

The background of the slide is a dense, overlapping field of 3D-rendered numbers in various shades of blue and white. The numbers are of different sizes and are scattered across the entire frame, creating a sense of depth and complexity. Some numbers are more prominent than others, while others are partially obscured.

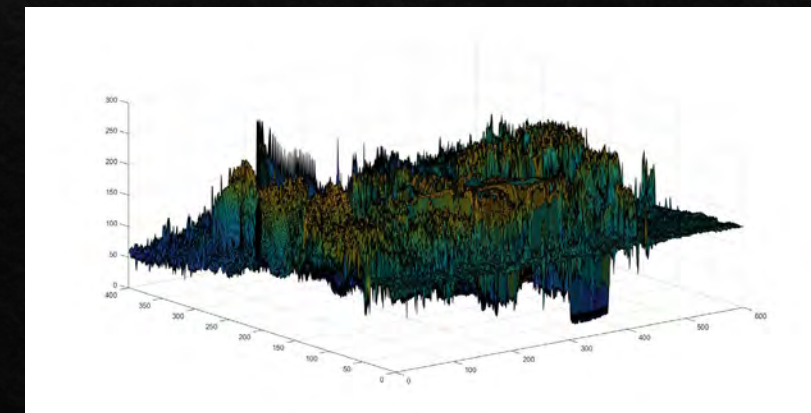
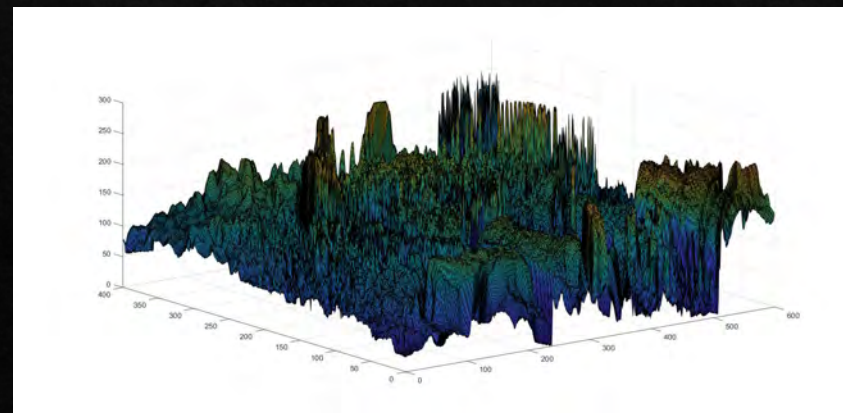
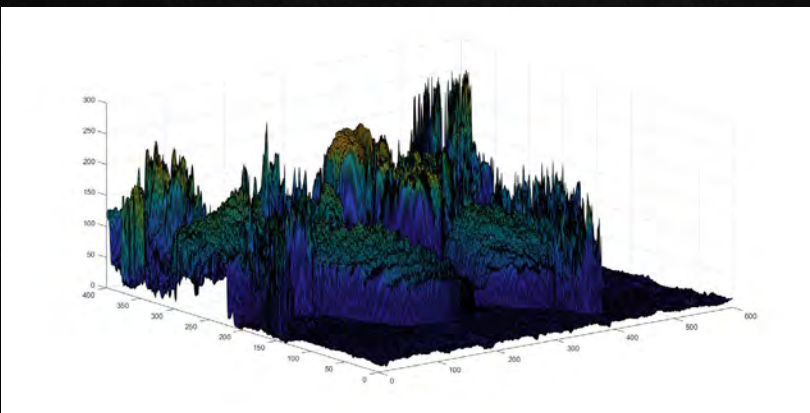
Image Features - 1

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What the Computer Sees



Problems with this view:

- ◆ Too much useless data
- ◆ Highly dependent on viewpoint and lighting changes
- ◆ All parts of the image have equal importance
- ◆ Not discriminative enough (all images look similar)
- ◆ Not task-specific
- ◆ Dependent on size of image

The Solution: Features

- ◆ Reduce computation cost
- ◆ Can be invariant to change of viewpoint, illumination
- ◆ Information content high
- ◆ Uniqueness
- ◆ Can be tuned to a task at hand
- ◆ Can be made independent of image size

