

Tesla Optimus Data Collection Documentation

Tesla Data Operations

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1 Overview

This script simulates real-time data collection for Tesla's Optimus robot, storing sensor data in MySQL, validating it for anomalies, and logging issues to Jira. It demonstrates skills in Python, MySQL, Linux, and Jira API integration, based on experience as a Data Collection Operator at Tesla.

2 Setup Instructions

2.1 MySQL Setup

- Create a MySQL database named `optimus_robot_data`.
- Execute the following SQL to create the required table:

```
1 CREATE TABLE sensor_data (  
2     id INT AUTO_INCREMENT PRIMARY KEY,  
3     timestamp DATETIME,  
4     joint_angle FLOAT,  
5     torque FLOAT,  
6     temperature FLOAT,  
7     battery_level FLOAT  
8 );
```

3 Python Script

The following Python script handles data collection, storage, validation, and issue reporting:

```
1 import mysql.connector  
2 import time  
3 import random  
4 import requests  
5 import json  
6 import logging
```

```
7 import os
8 from datetime import datetime
9
10 # Configure logging for debugging and tracking
11 logging.basicConfig(
12     filename='optimus_data_collection.log',
13     level=logging.INFO,
14     format='%(asctime)s - %(levelname)s - %(message)s'
15 )
16
17 # MySQL database connection configuration
18 db_config = {
19     'host': 'localhost',
20     'user': 'tesla_user',
21     'password': 'secure_password',
22     'database': 'optimus_robot_data'
23 }
24
25 # Jira API configuration
26 JIRA_URL = 'https://your-jira-instance.atlassian.net'
27 JIRA_API_TOKEN = 'your_api_token'
28 JIRA_USER = 'your_email@example.com'
29 JIRA_PROJECT_KEY = 'OPTIMUS'
30
31 # Simulate real-time sensor data collection from Optimus robot
32 def collect_sensor_data():
33     """Simulate collecting real-time sensor data from Optimus robot."""
34     return {
35         'timestamp': datetime.now(),
36         'joint_angle': round(random.uniform(0, 360), 2), # Joint angle
37                     in degrees
38         'torque': round(random.uniform(10, 100), 2),      # Torque in
39                     Nm
40         'temperature': round(random.uniform(20, 80), 2), # Temperature
41                     in Celsius
42         'battery_level': round(random.uniform(0, 100), 2) # Battery
43                     percentage
44     }
45
46 # Store sensor data in MySQL database
47 def store_data_in_mysql(data):
48     """Store sensor data in MySQL database."""
49     try:
50         conn = mysql.connector.connect(**db_config)
51         cursor = conn.cursor()
52
53         insert_query = """
```

```
50         INSERT INTO sensor_data (timestamp, joint_angle, torque,
51             temperature, battery_level)
52         VALUES (%s, %s, %s, %s, %s)
53         """
54         values = (
55             data['timestamp'],
56             data['joint_angle'],
57             data['torque'],
58             data['temperature'],
59             data['battery_level']
60         )
61         cursor.execute(insert_query, values)
62         conn.commit()
63         logging.info("Data stored successfully: %s", data)
64
65     except mysql.connector.Error as err:
66         logging.error("MySQL Error: %s", err)
67         raise
68     finally:
69         cursor.close()
70         conn.close()
71
72 # Validate data and detect potential bugs
73 def validate_data(data):
74     """Validate sensor data and flag potential issues."""
75     issues = []
76
77     if data['joint_angle'] > 350 or data['joint_angle'] < 10:
78         issues.append(f"Joint angle out of range: {data['joint_angle']} degrees")
79     if data['torque'] > 90:
80         issues.append(f"Excessive torque detected: {data['torque']} Nm")
81     if data['temperature'] > 70:
82         issues.append(f"High temperature detected: {data['temperature']} C")
83     if data['battery_level'] < 20:
84         issues.append(f"Low battery level: {data['battery_level']}%")
85
86     return issues
87
88 # Log issues to Jira
89 def log_issue_to_jira(issue_description):
90     """Log detected issues to Jira as bug tickets."""
91     headers = {
92         'Authorization': f'Basic {JIRA_USER}:{JIRA_API_TOKEN}',
```

```
93         'Content-Type': 'application/json'
94     }
95
96     issue_data = {
97         'fields': {
98             'project': {'key': JIRA_PROJECT_KEY},
99             'summary': f'Optimus Robot Sensor Issue: {issue_description[:50]}',
100             'description': issue_description,
101             'issuetype': {'name': 'Bug'}
102         }
103     }
104
105     try:
106         response = requests.post(
107             f'{JIRA_URL}/rest/api/3/issue',
108             headers=headers,
109             data=json.dumps(issue_data)
110         )
111         if response.status_code == 201:
112             logging.info("Jira issue created: %s", response.json()['key'])
113         else:
114             logging.error("Failed to create Jira issue: %s", response.text)
115     except requests.RequestException as e:
116         logging.error("Jira API error: %s", e)
117
118 # Main data collection and processing loop
119 def main():
120     """Main function to collect, store, validate, and report sensor data."""
121     try:
122         # Check for Linux environment
123         if os.name != 'posix':
124             logging.warning("This script is optimized for Linux/Unix environments.")
125
126         while True:
127             # Collect real-time sensor data
128             sensor_data = collect_sensor_data()
129             logging.info("Collected sensor data: %s", sensor_data)
130
131             # Store data in MySQL
132             store_data_in_mysql(sensor_data)
133
134             # Validate data for potential issues
```

```
135         issues = validate_data(sensor_data)
136     if issues:
137         for issue in issues:
138             logging.warning("Issue detected: %s", issue)
139             log_issue_to_jira(issue)
140
141     # Simulate real-time data collection (every 5 seconds)
142     time.sleep(5)
143
144 except KeyboardInterrupt:
145     logging.info("Data collection stopped by user.")
146 except Exception as e:
147     logging.error("Unexpected error: %s", e)
148
149 if __name__ == "__main__":
150     main()
```