagery of ten military vehicles
- Standard Common Dataset for Researchers
- Downloadable

MSTAR PUBLIC TARGETS



The following data set was collected in September of 1995 at the Redstone Arsenal, Huntsville, AL by the Sandia National Laboratory (SNL) SAR sensor platform. The collection was jointly sponsored by DARPA and Air Force Research Laboratory as part of the Moving and Stationary Target Acquisition and Recognition (MSTAR) program. SNL used an X-band SAR sensor in one foot resolution spotlight mode. Strip map mode was used to collect the clutter data.

Targets (# of)	Target Description	Amount	
T-72 (3)	T-72 Tank	3 replicate targets: each collected at 15 & 17 degree dep. angles and full aspect coverage	
BMP2 (3)	Infantry Fighting Vehicle	3 replicate targets: each collected at 15 & 17 degree dep. angles and full aspect coverage	
BTR-70 (1)	Armored Personnel Carrier	1 target: collected at 15 & 17 degree dep. angles and full aspect coverage	
Slicy (1)	Multiple simple geometric shaped static target	CAD Model November '96 Imagery: TBD in Jan '97	

The "Slicy" target is a precisely designed and machined engineering test target containing standard radar reflector primitive shapes such as flat plates, dihedrals, trihedrals, and top hats. The purpose of this target is to allow Image Understanding developers the ability to validate the functionality of their algorithm with a simple known target.

MSTAR/IU MIXED TARGETS

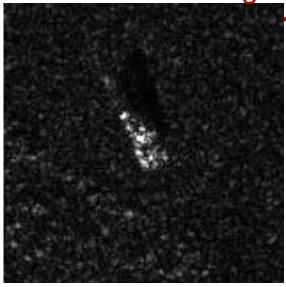


The following data set was collected as part of the MSTAR Data Collection #1, Scene 1 and as part of the MSTAR Data Collection #2, Scenes #1, #2, and #3. Sandia National Laboratory used an X-band STARLOS sensor at 1 foot resolution in Spotlight mode to collect the data at 15, 17, 30, and 45 degree depression angles. The image chips and JPEG files include 2S1, BDRM-2, BTR-60, D7, T62, ZIL-131, ZSU-23/4. and SLICY.

Target Photo

The 2S1 Gvozdika (Russian: 2c1 "Carnation") is a Soviet self-propelled artillery vehicle mounting a 122 mm howitzer. It's fully amphibious and when afloat it's propelled by its tracks. A variety of track widths are available to allow the 2S1 to operate in snow or swamp conditions. It is NBC protected and has infra-red night-vision capability.

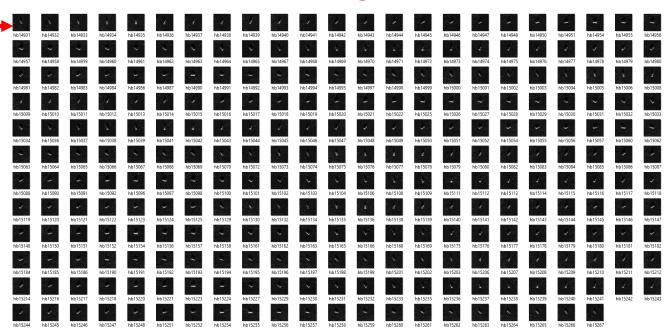
Processed Radar Image



Radar File Meta-Data

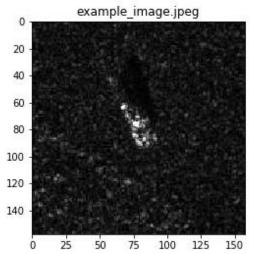
Detailed Ground Truth and sensor information





