EN2550 - Fundementals of Image Processing and Machine Vision

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Index No.: 190504H

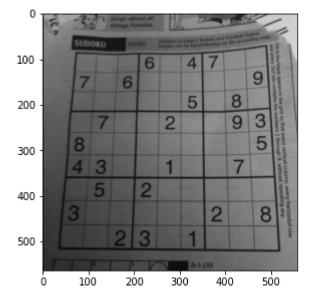
```
In [ ]: import cv2 as cv
import numpy as np
import matplotlib.pyplot as plt
```

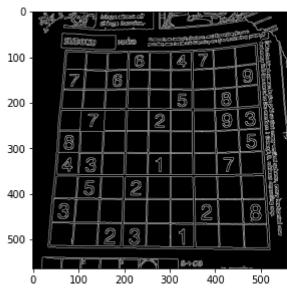
Hough Transform

Part1

```
In [ ]:
        img = cv.imread('sudoku.png', cv.IMREAD COLOR)
        assert img is not None
        gray = cv.cvtColor(img, cv.COLOR_BGR2GRAY)
        edges = cv.Canny(gray, 20, 120, apertureSize = 3)
        lines = cv.HoughLines(edges, 1, np.pi/180, 175)
        for line in lines:
             rho, theta = line[0]
            a = np.cos(theta)
            b = np.sin(theta)
            x0,y0 = a*rho,b*rho
            x1,y1 = int(x0+1000*(-b)), int(y0+1000*(-a))
            x2,y2 = int(x0-1000*(-b)), int(y0-1000*(-a))
            cv.line(img, (x1,y1),(x2,y2),(0,0,255),2)
        fig,ax = plt.subplots(1,2,figsize = (10, 10))
        ax[0].imshow(cv.cvtColor(gray, cv.COLOR_BGR2RGB))
        ax[1].imshow(cv.cvtColor(edges, cv.COLOR BGR2RGB))
```

Out[]: <matplotlib.image.AxesImage at 0x1b440d0cd30>





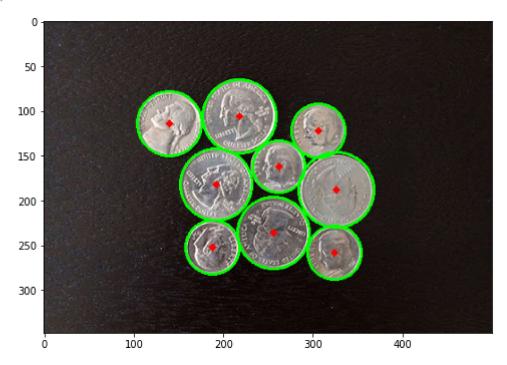
Part 2

```
img = cv.imread('coins.jpg', cv.IMREAD_COLOR)
assert img is not None

gray = cv.cvtColor(img, cv.COLOR_BGR2GRAY)
gray = cv.medianBlur(gray,5)
circles = cv.HoughCircles(gray,cv.HOUGH_GRADIENT,1,50, param1=150,param2=20,minRadius=circles = np.uint16(np.around(circles))
for i in circles[0,:]:
    # draw the outer circle
    cv.circle(img,(i[0],i[1]),i[2],(0,255,0),2)
# draw the center of the circle
    cv.circle(img,(i[0],i[1]),2,(0,0,255),3)

fig,ax = plt.subplots(figsize = (8, 8))
ax.imshow(cv.cvtColor(img, cv.COLOR_BGR2RGB))
```

Out[]: <matplotlib.image.AxesImage at 0x1b44306eeb0>



Part 3

```
In []: im = cv.imread('pic1.png', cv.IMREAD_REDUCED_GRAYSCALE_2)
    templ = cv.imread('templ.png', cv.IMREAD_REDUCED_GRAYSCALE_2)

im_edges = cv.Canny(im, 50, 250)
    templ_edges = cv.Canny(templ, 50, 250)

alg = cv.createGeneralizedHoughGuil()
    alg.setTemplate(templ_edges)
    alg.setAngleThresh(100000)
    alg.setScaleThresh(40000)
    alg.setPosThresh(1000)
    alg.setAngleStep(1)
    alg.setScaleStep(0.1)
    alg.setMinScale(0.9)
    alg.setMaxScale(1.1)
```

