

1 Fun Syntax

K	$:=$	<code>Nil, Cons, Tup</code>	<i>Constructors</i>
D	$:=$	<code>hd, tl, fst, snd</code>	<i>Destructors</i>
F	$:=$	<code>def $f(\bar{x}; \bar{\alpha}) := t$</code>	<i>Definitions</i>
t	$:=$		<i>Terms</i>
		x	<i>Variables</i>
		$\ulcorner n \urcorner$	<i>Literals</i>
		$t \odot t$	<i>Binary Operations</i>
		<code>ifz(t, t, t)</code>	<i>Zero Conditional</i>
		<code>let $x := t$ in t</code>	<i>Let-Bindings</i>
		$f(\bar{t}; \bar{\alpha}) := t$	<i>Top-Level Calls</i>
		$K(\bar{t})$	<i>Constructors</i>
		<code>case t of $\{K(\bar{x}) \Rightarrow t\}$</code>	<i>Case Expressions</i>
		$t.D(\bar{t})$	<i>Destructors</i>
		<code>cocase $\{D(\bar{x}) \Rightarrow t\}$</code>	<i>Cocase Expressions</i>
		$\lambda x. t$	<i>Lambda-Abstractions</i>
		$t \ t$	<i>Function Applications</i>
		<code>label $\alpha \ \{t\}$</code>	<i>Labels</i>
		<code>Goto($t; \alpha$)</code>	<i>Goto</i>

2 AxCore Syntax

K	$:=$	<code>Nil, Cons, Tup</code>	<i>Constructors</i>
D	$:=$	<code>hd, tl, fst, snd, ap</code>	<i>Destructors</i>
F	$:=$	<code>def $f(\bar{x}; \bar{\alpha}) := s$</code>	<i>Definitions</i>
p	$:=$		<i>Producers</i>
		x	<i>Variables</i>
		$\ulcorner n \urcorner$	<i>Literals</i>
		$\mu \alpha. s$	μ - Abstractions
		$K(\bar{p}; \bar{c})$	<i>Constructors</i>
		<code>cocase $\{D(\bar{x}; \bar{\alpha}) \Rightarrow s\}$</code>	<i>Cocase expressions</i>
c	$:=$		<i>Consumers</i>
		α	<i>Covariables</i>
		$\tilde{\mu} x. s$	$\tilde{\mu}$ - Abstractions
		$D(\bar{p}; \bar{c})$	<i>Destructors</i>
		<code>case $\{C(\bar{x}; \bar{\alpha}) \Rightarrow s\}$</code>	<i>Case-Expressions</i>
s	$:=$		<i>Statements</i>
		$\langle p \mid c \rangle$	<i>Cuts</i>
		$\odot(p, p; c)$	<i>Binary Operations</i>
		<code>ifz($p; s, s$)</code>	<i>Zero Conditional</i>
		$f(\bar{p}; \bar{c})$	<i>Top-level Calls</i>
		<code>Done</code>	<i>End of computation</i>