Imagery Test Data Example





158 pixels $\times 0.3 \text{m} = 47.4 \text{m}$

PhoenixHeaderLength= 01597
PhoenixSigSize= 00201309

PhoenixSigNum= 0001

PhoenixHeaderCallingSequence=

HeaderVersionNumber= 8CM

native_header_length= 0

Filename= hb14931.0000

ParentScene= hb14931

NumberOfColumns= 158

NumberOfRows= 158

TargetType= 2s1_gun

TargetSerNum= b01

TargetAz= 338.224854

TargetRoll= 358.749634

TargetPitch= 359.614655

TargetYaw= 357.094086

DesiredDepression= 15

DesiredGroundPlaneSquint= -90

DesiredSlantPlaneSquint= -90

DesiredRange= 5000

DesiredAimpointElevation= 39

MeasuredDepression= 15.042969

MeasuredGroundPlaneSquint= -91.617958

MeasuredSlantPlaneSquint= -91.562500

MeasuredRange= 4979

MeasuredAimpointElevation= 37.877998

MeasuredAircraftHeading= -178.375000

MeasuredAircraftAltitude= 1330.281006

RadarMode= mode 5 - spot light

SensorCalibrationFactor = 42.995998

RadarPosition= bottom

Range3dBWidth= 0.307800

CrossRange3dBWidth= 0.315300

SceneCenterReferenceLine= 180

X Velocity= 42.444336

DataCollectors= Sandia National Lab

<u>CollectionName= MSTAR Collection 2 Scene 1</u>

SensorName= Twin Otter

Classification= UNCLASSIFIED

MultiplicativeNoise= -10 dB

AdditiveNoise= -32 to -34 dB

CenterFrequency= 9.599000 GHz

CrossRangeWeighting= -35dB_Taylor

RangeWeighting= -35dB_Taylor

DynamicRange= 64 dB

Bandwidth= 0.591 GHz

RangeResolution= 0.304700

CrossRangeResolution= 0.304700

RangePixelSpacing= 0.202148

CrossRangePixelSpacing= 0.203125

AverageImageCalFactor= 1.253507

Polarization= HH

TargetSeasonalCover= only growing vegitation

TargetWaterContent= dry



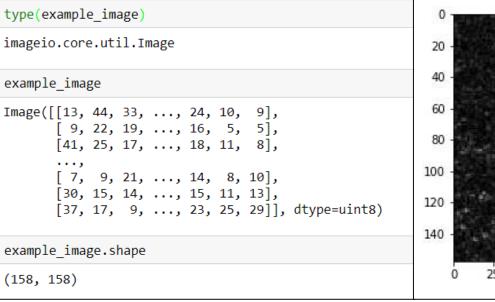


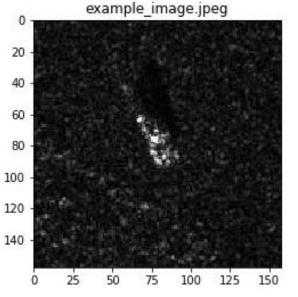
Sandia SAR on Twin Otter

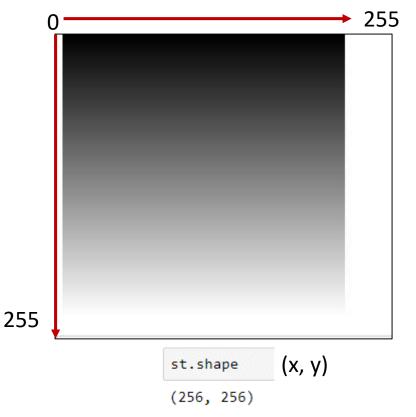
```
temp=np.zeros((1,256), dtype=np.uint8)
for i in range(1,256):
   grays = np.full((1,256), i,dtype =np.uint8)
   st = np.concatenate((temp,grays))
   temp = st
```

Images are arrays: Use NumPy

```
Image.fromarray(st)
```







Pixel Intensity is an integer on a Grey scale of 0 to 255

- 0 : Black
- 255: White
- Radar Returns from flat surfaces: black
- Radar Returns from uneven surfaces: white



Machine Learning Category

Machine Learning (Categories) Customer Retention Classification Classification Diagnostics Advertising Popularity Supervised Unsupervised Learning Learning Forecasting Machine Population Growth Forecasting Prediction Learning Real-time decisions Reinforcement Robot Navigation