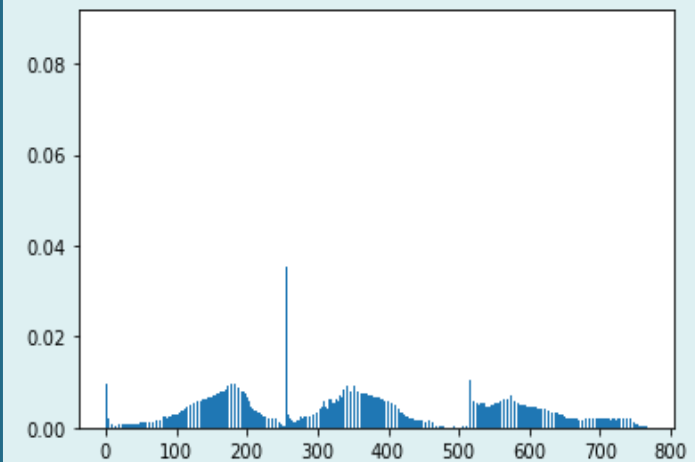
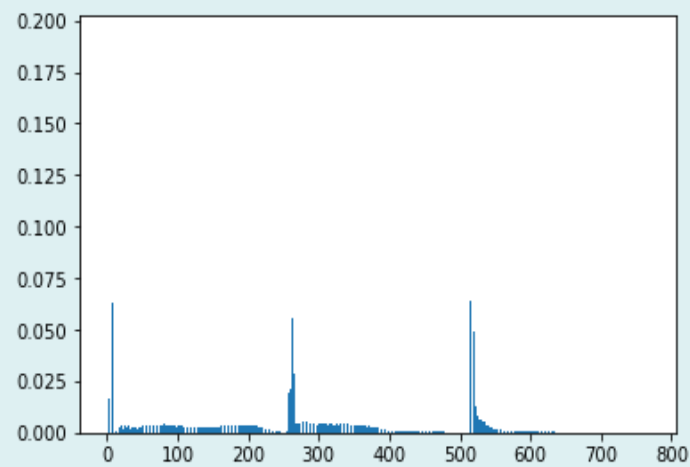
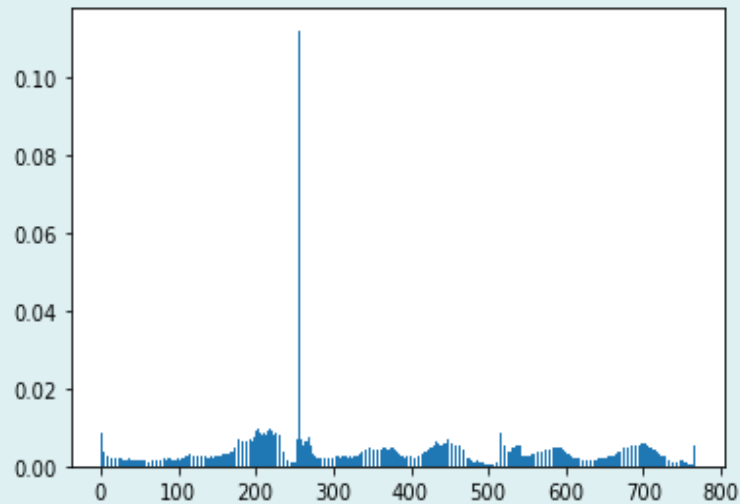
Features

- ◆ Features can be global or local
- ◆ Global
 - ◆ Collected from the whole image
 - ◆ Examples: Color histogram, LBP histogram
- ◆ Local
 - ◆ Collected from meaningful parts of the image, such as edges or corners.
 - ◆ Examples: SIFT features, HOG features

Color Histogram

- ◇ Global feature
- ◇ A frequency distribution of pixel intensity values in an image
- ◇ For grayscale images, there are at most 256 possible intensities
- ◇ For color images, there are at most 768 (256×3) possible intensities
- ◇ Needs to be normalized for image size
- ◇ Not very effective, but very simple to compute

Color Histogram



Distance Measures

- ◇ If A, B and C are points in space, then their distance $D(A,B)$ is any function that follows these rules:
 - ◇ $D(A, A) = 0$
 - ◇ $D(A, B) > 0$ if $A \neq B$
 - ◇ $D(A, B) = D(B, A)$ [Symmetry rule]
 - ◇ $D(A, B) + D(B, C) \geq D(A, C)$ [Triangle inequality]

Common Distance Measures

- ◊ Hamming Distance
- ◊ Euclidean Distance
- ◊ Manhattan Distance
- ◊ Cosine Distance
- ◊ Many, many more

