

# User Manual & Sensor Tutorials

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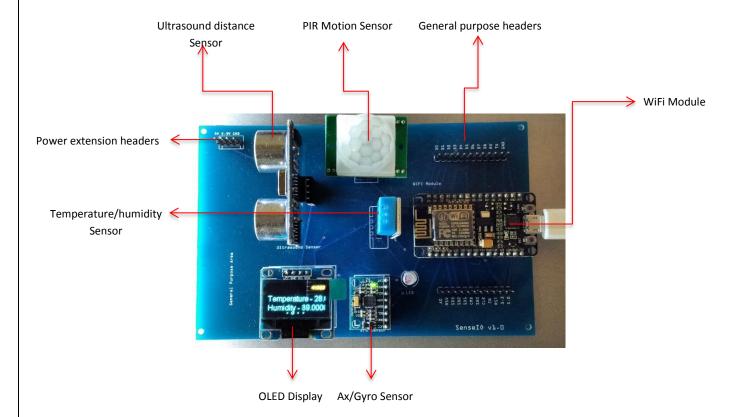
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Version 1.0



# SenselO<sup>™</sup> Platform consists of following components

- 1. WiFi module
- 2. DHT11 temperature sensor
- 3. PIR Motion sensor
- 4. Accelerometer/Gyroscope sensor
- 5. Ultrasound distance sensor
- 6. OLED display
- 7. General purpose headers
- 8. Power extension header