Use Supervised Learning to Solve the Radar Image Classification Problem

Supervised Learning Machine Learning

- Train the machine with labelled data tagged with the correct answer
- Test the machine by operating on labeled data to produce a correct output

```
In [9]: train_source_df.tail()
```

Out[9]:

	Class	Directory	Height	Width
2741	ZSU_23_4	MSTAR-10/train/ZSU_23_4/	158	158
2742	ZSU_23_4	MSTAR-10/train/ZSU_23_4/	158	158
2743	ZSU_23_4	MSTAR-10/train/ZSU_23_4/	158	158
2744	ZSU_23_4	MSTAR-10/train/ZSU_23_4/	158	158
2745	ZSU_23_4	MSTAR-10/train/ZSU_23_4/	158	158

In [10]: train_source_df.shape

Out[10]: (2746, 4)

2746 Training Files each 158 x 158 pixels

Getting Data

Subdirectory: MSTAR-10/train/2S1/ Class: 2S1 Number of Files: 299

Subdirectory: MSTAR-10/train/BMP2/ Class: BMP2 Number of Files: 233

Subdirectory: MSTAR-10/train/BRDM_2/
Class: BRDM 2 Number of Files: 298

Subdirectory: MSTAR-10/train/BTR60/ Class: BTR60 Number of Files: 256

Subdirectory: MSTAR-10/train/BTR70/ Class: BTR70 Number of Files: 233

Subdirectory: MSTAR-10/train/D7/ Class: D7 Number of Files: 299

Subdirectory: MSTAR-10/train/T62/ Class: T62 Number of Files: 298

Subdirectory: MSTAR-10/train/T72/ Class: T72 Number of Files: 232

Subdirectory: MSTAR-10/train/ZIL131/ Class: ZIL131 Number of Files: 299

Subdirectory: MSTAR-10/train/ZSU_23_4/Class: ZSU 23 4 Number of Files: 299

Train and Test Set Sizes

In [5]: test source df.head() Out[5]: Class Directory Height Width 2S1 MSTAR-10/test/2S1/ 158 158 test source df.shape Out[7]: (2425, 4)

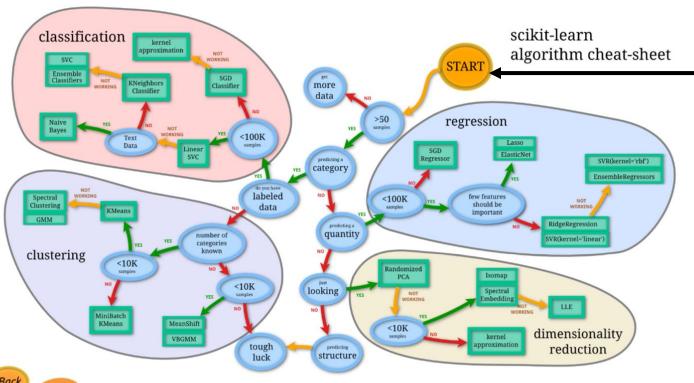
2425 Test Files each 158 x 158 pixels

Getting Data Subdirectory: MSTAR-10/test/2S1/ Class: 2S1 Number of Files: 274 Subdirectory: MSTAR-10/test/BMP2/ Class: BMP2 Number of Files: 195 Subdirectory: MSTAR-10/test/BRDM 2/ Class: BRDM 2 Number of Files: 274 Subdirectory: MSTAR-10/test/BTR60/ Class: BTR60 Number of Files: 195 Subdirectory: MSTAR-10/test/BTR70/ Class: BTR70 Number of Files: 196 Subdirectory: MSTAR-10/test/D7/ Class: D7 Number of Files: 274 Subdirectory: MSTAR-10/test/T62/ Class: T62 Number of Files: 273 Subdirectory: MSTAR-10/test/T72/ Class: T72 Number of Files: 196 Subdirectory: MSTAR-10/test/ZIL131/ Class: ZIL131 Number of Files: 274 Subdirectory: MSTAR-10/test/ZSU 23 4/ Class: ZSU 23 4 Number of Files: 274