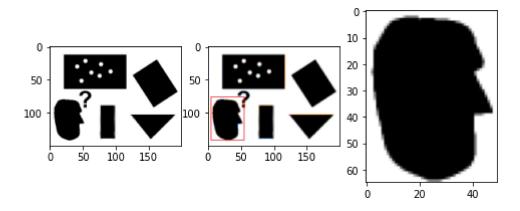
```
positions, votes = alg.detect(im_edges)

out = cv.cvtColor(im, cv.COLOR_BAYER_BG2BGR)

for x,y,scale, orientation in positions[0]:
    halfHeight = templ.shape[0] / 2. * scale
    halfWidth = templ.shape[1] / 2. * scale
    p1 = (int(x - halfWidth), int(y - halfHeight))
    p2 = (int(x + halfWidth), int(y + halfHeight))
    print("")
    cv.rectangle(out, p1, p2, (0,0,255))

fig,ax = plt.subplots(1,3, figsize = (8, 12))
ax[0].imshow(cv.cvtColor(im, cv.COLOR_BGR2RGB))
ax[1].imshow(cv.cvtColor(out, cv.COLOR_BGR2RGB))
ax[2].imshow(cv.cvtColor(templ, cv.COLOR_BGR2RGB))
```

Out[]: <matplotlib.image.AxesImage at 0x1b442f19490>

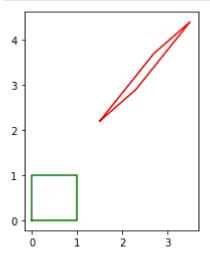


Alignment

Part 4

```
In [ ]: a, b, c, d = [0, 0, 1], [0, 1, 1], [1,1,1], [1,0,1]
        X = np.array([a,b,c,d]).T
        theta = np.pi*30/180
         s = 1
        tx, ty = 1.5, 2.2
        \# H = np.array([[s*np.cos(theta), -s*np.sin(theta), tx], [s*np.sin(theta), s*np.cos(theta)]
        # Y = H @ X
        a11, a12, a21, a22 = 0.8, 1.2, 0.7, 1.5 #Should be a non-singular matrix here
        A = np.array([[a11,a12,tx], [a21, a22, ty], [0,0,1]])
        Y = A @ X
        x = np.append(X[0, :], X[0, 0])
        y = np.append(X[1, :], X[1, 0])
        fig, ax = plt.subplots(1,1)
         ax.plot(x, y, color='g')
         ax.set_aspect('equal')
        x = np.append(Y[0, :], Y[0, 0])
        y = np.append(Y[1, :], Y[1, 0])
         ax.plot(x, y, color='r')
```

```
ax.set_aspect('equal')
plt.show()
```



Part 5

```
In []: # Warping using the given homogapghy

im1 = cv.imread(r'./graf/img1.ppm', cv.IMREAD_ANYCOLOR)
im4 = cv.imread(r'./graf/img4.ppm', cv.IMREAD_ANYCOLOR)

H = []
with open(r'./graf/H1to4p') as f:
    H = np.array([[float(h) for h in line.split()] for line in f])

im1to4 = cv.warpPerspective(im4, np.linalg.inv(H), (2000,2000))

fig,ax = plt.subplots(1,3, figsize = (18, 18))
ax[0].imshow(cv.cvtColor(im1, cv.COLOR_BGR2RGB))
ax[1].imshow(cv.cvtColor(im4, cv.COLOR_BGR2RGB))
ax[2].imshow(cv.cvtColor(im1to4, cv.COLOR_BGR2RGB))
```

Out[]: <matplotlib.image.AxesImage at 0x1b44802fa30>

