

# Backpropagation and Jacobian Matrices

## Lecture.10

### Expanded Jacobians in Deep Learning



## Mean Squared Error

$$J = \frac{1}{N} \sum_{i=1}^N (y^{(i)} - \hat{y}^{(i)})^2$$

$$\hat{Y} = \begin{pmatrix} \hat{y}^{(1)} \\ \hat{y}^{(2)} \\ \vdots \\ \hat{y}^{(N)} \end{pmatrix} \in \mathbb{R}^{N \times 1}, \quad Y = \begin{pmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(N)} \end{pmatrix} \in \mathbb{R}^{N \times 1}$$

$$\frac{\partial J}{\partial \hat{y}^{(i)}} = -\frac{2}{N} (y^{(i)} - \hat{y}^{(i)})$$

$$d\hat{Y} = \begin{pmatrix} d\hat{y}^{(1)} \\ d\hat{y}^{(2)} \\ \vdots \\ d\hat{y}^{(N)} \end{pmatrix} = \begin{pmatrix} -\frac{2}{N} (y^{(1)} - \hat{y}^{(1)}) \\ -\frac{2}{N} (y^{(2)} - \hat{y}^{(2)}) \\ \vdots \\ -\frac{2}{N} (y^{(N)} - \hat{y}^{(N)}) \end{pmatrix} \in \mathbb{R}^{N \times 1}$$

$$d\hat{Y} = -2/N * (Y - \hat{Y})$$

## Binary Cross Entropy Error

$$J = -\frac{1}{N} \sum_{i=1}^N \left[ y^{(i)} \log(\hat{y}^{(i)}) + (1 - y^{(i)}) \log(1 - \hat{y}^{(i)}) \right]$$

$$\hat{Y} = \begin{pmatrix} \hat{y}^{(1)} \\ \hat{y}^{(2)} \\ \vdots \\ \hat{y}^{(N)} \end{pmatrix} \in \mathbb{R}^{N \times 1}, \quad Y = \begin{pmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(N)} \end{pmatrix} \in \mathbb{R}^{N \times 1}$$

$$d\hat{y}^{(i)} = \frac{1}{N} \frac{\hat{y}^{(i)} - y^{(i)}}{\hat{y}^{(i)}(1 - \hat{y}^{(i)})}$$

$$d\hat{Y} = \begin{pmatrix} d\hat{y}^{(1)} \\ d\hat{y}^{(2)} \\ \vdots \\ d\hat{y}^{(N)} \end{pmatrix} = \frac{1}{N} \begin{pmatrix} \frac{\hat{y}^{(1)} - y^{(1)}}{\hat{y}^{(1)}(1 - \hat{y}^{(1)})} \\ \frac{\hat{y}^{(2)} - y^{(2)}}{\hat{y}^{(2)}(1 - \hat{y}^{(2)})} \\ \vdots \\ \frac{\hat{y}^{(N)} - y^{(N)}}{\hat{y}^{(N)}(1 - \hat{y}^{(N)})} \end{pmatrix} \in \mathbb{R}^{N \times 1}$$

$$d\hat{Y} = \frac{1}{N} * (\hat{Y} - Y) / (\hat{Y}(1 - \hat{Y}))$$



# Lecture.10 Expanded Jacobians in Deep Learning

## - Loss Functions and Expanded Jacobians

### Categorical Cross Entropy Error

$$J = -\frac{1}{N} \sum_{i=1}^N \sum_{k=1}^K y_k^{(i)} \log(\hat{y}^{(i)})$$

$$\hat{Y} = \begin{pmatrix} \hat{y}_1^{(1)} & \hat{y}_2^{(1)} & \dots & \hat{y}_K^{(1)} \\ \hat{y}_1^{(2)} & \hat{y}_2^{(2)} & \dots & \hat{y}_K^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ \hat{y}_1^{(N)} & \hat{y}_2^{(N)} & \dots & \hat{y}_K^{(N)} \end{pmatrix} \in \mathbb{R}^{N \times K}, \quad Y = \begin{pmatrix} y_1^{(1)} & y_2^{(1)} & \dots & y_K^{(1)} \\ y_1^{(2)} & y_2^{(2)} & \dots & y_K^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(N)} & y_2^{(N)} & \dots & y_K^{(N)} \end{pmatrix} \in \mathbb{R}^{N \times K}$$

$$\begin{aligned} \frac{\partial J}{\partial \hat{y}_\beta^{(\alpha)}} &= \frac{\partial}{\partial \hat{y}_\beta^{(\alpha)}} \left[ -\frac{1}{N} \sum_{i=1}^N \sum_{k=1}^K y_k^{(i)} \log(\hat{y}_k^{(i)}) \right] \\ &= -\frac{1}{N} \frac{\partial}{\partial \hat{y}_\beta^{(\alpha)}} \left[ \sum_{i=1}^N \sum_{k=1}^K y_k^{(i)} \log(\hat{y}_k^{(i)}) \right] \\ &= -\frac{1}{N} \frac{\partial}{\partial \hat{y}_\beta^{(\alpha)}} \left[ \sum_{k=1}^K y_k^{(\alpha)} \log(\hat{y}_k^{(\alpha)}) \right] \\ &= -\frac{1}{N} \frac{\partial}{\partial \hat{y}_\beta^{(\alpha)}} \left[ y_\beta^{(\alpha)} \log(\hat{y}_\beta^{(\alpha)}) \right] \\ &= -\frac{1}{N} \cdot \frac{y_\beta^{(\alpha)}}{\hat{y}_\beta^{(\alpha)}} \quad \frac{\partial J}{\partial \hat{y}_j^{(i)}} = -\frac{1}{N} \frac{y_j^{(i)}}{\hat{y}_j^{(i)}} \end{aligned}$$