Selection of the Supervised Learning Algorithm: Kneighbors

Use Kneighbors to Solve the Radar Image Classification Problem



Input Data

- 2746 Training Samples:
- 2425 Test Samples:
- Data labelled with the correct class

Output:

- Category: One of 10 classes
- Integers that Range from 0 to 9





KNeighborsClassifier

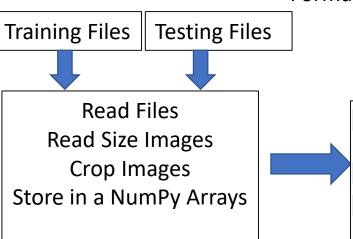
- How it works: Find a predefined number of training samples closest in distance to the new point, and predict the label from these points. It remembers all of its training data
- > Adjustments:
 - Number of training samples
 - Distance metric measure
- > Successful in handwriting and satellite image scenes according to scikit-learn.org
- > Features: An integer on a grey scale of 0 to 255 for each pixel in an image equivalent to the energy of the radar return
- > Classes: Ten military vehicles

Ten Classes for the Identification

["2S1", "BMP2", "BRDM_2", "BTR60", "BTR70", "D7", "T62", "T72", "ZIL131", "ZSU_23_4"]]

BTR60 BTR70 BRDM_2 **2S1** BMP2 T62 ZSU_23_4 T72 D7 **ZIL 131**

Format Data for Machine Learning



Reshape the Arrays

```
np_X_test.shape #Start with this array for the test input

(2425, 96, 96)

np_X_test = np.reshape(np_X_test, [np_X_test.shape[0], np_X_test.shape[1] * np_X_test.shape[2]]) #Reshape test data

np_X_test.shape

(2425, 9216)
```

```
np X train
                                          np y train
                                          array([0, 0, 0, ..., 9, 9, 9])
array([[[21, 15, 18, ..., 45, 29, 25],
        [12, 23, 23, ..., 45, 41, 23],
        [ 9, 19, 21, ..., 25, 26, 17],
                                        np y train.shape
        [20, 34, 33, ..., 11, 13, 13],
                                          (2425,)
        [14, 13, 18, \ldots, 13, 18, 29],
        [15, 6, 18, ..., 10, 16, 28]] np_X_train.shape
                                          (2425, 96, 96)
       [[9, 14, 27, ..., 19, 9, 15],
        [20, 23, 20, ..., 14, 7, 27],
        [20, 33, 23, ..., 20, 14, 23],
                                         np_X_test.shape
                                          (2425, 96, 96)
        [41, 28, 9, \ldots, 22, 22, 7],
        [25, 16, 21, ..., 9, 12, 16],
        [26, 26, 33, ..., 11, 15, 15]], np_y_test
                                          array([0, 0, 0, ..., 9, 9, 9])
       [[22, 25, 31, ..., 11, 22, 21],
        [14, 26, 34, \ldots, 11, 29, 27],
                                          np_y_test.shape
        [31, 30, 17, ..., 11, 12, 14],
                                          (2425,)
        [32, 20, 13, ..., 11, 8, 28],
        [29, 17, 25, ..., 15, 24, 34],
        [25, 25, 29, ..., 24, 23, 22]]
```

```
np y test[:, np.newaxis] #Slice up y into a array of 1-element arrays
array([[0],
       [0],
       [0],
       . . . ,
       [9],
       [9],
       [9]])
y_test = np_y_test[:, np.newaxis]
y_test
array([[0],
       [0],
       [0],
       [9],
       [9],
       [9]])
y test.shape
(2425, 1)
```