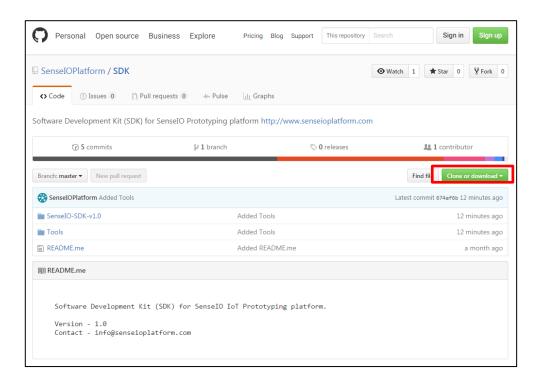


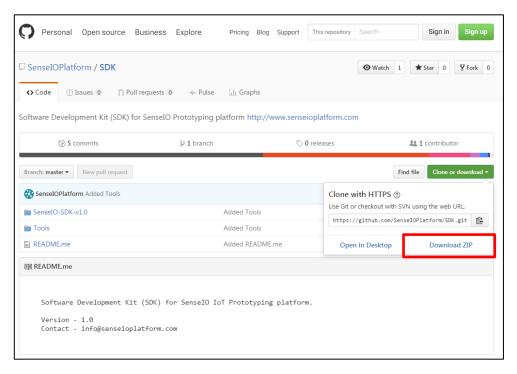


### **SDK & Drivers installation**

1. Download the SDK from below path:

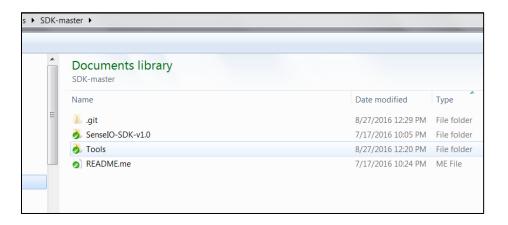
https://github.com/SenselOPlatform/SDK



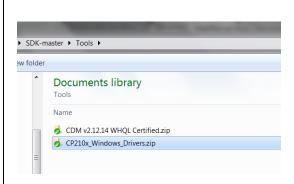


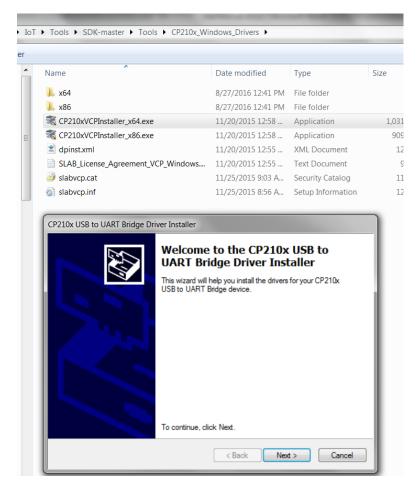


2. Unzip SDK zip file which was downloaded



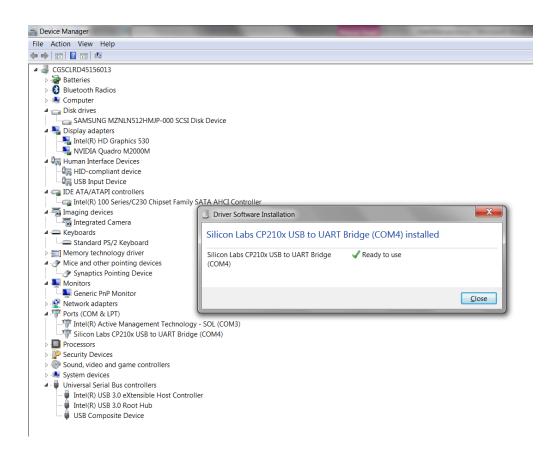
- 3. Connect the SenselO platform to PC using USB cable.
- 4. Navigate inside SDK-master/Tools folder & unzip the CP210x\_Windows\_Drivers.zip. Install the CP210xVCPInstaller\_x64.exe(if PC is 64 bit) or CP210xVCPInstaller\_x86.exe(if PC is 32 bit).





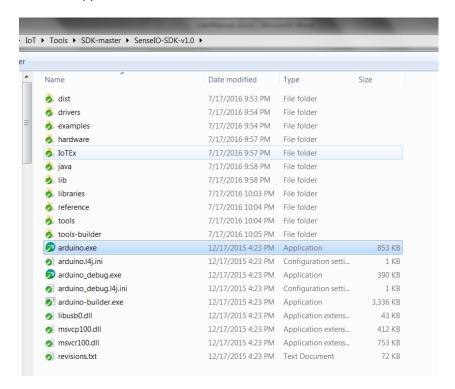


5. A pop will be shown on successful installation of the driver. Please note the COM port at which the SenselO platform is detected (COM4, in below case).

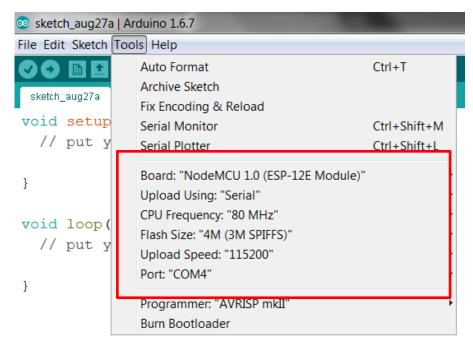


# **Basic Compile & Run test**

1. Open Arduino IDE application.

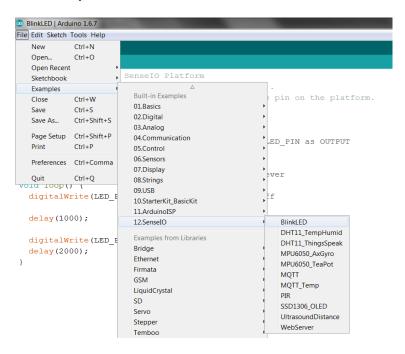


Select Board as "NodeMCU 1.0(ESP-12E Module)"; make sure other configuration parameters
are set as below. COM Port will be the PC's port at which device is currently connected; it may
be different than it is shown below.