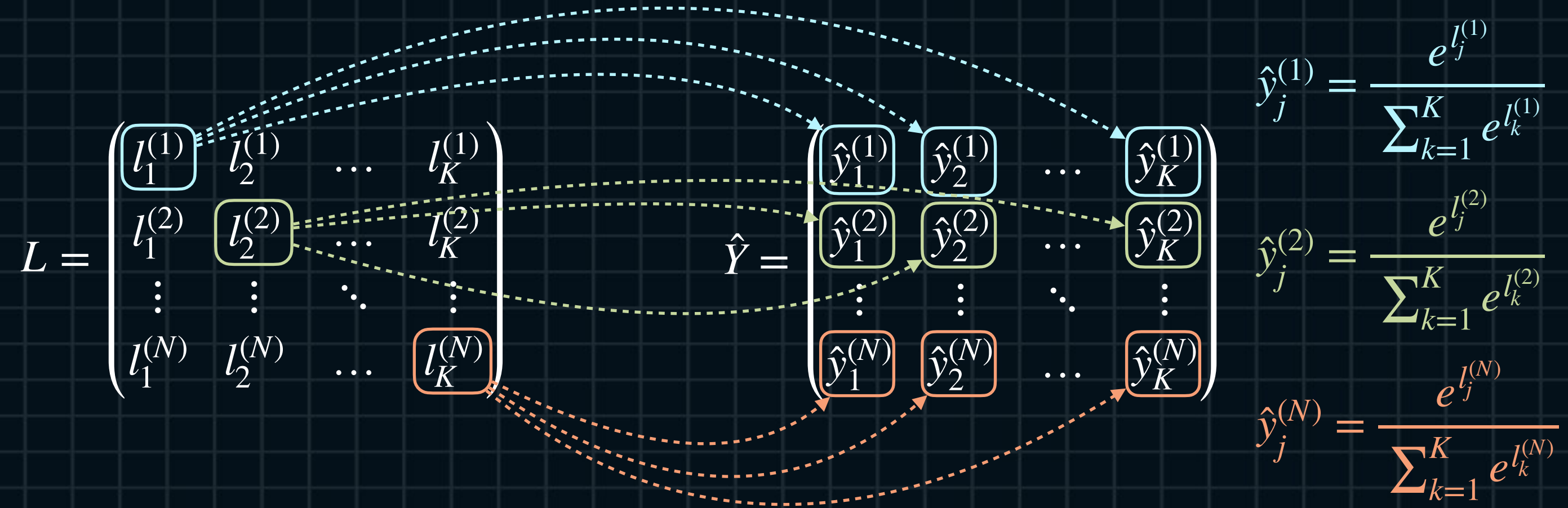
$$d\hat{Y} = \begin{pmatrix} d\vec{\hat{y}}^{(1)} \\ d\vec{\hat{y}}^{(2)} \\ \vdots \\ d\vec{\hat{y}}^{(N)} \end{pmatrix} = \begin{pmatrix} d\hat{y}_1^{(1)} & d\hat{y}_2^{(1)} & \dots & d\hat{y}_K^{(1)} \\ d\hat{y}_1^{(2)} & d\hat{y}_2^{(2)} & \dots & d\hat{y}_K^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ d\hat{y}_1^{(N)} & d\hat{y}_2^{(N)} & \dots & d\hat{y}_K^{(N)} \end{pmatrix} = -\frac{1}{N} \begin{pmatrix} \frac{y_1^{(1)}}{\hat{y}_1^{(1)}} & \frac{y_2^{(1)}}{\hat{y}_2^{(1)}} & \dots & \frac{y_K^{(1)}}{\hat{y}_K^{(1)}} \\ \frac{y_1^{(2)}}{\hat{y}_1^{(2)}} & \frac{y_2^{(2)}}{\hat{y}_2^{(2)}} & \dots & \frac{y_K^{(2)}}{\hat{y}_K^{(2)}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{y_1^{(N)}}{\hat{y}_1^{(N)}} & \frac{y_2^{(N)}}{\hat{y}_2^{(N)}} & \dots & \frac{y_K^{(N)}}{\hat{y}_K^{(N)}} \end{pmatrix}$$

$$d\hat{Y} = -\frac{1}{N} * Y / \hat{Y}$$

# Lecture.10 Expanded Jacobians - Softmax and Expanded Jacobians

## Total Derivative within Softmax

$$\hat{y}_j^{(i)} = \frac{e^{l_j^{(i)}}}{\sum_{k=1}^K e^{l_k^{(i)}}}$$



$$\begin{aligned} \frac{\partial J}{\partial l_j^{(i)}} &= \frac{\partial J}{\partial \hat{y}_1^{(i)}} \frac{\partial \hat{y}_1^{(i)}}{\partial l_j^{(i)}} + \frac{\partial J}{\partial \hat{y}_2^{(i)}} \frac{\partial \hat{y}_2^{(i)}}{\partial l_j^{(i)}} + \dots + \frac{\partial J}{\partial \hat{y}_j^{(i)}} \frac{\partial \hat{y}_j^{(i)}}{\partial l_j^{(i)}} + \dots + \frac{\partial J}{\partial \hat{y}_K^{(i)}} \frac{\partial \hat{y}_K^{(i)}}{\partial l_j^{(i)}} \\ &= \sum_{k=1}^K \frac{\partial J}{\partial \hat{y}_k^{(i)}} \frac{\partial \hat{y}_k^{(i)}}{\partial l_j^{(i)}} \end{aligned}$$