Randomize and Scale Feature Data to be on the same scale

Randomly Shuffle Arrays





```
#Randomly shuffle the data before training the neural network
#Use numpy.random.shuffle
#Multi-dimensional arrays are only shuffled along the first axis
#Modify a sequence in-place by shuffling its contents.
#Shuffle both training and test data
data[0:5,] #Before
array([[21, 15, 18, ..., 16, 28, 0],
       [ 9, 14, 27, ..., 15, 15, 0],
       [22, 25, 31, ..., 23, 22, 0],
       [32, 34, 28, ..., 16, 17, 0],
       [18, 14, 10, ..., 57, 39, 0]])
np.random.shuffle(data) #Shuffle
data[0:5,] # After, Look the data array has been shuffled
array([[15, 37, 44, ..., 20, 13, 5],
       [18, 12, 15, ..., 23, 18, 8],
       [18, 15, 25, ..., 31, 38, 0],
       [14, 16, 21, \ldots, 15, 25, 4],
       [40, 81, 42, ..., 34, 11, 4]])
X_test_shuffled = data[:, :-1] # Get everything before the least element in the array.
y test shuffled = data[:, -1] #Get only the last element of the data array. This is the class output
```

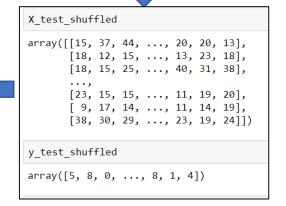
```
X_test_shuffled_scaled = X_test_shuffled/255

X_test_shuffled_scaled

array([[0.05882353, 0.14509804, 0.17254902, ..., 0.07843137, 0.07843137, 0.05098039],
    [0.07058824, 0.04705882, 0.05882353, ..., 0.05098039, 0.09019608, 0.07058824],
    [0.07058824],
    [0.07058824, 0.05882353, 0.09803922, ..., 0.15686275, 0.12156863, 0.14901961],
    ...,
    [0.09019608, 0.05882353, 0.05882353, ..., 0.04313725, 0.0745098, 0.07843137],
    [0.09329412, 0.066666667, 0.05490196, ..., 0.04313725, 0.05490196, 0.0745098],
    [0.14901961, 0.11764706, 0.11372549, ..., 0.09019608, 0.0745098],
    [0.09411765]])
```

Scale Training and Test Data to fall between 0 and 1.

Divide by 256 or 28



Feature Scaling Example

```
X_train_shuffled_scaled

array([[0.00392157, 0.08627451, 0.14117647, ..., 0.16862745, 0.16862745, 0.11372549],
        [0.03921569, 0.03529412, 0.07058824, ..., 0.03529412, 0.03529412, 0.0627451],
        [0.07058824, 0.12156863, 0.19215686, ..., 0.18431373, 0.23921569, 0.24313725],
        ...,
        [0.07058824, 0.04705882, 0.09803922, ..., 0.05882353, 0.05490196, 0.03137255],
        [0.11372549, 0.08627451, 0.03529412, ..., 0.14117647, 0.16862745, 0.16470588],
        [0.05882353, 0.08235294, 0.03921569, ..., 0.06666667, 0.10196078, 0.05490196]])

X_train_shuffled_scaled.shape

(2746, 9216)
```

To center the data (make it have zero mean and unit standard error), you subtract the mean and then divide the result by the standard deviation.

$$x'=(x-\mu)/\sigma$$

Note we have apriori knowledge that the different attributes are all on the same scale. Accordingly, do not divide each element by the variance

Center the testing data with the mean computed from the training data

```
X_train_shuffled_scaled.mean(axis=0)
                                     array([0.09042886, 0.08962198, 0.08860374, ..., 0.08802822, 0.08868943,
                                            0.08819959])
X train centered = X train shuffled scaled
                                                         X train shuffled scaled.mean(axis=0)
               #X train shuffled scaled centered
               X train centered
               array([[-0.08650729, -0.00334747, 0.05257273, ..., 0.08059923,
                       0.07993802, 0.0255259],
                      [-0.05121317, -0.05432786, -0.01801551, ..., -0.0527341,
                      -0.05339531, -0.02545449],
                      [-0.01984062, 0.03194665, 0.10355312, ..., 0.09628551,
                       0.15052626, 0.15493766],
                      [-0.01984062, -0.04256316, 0.00943547, ..., -0.02920469,
                      -0.03378747, -0.05682704],
                      [0.02329663, -0.00334747, -0.05330963, ..., 0.05314825,
                       0.07993802, 0.07650629],
                      [-0.03160533, -0.00726904, -0.04938806, ..., -0.02136155,
                       0.01327135, -0.03329763]])
```