# 3. Navigate to File->Examples->SenseIO->BlinkLED

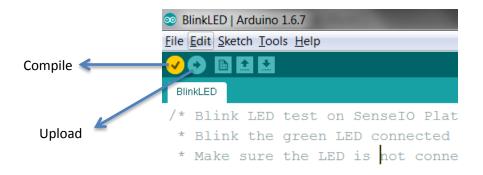


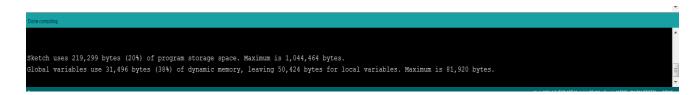


```
    BlinkLED | Arduino 1.6.7

<u>File Edit Sketch Tools Help</u>
 BlinkLED
/* Blink LED test on SenseIO Platform
 * Blink the green LED connected to the pin 4 (D4).
 ^{\star} Make sure the LED is not connected with reverse pin on the platform.
#define LED_PIN D4
void setup() {
  pinMode(LED_PIN, OUTPUT); // Initialize the LED_PIN as OUTPUT
  Serial.begin(115200);
  Serial.println();
  Serial.print("Setup is complete.... ");
// the loop function runs over and over again forever
void loop() {
  digitalWrite(LED PIN, LOW); // Turn the LED off
  Serial.println();
  Serial.print("LED is low...");
                                // Wait for a second
  delay(1000);
  digitalWrite(LED_PIN, HIGH); // Turn the LED on
  Serial.println();
  Serial.print("LED is high... ");
  delay(2000);
                   // Wait for two seconds
```

4. Press on compile button (Program will only be compiled & not uploaded on platform). Press on upload button to upload the program on platform.





5. Observe above compile message, when there are no errors in the code.



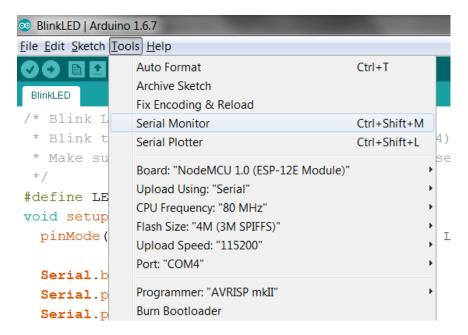
6. On upload button, binary will be flashed on the platform. Check the status of upload as progress bar.

```
Sketch uses 219,299 bytes (20%) of program storage space. Maximum is 1,044,464 bytes.

Global variables use 31,496 bytes (30%) of dynamic memory, leaving 50,424 bytes for local variables. Maximum is 81,920 bytes.

Uploading 223440 bytes from C: p\builda54e62155409d6289c78de5e587b37db.tmp/BlinkLED.ino.bin to flash at 0x000000000
```

7. Open the Serial Monitor to view the messages.

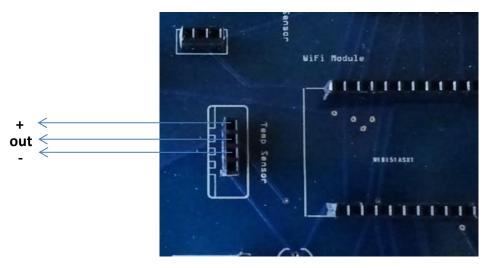


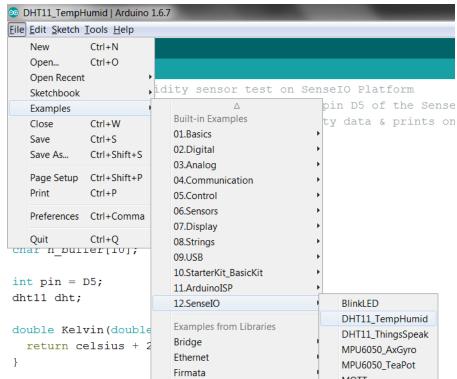
```
∞ COM4
LED is high... rl lœž| Œlà|
                               Œ lì b|Ž, ì 'r'bŒ bŒònnžlnnœâì b pìŽlrlrl , ,nlær' , nnn blb
Setup is complete....
LED is low...
LED is high...
LED is low...
```



# **Sensor Tutorials**

- 1. Temperature/Humidity Sensor
  - a. Test file: Files->Examples->SenseIO->DHT11\_TempHumid