# Lecture.10 Expanded Jacobians - Softmax and Expanded Jacobians

## Total Derivative Calculation

$$\begin{aligned}
 \frac{\partial J}{\partial l_j^{(i)}} &= \frac{\partial J}{\partial \hat{y}_1^{(i)}} \frac{\partial \hat{y}_1^{(i)}}{\partial l_j^{(i)}} + \frac{\partial J}{\partial \hat{y}_2^{(i)}} \frac{\partial \hat{y}_2^{(i)}}{\partial l_j^{(i)}} + \dots + \frac{\partial J}{\partial \hat{y}_j^{(i)}} \frac{\partial \hat{y}_j^{(i)}}{\partial l_j^{(i)}} + \dots + \frac{\partial J}{\partial \hat{y}_K^{(i)}} \frac{\partial \hat{y}_K^{(i)}}{\partial l_j^{(i)}} \\
 &= d\hat{y}_1^{(i)} \frac{\partial \hat{y}_1^{(i)}}{\partial l_j^{(i)}} + d\hat{y}_2^{(i)} \frac{\partial \hat{y}_2^{(i)}}{\partial l_j^{(i)}} + \dots + d\hat{y}_j^{(i)} \frac{\partial \hat{y}_j^{(i)}}{\partial l_j^{(i)}} + \dots + d\hat{y}_K^{(i)} \frac{\partial \hat{y}_K^{(i)}}{\partial l_j^{(i)}} \\
 &= d\hat{y}_1^{(i)} \cdot (-\hat{y}_1^{(i)}\hat{y}_j^{(i)}) + d\hat{y}_2^{(i)} \cdot (-\hat{y}_2^{(i)}\hat{y}_j^{(i)}) + \dots + d\hat{y}_j^{(i)} \cdot (\hat{y}_j^{(i)}(1 - \hat{y}_j^{(i)})) + \dots + d\hat{y}_K^{(i)} \cdot (-\hat{y}_K^{(i)}\hat{y}_j^{(i)}) \\
 &= d\hat{y}_j^{(i)}\hat{y}_j^{(i)} + d\hat{y}_1^{(i)} \cdot (-\hat{y}_1^{(i)}\hat{y}_j^{(i)}) + d\hat{y}_2^{(i)} \cdot (-\hat{y}_2^{(i)}\hat{y}_j^{(i)}) + \dots + d\hat{y}_j^{(i)} \cdot (-\hat{y}_j^{(i)}\hat{y}_j^{(i)}) + \dots + d\hat{y}_K^{(i)} \cdot (-\hat{y}_K^{(i)}\hat{y}_j^{(i)}) \\
 &= d\hat{y}_j^{(i)}\hat{y}_j^{(i)} - \hat{y}_j^{(i)} \sum_{k=1}^K d\hat{y}_k^{(i)} \cdot \hat{y}_k^{(i)} \\
 &= -\frac{1}{N} \left[ \frac{y_j^{(i)}}{\hat{y}_j^{(i)}} \cdot \hat{y}_j^{(i)} - \hat{y}_j^{(i)} \sum_{k=1}^K \frac{y_k^{(i)}}{\hat{y}_k^{(i)}} \cdot \hat{y}_k^{(i)} \right] \\
 &= -\frac{1}{N} \left[ y_j^{(i)} - \hat{y}_j^{(i)} \sum_{k=1}^K y_k^{(i)} \right] \\
 &= -\frac{1}{N} \left[ y_j^{(i)} - \hat{y}_j^{(i)} \right]
 \end{aligned}$$

$$\frac{\partial J}{\partial \hat{y}_j^{(i)}} = -\frac{1}{N} \frac{y_j^{(i)}}{\hat{y}_j^{(i)}} \quad \frac{\partial \hat{y}_\alpha^{(i)}}{\partial l_\beta^{(i)}} = \begin{cases} \hat{y}_\alpha^{(i)}(1 - \hat{y}_\alpha^{(i)}), & \text{if } \alpha = \beta \\ -\hat{y}_\alpha^{(i)}\hat{y}_\beta^{(i)}, & \text{if } \alpha \neq \beta \end{cases}$$

## Expanded Jacobians at Softmax

$$dl_j^{(i)} = -\frac{1}{N} \left[ y_j^{(i)} - \hat{y}_j^{(i)} \right]$$

$$dL = \begin{pmatrix} dl_1^{(1)} & dl_2^{(1)} & \dots & dl_K^{(1)} \\ dl_1^{(2)} & dl_2^{(2)} & \dots & dl_K^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ dl_1^{(N)} & dl_2^{(N)} & \dots & dl_K^{(N)} \end{pmatrix} = -\frac{1}{N} \begin{pmatrix} y_1^{(1)} - \hat{y}_1^{(1)} & y_2^{(1)} - \hat{y}_2^{(1)} & \dots & y_K^{(1)} - \hat{y}_K^{(1)} \\ y_1^{(2)} - \hat{y}_1^{(2)} & y_2^{(2)} - \hat{y}_2^{(2)} & \dots & y_K^{(2)} - \hat{y}_K^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(N)} - \hat{y}_1^{(N)} & y_2^{(N)} - \hat{y}_2^{(N)} & \dots & y_K^{(N)} - \hat{y}_K^{(N)} \end{pmatrix}$$