Reduce Dimensionality: Principal Component Analysis (PCA)

```
pca = PCA()
pca.fit(X_train_centered) #First don't reduce any of the dimensions
cumsum = np.cumsum(pca.explained_variance_ratio_)
d = np.argmax(cumsum >= 0.95) + 1
cumsum
array([0.15276593, 0.23165207, 0.27965282, ..., 0.99999311, 1.
                                                                                      Cumulative variances by array element
      1.
pca.explained_variance_ratio_ Variances of each principal component
array([1.52765926e-01, 7.88861425e-02, 4.80007543e-02, ...,
      7.74407398e-05, 7.71373640e-05, 7.69276289e-05])
        Number of dimensions that account for 95% of the variance
1284
                    Reduced dimensions from 9216 (96x96) to 1284
                                          Fit the training data to
pca = PCA(n components = d)
x pca fit = pca.fit(X train centered)
                                          the reduce dimensions
X Reduced train transform = x pca fit.transform(X train centered)
X Reduced test transform = x pca fit.transform(X centered test )
                                                                                 Project data to the reduce dimensions
```

Results

```
from sklearn.neighbors import KNeighborsClassifier

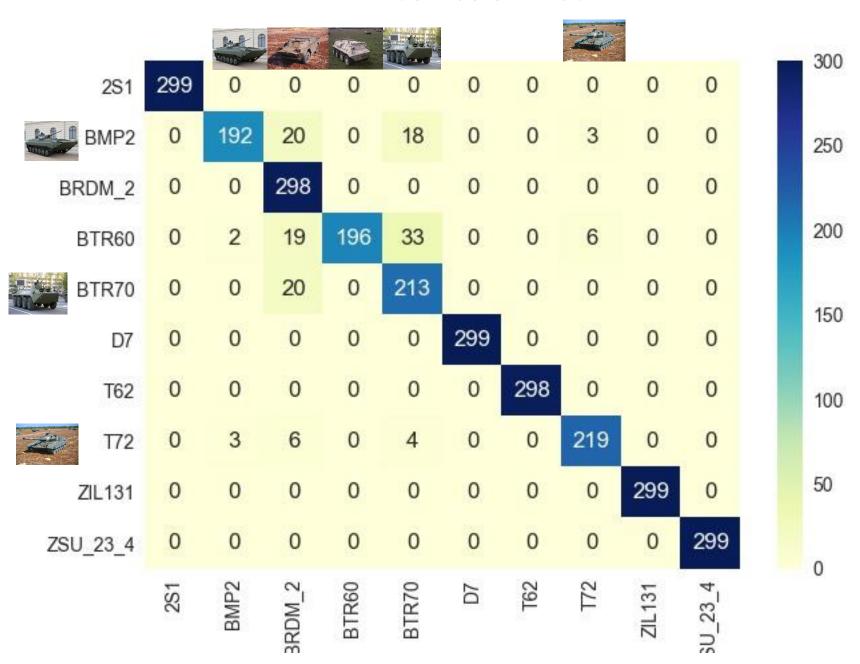
classifier = KNeighborsClassifier(n_neighbors=10, weights="distance",
algorithm="auto").fit(X_Reduced_train_transform,y_train_shuffled)
```

```
classifier.score(X_Reduced_test_transform, y_test_shuffled)
0.9512017479970867

y_predict = classifier.predict(X_Reduced_test_transform)
y_predict
array([2, 2, 4, ..., 3, 5, 1])

y_test_shuffled
array([2, 2, 4, ..., 3, 5, 1])
```

Confusion Matrix





Summary

- SAR Automatic Target Recognition using Machine Learning is Feasible
- > In the case presented, KNN is the appropriate classifier
- > 95% correct identification using the test data