## # 201700949 설재혁

## ## 2.

In [26]:

```
x = 2; z = 2
y = x**3 + x

#(1)
dfdx = 6*x*z + 2*(x**3 + x)

#(2) 미분 결과 값 : 44

#(3)
f = 2*x*y + 3*x**2*z + 4*x

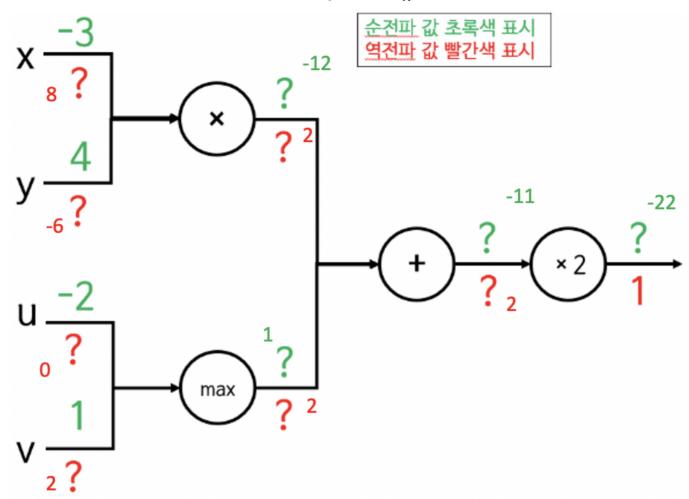
dfdx = 6*x*z + 2*(x**3 + x)
print('결과:',dfdx)
```

결과: 44

3.

$$f(x,y,u,v) = (x*y) + max(u,v)$$

(1)



## In [27]:

```
x = -3; y = 4; u = -2; v = 1
# forward
a = x * y
b = max(u,v)
c = a + b
f = 2 * c
# Backward
dfdc = 2
dfda = 2 \# dfda = 2(a+b)
dfdb = 2 \# dfdb = 2(a+b)
dfdx = 2.0 * y
dfdy = 2.0 * x
if(u>v):
    dfdu = dfdb
    dfdv = 0
else:
    dfdv = dfdb
    dfdu = 0
print('Forward pass: ',a,b,c,f)
print('Backward pass: ',dfdc,dfda,dfdb,dfdx,dfdy,dfdu,dfdv)
```

Forward pass: -12 1 -11 -22 Backward pass: 2 2 2 8.0 -6.0 0 2

## In [28]:

```
import numpy as np
\# (1)
def relu(x):
    return 2*(x>0)*x
input_data = np.array([1.0, 0.5])
W input output = np.array([[0.9, 0.2], [0.3, 0.8]])
X output = np.dot(input data, W input output)
actuals = relu(X output) # 실제 값
print('(1): ',actuals)
# (2)
targets = [1.85, 0.1] # 목표값
E_output = targets - actuals \# \mathcal{Q}\bar{\mathcal{H}}
W_input_output_sum = W_input_output.sum(axis=1, dtype="float") # 입력 계층과 출력 계층 간
W input output norm = W input output.T / W input output sum # \overline{\partial} \pi^{\underline{b}}
E_input = np.dot(W_input_output_norm, E output) # 입력 계층 오차
print('(2):' ,E input)
# (3)
alpha = 0.1 # 학습률
sum of weight = np.dot(W input output, X output)
result = -(E_output * relu(sum_of_weight) * (1 - relu(sum_of_weight)) * X_output) #
variance = alpha * result # 변화량 == 학습률 * 오차 기울기
updatedWeight = W_input_output - variance # 업데이트 된 가중치
print('(3):', updatedWeight)
(1): [2.1 1.2]
(2): [-0.50454545 - 0.84545455]
(3): [[0.96318113 0.2619146 ]
 [0.36318113 0.8619146 ]]
In [ ]:
```