$$dL = -\frac{1}{N} * (Y - \hat{Y})$$



# Lecture.10 Expanded Jacobians in Deep Learning

## - Affine Function and Expanded Jacobians

### Matrix Multiplication Review

$$A \in \mathbb{R}^{\alpha \times \beta}, B \in \mathbb{R}^{\beta \times \gamma}, C \in \mathbb{R}^{\alpha \times \gamma}$$

$$C = AB \quad c_{ij} = \sum_{k=1}^{\beta} a_{ik} b_{kj}$$

$$\text{Row}_i(A) \sim \text{Row}_i(C)$$

$$\text{Col}_j(B) \sim \text{Col}_j(C)$$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1\beta} \\ a_{21} & a_{22} & \dots & a_{2\beta} \\ \vdots & \vdots & & \vdots \\ a_{i1} & a_{i2} & \dots & a_{i\beta} \\ \vdots & \vdots & & \vdots \\ a_{\alpha 1} & a_{\alpha 2} & \dots & a_{\alpha \beta} \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1j} & \dots & b_{1\gamma} \\ b_{21} & b_{22} & \dots & b_{2j} & \dots & b_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ b_{\beta 1} & b_{\beta 2} & \dots & b_{\beta j} & \dots & b_{\beta \gamma} \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1j} & \dots & c_{1\gamma} \\ c_{21} & c_{22} & \dots & c_{2j} & \dots & c_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{i1} & c_{i2} & \dots & c_{ij} & \dots & c_{i\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha j} & \dots & c_{\alpha \gamma} \end{pmatrix}$$



# Lecture.10 Expanded Jacobians in Deep Learning

## - Affine Function and Expanded Jacobians

### Matrix Multiplication Review

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1\beta} \\ a_{21} & a_{22} & \dots & a_{2\beta} \\ \vdots & \vdots & & \vdots \\ a_{i1} & a_{i2} & \dots & a_{i\beta} \\ \vdots & \vdots & & \vdots \\ a_{\alpha 1} & a_{\alpha 2} & \dots & a_{\alpha \beta} \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1j} & \dots & b_{1\gamma} \\ b_{21} & b_{22} & \dots & b_{2j} & \dots & b_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ b_{\beta 1} & b_{\beta 2} & \dots & b_{\beta j} & \dots & b_{\beta \gamma} \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1j} & \dots & c_{1\gamma} \\ c_{21} & c_{22} & \dots & c_{2j} & \dots & c_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{i1} & c_{i2} & \dots & c_{ij} & \dots & c_{i\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha j} & \dots & c_{\alpha \gamma} \end{pmatrix}$$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1\beta} \\ a_{21} & a_{22} & \dots & a_{2\beta} \\ \vdots & \vdots & & \vdots \\ a_{i1} & a_{i2} & \dots & a_{i\beta} \\ \vdots & \vdots & & \vdots \\ a_{\alpha 1} & a_{\alpha 2} & \dots & a_{\alpha \beta} \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1j} & \dots & b_{1\gamma} \\ b_{21} & b_{22} & \dots & b_{2j} & \dots & b_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ b_{\beta 1} & b_{\beta 2} & \dots & b_{\beta j} & \dots & b_{\beta \gamma} \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1j} & \dots & c_{1\gamma} \\ c_{21} & c_{22} & \dots & c_{2j} & \dots & c_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{i1} & c_{i2} & \dots & c_{ij} & \dots & c_{i\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha j} & \dots & c_{\alpha \gamma} \end{pmatrix}$$



## Lecture.10 Expanded Jacobians in Deep Learning

### - Affine Function and Expanded Jacobians

#### Matrix Multiplication Review

$$M = (m_{ij}) \quad M^T = ((m_T)_{ij})$$

$$m_{ij} = (m_T)_{ji}$$

$$Row_i(M) = (m_{i1} \quad m_{i2} \quad \dots \quad m_{i\beta})$$

$$Col_j(M) = \begin{pmatrix} m_{1j} \\ m_{2j} \\ \vdots \\ m_{\alpha j} \end{pmatrix}$$



Related Tensors(Matrix Multiplication)

$$C = A \cdot B$$

$$A \in \mathbb{R}^{\alpha \times \beta}, B \in \mathbb{R}^{\beta \times \gamma}, C \in \mathbb{R}^{\alpha \times \gamma}$$

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1\beta} \\ a_{21} & a_{22} & \dots & a_{2\beta} \\ \vdots & \vdots & \ddots & \vdots \\ a_{\alpha 1} & a_{\alpha 2} & \dots & a_{\alpha\beta} \end{pmatrix}, \quad dA = \begin{pmatrix} da_{11} & da_{12} & \dots & da_{1\beta} \\ da_{21} & da_{22} & \dots & da_{2\beta} \\ \vdots & \vdots & \ddots & \vdots \\ da_{\alpha 1} & da_{\alpha 2} & \dots & da_{\alpha\beta} \end{pmatrix}$$

$$B = \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1\gamma} \\ b_{21} & b_{22} & \dots & b_{2\gamma} \\ \vdots & \vdots & \ddots & \vdots \\ b_{\beta 1} & b_{\beta 2} & \dots & b_{\beta\gamma} \end{pmatrix}, \quad dB = \begin{pmatrix} db_{11} & db_{12} & \dots & db_{1\gamma} \\ db_{21} & db_{22} & \dots & db_{2\gamma} \\ \vdots & \vdots & \ddots & \vdots \\ db_{\beta 1} & db_{\beta 2} & \dots & db_{\beta\gamma} \end{pmatrix}$$

$$C = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1\gamma} \\ c_{21} & c_{22} & \dots & c_{2\gamma} \\ \vdots & \vdots & \ddots & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha\gamma} \end{pmatrix}, \quad dC = \begin{pmatrix} dc_{11} & dc_{12} & \dots & dc_{1\gamma} \\ dc_{21} & dc_{22} & \dots & dc_{2\gamma} \\ \vdots & \vdots & \ddots & \vdots \\ dc_{\alpha 1} & dc_{\alpha 2} & \dots & dc_{\alpha\gamma} \end{pmatrix}$$