3 Translation

$\llbracket \cdot \rrbracket : \text{Fun} \rightarrow \text{AxCore}$

$\llbracket \text{def } f(\bar{x}; \bar{\alpha}) := t \rrbracket$	$:=$	$\text{def } f(\bar{x}; \bar{\alpha}, \alpha) := \langle \llbracket t \rrbracket \mid \alpha \rangle$
$\llbracket x \rrbracket$	$:=$	x
$\llbracket n \rrbracket$	$:=$	n
$\llbracket t_1 \odot t_2 \rrbracket$	$:=$	$\mu\alpha. \odot (\llbracket t_1 \rrbracket, \llbracket t_2 \rrbracket; \alpha)$
$\llbracket \text{ifz}(t_1, t_2, t_3) \rrbracket$	$:=$	$\mu\alpha. \text{ifz}(\llbracket t_1 \rrbracket, \langle \llbracket t_2 \rrbracket \mid \alpha \rangle, \langle \llbracket t_3 \rrbracket \mid \alpha \rangle)$
$\llbracket \text{let } x := t_1 \text{ in } t_2 \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t_1 \rrbracket \mid \tilde{\mu}x. \langle \llbracket t_2 \rrbracket \mid \alpha \rangle \rangle$
$\llbracket f(\bar{t}_i; \bar{\alpha}_j) \rrbracket$	$:=$	$\mu\alpha. f(\llbracket \bar{t}_i \rrbracket; \bar{\alpha}_j, \alpha)$
$\llbracket K(\bar{t}_i) \rrbracket$	$:=$	$K(\llbracket \bar{t}_i \rrbracket)$
$\llbracket \text{case } t \text{ of } \{ \overline{K_i(\bar{x}_{i,j}) \Rightarrow t_i} \} \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t \rrbracket \mid \text{case } \{ \overline{K_i(\bar{x}_{i,j}) \Rightarrow \langle \llbracket t_i \rrbracket \mid \alpha \rangle} \} \rangle$
$\llbracket t.D(\bar{t}_i) \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t \rrbracket \mid D(\llbracket \bar{t}_i \rrbracket; \alpha) \rangle$
$\llbracket \text{cocase } \{ \overline{D_i(\bar{x}_{i,j}) \Rightarrow t_i} \} \rrbracket$	$:=$	$\text{cocase } \{ \overline{D_i(\bar{x}_{i,j}; \alpha_i) \Rightarrow \langle \llbracket t_i \rrbracket \mid \alpha_i \rangle} \}$
$\llbracket \lambda x. t \rrbracket$	$:=$	$\text{cocase } \{ \text{ap}(x; \alpha) \Rightarrow \langle \llbracket t \rrbracket \mid \alpha \rangle \}$
$\llbracket t_1 \ t_2 \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t_1 \rrbracket \mid \text{ap}(\llbracket t_2 \rrbracket; \alpha) \rangle$
$\llbracket \text{label } \alpha \{ t \} \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t \rrbracket \mid \alpha \rangle$
$\llbracket \text{goto}(t; \alpha) \rrbracket$	$:=$	$\mu\beta. \langle \llbracket t \rrbracket \mid \alpha \rangle$

4 New Translation

$\llbracket \cdot \rrbracket : \text{Fun} \rightarrow \text{AxCore}$

$\llbracket \text{def } f(\bar{x}; \bar{\alpha}) := t \rrbracket$	$:=$	$\text{def } f(\bar{x}; \bar{\alpha}, \alpha) := \langle \llbracket t \rrbracket_\alpha \mid \alpha \rangle$
$\llbracket x \rrbracket$	$:=$	x
$\llbracket \lceil n \rceil \rrbracket$	$:=$	$\lceil n \rceil$
$\llbracket t_1 \odot t_2 \rrbracket$	$:=$	$\mu\alpha. \odot (\llbracket t_1 \rrbracket_\alpha, \llbracket t_2 \rrbracket_\alpha; \alpha)$
$\llbracket \text{ifz}(t_1, t_2, t_3) \rrbracket$	$:=$	$\mu\alpha. \text{ifz}(\llbracket t_1 \rrbracket_\alpha, \langle \llbracket t_2 \rrbracket_\alpha \mid \alpha \rangle, \langle \llbracket t_3 \rrbracket_\alpha \mid \alpha \rangle)$
$\llbracket \text{let } x := t_1 \text{ in } t_2 \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t_1 \rrbracket_\alpha \mid \tilde{\mu}x. \langle \llbracket t_2 \rrbracket_\alpha \mid \alpha \rangle \rangle$
$\llbracket f(\bar{t}_i; \bar{\alpha}_j) \rrbracket$	$:=$	$\mu\alpha. f(\llbracket \bar{t}_i \rrbracket_\alpha; \bar{\alpha}_j, \alpha)$
$\llbracket K(\bar{t}_i) \rrbracket$	$:=$	$K(\llbracket \bar{t}_i \rrbracket)$
$\llbracket \text{case } t \text{ of } \{ \overline{K_i(\bar{x}_{i,j}) \Rightarrow t_i} \} \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t \rrbracket_\alpha \mid \text{case } \{ \overline{K_i(\bar{x}_{i,j}) \Rightarrow \langle \llbracket t_i \rrbracket_\alpha \mid \alpha \rangle} \} \rangle$
$\llbracket t.D(\bar{t}_i) \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t \rrbracket_\alpha \mid D(\llbracket \bar{t}_i \rrbracket_\alpha; \alpha) \rangle$
$\llbracket \text{cocase } \{ \overline{D_i(\bar{x}_{i,j}) \Rightarrow t_i} \} \rrbracket$	$:=$	$\text{cocase } \{ \overline{D_i(\bar{x}_{i,j}; \alpha_i) \Rightarrow \langle \llbracket t_i \rrbracket_{\alpha_i} \mid \alpha_i \rangle} \}$
$\llbracket \lambda x. t \rrbracket$	$:=$	$\text{cocase } \{ \text{ap}(x; \alpha) \Rightarrow \langle \llbracket t \rrbracket_\alpha \mid \alpha \rangle \}$
$\llbracket t_1 \ t_2 \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t_1 \rrbracket_\alpha \mid \text{ap}(\llbracket t_2 \rrbracket_\alpha; \alpha) \rangle$
$\llbracket \text{label } \alpha \{ t \} \rrbracket$	$:=$	$\mu\alpha. \langle \llbracket t \rrbracket_\alpha \mid \alpha \rangle$
$\llbracket \text{goto}(t; \alpha) \rrbracket$	$:=$	$\mu\beta. \langle \llbracket t \rrbracket_\beta \mid \alpha \rangle$