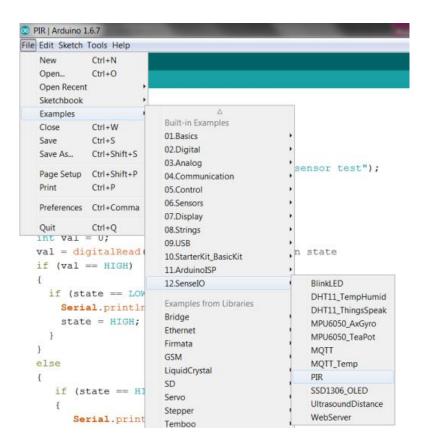




# © COM4 rl lœž| Œlà| Œ lì b|ž, ì 'r'bŒ bŒònnžlnnœâì b pŒžlrlrlpònà , l Œœ SenseIO platform - Temp/Humidity sensor test temperature:28.00 humidity:47.00 temperature:28.00 humidity:47.00 temperature:28.00 humidity:49.00 temperature:28.00 humidity:47.00 temperature:28.00 humidity:47.00

## 2. PIR Motion Sensor:

- a. Test file: Files->Examples->SenseIO->PIR
- b. Motion sensor will detect the human motion, the sensor output remains at detect level for few seconds before going back to not-detected state.



c. Make a motion in front of motion sensor to test this sensor.

```
© COM4

rl lœž| Œlà| Œ lì b|ž, ì 'r'bŒ bŒònnžlnnœâì b pŒžlrlrl;

SenseIO platform - Motion sensor test

Motion detected!

Motion stopped!

Motion detected!

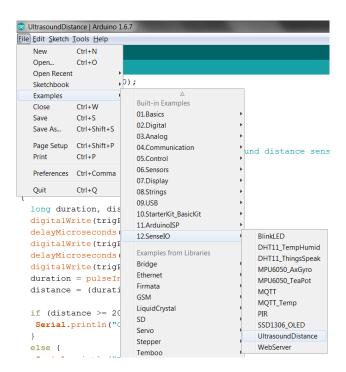
Motion stopped!

Motion detected!

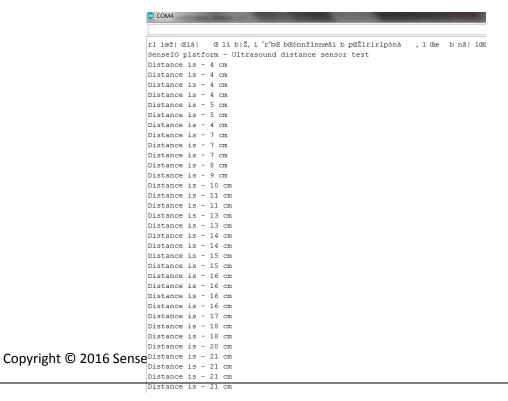
Motion detected!
```



- 3. Ultrasound Distance Sensor
  - a. Test file: Files->Examples->SenseIO->UltrasoundDistance
  - Ultrasound sensor detects the distance at which the obstacle is present in front of it.

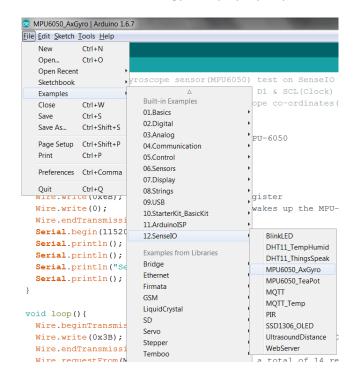


a. Distance detection test can be performed by varying the distance between an obstacle & the sensor.



SenselO

- 4. Accelerometer/Gyroscope sensor test
  - a. Test file: Files->Examples->SenseIO->MPU6050\_AxGyro
  - b. This sensor detects acceleration & gyroscope property in 3 directions.