# Lecture.10 Expanded Jacobians in Deep Learning

## - Affine Function and Expanded Jacobians

### Matrix Multiplication and Expanded Jacobians

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1\beta} \\ a_{21} & a_{22} & \dots & a_{2\beta} \\ \vdots & \vdots & & \vdots \\ a_{i1} & a_{i2} & \dots & a_{i\beta} \\ \vdots & \vdots & & \vdots \\ a_{\alpha 1} & a_{\alpha 2} & \dots & a_{\alpha \beta} \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1j} & \dots & b_{1\gamma} \\ b_{21} & b_{22} & \dots & b_{2j} & \dots & b_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ b_{\beta 1} & b_{\beta 2} & \dots & b_{\beta j} & \dots & b_{\beta \gamma} \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1j} & \dots & c_{1\gamma} \\ c_{21} & c_{22} & \dots & c_{2j} & \dots & c_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{i1} & c_{i2} & \dots & c_{ij} & \dots & c_{i\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha j} & \dots & c_{\alpha \gamma} \end{pmatrix}$$

$$\begin{aligned} \frac{\partial J}{\partial a_{ij}} &= \frac{\partial J}{\partial c_{i1}} \frac{\partial c_{i1}}{\partial a_{ij}} + \frac{\partial J}{\partial c_{i2}} \frac{\partial c_{i2}}{\partial a_{ij}} + \dots + \frac{\partial J}{\partial c_{i\gamma}} \frac{\partial c_{i\gamma}}{\partial a_{ij}} \\ &= dc_{i1} \cdot b_{j1} + dc_{i2} \cdot b_{j2} + \dots + dc_{i\gamma} \cdot b_{j\gamma} \\ &= dc_{i1} \cdot (b_T)_{1j} + dc_{i2} \cdot (b_T)_{2j} + \dots + dc_{i\gamma} \cdot (b_T)_{\gamma j} \\ &= Row_i(dC) \cdot Col_j(B^T) \end{aligned}$$

$$da_{ij} = Row_i(dC) \cdot Col_j(B^T)$$



## Matrix Multiplication and Expanded Jacobians

$$da_{ij} = \text{Row}_i(dC) \cdot \text{Col}_j(B^T)$$

$$dA = \begin{pmatrix} da_{11} & da_{12} & \dots & da_{1\beta} \\ da_{21} & da_{22} & \dots & da_{2\beta} \\ \vdots & \vdots & \ddots & \vdots \\ da_{\alpha 1} & da_{\alpha 2} & \dots & da_{\alpha\beta} \end{pmatrix} = \begin{pmatrix} \text{Row}_1(dC) \cdot \text{Col}_1(B^T) & \text{Row}_1(dC) \cdot \text{Col}_2(B^T) & \dots & \text{Row}_1(dC) \cdot \text{Col}_\beta(B^T) \\ \text{Row}_2(dC) \cdot \text{Col}_1(B^T) & \text{Row}_2(dC) \cdot \text{Col}_2(B^T) & \dots & \text{Row}_2(dC) \cdot \text{Col}_\beta(B^T) \\ \vdots & \vdots & \ddots & \vdots \\ \text{Row}_\alpha(dC) \cdot \text{Col}_1(B^T) & \text{Row}_\alpha(dC) \cdot \text{Col}_2(B^T) & \dots & \text{Row}_\alpha(dC) \cdot \text{Col}_\beta(B^T) \end{pmatrix}$$

$$dA = dC \cdot B^T$$

$$C = A \cdot B \quad \Rightarrow \quad dA = dC \cdot B^T$$

# Lecture.10 Expanded Jacobians in Deep Learning

## - Affine Function and Expanded Jacobians

### Matrix Multiplication and Expanded Jacobians

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1\beta} \\ a_{21} & a_{22} & \dots & a_{2\beta} \\ \vdots & \vdots & & \vdots \\ a_{i1} & a_{i2} & \dots & a_{i\beta} \\ \vdots & \vdots & & \vdots \\ a_{\alpha 1} & a_{\alpha 2} & \dots & a_{\alpha \beta} \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} & \dots & b_{1j} & \dots & b_{1\gamma} \\ b_{21} & b_{22} & \dots & b_{2j} & \dots & b_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ \vdots & \vdots & & \vdots & & \vdots \\ b_{\beta 1} & b_{\beta 2} & \dots & b_{\beta j} & \dots & b_{\beta \gamma} \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1j} & \dots & c_{1\gamma} \\ c_{21} & c_{22} & \dots & c_{2j} & \dots & c_{2\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{i1} & c_{i2} & \dots & c_{ij} & \dots & c_{i\gamma} \\ \vdots & \vdots & & \vdots & & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha j} & \dots & c_{\alpha \gamma} \end{pmatrix}$$