$\llbracket \cdot \rrbracket : \text{Fun} \times \text{Covariables} \rightarrow \text{AxCore}$

$\llbracket x \rrbracket_\alpha$	$:=$	x
$\llbracket \ulcorner n \urcorner \rrbracket_\alpha$	$:=$	$\ulcorner n \urcorner$
$\llbracket \odot(t_1, t_2) \rrbracket_\alpha$	$:=$	$\odot(\llbracket t_1 \rrbracket_\alpha, \llbracket t_2 \rrbracket_\alpha; \alpha)$
$\llbracket \text{ifz}(t_1, t_2, t_2) \rrbracket_\alpha$	$:=$	$\text{ifz}(\llbracket t_1 \rrbracket_\alpha, \langle \llbracket t_2 \rrbracket_\alpha \mid \alpha \rangle, \langle \llbracket t_3 \rrbracket_\alpha \mid \alpha \rangle)$
$\llbracket \text{let } x := t_1 \text{ in } t_2 \rrbracket_\alpha$	$:=$	$\langle \llbracket t_1 \rrbracket_\alpha \mid \tilde{\mu}x. \langle \llbracket t_2 \rrbracket_\alpha \mid \alpha \rangle \rangle$
$\llbracket f(\overline{t_i}; \overline{\alpha_j}) \rrbracket_\alpha$	$:=$	$f(\llbracket \overline{t_i} \rrbracket_\alpha; \overline{\alpha_j}, \alpha)$
$\llbracket K(\overline{t_i}) \rrbracket_\alpha$	$:=$	$K(\llbracket \overline{t_i} \rrbracket_\alpha)$
$\llbracket \text{case } t \text{ of } \{ \overline{K_i(\overline{x_{i,j}})} \Rightarrow \overline{t_i} \} \rrbracket_\alpha$	$:=$	$\langle \llbracket t \rrbracket_\alpha \mid \text{case } \{ \overline{K_i(\overline{x_{i,j}})}; \alpha_i \} \Rightarrow \langle \llbracket \overline{t_i} \rrbracket_{\alpha_i} \mid \alpha_i \rangle \rangle$
$\llbracket t.D(\overline{t_i}) \rrbracket_\alpha$	$:=$	$\langle \llbracket t \rrbracket_\alpha \mid D(\llbracket \overline{t_i} \rrbracket_\alpha; \alpha) \rangle$
$\llbracket \text{cocase } \{ \overline{D_i(\overline{x_{i,j}})} \Rightarrow \overline{t_i} \} \rrbracket_\alpha$	$:=$	$\text{cocase } \{ \overline{D_i(\overline{x_{i,j}})}; \alpha_i \} \Rightarrow \langle \llbracket \overline{t_i} \rrbracket_{\alpha_i} \mid \alpha_i \rangle \rangle$
$\llbracket \lambda x. t \rrbracket_\alpha$	$:=$	$\text{cocase } \{ \text{ap}(x; \beta) \Rightarrow \langle \llbracket t \rrbracket_\beta \mid \beta \rangle \}$
$\llbracket t_1 \ t_2 \rrbracket_\alpha$	$:=$	$\langle \llbracket t_1 \rrbracket_\alpha \mid \text{ap}(\llbracket t_2 \rrbracket_\alpha; \alpha) \rangle$
$\llbracket \text{label } \alpha \ \{ t \} \rrbracket_\beta$	$:=$	$\langle \llbracket t \rrbracket_\alpha \mid \alpha \rangle$
$\llbracket \text{goto}(t; \alpha) \rrbracket$	$:=$	$\mu\beta. \langle \llbracket t \rrbracket_\beta \mid \alpha \rangle$