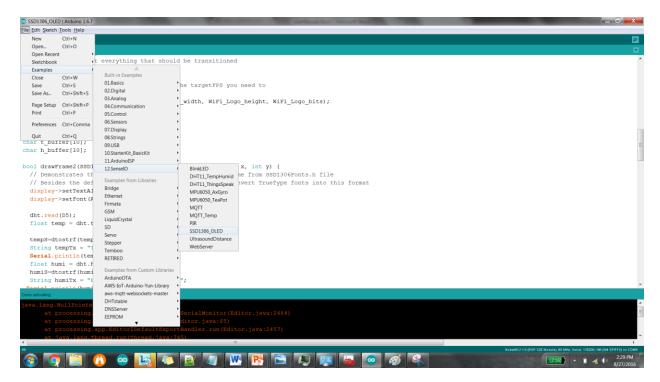
b. Change in values of Ax & Gyro can be observed by moving the platform in different axis (x, y & z).

```
Œ lì b|ž, ì 'r'bŒ bŒònnžlnnœâì b pŒŽlrlrlpònà , l Œœ b nâ| lŒŒŽŽbŒòi
SenseTO platform - Accelerometer/Gyroscope sensor test
AcX = 4648 \mid AcY = -1204 \mid AcZ = 14352 \mid Tmp = 30.69
| GyX = -4117 | GyY = -210 | GyZ = -498
AcX = 4696 | AcY = -1040 | AcZ = 14328 | Tmp = 30.74
 | GyX = -4119 | GyY = -201 | GyZ = -489
AcX = 4672 \mid AcY = -1204 \mid AcZ = 14268 \mid Tmp = 30.65
| GyX = -4134 | GyY = -185 | GyZ = -474
Acx = 4820 | AcY = -1136 | AcZ = 14308 | Tmp = 30.69
| GyX = -4106 | GyY = -221 | GyZ = -513
AcX = 4664 \mid AcY = -1092 \mid AcZ = 14304 \mid Tmp = 30.69
\mid GyX = -4116 \mid GyY = -206 \mid GyZ = -491
Acx = 4688 | Acy = -1196 | Acz = 14324 | Tmp = 30.69
| GyX = -4119 | GyY = -203 | GyZ = -482
Acx = 4748 | Acy = -988 | Acz = 14368 | Tmp = 30.69
| GyX = -4111 | GyY = -214 | GyZ = -482
AcX = 4700 \mid AcY = -1096 \mid AcZ = 14320 \mid Tmp = 30.74
| GyX = -4093 | GyY = -252 | GyZ = -506
```



# 5. OLED display test

a. Test file: Files->Examples->SenseIO->SSD1306\_OLED



# 6. Simple Web Server

- a. Test file: Files->Examples->SenseIO->WebServer
- b. This simple webserver controls the provides an url through which the LED connected to SenseIO can be controlled. LED can be controlled from a browser on a PC connected to the same network as SenseIO platform.
- c. URL will be as follows <server\_ip\_address>/gpio/1 → to turn LED on <server\_ip\_address>/gpio/0 → to turn LED off



```
    WebServer | Arduino 1.6.7

   <u>File Edit Sketch Tools Help</u>
    /*
    * A Simple WebServer example on SenseIO Platform
    ^{\star} \, The server will set a pin depending on the request
    * http://server_ip/gpio/0 will set the D4 low,
     * http://server_ip/gpio/1 will set the D4 high
    * server_ip is the IP address of the SenseIO platform, will
    * printed to Serial when the module is connected.
   #include <ESP8266WiFi h>
   const char* ssid = "wifi_ssid";
                                                                  Use your WiFi SSID &
   const char* password = "wifi_password"
                                                                       password
   \ensuremath{//} Create an instance of the server
   \ensuremath{//} specify the port to listen on as an argument
   WiFiServer server(80);
   COM4
rl lœž|Œlà|
                       Œ lì b|Ž, ì 'r'bŒ bŒònnžlnnœâ
Connecting to AirtelAp
. . . . . . . . . . . .
WiFi connected
Server started
192.168.43.244
new client
GET /gpio/1 HTTP/1.1
Client disonnected
```

d. LED on the platform will be turned ON/OFF based on the URL; HTTP response from the platform will be displayed on the webpage.