$$\begin{aligned} \frac{\partial J}{\partial b_{ij}} &= \frac{\partial J}{\partial c_{1j}} \frac{\partial c_{1j}}{\partial b_{ij}} + \frac{\partial J}{\partial c_{2j}} \frac{\partial c_{2j}}{\partial b_{ij}} + \dots + \frac{\partial J}{\partial c_{\alpha j}} \frac{\partial c_{\alpha j}}{\partial b_{ij}} \\ &= dc_{1j} \cdot a_{1i} + dc_{2j} \cdot a_{2i} + \dots + dc_{\alpha j} \cdot a_{\alpha i} \\ &= (a_T)_{i1} \cdot dc_{1j} + (a_T)_{i2} \cdot dc_{2j} + \dots + (a_T)_{i\alpha} \cdot dc_{\alpha j} \\ &= \text{Row}_i(A^T) \cdot \text{Col}_j(dC) \end{aligned}$$

$$db_{ij} = \text{Row}_i(A^T) \cdot \text{Col}_j(dC)$$

$$dB = A^T \cdot dC \quad \frac{\partial J}{\partial B} = A^T \cdot \frac{\partial J}{\partial C}$$

$$\begin{array}{c} a_{1i}, a_{2i}, \dots, a_{\alpha i} \sim b_{ij} \\ \downarrow \\ c_{1j}, c_{2j}, \dots, c_{\alpha j} \end{array}$$



## Matrix Multiplication and Expanded Jacobians

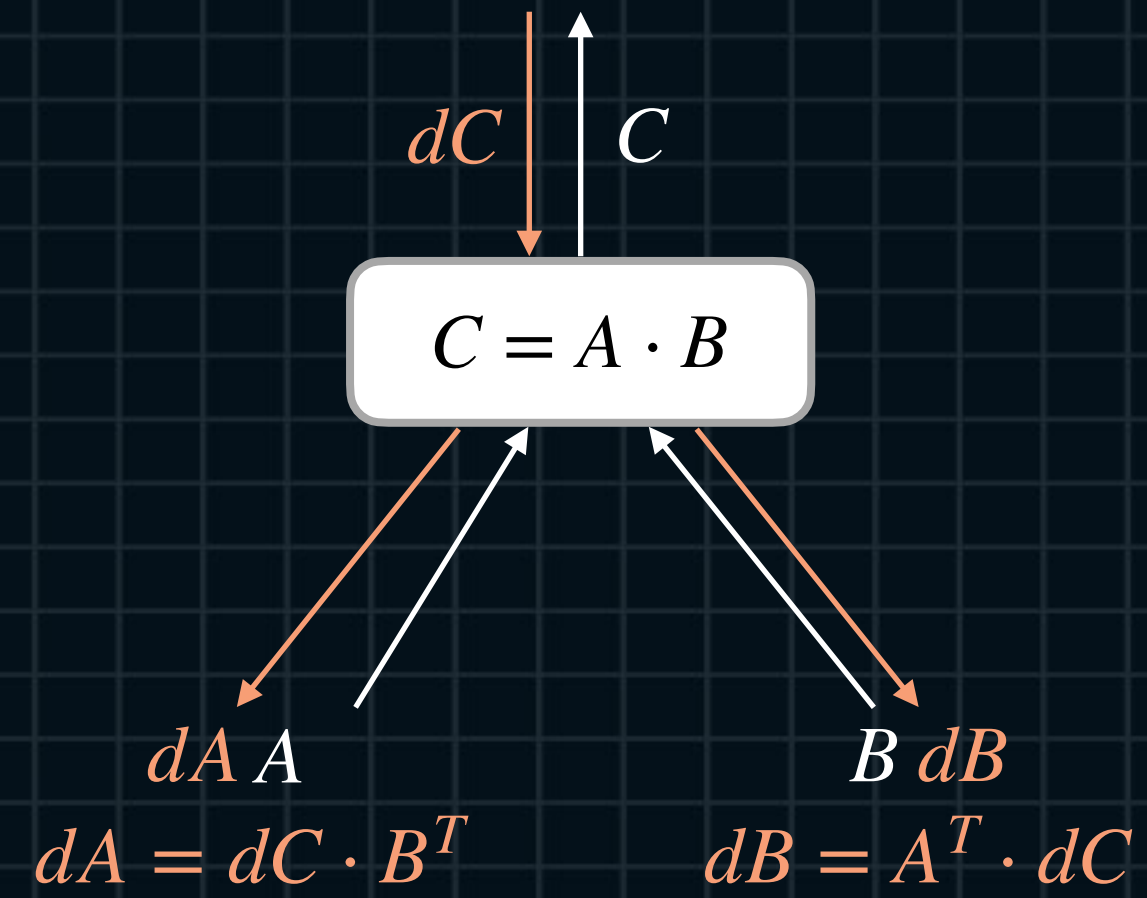
$$db_{ij} = \text{Row}_i(A^T) \cdot \text{Col}_j(dC)$$

$$dB = \begin{pmatrix} db_{11} & db_{12} & \dots & db_{1\gamma} \\ db_{21} & db_{22} & \dots & db_{2\gamma} \\ \vdots & \vdots & \ddots & \vdots \\ db_{\beta 1} & db_{\beta 2} & \dots & db_{\beta \gamma} \end{pmatrix} = \begin{pmatrix} \text{Row}_1(A^T) \cdot \text{Col}_1(dC) & \text{Row}_1(A^T) \cdot \text{Col}_2(dC) & \dots & \text{Row}_1(A^T) \cdot \text{Col}_\gamma(dC) \\ \text{Row}_2(A^T) \cdot \text{Col}_1(dC) & \text{Row}_2(A^T) \cdot \text{Col}_2(dC) & \dots & \text{Row}_2(A^T) \cdot \text{Col}_\gamma(dC) \\ \vdots & \vdots & \ddots & \vdots \\ \text{Row}_\beta(A^T) \cdot \text{Col}_1(dC) & \text{Row}_\beta(A^T) \cdot \text{Col}_2(dC) & \dots & \text{Row}_\beta(A^T) \cdot \text{Col}_\gamma(dC) \end{pmatrix}$$

$$dB = A^T \cdot dC$$

$$C = A \cdot B \quad \Longrightarrow \quad dB = A^T \cdot dC$$

## Matrix Multiplication and Expanded Jacobians





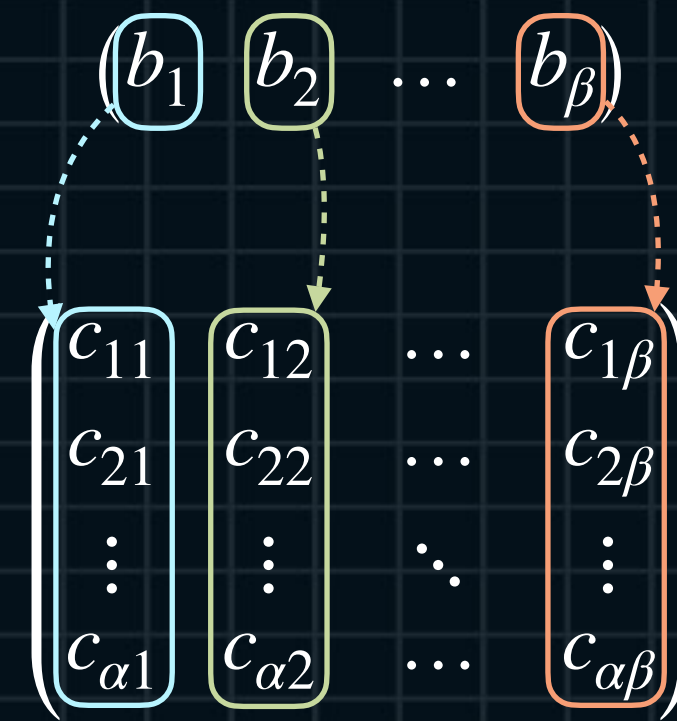
# Lecture.10 Expanded Jacobians in Deep Learning

## - Affine Function and Expanded Jacobians

### Bias Vector and Expanded Jacobians

$$C = A + (\vec{b})^T$$

$$\begin{pmatrix} c_{11} & c_{12} & \dots & c_{1\beta} \\ c_{21} & c_{22} & \dots & c_{2\beta} \\ \vdots & \vdots & \ddots & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha \beta} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1\beta} \\ a_{21} & a_{22} & \dots & a_{2\beta} \\ \vdots & \vdots & \ddots & \vdots \\ a_{\alpha 1} & a_{\alpha 2} & \dots & a_{\alpha \beta} \end{pmatrix} + (b_1 \ b_2 \ \dots \ b_\beta) = \begin{pmatrix} a_{11} + b_1 & a_{12} + b_2 & \dots & a_{1\beta} + b_\beta \\ a_{21} + b_1 & a_{22} + b_2 & \dots & a_{2\beta} + b_\beta \\ \vdots & \vdots & \ddots & \vdots \\ a_{\alpha 1} + b_1 & a_{\alpha 2} + b_2 & \dots & a_{\alpha \beta} + b_\beta \end{pmatrix}$$



## Bias Vector and Expanded Jacobians

$$C = A + (\vec{b})^T$$

$$\begin{pmatrix} c_{11} & c_{12} & \dots & c_{1\beta} \\ c_{21} & c_{22} & \dots & c_{2\beta} \\ \vdots & \vdots & \ddots & \vdots \\ c_{\alpha 1} & c_{\alpha 2} & \dots & c_{\alpha\beta} \end{pmatrix} = \begin{pmatrix} a_{11} + b_1 & a_{12} + b_2 & \dots & a_{1\beta} + b_\beta \\ a_{21} + b_1 & a_{22} + b_2 & \dots & a_{2\beta} + b_\beta \\ \vdots & \vdots & \ddots & \vdots \\ a_{\alpha 1} + b_1 & a_{\alpha 2} + b_2 & \dots & a_{\alpha\beta} + b_\beta \end{pmatrix}$$

$$\frac{\partial J}{\partial b_i} = \frac{\partial J}{\partial c_{1i}} \frac{\partial c_{1i}}{\partial b_i} + \frac{\partial J}{\partial c_{2i}} \frac{\partial c_{2i}}{\partial b_i} + \dots + \frac{\partial J}{\partial c_{\alpha i}} \frac{\partial c_{\alpha i}}{\partial b_i}$$

$$= dc_{1i} + dc_{2i} + \dots + dc_{\alpha i}$$

$$= \sum_{p=1}^{\alpha} dc_{pi}$$



## Lecture.10 Expanded Jacobians in Deep Learning

## - Affine Function and Expanded Jacobians

### Bias Vector and Expanded Jacobians

$$\frac{\partial J}{\partial b_i} = \sum_{p=1}^{\alpha} dc_{pi}$$

$$d\vec{b} = \begin{pmatrix} db_1 \\ db_2 \\ \vdots \\ db_{\beta} \end{pmatrix} = \begin{pmatrix} \sum_{p=1}^{\alpha} dc_{p1} \\ \sum_{p=1}^{\alpha} dc_{p2} \\ \vdots \\ \sum_{p=1}^{\alpha} dc_{p\beta} \end{pmatrix}$$

$$\begin{pmatrix} dc_{11} & dc_{12} & \dots & dc_{1\beta} \\ dc_{21} & dc_{22} & \dots & dc_{2\beta} \\ \vdots & \vdots & \ddots & \vdots \\ dc_{\alpha 1} & dc_{\alpha 2} & \dots & dc_{\alpha \beta} \end{pmatrix}$$
$$\sum_{k=1}^{\alpha} dc_{k1} \quad \sum_{k=1}^{\alpha} dc_{k2} \quad \sum_{k=1}^{\alpha} dc_{k\beta}$$

$$d\vec{b} = \text{sum}(dC, \text{axis} = 0)$$

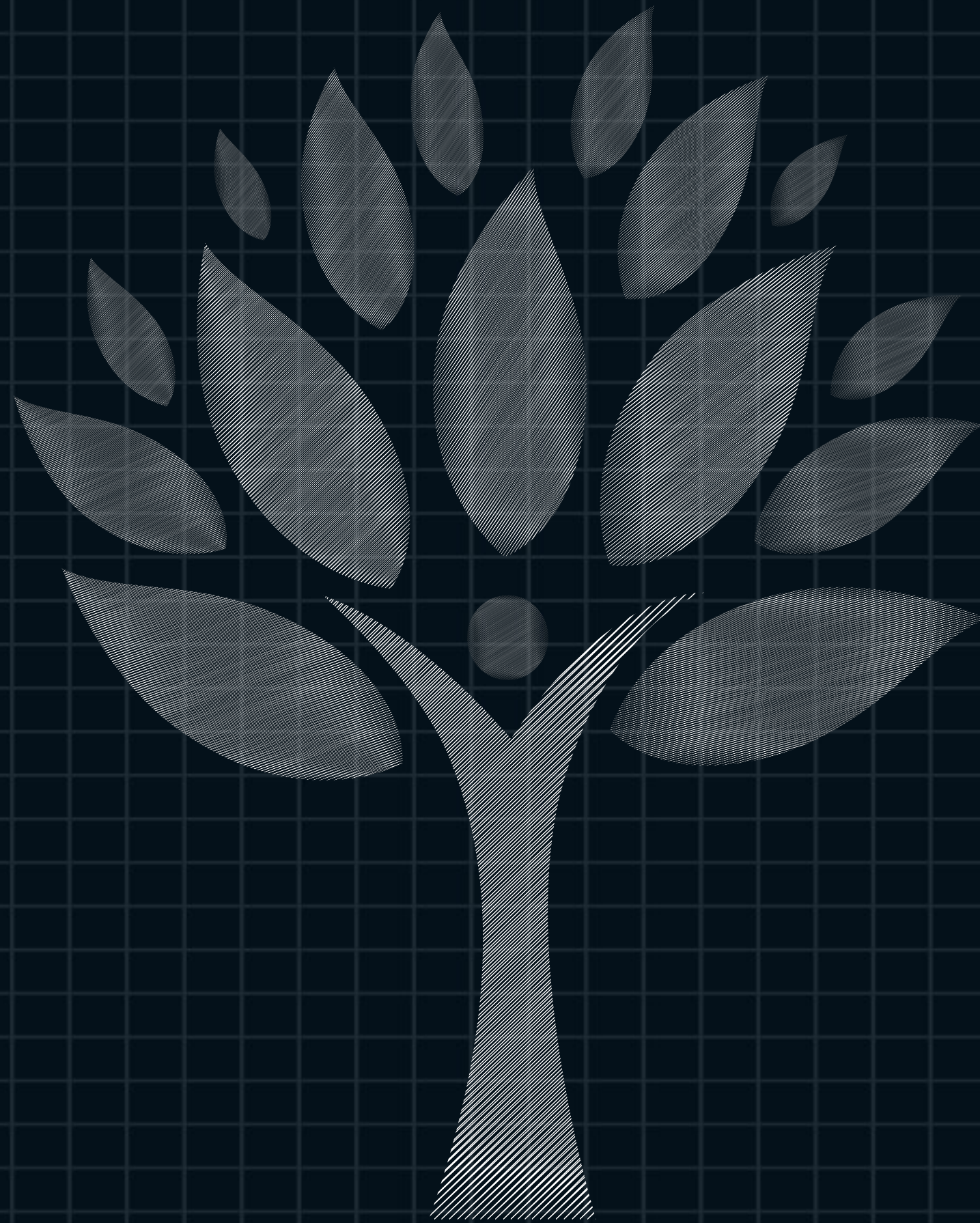
## Affine Function and Expanded Jacobians

$$\begin{array}{c} Z \in \mathbb{R}^{N \times l_o} \\ \uparrow \\ \boxed{Z = X \cdot W + (\vec{b})^T} \\ \uparrow \\ X \in \mathbb{R}^{N \times l_I} \end{array} \quad \begin{array}{l} W \in \mathbb{R}^{l_I \times l_o} \\ \vec{b} \in \mathbb{R}^{l_o} \end{array}$$

$$Z = X \cdot W + (\vec{b})^T$$
$$(N, l_o) = (N, l_I) \cdot (l_I, l_o) + (1, l_o)$$

$$dX = dZ \cdot W^T$$
$$dW = X^T \cdot dZ \quad d\vec{b} = \text{sum}(dZ, \text{axis} = 0)$$





# Backpropagation and Jacobian Matrices

## Lecture.10

### Expanded Jacobians in Deep Learning